

Review

$$T: V \rightarrow W$$

• Dim Thm: $\dim(N(T)) + \dim(R(T)) = \dim(V)$

• Theorem: $\dim(U) = \dim(W) \Rightarrow$ equivalency of $\left\{ \begin{array}{l} \textcircled{1} \text{ 1-on-1} \\ \textcircled{2} \text{ onto} \\ \textcircled{3} \text{ Nullity}(T) = 0 \end{array} \right.$
 $\Leftrightarrow \underline{\dim(R(T)) = \dim(V)}$

• $[V]_{\beta}$

• $T: V \rightarrow W$ $[T]_{\beta}^{\gamma}$
 $\beta \quad \gamma$
 $v \mapsto T(v)$ $\underline{[T(v)]_{\gamma} = [T]_{\beta}^{\gamma} [v]_{\beta}}$

• Theorem 2.19 V is isomorphic to $W \Leftrightarrow \dim(V) = \dim(W)$

There is $T: V \rightarrow W$
 1-on-1
 onto
 invertible
 T^{-1} is linear

• Theorem 2.20 V, W are v.s. over F .
 $\beta \quad \gamma$
 $\dim(V) = n \quad \dim(W) = m$

$\Phi_{\beta}^{\gamma}: \mathcal{L}(V, W) \rightarrow F^{m \times n}$ is an isomorphism.
 $T \mapsto [T]_{\beta}^{\gamma}$

• Corollary: $\dim(\mathcal{L}(V, W)) = \dim(F^{m \times n}) = mn$.

Ex: $\textcircled{1} \mathcal{L}(\mathbb{R}^3, \mathbb{R}^2) \sim F^{2 \times 3}$
 is isomorphic to

$\textcircled{2} \mathcal{L}(\mathbb{R}^2, \mathbb{R}^3) \sim F^{3 \times 2}$

$\textcircled{4} \mathcal{L}(V, W) \sim F^{n \times m}$

Then 2.20 $\Rightarrow \mathcal{L}(V, W) \sim F^{m \times n}$

$\Rightarrow \dim(\mathcal{L}(V, W)) = \dim(F^{m \times n})$

$$\Rightarrow \mathcal{L}(V, W) \sim F^{n \times m} \quad = mn = \dim(F^{n \times m})$$

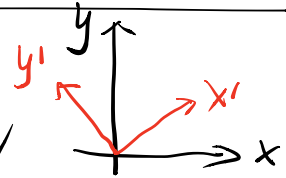
$$\textcircled{5} \quad \mathcal{L}(\mathbb{R}^3, \mathbb{R}^2) \sim \mathcal{L}(\mathbb{R}^2, \mathbb{R}^3)$$

$$\textcircled{6} \quad \mathcal{L}(\underbrace{\mathcal{L}(\mathbb{R}^2, \mathbb{R}^2)}_4, \underbrace{\mathcal{L}(\mathbb{R}^2, \mathbb{R}^2)}_4) \sim \mathbb{R}^{4 \times 4}$$

Elements in $\mathcal{L}(\mathcal{L}(\mathbb{R}^2, \mathbb{R}^2), \mathbb{R})$ are called functionals.

Change of Coordinates

Given $\beta = \{v_1, \dots, v_n\}$ } bases of V
 $\gamma = \{w_1, \dots, w_m\}$ }



Q: Given $[v]_\beta$, what is $[v]_\gamma$?

$$I_V: V \rightarrow V$$

$$v \mapsto v$$

$$[v]_\gamma = [I_V(v)]_\gamma = [I_V]_\beta^\gamma [v]_\beta$$

$$\left(\begin{array}{l} T: V \rightarrow W \\ \beta \quad \gamma \\ v \mapsto T(v) \\ [T]_\beta^\gamma = (a_{ij})_{m \times n} \\ T(v_j) = \sum_{i=1}^m a_{ij} w_i \end{array} \right)$$

$$[I_V]_\beta^\gamma = \left(\begin{array}{c} \text{j-th col} \\ \uparrow \\ \left. \begin{array}{c} \vdots \\ \vdots \\ \vdots \end{array} \right\} \right)_{n \times n} = \begin{pmatrix} 1 & & \\ 0 & 1 & \\ 0 & 0 & 1 \end{pmatrix}$$

Ex: $P_2(\mathbb{R})$ $\beta = \{1, x, x^2\}$
 $\gamma = \{1, (x-1), (x-1)^2\}$

$$I_v(1) = 1 = \underline{1} \cdot 1 + \underline{0} \cdot (x-1) + \underline{0} \cdot (x-1)^2$$

$$I_v(x) = x = \underline{1} \cdot 1 + \underline{1} \cdot (x-1) + \underline{0} \cdot (x-1)^2$$

$$I_v(x^2) = x^2 = a \cdot 1 + b(x-1) + c(x-1)^2$$

$$\text{Solve for } a, b, c \Rightarrow \begin{cases} a=1 \\ b=2 \\ c=1 \end{cases}$$

$$= 1 \cdot 1 + 2 \cdot (x-1) + 1 \cdot (x-1)^2$$

$$\text{Given } f(x) = ax^2 + bx + c$$

$$\text{want } f(x) = A(x-1)^2 + B(x-1) + C$$

$$[f]_{\beta} = \begin{pmatrix} c \\ b \\ a \end{pmatrix} > [f]_{\gamma} = \begin{bmatrix} C \\ B \\ A \end{bmatrix}$$

$$[f]_{\gamma} = [I_v]_{\beta}^{\gamma} [f]_{\beta}$$

$$\begin{bmatrix} C \\ B \\ A \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 2 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} c \\ b \\ a \end{bmatrix} = \begin{pmatrix} a+b+c \\ b+2a \\ a \end{pmatrix}$$

Chapter 3 Linear System (Geometric Meaning of Sols)

$$\text{Example: } W = \left\{ \begin{bmatrix} a \\ b \\ c \\ d \end{bmatrix} \in \mathbb{R}^4 : 2a = b+1, b=2c, 3c+6d=a \right\}$$

$$\begin{cases} 2a = b+1 \\ b = 2c \\ 3c + 6d = a \end{cases} \Rightarrow \begin{cases} 2a - b = 1 \\ b - 2c = 0 \\ -4 + 3c + 6a = 0 \end{cases} \Rightarrow \begin{cases} 2x_1 - x_2 + 0 \cdot x_3 + 0 \cdot x_4 = 1 \\ x_2 - 2x_3 = 0 \\ -x_1 + 3x_3 + 6x_4 = 0 \end{cases}$$

$$\text{Step 0. } \begin{pmatrix} 2 & -1 & 0 & 0 \\ 0 & 1 & -2 & 0 \\ -1 & 0 & 3 & 6 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$$

$$\left(\begin{array}{cccc|c} 2 & -1 & 0 & 0 & 1 \\ 0 & 1 & -2 & 0 & 0 \\ -1 & 0 & 3 & 6 & 0 \end{array} \right) \text{ Augmented Matrix}$$

Step I. Gaussian Elimination (Row Operations to get row echelon form)

$$\left(\begin{array}{cccc|c} 2 & -1 & 0 & 0 & 1 \\ 0 & 1 & -2 & 0 & 0 \\ -1 & 0 & 3 & 6 & 0 \end{array} \right)$$

$r_1 \leftrightarrow r_3$ (Type 1, switch 2 rows)

$$\Rightarrow \left(\begin{array}{cccc|c} -1 & 0 & 3 & 6 & 0 \\ 0 & 1 & -2 & 0 & 0 \\ 2 & -1 & 0 & 0 & 1 \end{array} \right)$$

$(-1) \cdot r_1 \rightarrow r_1$ (Type 2, scalar mul to a row)

$$\Rightarrow \left(\begin{array}{cccc|c} 1 & 0 & -3 & -6 & 0 \\ 0 & 1 & -2 & 0 & 0 \\ 2 & -1 & 0 & 0 & 1 \end{array} \right)$$

$(-2) \cdot r_1 + r_3$ (Type 3, add a scalar multiple of a row to another row)

$$\Rightarrow \left(\begin{array}{cccc|c} 1 & 0 & -3 & -6 & 0 \\ 0 & 1 & -2 & 0 & 0 \\ 0 & -1 & 6 & 12 & 1 \end{array} \right)$$

$r_2 + r_3 \rightarrow r_3$

$$\Rightarrow \left(\begin{array}{cccc|c} 1 & 0 & -3 & -6 & 0 \\ 0 & 1 & -2 & 0 & 0 \\ 0 & 0 & 4 & 12 & 1 \end{array} \right)$$

$\frac{1}{4} \cdot r_3 \rightarrow r_3$

(

$$\Rightarrow \left(\begin{array}{ccc|c} \underline{1} & 0 & -3 & 6 \\ 0 & \underline{1} & -2 & 0 \\ 0 & 0 & \underline{1} & 3 \end{array} \right)$$

Leading ones

Step II For cols w/o leading ones, the corresponding variables become parameter.

$$x_4 = t$$

Solve for the others.

$$\Rightarrow x_3 = \frac{1}{4} - 3x_4 = \frac{1}{4} - 3t$$

$$x_2 = 2x_3 = \frac{1}{2} - 6t$$

$$x_1 = 3x_3 + 6x_4 = \frac{3}{4} - 9t + 6t = \frac{3}{4} - 3t$$

Step III.

$$\begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} = \begin{pmatrix} 3/4 - 3t \\ 1/2 - 6t \\ 1/4 - 3t \\ t \end{pmatrix} = \begin{pmatrix} 3/4 \\ 1/2 \\ 1/4 \\ 0 \end{pmatrix} + \begin{pmatrix} -3t \\ -6t \\ -3t \\ t \end{pmatrix}$$

$$= \begin{pmatrix} 3/4 \\ 1/2 \\ 1/4 \\ 0 \end{pmatrix} + t \begin{pmatrix} -3 \\ -6 \\ -3 \\ 1 \end{pmatrix}, \quad \forall t \in \mathbb{R}.$$

Def Type 1, 2, 3 elementary matrices are generated by Type 1, 2, 3 row/col operations on I.

Ex: $\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \xrightarrow{r_1 \leftrightarrow r_2} \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix}$

$\begin{pmatrix} 1 & 0 & -2 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \xrightarrow{(-2)r_3 + r_1 \rightarrow r_1}$

Theorem 3.1 $A \in F^{m \times n}$. Let B be generated by a row (col) operation on A . Then there is a $m \times m$ ($n \times n$) elementary matrix E s.t.


$$B = EA. \quad (B = AE)$$

If $B = EA$, then B can be generated by a row operation on A .

Theorem 3.2 Elementary matrices are invertible. The inverse is elementary of the same type.

Def $A \in F^{m \times n}$, rank of A , denoted by $\text{rank}(A)$ is the rank of $LA: F^n \rightarrow F^m$

$\text{rank}(LA) \quad x \mapsto Ax$

$\text{dim}(R(LA))$ 

$$\text{Rank}(A) \triangleq \text{Rank}(LA) = \text{dim}(R(LA)) = n - \text{dim}(N(LA))$$

Theorem 3.3 $T: \underset{n}{V}^{\beta} \rightarrow \underset{m}{W}^{\gamma}$

$$\text{rank}(T) = \text{rank}([T]_{\beta}^{\gamma})$$

Proof: Let $A = [T]_{\beta}^{\gamma}$.

$$L_A: F^n \rightarrow F^m$$

$$x \mapsto Ax$$

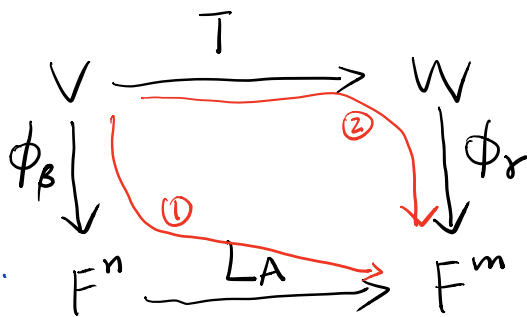
$\phi_{\beta}: V \rightarrow F^n$
 $v \mapsto [v]_{\beta}$
 is an isomorphism
 Independence of β
 $\Rightarrow [v]_{\beta} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$ iff $v = \vec{0}$.

$$N(\phi_{\beta}) = \{\vec{0}\}$$

$\Rightarrow \phi_{\beta}$ is 1-1, onto

$\Rightarrow \phi_{\beta}$ is invertible

$\Rightarrow \phi_{\beta}$ is an isomorphism.



$\phi_{\gamma}: W \rightarrow F^m$
 $w \mapsto [w]_{\gamma}$
 is isomorphism

Diagram Commutes
 $L_A \phi_{\beta} = \phi_{\gamma} T$

$$\textcircled{1} L_A \phi_{\beta} = V \rightarrow F^m$$

$$v \mapsto L_A(\phi_{\beta}(v))$$

$$= L_A([v]_{\beta})$$

$$= [T]_{\beta}^{\gamma} [v]_{\beta}$$

$$\textcircled{2} \phi_{\gamma} T = V \rightarrow F^m$$

$$v \mapsto \phi_{\gamma}(T(v))$$

$$= [T(v)]_{\gamma} = [T]_{\beta}^{\gamma} [v]_{\beta}$$

HW#3 p9 $T: V \rightarrow W$ is isomorphism

V_0 is a subspace of V .

$\Rightarrow \begin{cases} T(V_0) \text{ is a subspace of } W. \end{cases}$

$$\dim(V_0) = \dim(T(V_0))$$

Hint: $\tilde{T}: V_0 \rightarrow T(V_0)$
 $v \mapsto T(v)$

P9 means isomorphism can be removed
when counting dimension of a subspace.

$$LA\phi_\beta = \phi_\alpha T \Rightarrow N(LA\phi_\beta) = N(\phi_\alpha T)$$
$$\Rightarrow \dim(N(LA\phi_\beta)) = \dim(N(\phi_\alpha T))$$

$$\left(\begin{array}{l} P9 \Rightarrow \dim(N(T)) = \dim(\phi_\alpha(N(T))) \\ V_0 = N(T) \\ \phi_\alpha: N(T) \rightarrow \phi_\alpha(N(T)) \Rightarrow \dim(N(T)) = \dim(\phi_\alpha(N(T))) \end{array} \right)$$

$$\Rightarrow \dim(N(LA)) = \dim(N(T))$$

$$(\text{dim Thm}) \Rightarrow \text{rank}(LA) = \text{rank}(T)$$

\parallel
 $\text{rank}(A)$

Want to show $\dim(N(T)) = \dim(N(\phi_\alpha T))$

$$N(\phi_\alpha T) \subseteq V \quad \phi_\alpha T = V \rightarrow F^m$$

$$\underline{N(\phi_\alpha T) = \phi_\alpha(N(T)) ?}$$

$$\phi_\alpha: V \rightarrow F^m$$

$$\phi_\alpha: N(T) \rightarrow \phi_\alpha(N(T))$$

$$\dim(N(T)) = \dim(\phi_\alpha(N(T)))$$