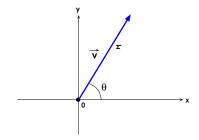
MA 16200 Study Guide - Exam # 1

- (1) Distance formula $D = \sqrt{(x_2 x_1)^2 + (y_2 y_1)^2 + (z_2 z_1)^2}$; equation of a sphere with center (h, k, l) and radius r: $(x h)^2 + (y k)^2 + (z l)^2 = r^2$.
- (2) Vectors in \mathbb{R}^2 and \mathbb{R}^3 ; displacement vectors \overrightarrow{PQ} ; vector arithmetic; components; Standard basis vectors $\vec{\mathbf{i}}, \vec{\mathbf{j}}, \vec{\mathbf{k}}$, hence $\vec{\mathbf{a}} = \langle a_1, a_2, a_3 \rangle = a_1 \vec{\mathbf{i}} + a_2 \vec{\mathbf{j}} + a_3 \vec{\mathbf{k}}$; length (magnitude) of a vector $|\vec{\mathbf{a}}| = \sqrt{a_1^2 + a_2^2 + a_3^2}$; dot (or inner) product of $\vec{\mathbf{a}}$ and $\vec{\mathbf{b}}$: $\vec{\mathbf{a}} \cdot \vec{\mathbf{b}} = a_1 b_1 + a_2 b_2 + a_3 b_3$; properties of dot products.
- (3) Useful Vector: $\vec{\mathbf{v}} = (r\cos\theta)\vec{\mathbf{i}} + (r\sin\theta)\vec{\mathbf{j}}$:



(4) Angle between vectors:

$$\cos \theta = \frac{\vec{\mathbf{a}} \cdot \vec{\mathbf{b}}}{|\vec{\mathbf{a}}| |\vec{\mathbf{b}}|}$$

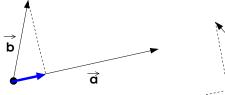


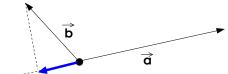
Perpendicular (orthogonal) vectors; direction cosines: $\cos \alpha = \frac{a_1}{|\vec{\mathbf{a}}|}$, $\cos \beta = \frac{a_2}{|\vec{\mathbf{a}}|}$, $\cos \gamma = \frac{a_3}{|\vec{\mathbf{a}}|}$, direction angles α, β, γ .

(5) Vector projection of $\vec{\mathbf{b}}$ onto $\vec{\mathbf{a}}$: $\left| \text{proj}_{\vec{\mathbf{a}}} \vec{\mathbf{b}} = \left(\frac{\vec{\mathbf{a}} \cdot \vec{\mathbf{b}}}{|\vec{\mathbf{a}}|} \right) \frac{\vec{\mathbf{a}}}{|\vec{\mathbf{a}}|} \right|$

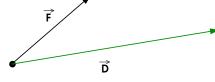
Scalar projection of $\vec{\mathbf{b}}$ onto $\vec{\mathbf{a}}$: $\operatorname{comp}_{\vec{\mathbf{a}}} \vec{\mathbf{b}} = \left(\frac{\vec{\mathbf{a}} \cdot \vec{\mathbf{b}}}{|\vec{\mathbf{a}}|}\right)$:

projection of b onto a





Work done by constant force is $W = \vec{\mathbf{F}} \cdot \vec{\mathbf{D}}$:

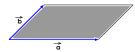


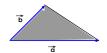
(6) Cross product: $\vec{\mathbf{a}} \times \vec{\mathbf{b}} = \begin{vmatrix} \vec{\mathbf{i}} & \vec{\mathbf{j}} & \vec{\mathbf{k}} \\ a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \end{vmatrix}$ (defined <u>only</u> for vectors in \mathbb{R}^3); $(\vec{\mathbf{a}} \times \vec{\mathbf{b}}) \perp \vec{\mathbf{a}}$ and

 $(\vec{\mathbf{a}} \times \vec{\mathbf{b}}) \perp \vec{\mathbf{b}}$; other properties of cross products; $|\vec{\mathbf{a}} \times \vec{\mathbf{b}}| = |\vec{\mathbf{a}}| |\vec{\mathbf{b}}| \sin \theta$;

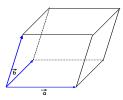
 $A = |\vec{\mathbf{a}} \times \vec{\mathbf{b}}| = \text{ area of parallelogram spanned by } \vec{\mathbf{a}} \text{ and } \vec{\mathbf{b}};$

 $A = \frac{1}{2} |\vec{\mathbf{a}} \times \vec{\mathbf{b}}| = \text{ area of triangle spanned by } \vec{\mathbf{a}} \text{ and } \vec{\mathbf{b}}.$



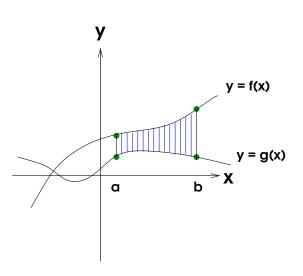


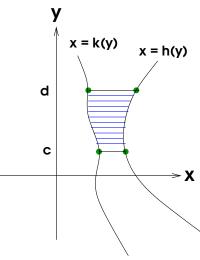
 $V = |\vec{\mathbf{a}} \cdot (\vec{\mathbf{b}} \times \vec{\mathbf{c}})| = \text{volume of parallelopiped spanned by } \vec{\mathbf{a}}, \vec{\mathbf{b}}, \vec{\mathbf{c}}:$



(7) Applications of Integration

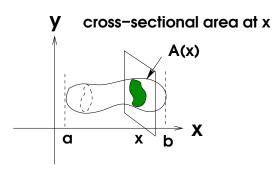
(a) Areas Between Curves: $A = \int_a^b \{f(x) - g(x)\} dx$ or $A = \int_c^d \{h(y) - k(y)\} dy$:

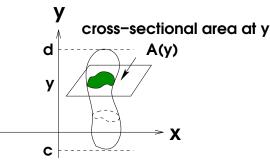




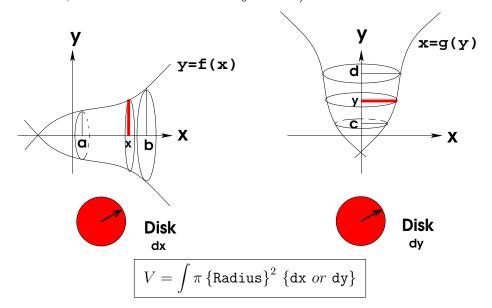
Note: If curves cross, you need to break up into several integrals.

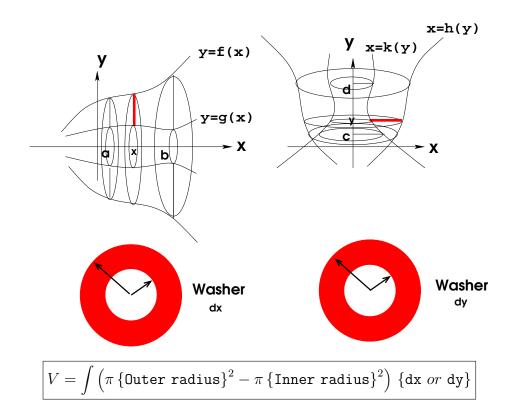
(b) Volumes of Solids by Cross-sectional Areas: $V = \int_a^b A(x) dx$, or $V = \int_c^d A(y) dy$, where A(x) = area of the cross-section of the solid with a plane $\perp x$ -axis at the point x, or A(y) = area of the cross-section of the solid with a plane $\perp y$ -axis at the point y:





(c) Volumes of Solids of Revolution by DISK METHOD OR WASHER METHOD: Use Disk Method or Washer Method when slices of area are <u>perpendicular</u> to axis of rotation. In either case, the cross-section is always a disk/washer:

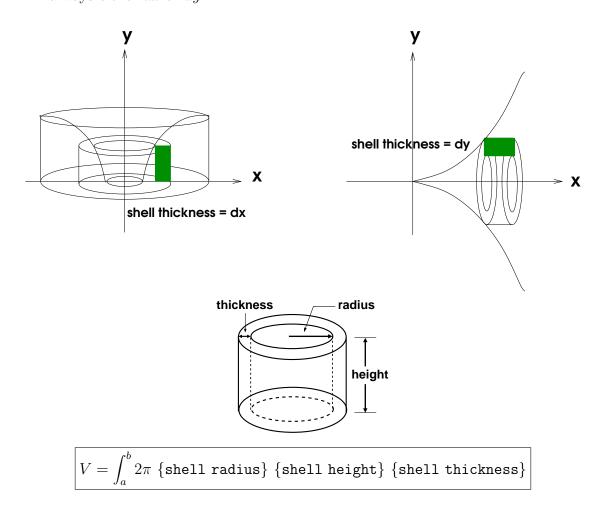




IMPORTANT - When to use dx or dy in Disk/Washer method?

- (i) If cross-sections are $\perp x$ axis, use dx.
- (ii) If cross-sections are $\perp y$ axis, use dy.

(d) Volumes of Solids of Revolution by CYLINDRICAL SHELLS METHOD: Use Cyclindrical Shells Method when slices of area are $\underline{parallel}$ to axis of rotation. Shell thickness is always either dx or dy.



(e) If force F is constant and distance object moved along a line is d, then Work is W = Fd. Here are the English and Metric systems compared:

Quantity	English System	Metric System
Mass m	$slug (= lb-sec^2/ft)$	kilogram kg
Force F	pounds (lbs)	Newtons $N = (\text{kg-m/sec}^2)$
Distance d	feet	meters m
Work W	ft-lbs	Joules J (= kg-m ² /sec ²)
g	32 ft/sec^2	9.8 m/sec^2

If the force is variable, say f(x), then Work $W = \int_a^b f(x) dx$; Hooke's Law: $f_s(x) = kx$; work done compressing/stretching springs, emptying tanks, pulling up chains.

(f) Average of a function over an interval: $f_{ave} = \frac{1}{b-a} \int_a^b f(x) dx$;

Mean Value Thm for Integrals: $f_{ave} = \frac{1}{b-a} \int_a^b f(x) \, dx = f(c)$, for some $a \le c \le b$.

(8) Techniques of Integration

(a) Simple Substitution:
$$\int_a^b f(g(x)) g'(x) dx = \int_{g(a)}^{g(b)} f(u) du$$
 (let $u = g(x)$)

(b) Integration by Parts:
$$\int u \, dv = uv - \int v \, du$$
; the **LIATE** rule: let $u = \mathbf{L}^{\text{og }} \mathbf{I}^{\text{nv trig}} \mathbf{A}^{\text{lg }} \mathbf{T}^{\text{rig }} \mathbf{E}^{\text{xp}}$.

(c) <u>Trig Integrals</u>: Integrals of the type $\int \sin^m x \cos^n x \, dx$ and $\int \tan^m x \sec^n x \, dx$ Some useful trig identities:

(i)
$$\sin^2 \theta + \cos^2 \theta = 1$$

(ii)
$$\sin^2 \theta = \frac{1 - \cos 2\theta}{2}$$
 and $\cos^2 \theta = \frac{1 + \cos 2\theta}{2}$

(iii)
$$\sin 2\theta = 2\sin\theta\cos\theta$$

(iv)
$$\tan^2 \theta + 1 = \sec^2 \theta$$

Some useful trig integrals:

(i)
$$\int \tan u \ du = \ln|\sec u| + C$$

(ii)
$$\int \sec u \ du = \ln|\sec u + \tan u| + C$$

(d) Trig integrals of the form: $\int \sin mx \sin nx \, dx$, $\int \cos mx \cos nx \, dx$, $\int \sin mx \cos nx \, dx$, use these trig identities:

$$\sin A \sin B = \frac{1}{2} \{\cos(A - B) - \cos(A + B)\}$$

$$\cos A \cos B = \frac{1}{2} \{\cos(A - B) + \cos(A + B)\}$$

$$\sin A \cos B = \frac{1}{2} \{ \sin(A - B) + \sin(A + B) \}$$

(e) <u>Trigonometric Substitutions</u>:

Expression*	Trig Substitution	Identity needed
$\sqrt{a^2 - x^2}$	$x = a\sin\theta$	$1 - \sin^2 \theta = \cos^2 \theta$
$\sqrt{a^2 + x^2}$	$x = a \tan \theta$	$1 + \tan^2 \theta = \sec^2 \theta$
$\sqrt{x^2 - a^2}$	$x = a \sec \theta$	$\sec^2\theta - 1 = \tan^2\theta$

^{*} Or powers of these expressions.