ON THE WEAK-TYPE CONSTANT OF THE BEURLING-AHLFORS TRANSFORM

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1. Introduction

The Beurling-Ahlfors operator $B$ defined on $L^p(\mathbb{C})$ by

$$Bf(z) = \frac{1}{\pi} \text{p.v.} \int_{\mathbb{C}} \frac{f(w)}{(z-w)^2} dm(w)$$

is a well-known example of a Calderón-Zygmund singular integral operator of convolution type. The operator arises naturally in the study of the regularity of solutions of the Beltrami equation and thus has applications to quasiconformal mapping theory and PDE. See [1], [9], [12], [14], [15]. In particular, the Iwaniec conjecture [12] that the $L^p$ norm

$$\|B\|_p = p^* - 1,$$

where $1 < p < \infty$ and $p^* = \max\{p, \frac{p}{p-1}\}$, is partly motivated by its relation to the Gehring-Reich conjecture proved by Astala in [1]. (The lower bound of $(p^* - 1)$ was obtained by Lehto [16] in 1965.) Recent work has revealed $B$ as an exemplary junction between Fourier analysis and probability, and martingale methods established by Burkholder have led to the present best known estimates on $\|B\|_p$. See [10], [3], [2].

In this paper we investigate the action of $B$ on the radial function subspaces (for $m$ non-negative integer)

$$\mathcal{R}_m^p = \left\{ f \in L^p(\mathbb{C}) : f(re^{i\theta}) = H(r)e^{-im\theta} \right\},$$

and arrive at a corresponding family of one-dimensional operators $\{\Lambda_m\}_{m \geq 0}$ on $L^p([0, \infty))$, defined by

$$\Lambda_m g(u) = (\mathcal{H}_m - I) g(u) = \frac{2m+2}{m+2} \int_0^1 g(uv^{\frac{2}{m+2}}) dv - g(u)$$

$$= \int_0^1 g(uv)(m+1)v^{\frac{m}{2}} dv - g(u).$$

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G.H. Hardy in his attempts to simplify the proof of Hilbert’s double series theorem showed in 1920 (Theorem 327 in [11], Sec. 2.4 in [18]), that

\[ \int_0^\infty |H_0 g(u)|^p du < \left( \frac{p}{p-1} \right)^p \int_0^\infty |g(u)|^p du. \]

This is Hardy’s famous inequality with best constant, that has led to wide research in basic inequalities and which is at the heart of much of modern harmonic analysis. In view of this fact, \( \mathcal{H}_m \) may be referred as the Hardy average operator of order \( m \), and \( \mathcal{H} := \mathcal{H}_0 \) as simply the Hardy operator.

The next objective is naturally to exploit the connection between \( B \) and the \( \Lambda \) family. The following is an immediate but non-trivial fact that follows from \( B \) being an \( L^2 \) isometry.

**Theorem 1.1.** For each \( m \geq 0 \), \( \Lambda_m \) is an \( L^2([0,\infty)) \) isometry.

Similarly, since \( \Lambda_m \) is a one dimensional operator, it is likely easier to derive information on its norm, and whatever gained automatically gives parallel information on \( B|_{\mathcal{R}_m^p} \). Indeed, better norm estimates are obtained on these spaces; and in the special case \( m = 0 \) and \( 1 < p \leq 2 \), the \( L^p \) norm \( \|\Lambda_0\|_p \) equals \( (p^* - 1) \) which is a direct consequence of results in [4]. These results are discussed in sections 4 and 5. The main result of this paper is the computation of the weak-type constant of \( \Lambda_0 \) and thereby a new lower bound for the weak-type constant of \( B \). Recall that the general Calderón-Zygmund theory shows that \( B \) is \( L^p \) bounded for \( 1 < p < \infty \) but not for \( p = 1 \). Instead there exists a universal constant \( C_1 > 0 \) such that for all \( f \in L^1(\mathbb{C}) \) and \( \lambda > 0 \), we have

\[ m\{z \in \mathbb{C} : |Bf(z)| > \lambda \} \leq \frac{C_1}{\lambda} \|f\|_1. \]

This is the weak-type \((1,1)\) inequality, and the minimal \( C_1 \) is the weak-type \((1,1)\) norm of \( B \) denoted in this paper by \( \|B\|_{w(1)} \).

**Theorem 1.2.**

(1.5) \[ \|B\|_{w(1)} \geq \|\Lambda_0\|_{w(1)} = \frac{1}{\log 2}. \]

**Remark 1.1.** In the first version of this paper, the authors had made the assumption in the proof of Theorem 3.2 (without actually calculating (3.4)) that \( \mu([0,\beta]) = 0 \) is an optimizing condition. This had given the smaller bound of \( \frac{2}{\log 2} \). James Gill (personal communication) pointed out that this condition is not optimizing and that the constant is indeed \( \frac{1}{\log 2} \). Except for the change in (3.3) and (3.4), the proof is exactly the same as in the original version.

The rest of the paper is organized as follows. In §2, we prove the isometry of \( \Lambda_m \) on \( L^2 \) and along the way derive various properties of \( B \) acting on \( \mathcal{R}_m^p \). In this section, we also prove Theorem 1.1. In §3, we prove the weak–type estimates for \( \Lambda_0 \) and derive the consequences for \( B \). In §4 and §5, we derive \( L^p \) estimates for \( \Lambda_0 \) and \( \Lambda_m \), respectively. We end the paper with a
conjecture on the possible best weak-type $(1, 1)$ constant for $B$ restricted to real valued functions.

2. $\Lambda_m$ is an $L^2$ isometry

T. Iwaniec shows in [13] that the $BMO_2$ norm of $B$ is exactly 3. In section 1, he writes (independent of his main result) “The following formulas are worth recording.” For each integer $m \geq 0$ let

$$\rho_{m,r}(z) = \overline{z}^m \chi_{B(0,r)}(z).$$

Then

$$B\rho_{m,r}(z) = \frac{r^{2m+2}}{z^{m+2}} \chi_{B(0,r)^c}(z).$$

Here $B(0,r) = \{ z \in \mathbb{C} : |z| < r \}$ is the disk of radius $r$ and $B(0,r)^c = \mathbb{C} \setminus B(0,r)$ is the complement. Iwaniec actually proves this formula for the special case when $r = 1$. The above formula follows from this since the Beurling-Ahlfors commutes with dilations. It is used below to find the formula that relates $\Lambda_m$ and $B$.

Remark 2.1. (1) Iwaniec also gives $B\rho(z) = (1 + \log |z|^2) \chi_B(z)$ where $\rho(z) = \left( \frac{1}{|z|} \right)^2 \chi_B(z)$. Since $\int B\rho \cdot \overline{g} = \int \rho B\overline{g}$ where $g$ is radial complex valued function (see Theorem 2.1), the action of $B$ on $\rho$ corresponds to the action of the adjoint of $\Lambda_0$. Hence for such a class of functions, we expect parallel $L^p$ estimates in the range $2 < p < \infty$.

(2) James Gill (personal communication) has computed that the adjoint also has the weak-type constant $\frac{1}{\log 2}$. This is work in preparation.

(3) We may also ask the question whether the non-negative integer $m$ may be replaced by non-negative reals and similar formulas obtained.

2.1. $\Lambda_m$ and $B$. Let $S^p_m$ be the subspace of $\mathcal{R}^p_m$ containing functions of the form

$$\overline{z}^m \sum_k a_k \chi_{B(0,r_k)}(z)$$

where $a_k \in \mathbb{C}$ for each $k$ and $0 < r_1 < r_2 < \cdots$.

Proposition 2.1. $S^p_m$ is an $L^p$ dense subset of $\mathcal{R}^p_m$. That is, given $\epsilon > 0$ and $f \in \mathcal{R}^p_m$, there exists $g \in S^p_m$ such that $\|f - g\|_p < \epsilon$.

Proof. Let $f(z) = \frac{z^m}{|z|^m} h(z)$ where without loss of generality $h \in \mathcal{R}^p_0(\mathbb{C}) \cap C^\infty_c(\mathbb{C})$. Assume $f$ is supported in $B(0,R)$. For $M$ a positive integer and $N$ such that $\lceil \frac{N}{M} \rceil = \lceil R \rceil$, define

$$f_M(z) = \frac{z^m}{|z|^m} \sum_{k=1}^N h\left( \frac{k - 1}{M} \right) \chi_{A_k}(z)$$
where $A_k = B(0, \frac{k}{M}) \setminus B(0, \frac{k-1}{M})$. Choose $M$ large so that $\|f - f_M\|_\infty < \epsilon$. Then $\|f - f_M\|_p < \epsilon|B(0, R)|$. In particular, $f_M \to f$ in $L^p$. Therefore assume without loss of generality that

$$f(z) = \frac{z^m}{|z|^m} \sum_{k=1}^N a_k \chi_{B(0, \frac{k}{M})}(z) = \frac{z^m}{|z|^m} \sum_{k=1}^N \tilde{a}_k \chi_{A_k}(z).$$

Define also for $\delta > 0$

$$\tilde{f}_\delta(z) = \frac{z^m}{|z|^m} \sum_{k=2}^N \tilde{a}_k \left( \frac{|z|^m}{r_{k-1}} - 1 \right) \chi_{A_k}(z).$$

Then

$$|\tilde{f}_\delta - f| \leq |f\chi_{B(0,\delta)}| + \sum_{k=[\delta M]}^N |\tilde{a}_k| \left( \frac{|z|^m}{r_{k-1}} - 1 \right) \chi_{A_k}(z) \leq |f\chi_{B(0,\delta)}| + \left( \frac{|z|^m}{r_{k-1}} - 1 \right) |f\chi_{B(0,\delta)}|^c.$$ 

It is clear that $\|\tilde{f}_\delta - f\|_p < \epsilon$ for $\delta$ small and $M$ large. Since $g = \tilde{f}_\delta$ is in $S^p_{m+2}$, the proof is complete.

Given $f(z) = z^m \sum_k a_k \chi_{B(0, r_k)}(z)$, it follows from (2.2) that

$$(2.3) \quad Bf(z) = \sum_{j=1}^j a_k r_j^{2m+2} \frac{z^m}{z^{m+2}}, \quad r_j \leq |z| < r_{j+1}.$$ 

The fundamental representation theorem is

**Theorem 2.1.** Let $f \in \mathcal{R}_m^p$. Then $Bf \in \mathcal{R}_{m+2}^p$ and

$$(2.4) \quad Bf(z) = \frac{z^2}{|z|^2} \left[ \frac{2m+2}{m+2} \int_0^1 f\left( \frac{1}{m+2} z \right) dv - f(z) \right].$$ 

**Proof.** The formula clearly shows that $B : \mathcal{R}_m^p \to \mathcal{R}_{m+2}^p$. It suffices to prove the theorem for $f(z) = z^m \sum_k a_k \chi_{B_k}(z)$. The general case follows by
approximation. Let $r_n \leq |z| < r_{n+1}$ and define $\sigma(k, z) = \left( \frac{r_k}{|z|} \right)^{m+2}$.

\[
\int_0^1 f(v^{m+2}z)dv = \bar{z}^m \int_0^1 v^{m+2} \sum_k a_k \chi_{B_k}(v^{m+2}z)dv
\]
\[
= \bar{z}^m \int_0^1 v^{m+2} \sum_k a_k \chi_{[0,\sigma(k,z)]}(v)dv
\]
\[
= \sum_{k=1}^n \left( \int_{\sigma(k-1,z)}^{\sigma(k,z)} v^{m+2} \sum_{l=k}^{\infty} a_l dv \right) \bar{z}^m
\]
\[
+ \int_{\sigma(n,z)}^1 v^{m+2} \sum_{l=n+1}^{\infty} a_l \bar{z}^m
\]
\[
= \frac{m+2}{2} \frac{\bar{z}^m}{|z|^{2m+2}} \sum_{k=1}^n \left( \sum_{l=k}^{\infty} a_l \right) \left( r_k^{2m+2} - r_{k-1}^{2m+2} \right)
\]
\[
+ \frac{m+2}{2} \frac{\bar{z}^m}{|z|^{2m+2}} \left( 1 - \left( \frac{r_n}{|z|} \right)^{2m+2} \right) \left( \sum_{l=n+1}^{\infty} a_l \right).
\]

Since $f(z) = \sum_{l=n+1}^{\infty} a_l$, it follows that
\[
\frac{\bar{z}^2}{|z|^2} \left( \frac{2m+2}{m+2} \int_0^1 f(v^{m+2}z)dv - f(z) \right) = \frac{1}{z^{m+2}} \sum_{l=1}^{n} a_l r_l^{2m+2}.
\]

This by (2.3) equals $Bf(z)$.

Given $f \in L^2(0, \infty)$, let $\tilde{f}(z) = f(|z|^2)$ be the associated radial function and $F(z) = \frac{\bar{z}^m}{|z|^{m+2}} \tilde{f}(z)$. Define the operator $\tilde{\Lambda}_m$ by
\[
\tilde{\Lambda}_m g(z) = \frac{2m+2}{m+2} \int_0^1 g(v^{m+2}z)dv - g(z),
\]
so that $BF(z) = \left( \frac{\bar{z}}{|z|} \right)^2 \tilde{\Lambda}_m F(z)$ by Theorem 2.1. Observe finally that

\[
(2.5) \quad BF(z) = \frac{\bar{z}^{m+2}}{|z|^{m+2}} \Lambda_m f(|z|^2).
\]

2.2. Proof of Theorem 1.1. The first step is to prove that $\Lambda_m$ preserves the $L^2$-inner product.

**Theorem 2.2.** Let $f, g \in L^2(0, \infty)$. Then
\[
\int_0^\infty \Lambda_m f(u) \bar{\Lambda}_m \bar{g}(u)du = \int_0^\infty f(u) \bar{g}(u)du.
\]
Proof.

\[
\int_0^\infty \Lambda_m f(u) \Lambda_m \overline{g}(u) du = \int_0^\infty \Lambda_m f(|z|^2) \overline{\Lambda_m g(|z|^2)} d(|z|^2)
\]

\[
= \int_0^\infty \Lambda_m \bar{f}(re^{i\theta}) \overline{\Lambda_m g(re^{i\theta})} dr
\]

\[
= \frac{1}{\pi} \int_0^\infty \int_{\partial B(0,r)} \Lambda_m \bar{f}(\eta) \overline{\Lambda_m g(\eta)} d\sigma(\eta) dr
\]

\[
= \frac{1}{\pi} \int_{\mathbb{R}^2} \Lambda_m \tilde{F}(z) \overline{\Lambda_m \tilde{G}(z)} dz.
\]

In the last line, \( F(z) = \frac{z^m}{|z|^m} \tilde{f}(z) \) and \( G(z) = \frac{z^m}{|z|^m} \tilde{g}(z) \). Due to the conjugation of \( G \), the two unimodular terms cancel out and the integral value does not change. Observe importantly that \( F, G \in \mathcal{R}_m^2 \), hence for instance,

\[
BF(z) = \frac{z^2}{|z|^2} \Lambda_m F(z).
\]

As a consequence,

\[
\int_0^\infty \Lambda_m f(u) \Lambda_m \overline{g}(u) du = \frac{1}{\pi} \int_{\mathbb{R}^2} BF(z) \overline{BG(z)} dz
\]

\[
= \frac{1}{\pi} \int_{\mathbb{R}^2} F(z) \overline{G(z)} dz
\]

\[
= \cdots = \int_0^\infty f(u) \overline{g}(u) du.
\]

This completes the proof of the theorem. \( \square \)

Proof. An alternate direct proof may also be obtained using the integration-by-parts technique employed by Hardy. We outline such a proof.

Let \( f, g \in C_c^\infty([0, \infty)) \). A change of variables reveals that

\[
\mathcal{H}_m f(u) = \frac{1}{u^{m+2}} \int_0^u f(v)(m+1)v^{m/2} dv.
\]

Let \( F(u) = \int_0^u f(v)(m+1)v^{m/2} dv \) and \( G(u) = \int_0^u g(v)(m+1)v^{m/2} dv \). Then

\[
\int \Lambda_m f \cdot \Lambda_m \overline{g} = \int \left( F - \frac{m+2}{u^{m+2}} f \right) \cdot \left( \overline{G} - \frac{m+2}{u^{m+2}} \overline{g} \right)
\]

\[
= \frac{1}{m+1} \int \left[ (\overline{G} - \frac{m+2}{u^{m+2}} \overline{g})(\frac{m}{2} f - uf') + (F - \frac{m+2}{u^{m+2}} f)(\frac{m}{2} \overline{g} - u\overline{g}') \right] u^{-m+2} du
\]

\[
= -\frac{m}{m+1} \int f \overline{g} + \frac{m}{2(m+1)} \int u^{-m+2} (\overline{G}f + F\overline{g})
\]

\[
+ \frac{1}{m+1} \int \left[ (\overline{G} - \frac{m+2}{u^{m+2}} \overline{g})(-u^{m/2} f') + (F - \frac{m+2}{u^{m+2}} f)(-u^{m/2} \overline{g}') \right]
\]

This completes the proof of the theorem. \( \square \)
Applying integration-by-parts to the last term shows that it equals
\[-\frac{m}{2(m+1)} \int u^{-\frac{m+2}{2}} (Gf + F\tilde{g}) + \frac{2m+1}{m+1} \int f\tilde{g}.\]
Hence the sum equals \(\int f\tilde{g}\) as required. \(\square\)

While this proof is straight forward, it would not be intuitive to guess that \(\Lambda_m\) preserves inner-product without knowledge of its relationship with \(B\). Furthermore, our proof that \(\Lambda_m\) is a surjection, and hence an isometry on \(L^2([0,\infty))\), depends on the corresponding property of \(B\).

**Theorem 2.3.** \(\Lambda_m : L^2([0,\infty)) \rightarrow L^2([0,\infty))\) is a surjection.

**Proof.** Let \(h \in L^2([0,\infty))\) and let \(\tilde{h} \in L^2(\mathbb{C})\) be the associated radial function: \(\tilde{h}(z) = h(|z|^2)\). Define \(H(z) = \frac{z^m}{|z|^{m+2}} \tilde{h}(z)\). Then it is easy to check \(\tilde{H} = \tilde{B}H \in \mathcal{R}_m^2\). To see this, write out the singular integral and observe how the argument of \(\tilde{H}\) changes as that of \(z\) is varied. It follows that \(H(z) = \frac{z^2}{|z|^2} \Lambda_m \tilde{H}(z)\) and \(\tilde{h}(z) = \tilde{\Lambda}_m \left(\frac{|z|^m}{2m} H\right)(z)\). It follows that \(h\) is in the range of \(\Lambda_m\). \(\square\)

Thus \(\Lambda_m\) preserves inner product and is onto. Therefore it is an \(L^2\) isometry; this completes the proof of Theorem 1.1.

### 3. The weak-type estimates for \(\Lambda_0\) and \(B\)

\(\Lambda := \Lambda_0\) is defined on \(L^1([0,\infty))\) by
\[
\Lambda f(u) = \mathcal{H}f(u) - f(u) = \frac{1}{u} \int_0^u f(v)dv - f(u) = \int_0^1 f(uv)dv - f(u).
\]
Since the Delta measure plays a crucial role in the optimization procedures of the proofs, it is useful to generalize the definition for arbitrary finite measures as follows. Let \(d\mu(v) = f(v)dv + d\nu(v)\) where \(\nu\) is mutually singular with respect to the Lebesgue measure. Define
\[
\Lambda \mu(u) = \mathcal{H}\mu(u) - f(u) = \frac{\mu([0,u])}{u} - f(u).
\]
Define the weak-type “norm” of a function \(F\) as
\[
\|F\|_{w(1)} = \sup_{\lambda > 0} \lambda \{u \in [0,\infty) : |F(u)| > \lambda\},
\]
where \(d\mu(u)\) as always denotes the Lebesgue measure.
Theorem 3.1. Let \( d\mu = f \, dv + dv \) be a positive finite measure \([0, \infty)\). Then
\[
\|\Lambda \mu\|_{w(1)} \leq \|\mu\|_1.
\]
This is best possible.

Proof. Without loss of generality, assume \( \|\mu\|_1 = 1 \). Observe
\begin{enumerate}
\item \( \mathcal{H} \delta_0(x) = \frac{1}{x} \).
\item Since \( \mu \geq 0, |\Lambda \mu| \leq \max(f, \mathcal{H} \mu) \).
\item \( \{ \max(f, \mathcal{H} \mu) \geq \lambda \} = \{ \max(f \wedge \lambda, \mathcal{H} \mu) \geq \lambda \} \).
\item If \( \int_0^x f \leq \int_0^x g \) for all \( x > 0 \), then \( \mathcal{H} f \leq \mathcal{H} g \).
\end{enumerate}

Based on the third and fourth observations, it is optimizing to assume that \( \mu = a \delta_0 + \lambda \chi_E \), where \( m(E) = \frac{1-a}{\lambda} \). (In regions where \( f < \lambda, |\Lambda \mu| \geq \lambda \) only if \( \mathcal{H} \mu \geq \lambda \), and \( \mathcal{H} \mu \) would be higher if we took the \( f \) values here, along with the singular \( \nu \) measure, and stored them at 0.)

So assume \( \mu \) has the above form with \( f = \lambda \chi_E \). Then
\[
\mathcal{H} \mu(u) = \frac{a}{u} + \frac{\lambda |E \cap [0, u]|}{u}.
\]
\( \mathcal{H} \mu(u) \geq \lambda \) iff \( |E \cap [0, u]| \geq \frac{\lambda u - a}{\lambda} \). Since \( u - |E \cap [0, u]| = |[0, u] \setminus E| \), it follows that \( \mathcal{H} \mu(u) \geq \lambda \) if and only if \( |[0, u] \setminus E| \leq \frac{a}{\lambda} \). Let \( u^* \) be the maximal such \( u \). Note that \( u^* \leq \frac{1}{\lambda} \).

The set \( \{ \max(f, \mathcal{H} \mu) \geq \lambda \} \) has an intersection within \([0, u^*] \) and outside of it. The outside part reduces to \( E \setminus [0, u^*] \). The inside part is the union of \( \{ \mathcal{H} \mu \geq \lambda \} \) and \( E \cap [0, u^*] \). This is same as
\[
(\{ \mathcal{H} \mu \geq \lambda \} \setminus E) \cup (E \cap [0, u^*]) \subset ([0, u^*] \setminus E) \cup (E \cap [0, u^*]).
\]

Thus joining the outside and inside shows that
\[
\{ \max(f, \mathcal{H} \mu) \geq \lambda \} \subset ([0, u^*] \setminus E) \cup E.
\]

Therefore, conclude
\[
m(|\Lambda \mu| \geq \lambda) \leq m(\max(f, \mathcal{H} \mu) \geq \lambda) \leq |[0, u^*] \setminus E| + |E| \leq \frac{a}{\lambda} + \frac{1-a}{\lambda} = 1.
\]

Since \( \|\mu\|_1 = 1 \), this completes the proof of the theorem. To show this is optimal, just take \( \mu \) to be the delta measure \( \delta_0 \). \( \square \)

Alternatively, we can argue as follows:

Proof. Let \( a_1 = \sup \{ x > 0 : \mathcal{H} \mu(x) \geq \lambda \} \). Then \( \mathcal{H} \mu(a_1) = \lambda \) and \( \mathcal{H} \mu(x) < \lambda \) for \( x > a_1 \). Store all of \( \mu([0, a_1)) \) in 0: that is, replace \( \mu \) by \( \mu([0, a_1)) \delta_0 + \mu|_{(a_1, \infty)} \). Observe that the choice of \( a_1 \) implies \( \mu([0, a_1)) = \lambda a_1 \). In particular,
\[
m \{ x < a_1 : |\Lambda \mu(x)| \geq \lambda \} = a_1 = \frac{\mu([0, a_1))}{\lambda}.
\]
Notice that \( \{ x > a_1 : |\Lambda \mu(x)| \geq \lambda \} \) is a subset of \( \{ x > a_1 : f(x) \geq \lambda \} \) since
\[ |\Lambda f| \leq \max(f, H\mu) \] and \( H\mu(x) < \lambda \) here. Therefore
\[
(3.2) \quad m \{ x > a_1 : |\Lambda \mu(x)| \geq \lambda \} \leq \frac{1}{\lambda} \int_{a_1}^{\infty} f \leq \frac{\mu((a_1, \infty))}{\lambda}.
\]
Combining (3.1) and (3.2) finishes the proof. \( \square \)

Thus the positive measure case follows from a rather trivial looking proof. The behavior of \( \Lambda \) on positive measures is controlled by that of the maximum of the Hardy operator and the identity, which fortunately is easy to analyze in the weak-type case. What happens then when the domain is the general finite measure space? It is easy to see that since \( |H\mu| \leq H|\mu| \), the weak-type norm of the Hardy operator remains the same (one) with the delta measure \( \delta_0 \) as extremal. The \( \Lambda \) operator on the other hand appears much more formidable, and the subtracted \( H - I \) actually turns out to have a higher weak-type constant \( \frac{1}{\log 2} \) as stated in Theorem 1.2. Fortunately again, the operator allows for a constructive optimization procedure (in the weak-type case) that can be taken to the end. We begin with obtaining upper estimates by finding the weak-type constants of a couple of bigger operators.

Consider \( \Theta \) defined by
\[
\Theta f(u) = f(u) + \frac{\|f\|_1}{u}.
\]
It is clear that \( |\Lambda f| \leq H|f| + |f| \leq \Theta|f| \) and hence \( \|\Lambda\|_{w(1)} \leq \|H + I\|_{w(1)} \leq \|\Theta\|_{w(1)} \).

**Proposition 3.1.** \( \|\Theta\|_{w(1)} \) is the unique solution of the equation
\[
\alpha - e^{\alpha-2} = 0.
\]

**Proof.** Without loss of generality assume \( \|f\|_1 = 1 \) and non-negative. Note that \( \Theta f(u) = f(u) + \frac{1}{u} \) is bigger than \( \lambda \) when \( u \leq \frac{1}{\lambda} \). To get the upper bound, consider the graph of \( \frac{1}{u} \) and find \( \alpha \) such that
\[
\int_{\frac{1}{\lambda}}^{\alpha} (\lambda - \frac{1}{u})du = 1.
\]

Thus the contribution of
\[
f(u) = (\lambda - \frac{1}{u})\chi_{(\frac{1}{\lambda}, \alpha)}(u)
\]
is kept completely separate from the place where \( \frac{1}{u} \) exceeds \( \lambda \). Moreover, this is the optimal way to choose \( f \) since at points further away, more height is required to make \( f(u) + 1/u = \lambda \).

It is a simple exercise to show that \( \alpha \) solves the equation \( \alpha \lambda - e^{\alpha \lambda-2} = 0 \). As this choice of \( f \) is optimizing, the weak-type constant of \( \Theta \) is as required. By a numerical calculation we see that the value is slightly smaller than 3.15. \( \square \)

A better estimate is obtained by considering \( H + I \).
Proposition 3.2. \[ \| \Lambda \|_{w(1)} \leq \| H + I \|_{w(1)} = 2. \]

Proof. It suffices to work with non-negative functions. Observe that \( Hf + f \leq 2 \max\{Hf, f\} \), and hence 2 is an upper bound (following the proof of Theorem 3.1). To see that it is also a lower bound, consider \( f(u) = \frac{\lambda}{2} \chi_{[0,1]} \).

The next theorem estimates \( \| \Lambda \|_{w(1)} \) from below.

Theorem 3.2. \( \| \Lambda \|_{w(1)} \geq \frac{1}{\log 2} \).

Proof. In the previous theorem, it is shown that the positive function case is optimized by the delta measure. Then \( \Lambda \delta_0(u) = H\delta_0(u) = \frac{1}{u} \). Starting at \( u = \frac{1}{\lambda} \), a negative function \( f = f \chi_{(\frac{1}{\lambda}, \beta)} \) can be added so that \( \Lambda \mu = H\mu - f = \lambda \) in \( (\frac{1}{\lambda}, \beta) \). This addition increases both the measure in consideration and the total integral. It is shown that the optimal \( \beta = \frac{2}{\lambda} \).

Let \( d\mu(u) = \delta_0(u) + f(u)du \) satisfy the conditions:

1. For \( 0 \leq t < \beta - \frac{1}{\lambda} \),
   \[ \frac{1 + \int_{\frac{1}{\lambda}}^{1/\lambda+t} f(v)dv}{1/\lambda + t} - f\left(\frac{1}{\lambda} + t\right) = \lambda. \]

2. \( f(u) = 0 \) for \( u > \beta \).

The unique solution is

\[ d\mu(u) = \delta_0(u) - \lambda \log(\lambda u) \chi_{(\frac{1}{\lambda}, \beta)}(u)du. \]

It can be verified that

\[ \frac{\lambda m\{\| \Lambda \mu \| \geq \lambda \}}{\| \mu \|} = \frac{\beta \lambda}{2 - \beta \lambda + \beta \lambda \log \beta \lambda}, \]

which acquires maximum value \( \frac{1}{\log 2} \) at \( \beta = \frac{2}{\lambda} \). Hence \( \frac{1}{\log 2} \) is a lower bound for the weak-type constant.

From Theorem 3.2 it follows immediately that

Corollary 3.1. \( \| B \|_{w(1)} \geq \frac{1}{\log 2} \).
Proof. Let \( \tilde{f}(z) = f(|z|^2) \) be radial.

\[
m(|B\tilde{f}| \geq \lambda) = m(|\tilde{\Lambda}\tilde{f}| \geq \lambda)
\]
\[
= \int_0^\infty \chi\{r:|\tilde{\Lambda}\tilde{f}(re^{i\phi})| \geq \lambda\}(s)2\pi s ds
\]
\[
= \pi \int_0^\infty \chi\{r:|\Lambda f(r)| \geq \lambda\}((\sqrt{s})d s
\]
\[
= \pi \int_0^\infty \chi\{r:|\Lambda f(r)| \geq \lambda\}(s) ds
\]
\[
= \pi |\{|\Lambda f| \geq \lambda\}|.
\]

Next observe that \( \|\tilde{f}\|_{L^1(\mathbb{R}^2)} = \pi \|f\|_{L^1(0,\infty)} \). The proof follows from the corresponding lower-bound theorem for \( \Lambda \). \( \square \)

This also proves the first inequality of Theorem 1.5. The most difficult work is in showing that \( \frac{1}{\log 2} \) is also the upper bound for the weak-type constant of \( \Lambda \). Luckily the most straight-forward approach works. We are able to establish an optimization process that starts with an arbitrary function and ends up with a measure that has a form analogous to (3.3). That is, the optimizing representative will have a delta measure followed by a logarithmic negative function. Then Theorem 3.2 shows that the function in (3.3) is the weak-type extremal, and hence \( \frac{1}{\log 2} \) is the upper bound.

Notation: For convenience, \( f \) is used to denote the entire measure \( \mu \) and not just the absolutely continuous part.

**Theorem 3.3.** Let \( f \) be real-valued and integrable. Then

\[
\|\Lambda f\|_{w(1)} \leq \frac{1}{\log 2} \|f\|_1.
\]

This is best possible.

**Proof.** Start, without loss of generality, with a continuous function \( f \) on \([0, \infty)\). We enumerate the procedure as follows.

(1) A slight modification will ensure that \( \mathcal{H} f \) is non-negative. Just change the sign of \( f \) in the intervals where it is negative, in a sequential manner. (Changing \( f \) at \( x \) does not affect values at \( y < x \) but could affect for \( y > x \). This is why the procedure should be done from left to right.) The resulting function is piece-wise continuous, but neither \( |f| \) nor \( |\Lambda f| \) has been changed. In all the modifications below, \( \mathcal{H} f \) stays nonzero and generally increases. This is mentioned at various points in the steps below.

(2) Type-1 Optimization: Identify the maximal \( a_1 \) satisfying \( \mathcal{H} f(a_1) = \lambda \). Without loss of generality, assume \( a_1 > 0 \). (Otherwise add an
infinitesimal value at 0.) Observe that by storing \( f\chi_{(0,a_1)} \) at 0, as 
\[
(\int_0^{a_1} f)\delta_0, \quad Hf(x) > \lambda \quad \text{for} \ 0 < x < a_1 \quad \text{and values after} \ a_1 \quad \text{remain unchanged.}
\]

(3) Partition as \( 0 < a_1 < a_2 < \cdots \to \infty \), where \( f < 0 \) in \( (a_1,a_2) \), \( \geq 0 \) in \( (a_2,a_3) \) and so on in an alternating manner. Without loss of generality assume that \( f < 0 \) immediately after \( a_1 \); otherwise an infinitesimal modification will obtain this.

(4) Type-2 Optimization. It is shown next that \( f \) may be assumed to equal either \( \lambda \) or 0 wherever it is non-negative. Suppose \( f \geq 0 \) in \( I_i = (a_i,a_{i+1}) \) for some \( i \neq 0 \). Then \( Hf(u) < \lambda \) in this region (since \( u > a_1 \)), hence if \( |\Lambda f| \geq \lambda \), then \( f \geq \lambda \). The upper estimate will be obtained by only considering \( f \), hence a modification that increases \( Hf \) without changing where \( f \geq \lambda \) (or properly compensating for any changes) will not adversely affect the net measure.

(5) For this purpose, replace \( f \) here with \( f \wedge \chi_{f \geq \lambda} \) and store all the removed integral at 0. The storage at 0 increases \( Hf \) everywhere. The estimation in regions where \( f < 0 \) will be improved since \( |\Lambda f| \) increases here. Where \( f \geq 0 \), as said before, since only \( f \) is considered, the maximal region where the original function was \( \geq \lambda \) will still remain the same (with = \( \lambda \)). As for the possibility that in these regions more points occur (due to modification) where \( Hf > \lambda \), the issue is avoided by repeating Type-1 optimization with this new function. So a new \( a_1 \) starts off the show, with all of \( (0,a_1) \) being included in the measure count and after which \( Hf \) may play a role only where \( f < 0 \). In the end, \( f \) starts as a delta measure, then after \( a_1 \) switches between – and +, taking in + regions either 0 or \( \lambda \) as value. \( Hf \) remains non-negative throughout and is \( < \lambda \) after \( a_1 \).

(6) The objective is to initiate a reduction process that eliminates all but \( [a_0,a_1), [a_1,a_2) \) and \( [a_2,\infty) \). Then a simple optimization is done to prove the theorem.

(7) MOD 1: First remove \( f \) in \( (a_2,a_3) \) (where \( f \geq 0 \)) and make it 0 there. The integral loss would be \( \beta = \int_{a_{i-1}}^{a_3} f \) store this instead at 0. Observe that \( \frac{\beta}{X} \leq a_3 - a_2 \) since \( f \leq \lambda \) in this region by Second Optimization. The values after \( a_3 \) are unchanged for \( f \) and \( Hf \); however the \( Hf \) has increased in \( (0,a_3) \).

(8) Two things must be considered. There may have been points in \( (a_2,a_3) \) where \( f = \lambda \). These must be compensated. 2. The modification has made \( Hf(a_1) > \lambda \). These are fixed in the next step.

(9) Compensation for potential loss of \( \{f = \lambda\} \) Note that \( \frac{\beta}{X} = \frac{1}{X} \int_{a_{i-1}}^{a_3} f \leq a_3 - a_2 \) is the maximal measure in the region of removal where \( f \) could have equalled \( \lambda \); we would obtain this measure if and only if \( f = \lambda \) wherever it is nonzero. Now do the second modification MOD 2: Shift the negative \( f \) in \( (a_1,a_2) \) to \( (a_1 + \frac{\beta}{X},a_2 + \frac{\beta}{X}) \) without any changes (just translation). Since we have stored at 0 the measure
\((\lambda a_1 + \frac{\beta}{\lambda})\delta_0, \text{ and } \mathcal{H}((\lambda a_1 + \frac{\beta}{\lambda})\delta_0)(a_1 + \frac{\beta}{\lambda}) = \lambda\), the MOD 2 acquires the entire set \( (a_1, a_1 + \frac{\beta}{\lambda}) \) of measure \( \frac{\beta}{\lambda} \) within \( \{|\Lambda f_{\text{new}}| \geq \lambda\} \), where \( f_{\text{new}} \) is modified \( f \). Thus the potential loss of \( \{f = \lambda\} \cap (a_2, a_3) \) that occurred from MOD 1 is optimally compensated by MOD 2.

(10) It is clear that the “new \( a_1 \)” should equal the present \( a_1 + \frac{\beta}{\lambda} \). This change in notation is made in Step 12. Next it is verified that MOD 2 did not reduce the subset in \((a_1, a_2)\) where \( \Lambda f \geq \lambda \). Thus the potential loss of \( \{f = \lambda\} \cap (a_2, a_3) \) that occurred from MOD 1 is optimally compensated by MOD 2.

\[
|\{|\Lambda f| \geq \lambda\} \cap (a_1, a_2)| \leq |\{|\Lambda f_{\text{new}}| \geq \lambda\} \cap (a_1 + \frac{\beta}{\lambda}, a_2 + \frac{\beta}{\lambda})|.
\]

Since \( f_{\text{new}}(x + \frac{\beta}{\lambda}) = f(x) \) for \( a_1 < x < a_2 \), it remains to check that \( \mathcal{H}f_{\text{new}}(a_1 + \frac{\beta}{\lambda} + t) \geq \mathcal{H}f(a_1 + t) \) for \( 0 < t < a_2 - a_1 \). In other words, is \( \frac{(\lambda a_1 + \beta) + \gamma}{a_1 + \frac{\beta}{\lambda} + t} \geq \frac{\lambda a_1 + \gamma}{a_1 + t} \).

Here \( \lambda a_1 \) is the original measure stored at 0 and hence integral of \( f \) upto \( a_1 \) (recall \( \mathcal{H}f(a_1) = \lambda \); the new \( a_1 \) after verifications are done will be \( a_1 + \frac{\beta}{\lambda} \), but not yet.). \( \gamma \) is the integral of \( f \) in \((a_1, a_1 + \frac{\beta}{\lambda})\) and \( f_{\text{new}} \) in \((a_1 + \frac{\beta}{\lambda}, a_1 + \frac{\beta}{\lambda} + t)\) respectively. It is negative in value.

\[
((\lambda a_1 + \beta) + \gamma)(a_1 + t) \geq (\lambda a_1 + \gamma)(a_1 + \frac{\beta}{\lambda} + t)
\]

\[
\beta(a_1 + t) \geq \frac{\beta}{\lambda} (\lambda a_1 + \gamma)
\]

\[
a_1 + t \geq a_1 + \frac{\gamma}{\lambda}
\]

\[
t \geq \frac{\gamma}{\lambda}.
\]

Since \( \gamma \) is negative, the ? marks may be replaced with \( \geq \). In other words, the shifting of \( f \) is beneficial and increases the measure of set where \( \Lambda f \geq \lambda \). Thus \( f_{\text{new}} \) is indeed a good optimization.

(11) After MOD 1 and MOD 2, \( f_{\text{new}} < 0 \) in \((a_1 + \frac{\beta}{\lambda}, a_2 + \frac{\beta}{\lambda})\), is \( = 0 \) in \((a_2 + \frac{\beta}{\lambda}, a_3)\) and is \( < 0 \) in \((a_3, a_4)\). MOD 3: Switch \((a_2 + \frac{\beta}{\lambda}, a_3)\) and \((a_3, a_4)\) (along with the corresponding function values). This joins the two alternate negative intervals into one: \((a_1 + \frac{\beta}{\lambda}, a_2 + \frac{\beta}{\lambda} + (a_4 - a_3))\) and moves the intermediate 0 interval to \((a_2 + \frac{\beta}{\lambda} + (a_4 - a_3), a_4)\).

DENOTE \( f_{\text{new}} \) as the function after MOD 1 and MOD 2, and \( f_{\text{new}} \) as the function after MOD 3 as well. Then for \( x < a_4 - a_3 \)

(a) \( a_2 + \frac{\beta}{\lambda} \leq a_3 \)

(b) \( f_{\text{new}}(a_2 + \frac{\beta}{\lambda} + x) = f_{\text{new}}(a_3 + x) \).
(c) \[
\mathcal{H} \tilde{f}_{\text{new}}(a_2 + \frac{\beta}{\lambda} + x) = \frac{1}{a_2 + \frac{\beta}{\lambda} + x} \int_0^{a_2 + \frac{\beta}{\lambda} + x} \tilde{f}_{\text{new}} dx
= \frac{1}{a_2 + \frac{\beta}{\lambda} + x} \int_0^{a_3 + x} f_{\text{new}} dx
\geq \frac{1}{a_3 + x} \int_0^{a_3 + x} f_{\text{new}} dx = \mathcal{H} f_{\text{new}}(a_3 + x).
\]

(d) Both \(\mathcal{H} \tilde{f}_{\text{new}}\) and \(\mathcal{H} f_{\text{new}}\) are \(\leq \lambda\) in their corresponding 0-intervals
where \(f_{\text{new}} = f_{\text{new}} = 0\).
These facts imply that
\[
m\{|\Lambda \tilde{f}_{\text{new}}| \geq \lambda\} \geq m\{|\Lambda f_{\text{new}}| \geq \lambda\}.
\]
Thus MOD 3 is also optimizing.

(12) Relabel \(f\) as \(\tilde{f}_{\text{new}}, a_1\) as \(a_1 + \frac{\beta}{\lambda}\), \(a_2\) as \(a_2 + \frac{\beta}{\lambda} + (a_4 - a_3)\), and so on,
following the rule described in Step 3.

(13) Repeat steps 3-12 indefinitely to obtain an optimizing \(f\) of the following form: it is \(\lambda a_1 \delta_0\) at 0, has strictly negative values in some \((a_1, a_2)\) and is 0 in \((a_2, \infty)\). Since \(\mathcal{H} f\) is non-negative throughout,
the absolute value of the integral in \((a_1, a_2)\) is \(\leq \lambda a_1\).

(14) But at this stage the question remains: What is the optimal way to
decrease \(f\) in \((a_1, a_2)\)? The log-decrease of the previous theorem is
the right answer.

(a) First, note that if \(|\Lambda f| > \lambda\) anywhere in \((a_1, a_2)\), then there
is loss in measure of where \(\Lambda f \geq \lambda\). (The excess function
pulls down \(\mathcal{H} f\) quicker and dissipates quicker its allowed in-
tegral value.) So \(f\) should satisfy \(\Lambda f \leq \lambda\). Now suppose in a
sub-interval \((x, x + \epsilon)\), \(\Lambda f < \lambda\).

(b) Set \(f = 0\) in \((x, x + \epsilon)\). Observe that this modification 1.
does not change the values of \(f\), \(\mathcal{H} f\) and \(\Lambda f\) to the left of \(x\), 2.
increases \(\mathcal{H} f\) and so \(\Lambda f = \mathcal{H} f - f\) to the right of \(x + \epsilon\), and 3.
leaves \(\mathcal{H} f \geq 0\) everywhere. Although we have increased \(\mathcal{H} f\) in
\((x, x + \epsilon)\) (by eliminating negative values of \(f\)), the value of \(\mathcal{H} f\)
remain \(\leq \lambda\). This is because \(x > a_1\) and \(\mathcal{H} f(a_1) = \lambda\): so for the
modified \(f_{\text{new}}\),
\[
\mathcal{H} f_{\text{new}}(x + \delta) = \frac{1}{x + \delta} \int_0^x f_{\text{new}} \leq \mathcal{H} f(x) \leq \lambda.
\]
In conclusion, it is favorable to set \(f = 0\) in \((x, x + \epsilon)\), and we
do it.

(c) Next as shown before, it is optimizing to push out the inter-
vening 0 regions of \(f\); so repeating the above optimizing proce-
dures shows that the best option is to have \(|\Lambda f| = \lambda\) in \((a_1, a_2)\).
This is achieved by having $f$ decrease logarithmically to an optimizing choice of $a_2$, which is precisely how the lower-bound is computed in Theorem 3.2. Thus the lower-bound example is also an upper-bound extremal, and the weak-type constant $\|\Lambda\|_p(1) = \frac{1}{\log 2}$.

This completes the proof of the theorem. \hfill $\Box$

Theorem 3.3 and corollary 3.1 together complete the proof of Theorem 1.5. An interesting problem is to try and extend this result for complex valued radial functions.

4. $\|\Lambda_0\|^p$ For $1 < p < 2$

Baernstein and Smith introduce in [4] the family $S$ of stretch functions of the form $g(r)e^{i\theta}$ where $g : [0, \infty) \to [0, \infty)$ is non-negative, locally Lipschitz, $g(0) = g(0^+) = 0$ and $\lim_{r \to \infty} g(r) = 0$. Consider the Cauchy–Riemann differential operators

$$\partial = \frac{\partial_x - i\partial_y}{2}, \quad \bar{\partial} = \frac{\partial_x + i\partial_y}{2}.$$ 

Then for a stretch function $h(r)e^{i\theta} = g(r)e^{i\theta}$,

$$\tilde{f} = \partial h = \frac{1}{2}(g' + r^{-1}g) \text{ and } B\tilde{f} = \bar{\partial} h = \frac{e^{r^2\theta}}{2}(g' - r^{-1}g).$$

It is shown in [4] that $\|B\tilde{f}\|^p \leq (p^* - 1)\|\tilde{f}\|^p$ for $1 < p < 2$. Hence Iwaniec’s conjecture is verified (when $1 < p < 2$) for the subspace

$$\partial S = \{\partial h \in L^p(\mathbb{C}; \mathbb{R}) : h \in S\} \subseteq \tilde{R}_0^p(\mathbb{C}).$$

Define

$$\tilde{R}_0^p(\mathbb{C}) = \{\tilde{f} \in \tilde{R}_0^p(\mathbb{C}) : \mathcal{H}f \geq 0\},$$

and $\partial S^* = \partial S \cap \tilde{R}_0^p(\mathbb{C})$.

Lemma 4.1. $\partial S^*$ is $L^p$ dense in $\tilde{R}_0^p(\mathbb{C})$.

Proof. Let $\tilde{f} \in \tilde{R}_0^p(\mathbb{C}) \cap C_c^\infty(\mathbb{C})$. As before, let $f : [0, \infty) \to \mathbb{R}$ satisfy

$$\tilde{f}(z) = f(|z|^2); \text{ then } \mathcal{H} f \geq 0. \text{ Define } g(r) = r\mathcal{H} f(r^2). \text{ Then }$$

$$\frac{1}{2}(g'(r) + r^{-1}g(r)) = f(r^2) = \tilde{f}(z).$$

Thus $\partial S^* \subseteq \tilde{R}_0^p(\mathbb{C}) \cap C_c^\infty(\mathbb{C})$ and hence is dense in $\tilde{R}_0^p(\mathbb{C})$. \hfill $\Box$

Theorem 4.1. For $1 < p < 2$, $\|\Lambda_0\|_{L^p([0, \infty), \mathbb{R})} = p^* - 1 = \frac{1}{p - 1}$.

Proof. It suffices to consider the action of $\Lambda_0$ on functions satisfying $\mathcal{H} f \geq 0$, or equivalently the action of $B$ on $\tilde{R}_0^p(\mathbb{C})$. In particular, $\|B\|_{\tilde{R}_0^p} = \|B\|_{\tilde{R}_0^p} = \|\Lambda_0\|^p$. Refer to step 1 of the proof of Theorem 3.3.

By Lemma 4.1, $\partial S^*$ is dense in $\tilde{R}_0^p(\mathbb{C})$. Therefore since Iwaniec’s conjecture holds on $\partial S^*$, it follows that $\|B\|_{\tilde{R}_0^p} = \|\Lambda_0\|^p \leq p^* - 1$. The extremal
family $f_1(u) = u^{\epsilon - 1/p} \chi_{(0,1)}(u)$ verifies that $p^* - 1$ is also the lower bound. This completes the proof of the theorem. □

**Remark 4.1.** (1) Theorems 3.3 and 4.1 also hold for the Beurling-Ahlfors transform acting on functions of the form $\sum_k f_k \chi_{B_k}$ where $B_k$ are disjoint disks and $f_k$ is radially supported in $B_k$ and with integral 0. This is because $Bf_k$ is supported in $B_k$ for each $k$.

(2) Instead of relying on the Baerstein-Smith result for stretch functions, it may be possible to apply parallel techniques (i.e. prove Sverák’s conjecture; see [4]) directly to $\Lambda_0$. The authors were able to verify this for $f$ smooth and decreasing in $[0, \infty)$ and believe that some standard analysis should lead to the general result.

### 4.1. An estimate for $\|\Lambda_0\|_{L^p([0,\infty),\mathbb{C})}$.

**Proposition 4.1.** Given $F : [0, a) \to \mathbb{C}$, smooth and compactly supported, there exists $G = g_1 + ig_2$ such that $Hg_2(t) < \epsilon$,

$$|\Lambda_0 F(t)| = |\Lambda_0 G(t)| \text{ and } |F(t)| = |G(t)|$$

for each $t \in [0, a)$.

**Proof.** Let $F = f_1 + if_2$. First change the sign of $f_2$ in all intervals where $Hf_2 < 0$. Then change the sign of $f_1$ in all intervals where $Hf_1 < 0$. Observe that the modifications ensure that $Hf_1$ and $Hf_2$ are non-negative, hence $HF$ maps into the first quadrant of the plane. Moreover, $|\Lambda_0 F|$ and $|F|$ remain unchanged since the signs of $Hf_i$ and $f_i$ are modified simultaneously.

Let $k$ initially equal 2. Let $F_1 = F$.

1. Multiply $F_{k-1}$ by $e^{i\pi k}$. Then the range of the function is contained within the arguments $-\pi/2$ and $\pi/2$.

2. If $F_{k-1} = h_1 + ih_2$, then change the sign of $h_2$ wherever $Hh_2 < 0$. Let this modified function be $F_k$. Note that $HF_k$ has arguments between 0 and $\pi/2$.

3. Add 1 to $k$.

Repeat these three steps till $\|Hf_2\|_\infty < \epsilon$ (where $F_k = h_1 + ih_2$). Let $G = F_k$. Note that $|\Lambda_0 G| = |\Lambda_0 F|$ and similarly $|G| = |F|$.

Observe that since $G$ is bounded and compactly supported, $\|Hg_2\|_p$ may be taken arbitrarily small by choosing $\epsilon$ small enough. Therefore

$$\|\Lambda_0 F\|_p = \|\Lambda_0 G\|_p \approx \|\Lambda_0 g_1 + ig_2\|_p.$$ 

Hence the norm of $\Lambda_0$ on complex functions over $[0, \infty)$ is no greater than the norm of the operator $L$ defined $LF = \Lambda_0 f_1 + if_2$. In fact it is equal since for any real-valued function $f$, there exists $\tilde{f}$ with $|H\tilde{f}|$ small. This is obtained by multiplying $f$ with a suitable sharply oscillating function with absolute value 1.
\textbf{Theorem 4.2.} Let \( f = f_1 + if_2 \in L^p([0, \infty)) \) for \( 1 < p < 2 \).

(4.1) \[
\|Lf\|_p = \|A_0f_1 + if_2\|_p \leq \frac{C_p}{p - 1}\|f\|_p
\]

where

(4.2) \[
C_p = \frac{(1 + (p - 1) \frac{2p}{p - 1})^{\frac{1}{2}}}{\sqrt{1 + (p - 1) \frac{2p}{p - 1}}}.
\]

This \( C_p \) is slightly larger than the expected norm \( 1 \). The maximum is approximately \( 1.003074795 \) at \( p = 1.3224 \) (checked for various \( p \) values using MAPLE). The main estimate in the proof is not sharp enough to give \( 1 \).

\textit{Proof.} The key estimate is

\[
|A_0f_1 + if_2|^p \leq |A_0f_1|^p + |f_2|^p.
\]

Since \( \int |A_0f_1|^p \leq (p^* - 1)p \int |f_1|^p \), the goal becomes to show

\[
(p^* - 1)p \int |f_1|^p + \int |f_2|^p \leq C_p(p^* - 1)p \int |f_1 + if_2|^p
\]

or equivalently,

\[
\int (|f_1|^p + (p - 1)p|f_2|^p - C_p\sqrt{f_1^2 + f_2^2}) \leq 0.
\]

By maximizing the function \( s^p + (p-1)p\sqrt{1-s^2} \) on \((0, 1)\), it can be deduced that \( C_p \) equals the value in (4.2). (Note that the functions can be chosen so that this is best possible.) \( \square \)

5. THE \( L^p \) NORM ESTIMATES FOR \( \Lambda_m, \ m \geq 1 \)

In this section, we give upper and lower estimates for the \( L^p \) norm of \( \mathcal{H}_m \), \( \Lambda_m \) and hence of \( B \) restricted to \( \mathcal{R}^p_m \) spaces. Like for the special case \( m = 0 \), the norm of general Hardy average operator \( \mathcal{H}_m \) is amenable to computation via the standard Minkowski’s integral inequality. And the same extremal class works for all \( m \).

\textbf{Proposition 5.1.} \( \|\mathcal{H}_m\|_p = \frac{p(2m+2)}{p(m+2)-2} \|f\|_p \). 

\textit{Proof.}

\[
\|\mathcal{H}_m f\|_p = \left( \int_0^\infty \left( \int_0^1 f(uv)(m+1)v^\frac{m}{p} dv \right)^p du \right)^{\frac{1}{p}}
\]

\[
\leq \int_0^1 \left( \int_0^\infty |f(uv)|^p du \right)^{\frac{1}{p}} (m+1)v^\frac{m}{p} dv
\]

\[
= \int_0^1 (m+1)v^\frac{m}{p} - \frac{1}{p} dv \|f\|_p
\]

\[
= \frac{p(2m+2)}{p(m+2)-2} \|f\|_p.
\]
To show that the same constant is also lower bound, verify that

\[
(5.1) \quad f_{\epsilon}(x) = x^{-\frac{1}{p}} + \epsilon \chi(0,1)
\]

extremizes the norm as \( \epsilon \to 0 \). □

An immediate corollary is

**Corollary 5.1.**

\[
(5.2) \quad \|B\|_{R_p^m} = \|\Lambda_m\|_p \leq \frac{(3m + 4)p - 2}{(m + 2)p - 2}.
\]

The first equality follows from the representation Theorem 2.1 and the second inequality from the fact that \( \|\Lambda_m\| = \|H_m - I\| \leq \|H_m\| + 1 \). It is evident that this upper-bound is not the right constant since for \( p = 2 \) the value does not equal 1 (though \( \Lambda_m \) is an \( L^2 \) isometry). A lower bound

\[
(5.3) \quad \|\Lambda_m\|_p \geq \frac{mp + 2}{p(m + 2) - 2}, \quad 1 < p < \infty,
\]

may be obtained by considering the extremal family in (5.1) for \( H_m \). Recall that Iwaniec’s conjecture predicts \( \|B\|_p = \frac{1}{p-1} \) for \( 1 < p < 2 \), and observe that \( \|\Lambda_0\|_p = \frac{1}{p-1} = \frac{p}{p-1} - 1 \) for \( 1 < p < 2 \). Since \( \|B\|_{R_0^p} = \|\Lambda_0\|_p \leq \|B\|_p \), a reasonable conjecture is

**Conjecture 1.** For \( 1 < p < 2 \),

\[
(5.4) \quad \|\Lambda_m\|_p = \|H_m - I\|_p = \|H_m\|_p - 1 = \frac{mp + 2}{p(m + 2) - 2}.
\]

with the extremal family as given in (5.1).

Naturally one might consider generalizing the techniques for the case \( m = 0 \) (in [4]) to verify the Conjecture 1. The conjecture is probably false for \( p > 2 \). In fact, it is easy to see that

\[
(5.5) \quad \|\Lambda_m\|_\infty = \frac{2(m + 1)}{m + 2} + 1.
\]

An extremal is the function \( \chi[0,1) - \chi[1,2) \). At present, we do not have a conjecture for \( p > 2 \).

**Remark 5.1.** For the operator \( \Lambda_m \) (and \( \Lambda_0 \)), we may conjecture that the main results of the paper hold when \( \Lambda_m \) acts on complex valued functions. This is true for the Hardy operators, but the subtraction by identity makes the problem non-trivial.

6. **Concluding remarks**

Observe from Theorem 4.1 that the extremals for \( \|B\|_p, 1 < p < 2 \), are expected to be radial, non-negative and decreasing. For \( p = 1 \), we have shown that the extremals for \( \|B\|_{w(1)} \) are definitely not non-negative and radially decreasing. However, it may be expected that (at least) in the
real-valued setting the extremals remain real-valued and radial. Therefore a conjecture based on Theorem 1.2 could be

**Conjecture 2.** For \( f \in L^1(\mathbb{C}; \mathbb{R}) \) and \( \lambda > 0 \),

\[
\lambda \, m\{z \in \mathbb{C} : |Bf(z)| > \lambda \} \leq \frac{1}{\log 2} \|f\|_1.
\]

This is best possible.

A natural question is whether the radial result can lead to a proof for Iwaniec’s conjecture. It suffices to show that the conjecture is true for the class of simple functions of the form \( \sum_i a_i \chi_{B_i} \), where \( a_i \in \mathbb{C} \), and \( \{B_i\} \) is a finite collection of disjoint unit disks. Given any fixed function \( f \) in this family, \( Bf \) can be explicitly computed; however even the case \( f = a_1 \chi_{B_1} + a_2 \chi_{B_2} \) appears impossible to verify due to lack of integration techniques. Still, due to the explicit nature of \( f \) and \( Bf \), this class may be amenable to computer evaluations, similar to those done in [4].

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**References**


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