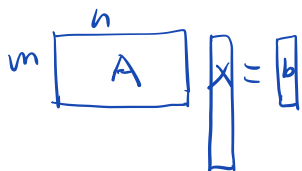


Def Indicator function of a set  $S$

$$\hat{i}_S(x) = \begin{cases} 0 & x \in S \\ +\infty & x \notin S \end{cases}$$

$S$  is convex  
 $\Rightarrow \hat{i}_S$  is convex

Example:  $\begin{cases} \min_{x \in \mathbb{R}^n} \|x\|_1 \\ \text{s.t. } Ax = b \end{cases} (*)$



$$S = \{x \in \mathbb{R}^n : Ax = b\}$$

$$\text{or } S = \{x : Ax = b\}$$

$(*)$  is equivalent to

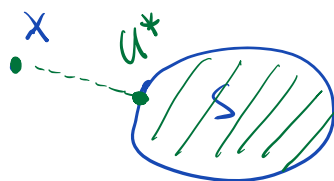
$$\min_{x \in \mathbb{R}^n} \|x\|_1 + \hat{i}_{\{x : Ax = b\}} \quad (**)$$

Theorem The proximal operator of  $\hat{i}_S(x)$  is the projection to  $S$

Proof:  $f(x) = \hat{i}_S(x)$

$$\begin{aligned} \text{Prox}_f^\gamma(x) &= \arg\min_u \left[ f(u) + \frac{1}{2\gamma} \|u - x\|^2 \right] \\ &= \arg\min_u \left[ \hat{i}_S(u) + \frac{1}{2\gamma} \|u - x\|^2 \right] \end{aligned}$$

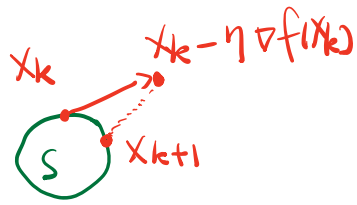
The minimizer is projection of  $x$  onto  $S$



$$P_S(x)$$

## Constrained Minimization

$$\begin{cases} \min_x f(x) \\ \text{s.t. } x \in S \end{cases}$$



$$\Leftrightarrow \min_x [f(x) + g(x)] \quad g(x) = i_S(x)$$

## Projected Gradient Method

$$\begin{aligned} x_{k+1} &= P_S(x_k - \eta \nabla f(x_k)) \\ &= \underline{(I + \eta \partial g)^{-1}}(x_k - \eta \nabla f(x_k)) \end{aligned}$$

## Forward-Backward Splitting:

for solving  $0 \in A(x) + B(x)$  ●  
where  $A$  &  $B$  are operators

$$x_{k+1} = x_k - \eta [A(x_k) + B(x_{k+1})] \bullet$$

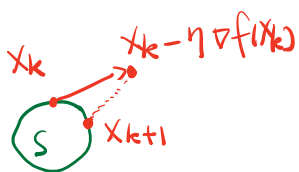
$$(I + \eta B)(x_{k+1}) = x_k - \eta A(x_k)$$

$$\bullet \quad x_{k+1} = \underline{(I + \eta B)^{-1}}(I - \eta A)(x_k)$$

Example: ① Projected Gradient Method

$$\begin{cases} \min_x f(x) \\ \text{s.t. } x \in S \end{cases} \Leftrightarrow \min_x f(x) + g(x) \quad g(x) = i_S(x)$$

$0 \in \nabla f(x) + \partial g(x)$



$$A(x) = \nabla f(x), \quad B(x) = \partial g(x)$$

$$x_{k+1} = \underline{(I + \eta B)^{-1}}(I - \eta A)(x_k)$$

$$= P_S (x_k - \eta \nabla f(x_k))$$

② Proximal Gradient for Composite Optimization

$$\min_x [f(x) + g(x)] \quad \begin{array}{l} f(x) \text{ is smooth} \\ g(x) \text{ is nonsmooth} \end{array}$$

$$A(x) = \nabla f(x), \quad B(x) = \partial g(x)$$

$$\begin{aligned} x_{k+1} &= (I + \eta B)^{-1} (I - \eta A)(x_k) \\ &= (I + \eta \partial g)^{-1} (x_k - \eta \nabla f(x_k)) \end{aligned}$$

③ Implicit - Explicit (IMEX) for ODE

$$\frac{d}{dt} u(t) = A(u) + B(u)$$

$$\bullet \frac{u^{n+1} - u^n}{\Delta t} = \underbrace{A(u^n)}_{\text{explicit}} + \underbrace{B(u^{n+1})}_{\text{implicit}}$$

Example:  $u_t = u_x + u_{xx}$

④ LASSO:  $\min_x \left( \frac{\lambda}{2} \|Ax - b\|^2 + \|x\|_1 \right)$

ISTA (Iterative Shrinkage-Thresholding Alg)

$$x_{k+1} = T_\gamma [x_k - \gamma \lambda A^T (Ax_k - b)]$$

$$\text{Shrinkage } T_\gamma(x)_i = \begin{cases} x_i - \gamma & , \text{ if } x_i > \gamma \\ x_i + \gamma & , \text{ if } x_i < -\gamma \\ 0 & , x_i \in [-\gamma, \gamma] \end{cases}$$

$$\begin{aligned} f(x) &= \frac{\lambda}{2} \|Ax - b\|^2 & g(x) &= \|x\|_1 \\ \nabla f(x) &= \lambda A^T(Ax - b) \end{aligned}$$

$$A(x) = \nabla f(x), \quad B(x) = \partial g(x)$$

$$x_{k+1} = (I + \gamma B)^{-1} (I - \gamma A)(x_k)$$

$$= T_\gamma [x_k - \gamma \lambda A^T(Ax_k - b)]$$

Forward-Backward splitting

{ Projected Gradient  
 Proximal Gradient  
 IMEX  
 ISTA