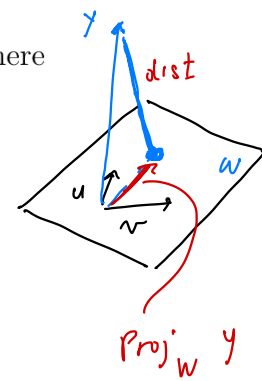


22. Find the distance from the vector y to the subspace $W = \text{Span}\{u, v\}$, where

$$y = \begin{bmatrix} -1 \\ -5 \\ 10 \end{bmatrix}, \quad u = \begin{bmatrix} -2 \\ 0 \\ 0 \end{bmatrix}, \quad v = \begin{bmatrix} 1 \\ 2 \\ -1 \end{bmatrix}.$$



- A. 12.
- B. $2\sqrt{2}$.
- C. $3\sqrt{3}$.
- D. 8.
- E. $3\sqrt{5}$.

$$\text{dist}(y, W) = \|y - \text{Proj}_W y\|$$

$$\text{Proj}_W y = ? =$$

If v_1, v_2 orthogonal basis of W

$$\text{Proj}_W y = \frac{y \cdot v_1}{v_1 \cdot v_1} v_1 + \frac{y \cdot v_2}{v_2 \cdot v_2} v_2$$

In our case $u \cdot v = -2 \neq 0$ not orthogonal
 Need to apply Gram-Schmidt to go from $\{u, v\} \rightarrow \{v_1, v_2\}$

$$v_1 = u$$

$$v_2 = v - \frac{v \cdot u}{u \cdot u} u$$

wrong

$$v_2 = v - \frac{v \cdot v_1}{v_1 \cdot v_1} v_1$$

$$v_1 = \begin{bmatrix} -2 \\ 0 \\ 0 \end{bmatrix}$$

$$v_2 = \begin{bmatrix} 1 \\ 2 \\ -1 \end{bmatrix}$$

$$v_2 = \begin{bmatrix} 1 \\ 2 \\ -1 \end{bmatrix} - \frac{(-2)}{4} \begin{bmatrix} -2 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 2 \\ -1 \end{bmatrix}$$

$$\text{Proj}_W y = \frac{y \cdot v_1}{v_1 \cdot v_1} v_1 + \frac{y \cdot v_2}{v_2 \cdot v_2} v_2 = -\frac{1}{1} v_1 + \frac{-20}{5} v_2 = -v_1 - 4v_2$$

$$= \begin{bmatrix} -1 \\ -8 \\ 4 \end{bmatrix}$$

$$\|y - \text{Proj}_W y\| = \left\| \begin{bmatrix} -1 \\ -5 \\ 10 \end{bmatrix} - \begin{bmatrix} -1 \\ -8 \\ 4 \end{bmatrix} \right\| = \sqrt{45} = 3\sqrt{5}$$

Say $A = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} = I_3$

$\lambda_1 = \lambda_2 = \lambda_3 = 1$ Null $(A - I) = \mathbb{R}^3$
 $A - I = 0_3$

$Q = I_3$ would work!
 any orthogonal matrix

$A = Q I_3 Q^T = Q Q^T = I_3$

$A = P D P^{-1}$

25. Suppose that $A = \begin{bmatrix} 0 & 1 & 1 \\ 1 & 0 & 1 \\ 1 & 1 & 0 \end{bmatrix} = Q D Q^T$ where $D = \begin{bmatrix} \lambda_1 & 0 & 0 \\ 0 & \lambda_2 & 0 \\ 0 & 0 & \lambda_3 \end{bmatrix}$ and Q is an orthogonal matrix. In the following select a pair of Q and D with required properties.

A. $Q = \begin{bmatrix} \frac{1}{\sqrt{2}} & 0 & -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{6}} & -\frac{2}{\sqrt{6}} & \frac{1}{\sqrt{6}} \\ \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{3}} \end{bmatrix}, D = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -2 \end{bmatrix}$

B. $Q = \begin{bmatrix} 1 & 1 & 1 \\ -1 & 0 & 1 \\ 0 & -1 & 1 \end{bmatrix}, D = \begin{bmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 2 \end{bmatrix}$

C. $Q = \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{3}} \\ -\frac{1}{\sqrt{2}} & 0 & \frac{1}{\sqrt{3}} \\ 0 & -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{3}} \end{bmatrix}, D = \begin{bmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 2 \end{bmatrix}$

D. $Q = \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{6}} & \frac{1}{\sqrt{3}} \\ -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{6}} & \frac{1}{\sqrt{3}} \\ 0 & -\frac{2}{\sqrt{6}} & \frac{1}{\sqrt{3}} \end{bmatrix}, D = \begin{bmatrix} 2 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{bmatrix}$

E. $Q = \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{6}} & \frac{1}{\sqrt{3}} \\ -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{6}} & \frac{1}{\sqrt{3}} \\ 0 & -\frac{2}{\sqrt{6}} & \frac{1}{\sqrt{3}} \end{bmatrix}, D = \begin{bmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 2 \end{bmatrix}$

$A = Q D Q^T$
 Q orthogonal
 A orthogonally diagonalizable

\iff
 A symmetric
 $A^T = A$

How do we find D and Q ?

1. Eigenvalues $0 = \det(A - \lambda I) = \begin{vmatrix} -\lambda & 1 & 1 \\ 1 & -\lambda & 1 \\ 1 & 1 & -\lambda \end{vmatrix} = (-\lambda) \begin{vmatrix} -\lambda & 1 \\ 1 & -\lambda \end{vmatrix} - 1 \begin{vmatrix} 1 & 1 \\ 1 & -\lambda \end{vmatrix} + (1) \begin{vmatrix} 1 & -\lambda \\ 1 & 1 \end{vmatrix}$

$= -\lambda(\lambda^2 - 1) - (-\lambda - 1) + (1 + \lambda)$
 $= (\lambda + 1)(-\lambda(\lambda - 1) + 2) = (\lambda + 1)(\lambda + 1)(2 - \lambda)$
 $= (\lambda + 1)^2(2 - \lambda) = 0$

$\lambda_1 = \lambda_2 = -1$ $\lambda_3 = 2$

2. Eigenvectors: $\lambda = 2$ $A - 2I = \begin{bmatrix} 2 & 1 & 1 \\ 1 & -2 & 1 \\ 1 & 1 & -2 \end{bmatrix}$ $\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$

Null $(A - 2I) = \text{span} \left\{ \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \right\}$

$\lambda = -1$ $A - (-1)I = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix}$ Null $(A + I) = 2\text{-dim}$

basis $\begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}$
Gram-Schmidt

rank = 1
 $x_1 + x_2 + x_3 = 0$
 $x_2 = s$ $x_3 = t$

$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} -s-t \\ s \\ t \end{bmatrix} = s \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix} + t \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}$

$\begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ -2 \end{bmatrix}$

$Q = \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} & 0 \\ \frac{1}{\sqrt{6}} & \frac{1}{\sqrt{6}} & \frac{2}{\sqrt{6}} \\ \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{3}} \end{bmatrix}$

rescale to unit vectors

9. Let \mathbb{P}_3 be the space of all polynomials of degree at most 3. Which of the following sets are subspaces of \mathbb{P}_3 ?

- (i) Set of all polynomials p in \mathbb{P}_3 such that $p(0)p(2) = 0$. ← not subspace
- (ii) Set of all polynomials p in \mathbb{P}_3 such that $p(1) = 4p(0) + 2$. ← not subspace since 0 not in W
- (iii) Set of all polynomials p in \mathbb{P}_3 such that $p(1) = 0$ and $p(4) = 0$. subspace

- A. (i) and (ii) only
- B. (i) only
- C. (i) and (iii) only
- D. (ii) and (iii) only
- E. (iii) only

$W \subset V$ vector space

- (1) contains 0
- (2) closed under addition
- (3) closed under scalar multiplication

$V = \mathbb{P}_3$

(i) $W = \{ p \in \mathbb{P}_3 : p(0)p(2) = 0 \}$ not closed under addition
 p in $W \Leftrightarrow$ either 0 or 2 is a root.

$p(t) = t$ in W
 $q(t) = t - 2$ in W

$\frac{p(t) + q(t)}{r(t)} = \frac{2t - 2}{r(t)}$
 $r(0) \cdot r(2) \neq 0$
 r not in W .

W $p(1) = 4p(0) + 2$ | $\frac{z(1)}{0} = \frac{4z(0) + 2}{0}$ false.

0_V polynomial $= 0 = 0 \cdot 1 + 0 \cdot t + 0 \cdot t^2 + 0 \cdot t^3 = 0$
 basis $\mathbb{P}_3 : 1, t, t^2, t^3$

$\Rightarrow z(t) = 0$ for all t

(iii) fails scalar multiplication
 Say p is in W

Is $10p(t)$ in W ?
 $q(t) = 10p(t)$

Say p in W
 q in W $\Rightarrow r = p + q$ in W

$\otimes p(1) = 4p(0) + 2$
 \downarrow
 $q(1) = 4q(0) + 2$?
 $\otimes 10p(1) = 10 \cdot 4p(0) + 2$
 $r(1) = 4r(0) + 2$?

$p(1) + q(1) = 4(p(0) + q(0)) + 2$
 not in W .

19. Let $C[-1, 1]$ be the vector space of all continuous functions defined on $[-1, 1]$. Define with the inner product on $C[-1, 1]$ by

$$\langle f, g \rangle = \int_{-1}^1 f(t)g(t) dt.$$

Find the orthogonal projection of $10t^3 - 5$ onto the subspace spanned by 1 and t (with respect to the above inner product on $C[-1, 1]$).

A. $6t - 10$

B. $6t + 5$

C. $10t^3 - 6t$

D. $10t^3 - 5$

E. $6t - 5$

Formalize: $W = \text{span} \langle 1, t \rangle$
 v_1, v_2

$$f(t) = 10t^3 - 5$$

$$\text{proj}_W(f) = ?$$

Need orthogonal basis of W

are 1 and t orthogonal? Yes

$$\langle 1, t \rangle = \int_{-1}^1 1 \cdot t dt = \int_{-1}^1 t dt = \frac{t^2}{2} \Big|_{-1}^1 = 0$$

$$\text{proj}_W(f) = \frac{\langle f, 1 \rangle}{\langle 1, 1 \rangle} 1 + \frac{\langle f, t \rangle}{\langle t, t \rangle} t$$

$$\langle f, 1 \rangle = \int_{-1}^1 f(t) \cdot 1 dt = \int_{-1}^1 (10t^3 - 5) dt = -10$$

$$\langle 1, 1 \rangle = \int_{-1}^1 1 \cdot 1 dt = 2$$

$$\langle f, t \rangle = \int_{-1}^1 (10t^3 - 5)t dt = 4$$

$$\langle t, t \rangle = \int_{-1}^1 t^2 dt = \frac{t^3}{3} \Big|_{-1}^1 = \frac{2}{3}$$

$$\text{proj}_W(f) = -\frac{10}{2} 1 + \frac{4}{\frac{2}{3}} t = -5 + 6t$$

$$\frac{\langle f, q_1 \rangle}{\langle q_1, q_1 \rangle} q_1 + \frac{\langle f, q_2 \rangle}{\langle q_2, q_2 \rangle} q_2$$

$$\langle q_1, q_2 \rangle = 0$$

If instead of 1, t

$p_1(t), p_2(t)$

given

need to apply G-S:

$$p_1 \quad \left[p_2 - \frac{\langle p_2, p_1 \rangle}{\langle p_1, p_1 \rangle} p_1 \right]$$

1. Consider the system of linear equations

$$x + 2y + 3z = 1$$

$$3x + 5y + 4z = 2$$

$$2x + 3y + a^2z = 0$$

For which values of a is the system inconsistent?

Remark row operation change eigenvalues

$$A = \begin{bmatrix} 2 & 1 \\ 0 & 3 \end{bmatrix}$$

$$\underline{\text{RREF}}(A) = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$\lambda_1 = 2 \quad \lambda_2 = 3$$

$n \times n$

A invertible

$$\text{RREF}(A) = I_n$$

rank is preserved

column space is preserved.

A singular

\iff
det

not-invertible

$$\iff \det(A) = 0.$$

$\iff \lambda = 0$ eigenvalue.

A $n \times n$

$$A = I_n$$

$A \neq 0$

$$Av = v \text{ for all } v.$$

Review:

$$\dot{x} = Ax$$
$$\begin{bmatrix} x_1'(t) \\ \vdots \\ x_n'(t) \end{bmatrix} = \begin{bmatrix} a_{11} & \dots & a_{1n} \\ \vdots & \ddots & \vdots \\ a_{n1} & \dots & a_{nn} \end{bmatrix} \begin{bmatrix} x_1(t) \\ \vdots \\ x_n(t) \end{bmatrix}$$

The solution set forms an n -dimensional vector space
Each solution is uniquely determined by an
initial condition $\vec{x}(0) = \vec{x}_0$

The case when A has n distinct real eigenvalues

$$\lambda_1 < \lambda_2 < \dots < \lambda_n$$

$$\vec{v}_1 \quad \vec{v}_2 \quad \vec{v}_n \quad \leftarrow \text{eigenvectors}$$

general solution :

$$\vec{x}(t) = c_1 e^{\lambda_1 t} \vec{v}_1 + \dots + c_n e^{\lambda_n t} \vec{v}_n$$

If $\vec{x}(0) = \vec{x}_0$ then $\begin{bmatrix} c_1 \\ \vdots \\ c_n \end{bmatrix} = P^{-1} \vec{x}_0$

where $P = [\vec{v}_1, \dots, \vec{v}_n]$