

Convex Conjugate (Fenchel Dual Function)

$$f^*(x) = \max_y \langle x, y \rangle - f(y) \quad \begin{aligned} & f(x) \text{ is convex} \\ & \Rightarrow (f^*)^* = f \end{aligned}$$

$$\begin{aligned} & \left\{ \begin{array}{l} \text{Primal Problem (P)} \quad f(x) \text{ & } g(x) \text{ are convex} \\ \min_x f(x) + g(x) \end{array} \right. \\ \Leftrightarrow & \left\{ \begin{array}{l} \text{Dual Problem (D)} \\ -\min_y f^*(y) + g^*(-y) \end{array} \right. \Rightarrow \left\{ \begin{array}{l} f^*(y) \text{ is convex} \\ g^*(-y) \text{ is convex} \end{array} \right. \\ \Leftrightarrow & \left\{ \begin{array}{l} \text{Primal Dual (PD)} \\ \min_x \sup_y \langle x, y \rangle - f^*(y) + g(x) \end{array} \right. \end{aligned}$$

Ex: $f(x) = \|x\|_1$,
 $f^*(x) = \begin{cases} 0 & \|x\|_\infty \leq 1 \\ +\infty & \|x\|_\infty > 1 \end{cases}$

Primal Dual Minizers Relation

$$\left\{ \begin{array}{l} x^* \in \partial f^*(y^*) \\ y^* \in -\partial g(x^*) \end{array} \right.$$

In (PD), the cost function is

$$L(x, y) = \langle x, y \rangle - f^*(y) + g(x)$$

$$\frac{\partial L}{\partial x}(x, y) = y + \partial g(x)$$

$$\frac{\partial L}{\partial y}(x, y) = x - \partial f^*(y)$$

Primal Dual (PD)
 $\min_x \sup_y \langle x, y \rangle - f^*(y) + g(x)$

For $\min_x \max_y L(x, y)$, a simple algorithm is

to use gradient descent/ascent for approaching saddle point

$$\begin{cases} \frac{x_{k+1} - x_k}{\eta} = - \frac{\partial L}{\partial x}(x_{k+1}, y_k) \\ \frac{y_{k+1} - y_k}{\tau} = - \frac{\partial L}{\partial y}(x_{k+1}, y_{k+1}) \end{cases}$$

$$\Leftrightarrow \begin{cases} x_{k+1} = x_k - \eta y_k - \eta \partial g(x_{k+1}) \\ y_{k+1} = y_k + \tau x_{k+1} - \tau \partial f^*(y_{k+1}) \end{cases}$$

\Leftrightarrow ① Arrow-Hurwitz Algorithm (1958)

$$\begin{cases} x_{k+1} = (I + \eta \partial g)^{-1}[x_k - \eta y_k] \\ y_{k+1} = (I + \tau \partial f^*)^{-1}[y_k + \tau x_{k+1}] \end{cases} \quad \eta > 0, \tau > 0$$

② Primal-Dual-Hybrid-Gradient (PDHG, 2010)

$$\begin{cases} x_{k+1} = (I + \eta \partial g)^{-1}[x_k - \eta y_k] \\ y_{k+1} = (I + \tau \partial f^*)^{-1}[y_k + \tau(2x_{k+1} - x_k)] \\ y_{k+1} = \text{Prox}_{f^*}^{\frac{\eta}{\tau}}[\frac{1}{\eta}(\eta y_k + 2x_{k+1} - x_k)] \end{cases} \quad \eta, \tau > 0$$

③ PDHG with $\tau = \frac{1}{\eta}$

Moreau-Decomposition

$f(x)$ is convex

$$\text{Prox}_f^\eta(x) + \eta \text{Prox}_{f^*}^{\frac{y}{\eta}}(x/\eta) = x$$

$$\boxed{\text{Let } v_k = x_k - \eta y_k \Leftrightarrow y_k = \frac{x_k - v_k}{\eta}}$$

$$\eta (I + \frac{1}{\eta} \partial f^*)^{-1} \left(\eta [y_k + \frac{1}{\eta} (2x_{k+1} - x_k)] / \eta \right)$$

$$= \eta [y_k + \frac{1}{\eta} (2x_{k+1} - x_k)] - \text{Prox}_f^\eta (2x_{k+1} - x_k + \eta y_k)$$

$$= 2x_{k+1} - (x_k - \eta y_k) - \text{Prox}_f^\eta (2x_{k+1} - (x_k - \eta y_k))$$

$$\begin{cases} x_{k+1} = (I + \eta \partial g)^{-1} [x_k - \eta y_k] \\ y_{k+1} = (I + \frac{1}{\eta} \partial f^*)^{-1} [y_k + \frac{1}{\eta} (2x_{k+1} - x_k)] \end{cases}$$

$$\Rightarrow \begin{cases} x_{k+1} = \text{Prox}_g^\eta (v_k) \end{cases}$$

$$y_{k+1} = \frac{2x_{k+1} - v_k - \text{Prox}_f^\eta (2x_{k+1} - v_k)}{\eta}$$

$$\Rightarrow \begin{cases} x_{k+1} = \text{Prox}_g^\eta (v_k) \end{cases}$$

$$\text{Prox}_f^\eta (2x_{k+1} - v_k) = x_{k+1} - v_k + (x_{k+1} - \eta y_{k+1})$$

$$\Rightarrow \begin{cases} x_{k+1} = \text{Prox}_g^\eta (v_k) \end{cases} \boxed{v_k = x_k - \eta y_k}$$

$$v_{k+1} = v_k - x_{k+1} + \text{Prox}_f^\eta (2x_{k+1} - v_k)$$

$$\begin{aligned} \frac{I + R_f R_g}{2} [v_k] &= \frac{v_k + R_f [R_g(v_k)]}{2} = \frac{1}{2} v_k + \frac{1}{2} R_f [z x_{k+1} - v_k] \\ &= \frac{1}{2} v_k + \frac{1}{2} [2 \text{Prox}_f^\eta (2x_{k+1} - v_k) - (2x_{k+1} - v_k)] \end{aligned}$$

So PDHG ($\eta \tau \leq 1$) with $\tau = \frac{1}{\eta}$

is Douglas-Rachford on (P)

thus converges with $\tau = \frac{1}{\eta}, \forall \eta > 0$.

④ ADM (Alternating Direction Method of Multipliers)
since 1975

$$\min_x f(x) + g(x)$$

$$\Leftrightarrow \min_w f(w) + g(z) \quad \text{s.t. } w = z$$

The Lagrangian for constrained minimization:

$$L(w, z, y) = f(w) + g(z) - \underbrace{\langle y, w-z \rangle}_{\downarrow}$$

Lagrangian multiplier

If (w^*, z^*, y^*) is a solution (saddle point) to

$$\min_w \max_z L(w, z, y)$$

then $w^* = z^*$ is a solution to

$$\min_{w,z} f(w) + g(z) \quad \text{s.t. } w = z$$

Augmented Lagrangian is

$$L(w, z, y) = f(w) + g(z) - \langle y, w-z \rangle + \frac{\tau}{2} \|w-z\|^2$$

The saddle point of Augmented Lagrangian still gives minimizer to (P)

ADMN :

$$\begin{cases} z_{k+1} = \operatorname{argmin}_z \mathcal{L}(w_k, z, y_k) \\ w_{k+1} = \operatorname{argmin}_w \mathcal{L}(w, z_{k+1}, y_k) \\ y_{k+1} = y_k + \sigma \frac{\partial}{\partial y} \mathcal{L}(w_{k+1}, z_{k+1}, y_k) \end{cases} \quad \min_{w,z} \max_y \mathcal{L}(w, z, y)$$

$$\mathcal{L}(w, z, y) = f(w) + g(z) - \langle y, w - z \rangle + \frac{\tau}{2} \|w - z\|^2$$

$$\Leftrightarrow \begin{cases} z_{k+1} = \operatorname{argmin}_z g(z) - \langle y_k, w_k - z \rangle + \frac{\tau}{2} \|w_k - z\|^2 \\ w_{k+1} = \operatorname{argmin}_w f(w) - \langle y_k, w - z_{k+1} \rangle + \frac{\tau}{2} \|w - z_{k+1}\|^2 \\ y_{k+1} = y_k - \sigma (w_{k+1} - z_{k+1}) \end{cases}$$

$$\Leftrightarrow \begin{cases} z_{k+1} = \operatorname{argmin}_z g(z) + \langle y_k, z \rangle + \frac{\tau}{2} \|z\|^2 - \tau \langle w_k, z \rangle \\ w_{k+1} = \operatorname{argmin}_w f(w) - \langle y_k, w \rangle + \frac{\tau}{2} \|w\|^2 - \tau \langle w, z_{k+1} \rangle \\ y_{k+1} = y_k - \sigma (w_{k+1} - z_{k+1}) \end{cases}$$

$$\text{Let } \sigma = \tau \quad \frac{v_{k+1} - y_k}{\eta} = z_{k+1} \quad \& \quad \frac{v_k - y_k}{\eta} = w_k$$

$$\Leftrightarrow \begin{cases} z_{k+1} = \operatorname{argmin}_z g(z) + \frac{\tau}{2} \|z - w_k + \frac{1}{\tau} y_k\|^2 \\ w_{k+1} = \operatorname{argmin}_w f(w) + \frac{\tau}{2} \|w - z_{k+1} - \frac{1}{\tau} y_k\|^2 \\ y_{k+1} = y_k - \tau (w_{k+1} - z_{k+1}) \end{cases} \quad (\text{ADMM})$$

Claim : (ADMM) \Leftrightarrow Douglas-Rankford on (D)

$$(\text{ADMM}) : \begin{cases} z_{k+1} = \operatorname{argmin}_z g(z) + \frac{\tau}{2} \|z - (w_k - \frac{1}{\tau} y_k)\|^2 \\ w_{k+1} = \operatorname{argmin}_w f(w) + \frac{\tau}{2} \|w - (z_{k+1} + \frac{1}{\tau} y_k)\|^2 \\ y_{k+1} = y_k - \tau (w_{k+1} - z_{k+1}) \end{cases}$$

$$\Leftrightarrow \begin{cases} z_{k+1} = \text{Prox}_g^{\gamma_k}(w_k - \frac{1}{\gamma_k}y_k) \\ w_{k+1} = \text{Prox}_f^{y_k}(z_{k+1} + \frac{1}{\gamma_k}y_k) \\ y_{k+1} = y_k - \gamma_k(w_{k+1} - z_{k+1}) \end{cases}$$

Consider $\min_y \underbrace{f^*(y) + g^*(-y)}_{G(y)} + \underbrace{\frac{I + R_F R_G}{2}}_{F(y)}$

Moreau Decomposition

$$\text{Prox}_{f^*}^{\eta}(x) + \eta \text{Prox}_f^{\gamma_h}\left(\frac{x}{\eta}\right) = x$$

$$\text{Prox}_{G^*}^{\eta}(x) = \text{Prox}_{f^*}^{\eta}(x) = x - \eta \text{Prox}_f^{\gamma_h}\left(\frac{x}{\eta}\right) \quad F(x) = g^*(-x)$$

$$\text{Prox}_{F^*}^{\eta}(x) = \arg \min_u [g^*(-u) + \frac{1}{2\eta} \|u - x\|^2] \quad u = -v$$

$$\begin{aligned} u^* &= -v^* \leftarrow \arg \min_v [g^*(v) + \frac{1}{2\eta} \|v - x\|^2] \\ &= -\arg \min_v [g^*(v) + \frac{1}{2\eta} \|v - (-x)\|^2] \\ &= -\text{Prox}_{g^*}^{\gamma_h}(-x) \\ &= \eta \text{Prox}_g^{\gamma_h}\left(-\frac{x}{\eta}\right) - (-x) \\ &= \eta \text{Prox}_g^{\gamma_h}\left(-\frac{x}{\eta}\right) + x \end{aligned}$$

DR :

$$\begin{cases} v_{k+1} = \frac{I + R_F R_G}{2}(v_k) \\ y_k = \text{Prox}_G(v_k) \end{cases}$$

$$\left\{ \begin{array}{l} y = \text{Prox}_g^\eta(v) = v - \eta \text{Prox}_f^{\frac{\eta}{\lambda}}(v/\eta) \\ \frac{I + RFRG}{2}(v) = v - y + \text{Prox}_f[2y - v] \\ = v - y + (2y - v) + \eta \text{Prox}_g^{\frac{\eta}{\lambda}}(-\frac{2y}{\eta} + \frac{v}{\eta}) \\ = y + \eta \text{Prox}_g^{\frac{\eta}{\lambda}}(-\frac{2y}{\eta} + \frac{v}{\eta}) \end{array} \right.$$

$$\left\{ \begin{array}{l} v_{k+1} = y_k + \eta \text{Prox}_g^{\frac{\eta}{\lambda}}(-\frac{2y_k}{\eta} + \frac{v_k}{\eta}) \quad y_k \rightarrow y^* \\ y_{k+1} = v_{k+1} - \eta \text{Prox}_f^{\frac{\eta}{\lambda}}(v_{k+1}/\eta) \quad \min_y f^*(y) + g^*(-y) \\ \text{Let } \frac{v_{k+1} - y_k}{\eta} = z_{k+1} \quad \& \quad \frac{v_k - y_k}{\eta} = w_k \\ \text{Then } \left\{ \begin{array}{l} z_{k+1} = \text{Prox}_g^{\frac{\eta}{\lambda}}(w_k - \frac{1}{\eta}y_k) \quad \text{DR} \\ w_{k+1} = \text{Prox}_f^{\frac{\eta}{\lambda}}(z_{k+1} + \frac{1}{\eta}y_k) \quad \min_y \underbrace{f^*(y)}_{G(y)} + \underbrace{g^*(-y)}_{F(y)} \\ y_{k+1} = y_k - \tau(z_{k+1} - w_{k+1}) \quad (I + RFRG)/2 \end{array} \right. \\ \text{OR} \\ \left\{ \begin{array}{l} z_{k+1} = \text{Prox}_g^{\frac{\eta}{\lambda}}(w_k - \frac{1}{\tau}y_k) \\ w_{k+1} = \text{Prox}_f^{\frac{\eta}{\lambda}}(z_{k+1} + \frac{1}{\tau}y_k) \\ y_{k+1} = y_k - \tau(w_{k+1} - z_{k+1}) \end{array} \right. \quad (\text{ADMM}) \end{array} \right.$$

$$\begin{cases} w_{k+1} = \text{Prox}_f^{\frac{1}{\tau}}(z_k + \frac{1}{\tau}y_k) \\ z_{k+1} = \text{Prox}_g^{\frac{1}{\tau}}(w_{k+1} - \frac{1}{\tau}y_k) \\ y_{k+1} = y_k + \tau(w_{k+1} - z_{k+1}) \end{cases} \quad (\text{ADMM 2})$$

$$\min_y \underbrace{f^*(y)}_{F(y)} + \underbrace{g^*(-y)}_{G(y)}$$

$\frac{(I + R_F R_G)/_2}{\tau}$

Conclusion: Convergence of Douglas-Rachford

\Rightarrow Convergence of $\begin{cases} 1) \text{ ADMM} \\ 2) \text{ PDHG with } \tau = \frac{1}{\eta} \end{cases}$

$$\text{Prox}_F^\eta(x) = x - \eta \text{Prox}_{F^*}^{y_\eta}\left(\frac{x}{\eta}\right) = x - \eta \text{Prox}_g^{y_\eta}\left(-\frac{x}{\eta}\right)$$

$$\begin{aligned} F^*(x) &= \max_y \langle x, y \rangle - F(y) \\ &= \max_y \langle x, y \rangle - g^*(-y) \\ &= \max_y \langle -x, -y \rangle - g^*(-y) \\ &= \max_v \langle -x, v \rangle - g^*(v) \\ &= g^{**}(-x) = g(-x) \end{aligned}$$

$$\begin{aligned} \text{Prox}_{F^*}^T(x) &= \underset{u}{\operatorname{argmin}} F^*(u) + \frac{1}{2T} \|u-x\|^2 \\ &= \underset{u}{\operatorname{argmin}} g(-u) + \frac{1}{2T} \|u-x\|^2 \\ &= \underset{v}{\operatorname{argmin}} g(v) + \frac{1}{2T} \|v+x\|^2 = \text{Prox}_g^T(-x) \end{aligned}$$