## Math 353 Practice Final Exam

Name: \_\_\_\_\_

This exam consists of 12 pages including this front page.

## Ground Rules

- 1. No calculator is allowed.
- 2. Show your work for every problem unless otherwise stated.

Score						
1	16					
2	24					
3	10					
4	10					
5	10					
6	10					
7	10					
8	10					
Total	100					

**Notations:**  $\mathbb{R}$  denotes the set of real number; F is always a field, for example,  $F = \mathbb{R}$ ;  $M_{m \times n}(F)$  denotes the set of  $m \times n$ -matrices with entries in F;  $F^n = M_{n \times 1}(F)$  denotes the set of *n*-column vectors;  $P_n(F)$  denotes the set of polynomials with coefficients in F and the most degree n, that is,

$$P_n(F) = \{ f(x) = a_n x^n + a_{n-1} x^{n-1} + \dots + a_1 x + a_0, \ a_i \in F, \ \forall i \}.$$

V is always a finite dimensional vector space over F and T is always a linear operator  $T : V \to V$ .  $A^*$  always denote complex conjugate and transpose of A. For an eigenvalue  $\lambda$  of A,  $E_{\lambda}$  denotes the  $\lambda$ -eigenspace and  $K_{\lambda}$  denote the generalized eigenspace.

- 1. The following are true/false questions. You don't have to justify your answers. Just write down either T or F in the table below. (2 points each)
  - (a) There is a matrix A with an eigenvalue  $\lambda$  such that the algebraic multiplicity of  $\lambda$  is 5 and dim  $K_{\lambda} = 4$ .
  - (b) Let  $v_1, \ldots, v_m$  are nonzero generalized eigenvectors of A with eigenvalues  $\lambda_1, \ldots, \lambda_m$ . Suppose that  $\lambda_1, \ldots, \lambda_m$  are distinct then  $v_1, \ldots, v_m$  are linearly independent.
  - (c) For an matrix A with all real entries, then all eigenvalues of A are real numbers.
  - (d) Suppose the Jordan canonical form A has one Jordan block with size > 1. Then A is diagonalizable.
  - (e) Suppose  $W = \text{Span}\{v_1, \ldots, v_n\}$ . Then  $u \in W^{\perp}$  if and only if u and  $v_i$  are orthogonal for all  $i = 1, \ldots, n$ .
  - (f) Let A is be an invertible matrix. Then singular values of A are the same as eigenvalues of A.
  - (g) If A is a square matrix then  $B = A A^*$  is normal.
  - (h) If A is unitary then  $det(A) = \pm 1$ .

	(a)	(b)	(c)	(d)	(e)	(f)	(g)	(h )
Answer	F	Т	F	F	Т	F	Т	F

- 2. Multiple Choice. (3 points each)
  - (i) Let A be an  $m \times n$ -matrix. Consider the system of linear equations AX = b, which of the following statement is always true:
    - (a) Suppose m > n then rank of augmented matrix (A|b) can not larger than m.
    - (b) Suppose  $m \leq n$  then  $(A^*A)X = A^*b$  always has a unique solution.
    - (c) Suppose A has full rank then AX = b always has a solution.
    - (d) If AX = b has a solution then AX = 0 has unique solution.
    - (e) If AX = b has a unique solution then A has to be invertible.

The correct answer is (a).

(ii) Let 
$$v_1 = \begin{pmatrix} 1 \\ 2 \\ -1 \\ 1 \end{pmatrix}$$
,  $v_2 = \begin{pmatrix} 2 \\ 3 \\ -2 \\ 2 \end{pmatrix}$ . Which vectors from  $e_1, e_2, e_3, e_4$  should

be added to  $v_1, v_2$  to form a basis of  $\mathbb{R}^4$ ?

- (a)  $e_1, e_2$
- (b)  $e_2, e_3$
- (c)  $e_2, e_4$
- (d)  $e_1, e_4$
- (e) such vectors do not exists.

The correct answer is (d).

- (iii) Let V be the real vector space of continuous function over [-1, 1] with the inner product  $\langle f, g \rangle = \int_{-1}^{1} f(x)g(x)dx$ . Which of the following set is orthonormal?
  - (a)  $1, x, x^2$
  - (b)  $1, e^x$
  - (c)  $1, x, x^2 \frac{1}{3}$
  - (d)  $\sin x, \cos x$
  - (e)  $\frac{1}{\sqrt{2}}, \frac{\sqrt{3}x}{\sqrt{2}}.$

The correct answer is (e).

(iv) Let

$$A = \begin{pmatrix} 0 & 0 & 0 & a \\ -1 & 0 & 0 & b \\ 0 & -1 & 0 & c \\ 0 & 0 & -1 & d \end{pmatrix}$$

Suppose 0 is an eigenvalue of A with algebraic multiplicity 2. Then which of the following statement is correct?

- (a)  $a = 0, b \neq 0$ (b) a = b = 0 and  $c \neq 0$
- (c) a = c = 0 but  $b \neq 0$ .
- (d) a = d = 0 but  $b \neq 0$ .
- (e) b = c = 0 but  $a \neq 0$ .

The correct answer is (b).

- (v) Suppose  $T: V \to V$  be a linear operator with characteristic polynomial  $f(t) = t^3 t^2$ . Which of the following statement is always correct?
  - (a) T is an isomorphism.
  - (b) T can not be diagonalizable.
  - (c) For any  $v \in V$ ,  $T^{3}(v) = T^{2}(v)$ .
  - (d) Such T is unique.
  - (e) It is possible that T is a unitary operator.

The correct answer is (c).

- (vi) Which of the following statement is NOT equivalent that  $A \in M_{n \times n}(\mathbb{C})$  is invertible?
  - (a) Columns of A are linearly independent.
  - (b) A is normal.
  - (c) All eigenvalues of A are nonzero.

- (d) A has n positive singular values.
- (e) The linear system AX = b has unique solution.

The correct answer is (b).

(vii) Let 
$$A = \begin{pmatrix} 0.6 & 0.4 & 0 \\ 0.4 & 0.2 & 0.4 \\ 0 & 0.4 & 0.6 \end{pmatrix}$$
. Which of the following statement is NOT

correct?

- (a) A is a regular transition matrix.
- (b) A is diagonalizable.
- (c) All eigenvalues of A are real numbers.

(d) 
$$\lim_{m \to \infty} A^m$$
 exists.  
(e)  $\lim_{m \to \infty} A^m = \begin{pmatrix} \frac{1}{3} & 0.5 & 0.5\\ \frac{1}{3} & 0.5 & 1\\ \frac{1}{3} & 0 & 0.5 \end{pmatrix}$ .

The correct answer is (e).

(viii) Consider the linear system 
$$\begin{pmatrix} 1 & 2\\ 1 & -1\\ 1 & 0\\ 1 & 1 \end{pmatrix} \begin{pmatrix} x\\ y \end{pmatrix} = \begin{pmatrix} a\\ b\\ c\\ d \end{pmatrix}$$
. Consider the least

square solution  $\begin{pmatrix} \hat{x} \\ \hat{y} \end{pmatrix}$  of the above system then  $\hat{y} =$ (a)  $\frac{1}{5}(\frac{3}{2}a - \frac{3}{2}b - \frac{c}{2} + \frac{d}{2}).$ (b)  $\frac{a}{2} + \frac{b}{2} + \frac{c}{2} + \frac{d}{2}.$ (c)  $(\frac{3}{2}a - \frac{3}{2}b - \frac{c}{2} + \frac{d}{2})..$ (d) 2a - b + d.

- (e) None of the above answers are correct.

The correct answer is (a).

**3.** Let 
$$A = \begin{pmatrix} 1 & 1 & 0 & 0 \\ -1 & -1 & 0 & 0 \\ -2 & -2 & 2 & 1 \\ 1 & 1 & -1 & 0 \end{pmatrix}$$
.

- (a) Find Jordan canonical form J of A. (5 points)
- (b) Find the invertible matrix S so that  $A = SJS^{-1}$ . (5 points)

Solutions: By cofactor expansion, it is not hard to compute the characteristic polynomial  $f_A(t) = t^2(t-1)^2$ . Hence we get two distinct eigenvalue  $\lambda_1 = 0$  and  $\lambda_2 = 1$  both with algebraic multiplicity 2. Now let us compute the  $K_{\lambda}$  for each  $\lambda_i$ .

For 
$$\lambda_1 = 0$$
, we have to solve  $AX = 0$ . We easily see that the eigenspace  $E_{\lambda_1}$   
has dimension 1, generated by  $v_1 = \begin{pmatrix} 1 \\ -1 \\ 0 \\ 0 \end{pmatrix}$ . Now  $A^2 = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ -3 & -3 & 3 & 3 \\ 2 & 2 & -2 & -2 \end{pmatrix}$   
By solving  $A^2X = 0$ , we get basis  $v_1$ ,  $v_2$  of  $K_{\lambda_1}$  where  $v_2 = \begin{pmatrix} 1 \\ 0 \\ 1 \\ 0 \end{pmatrix}$ . Now we  
build cycle  $\{Av_2, v_2\}$ , we get  $Av_2 = \begin{pmatrix} 1 \\ -1 \\ 0 \\ 0 \end{pmatrix} = v_1$ .  
Now for  $\lambda_2 = 1$ , we have  $(A - I) = \begin{pmatrix} 0 & 1 & 0 & 0 \\ -1 & -2 & 0 & 0 \\ -2 & -2 & 1 & 1 \\ 1 & 1 & -1 & -1 \end{pmatrix}$ . The eigenspace  
has dimension 1 which is spanned by  $v_3 := \begin{pmatrix} 0 \\ 0 \\ 1 \\ -1 \end{pmatrix}$ . We have  
 $\begin{pmatrix} -1 & -2 & 0 & 0 \end{pmatrix}$ 

$$(A-I)^{2} = \begin{pmatrix} 1 & 2 & 0 & 0 \\ 2 & 3 & 0 & 0 \\ 1 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}.$$

Hence  $N(A-I) = K_{\lambda_2}$  is spanned by  $v_3$  and  $e_4$ . We build a cycle  $(A-I)e_4, e_4$ . We easily calculate that  $Ae_4 = v_3$ .

In summary, the Jordan canonical form of A is  $\begin{pmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 1 \end{pmatrix}$ . And  $S = (v_1, v_2, v_3, e_4) = \begin{pmatrix} 1 & 1 & 0 & 0 \\ -1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & -1 & 1 \end{pmatrix}.$  **4.** Compute singular value decomposition of  $A = \begin{pmatrix} 1 & -1 & 1 \\ 1 & -1 & 1 \end{pmatrix}$ . (10 points)

Solutions: To obtain the SVD of A, we first decompose A \* A.

We first have  $A^*A = 2\begin{pmatrix} 1 & -1 & 1 \\ -1 & 1 & -1 \\ 1 & -1 & 1 \end{pmatrix}$ . It is not hard to calculate the characteristic polynomial is  $f(t) = -t^2(t-6)$ . For  $\lambda_1 = 6$ , we easily compute that the eigenspace has a basis  $v_1 = \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix}$ . For  $\lambda_2 = 0$ , the eigenspace

is defined by equation x - y + z = 0. So we get two basis  $v_2 = \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}$  and

 $v_3 = \begin{pmatrix} 0\\1\\1 \end{pmatrix}$ . But  $v_2$  and  $v_3$  are not orthogonal. By Gram-Schmidt as in the

next problem, we can replace  $v_3$  by  $\begin{pmatrix} -1\\ 1\\ 2 \end{pmatrix}$ . By replacing  $v_i$  by  $v_i/||v_i||$ . We obtained orthonormal eigenvectors as basis, and hence

$$V = (v_1, v_2, v_3) = \left(\frac{1}{\sqrt{3}} \begin{pmatrix} 1\\ -1\\ 1 \end{pmatrix}, \frac{1}{\sqrt{2}} \begin{pmatrix} 1\\ 1\\ 0 \end{pmatrix}, \frac{1}{\sqrt{6}} \begin{pmatrix} -1\\ 1\\ 2 \end{pmatrix}\right)$$

Therefore  $A^*A = V\Lambda V^*$  where  $\Lambda$  has 6,0,0 on the main diagonal. So the singular value only has  $\sigma_1 = \sqrt{6}$ .

Now  $u_1 = \frac{1}{\sigma_1} v_1 = \begin{pmatrix} 1 & -1 & 1 \\ 1 & -1 & 1 \end{pmatrix} \frac{1}{\sqrt{3}} \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix} = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \end{pmatrix}$ . Now it suffices to select  $u_2$  such that  $u_1, u_2$  forms an orthonormal basis of  $\mathbb{R}^2$ . We can select  $u_2 = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ -1 \end{pmatrix}$ . Finally, we get a SVD of A:

$$A = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & 1\\ 1 & -1 \end{pmatrix} \begin{pmatrix} \sqrt{6} & 0 & 0\\ 0 & 0 & 0 \end{pmatrix} V^*.$$

- **5.** Let  $W \subset \mathbb{R}_3$  be the subapace spanned by w = (1, 1, 1). Let  $W^{\perp}$  be the orthogonal complement of W. Let v = (1, 0, 1).
  - 1. Find an orthonormal basis of  $W^{\perp}$ . (4 points)
  - 2. Find the projection of v to  $W^{\perp}$ . (3 points)
  - 3. Find the  $\min_{w \in W^{\perp}} ||w v||$ . (3 points)

Solutions : It is easy to check that  $W^{\perp} := \{ \begin{pmatrix} x \\ y \\ z \end{pmatrix} | x + y + z + 0 \}.$  We can

pick two basis vector of  $W^{\perp}$  to be  $v_2 = \begin{pmatrix} 1 \\ -1 \\ 0 \end{pmatrix}$  and  $v_1 = \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix}$ . But  $v_1$  and  $v_2$  is not orthogonal. By Gram-Schmidt, we set  $w_1 = v_1$  and

$$w_{2} = v_{2} - \frac{\langle v_{2}, w_{1} \rangle}{\langle w_{1}, w_{1} \rangle} w_{1} = \begin{pmatrix} 1 \\ -1 \\ 0 \end{pmatrix} - \frac{1}{2} \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix} = \begin{pmatrix} \frac{1}{2} \\ -1 \\ \frac{1}{2} \end{pmatrix}.$$

Replace  $w_i$  by  $w_i/||w_i||$ , we obtain an orthonormal basis of  $W^{\perp}$ :  $u_1 = \frac{1}{\sqrt{2}} \begin{pmatrix} 1\\0\\-1 \end{pmatrix}, u_2 = \frac{1}{\sqrt{6}} \begin{pmatrix} 1\\-2\\1 \end{pmatrix}.$ 

Now we can use the formula of projection

$$\operatorname{Proj}_{W^{\perp}} v = \frac{\langle v, u_1 \rangle}{\langle u_1, u_1 \rangle} u_1 + \frac{\langle v, u_2 \rangle}{\langle u_2, u_2 \rangle} u_2$$

So the projection is

$$0\begin{pmatrix}1\\-1\\0\end{pmatrix} + \frac{1}{3}\begin{pmatrix}1\\-2\\1\end{pmatrix} = \frac{1}{3}\begin{pmatrix}1\\-2\\1\end{pmatrix}$$

Then

$$\min_{w \in W^{\perp}} \|w - v\| = \|v - \operatorname{Proj}_{W^{\perp}} v\| = \|\frac{2}{3} \begin{pmatrix} 1\\ 1\\ 1 \end{pmatrix}\| = \frac{2}{\sqrt{3}}.$$

- 6. Let A be an  $n \times n$ -matrix with real entries. Suppose A is skew-symmetric, that is,  $A^T = -A$ .
  - (a) Show that if n is odd then det(A) = 0 (3 points)
  - (b) Show that A is always diagonalizable. (3 points)
  - (c) Show that eigenvalues of A are either 0 or purely imaginary, that is,  $\lambda = bi$  for  $b \in \mathbb{R}$ . (4 points)

proof

- (a) Since  $A^T = -A$ , we have  $\det(A^T) = \det(-A) = (-1)^n \det(A)$ . Note that n is odd,  $(-1)^n = -1$ . So  $\det(A) = \det(A^T) = -\det(A)$ . That is,  $\det(A) = 0$ .
- (b) Since A is real matrix and  $A^T = -A$ , we have  $A^*A = A^TA = -AA = A(-A) = AA^*$ . That is A is normal. So A is diagonalizable.
- (c) Since A is normal, A admits spectral decomposition  $A = U\Lambda U^*$  where U is a unitary matrix and  $\Lambda$  is a diagonal matrix with eigenvalue  $\lambda_i$  on the main diagonal. Since A is real matrix, we have  $A^T = A^* = (U\Lambda U^*)^* = (U^*)^*\Lambda^*U^* = U\Lambda^*U^*$ . But  $A^T = -A = -U\Lambda U^*$ . So  $U\Lambda^*U^* = -U\Lambda U^*$ . Since U is invertible, we have  $\Lambda^* = -\Lambda$ . That is,  $\bar{\lambda}_i = \lambda_i$  for all i. Then  $\lambda_i$  is either 0 or imaginary.

- 7. Suppose A and B are square matrices and AB = BA.
  - (a) If v is a generalized eigenvector of A with eigenvalue  $\lambda$ . So is Bv. (5 points)
  - (b) Suppose that all eigenvalues of A are distinct. Show that there exists an invertible matrix S so that  $A = S\Lambda_1 S^{-1}$  and  $B = S\Lambda_2 S^{-1}$  with  $\Lambda_1, \Lambda_2$  being diagonal matrices. (5 points)

## Proof:

(a) Let  $K_{\lambda}$  be the generalized eigenspace of A with the eigenvalue  $\lambda$  and  $v \in K_{\lambda}$ . So  $(A - \lambda)^p v = \vec{0}$  for some p > 0. Now we check that  $(A - \lambda I)^p B = B(A - \lambda I)^p$ . Indeed, since AB = BA,

$$(A - \lambda I)^p B = (A - \lambda I)^{p-1} (A - \lambda I) B = (A - \lambda I)^{p-1} (AB - \lambda B) = (A - \lambda I)^{p-1} (BA - B\lambda I) = (A - \lambda I)^{p-1} B(A - \lambda I).$$

Repeat the above steps, we have  $(A - \lambda I)^p B = B(A - \lambda I)^p$ . Then  $(A - \lambda I)^p Bv = B(A - \lambda)^p v = B\vec{0} = \vec{0}$ . That is,  $Bv \in K_{\lambda}$ .

(b) Since eigenvalues of A are distinct, A is diagonalizable. So there exists an invertible matrix S such that  $A = S\Lambda_1 S^{-1}$  where  $\Lambda_1$  is a diagonal matrix with distinct eigenvalues  $\lambda_i$  in the main diagonal. Since AB =BA, we have  $S\Lambda_1 S^{-1}B = BS\Lambda_1 S^{-1}$ . Note that S is invertible, this is equivalent to that  $\Lambda_1(S^{-1}BS) = (S^{-1}BS)\Lambda_1$ . Now we claim that  $C = S^{-1}BS = (c_{ij})$  is necessarily a diagonal matrix. In fact  $\Lambda_1 C$  is equivalent to times  $\lambda_i$  to the *i*-th row of C, where  $C\Lambda_1$  is equivalent to times  $\lambda_j$  to *j*-th column of C. Then  $\Lambda_1 C = C\Lambda_1$  means that  $\lambda_i c_{ij} =$  $\lambda_j c_{ij}$ . Since all  $\lambda_i$  are distinct, we conclude that  $c_{ij} = 0$  unless i = j. That is  $S^{-1}BS = C = \Lambda_2$  is a diagonal matrix. So  $B = S\Lambda_2 S^{-1}$ . **8.** Let  $A \in M_{m \times n}(\mathbb{C})$ . Show the following:

- 1.  $\operatorname{rank}(AA^*) = \operatorname{rank}(A)$ . (5 points)
- 2. If  $\lambda$  is an eigenvalue of  $AA^*$  then  $\lambda \ge 0$ . (5 points).

## Proof:

By singular value decomposition,  $A = U\Sigma V^*$  where U and V are unitary matrices, and  $\Sigma$  has singular values  $\sigma_1 \geq \sigma_2 \geq \cdots \geq \sigma_r > 0$  on the main diagonal, and  $r = \operatorname{rank}(A)$ . Then

$$AA^* = U\Sigma V^* (U\Sigma V^*)^* = U\Sigma V^* V\Sigma^* U^* = U\Sigma \Sigma^* U^*.$$

It is easy to check that  $\Lambda := \Sigma\Sigma^*$  is an  $m \times m$ -matrix with  $\sigma_i^2$  on the main diagonal for  $i = 1, \ldots, r$ . In particular,  $AA^*$  is similar to  $\Lambda := \Sigma\Sigma^*$  and hence and they share the same eigenvalues and the same rank (note that Uis invertible so rank $(AA^*)$ rank $(U\Lambda U^*) = \operatorname{rank}(\Lambda)$ ). Hence  $AA^*$ 's eigenvalues  $\lambda_i$  are either  $\sigma_i^2$  or 0. Hence  $\lambda_i \geq 0$ . Since  $\sigma_i^2 > 0$  has exact  $r = \operatorname{rank}(A)$ many on the main diagonal of  $\Lambda$ , rank $(AA^*) = \operatorname{rank}(\Lambda) = r = \operatorname{rank}(A)$ .