

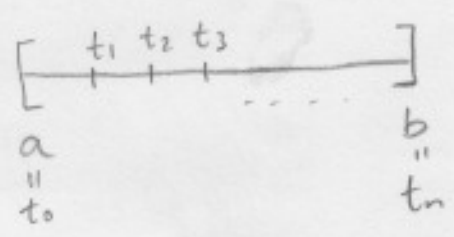
Section 4.2

Arc length.

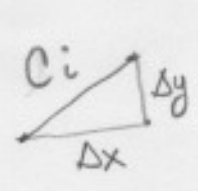
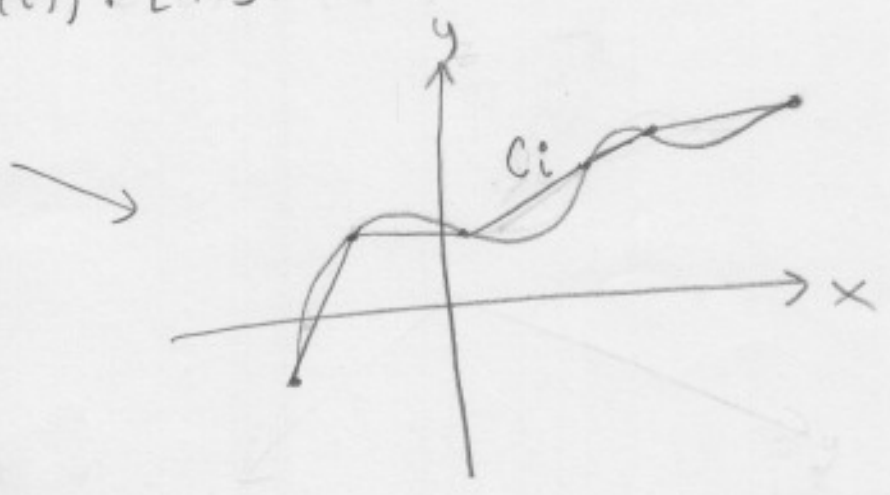
The quantity $l = \int_{t_0}^{t_1} \|\vec{r}'(t)\| dt$ is the arc length of the curve C given by $\vec{r}(t)$, $t_0 \leq t \leq t_1$

In order to see that this formula is true we partition the curve into pieces of line:

$\vec{r}(t) = (x(t), y(t)) : [a, b] \rightarrow \mathbb{R} \rightarrow \mathbb{R}$



$\Delta t = t_{i+1} - t_i = \frac{b-a}{n}$



$l_i = \sqrt{\Delta x^2 + \Delta y^2}$
 $= \sqrt{(x(t_{i+1}) - x(t_i))^2 + (y(t_{i+1}) - y(t_i))^2}$

$l \approx \sum_{i=0}^{n-1} l_i = \sum_{i=0}^{n-1} \sqrt{(x(t_{i+1}) - x(t_i))^2 + (y(t_{i+1}) - y(t_i))^2}$

⇒

$$L \cong \sum_{i=0}^{n-1} \sqrt{\left[\frac{x(t_{i+1}) - x(t_i)}{\Delta t}\right]^2 + \left[\frac{y(t_{i+1}) - y(t_i)}{\Delta t}\right]^2} \Delta t$$

We let $n \rightarrow \infty$ (or $\Delta t \rightarrow 0$) to get the exact length

$$L = \lim_{\Delta t \rightarrow 0} \sum_{i=0}^{n-1} L_i = \int_a^b \sqrt{(x'(t))^2 + (y'(t))^2} dt$$

$$= \int_a^b \|\vec{r}'(t)\| dt$$

(Note that $x(t_{i+1}) = x(t_i + \Delta t)$, $y(t_{i+1}) = y(t_i + \Delta t)$).

Ex: $\vec{r}(t) = (\cos t, \sin t, t^2)$, $0 \leq t \leq \pi$

$$\vec{r}'(t) = (-\sin t, \cos t, 2t)$$

$$\|\vec{r}'(t)\| = \sqrt{\sin^2 t + \cos^2 t + 4t^2}$$

$$= 2\sqrt{t^2 + \frac{1}{4}}$$

$$L = 2 \int_0^{\pi} \sqrt{t^2 + \frac{1}{4}} dt.$$

This can be evaluated by making the substitution $t = \frac{1}{4} \tan x$, $dt = \frac{1}{4} \sec^2 x dx$,

Parametrization with respect to arc length.

Problem: Given C , find a parametrization $\vec{r}(t)$ such that $\|\vec{r}'(t)\| = 1$ (unit speed path). Notice that for a unit speed curve, $\vec{r}(t)$ $a \leq t \leq b$, then:

$$L = \int_a^b \|\vec{r}'(t)\| dt = \int_a^b dt = b - a.$$

Ex: Let $\vec{r}(t) = (1, 3t^2, t^3)$, $0 \leq t \leq 1$.

Reparametrize with respect to arc length.

$\vec{r}'(t) = (0, 6t, 3t^2)$. This is not a unit speed parametrization.

$$\begin{aligned} s(t) &= \int_0^t \sqrt{36\tau^2 + 9\tau^4} d\tau = \frac{3}{2} \int_0^t 2\tau \sqrt{4 + \tau^2} d\tau \\ &= \frac{3}{2} \left[\frac{(4 + \tau^2)^{3/2}}{3/2} \right]_0^t = (4 + t^2)^{3/2} - 8 \end{aligned}$$

$$\therefore s(t) = (4 + t^2)^{3/2} - 8$$

We can solve $t(s)$; i.e., t in terms of s :

$$(4+t^2)^{3/2} = s+8$$

$$4+t^2 = (s+8)^{2/3}$$

$$t = \sqrt{(s+8)^{2/3} - 4}$$

$$\Rightarrow \vec{R}(s) = \vec{r}(t(s))$$

$$= (1, 3(s+8)^{1/3} - 12, ((s+8)^{2/3} - 4)^{3/2}).$$

• Hence, in order to reparametrize with respect to arc length we take the function $s(t)$:

$$s(t) = \int_0^t \|\vec{r}'(\tau)\| d\tau \quad (\text{length of curve between } \vec{r}(0) \text{ and } \vec{r}(t)).$$

$$\Rightarrow \frac{ds}{dt} = \|\vec{r}'(t)\| ; \quad \text{using the fundamental theorem of Calculus.}$$

Since $s'(t) > 0$, $s(t)$ is always increasing and hence the inverse function $t(s)$ exists.

We define:

$$\boxed{\vec{R}(s) = \vec{r}(t(s))}$$

When we parametrize with respect to arc length, the speed is always 1:

$$\frac{d\vec{R}}{ds} = \frac{d}{ds} \vec{r}(t(s))$$

$$= \frac{d\vec{r}}{dt} \cdot \frac{dt}{ds}; \quad \text{using chain rule}$$

$$= \frac{d\vec{r}/dt}{ds/dt}; \quad \text{since } \frac{dt}{ds} \cdot \frac{ds}{dt} = 1,$$

because, if $f = t(s)$,
and $g = s(t)$,

$$(f \circ g)(t) = t$$

$$\frac{d}{dt} (f \circ g)(t) = 1$$

$$f'(g(t)) g'(t) = 1$$

$$\frac{dt}{ds} (s(t)) \cdot \frac{ds}{dt} = 1$$

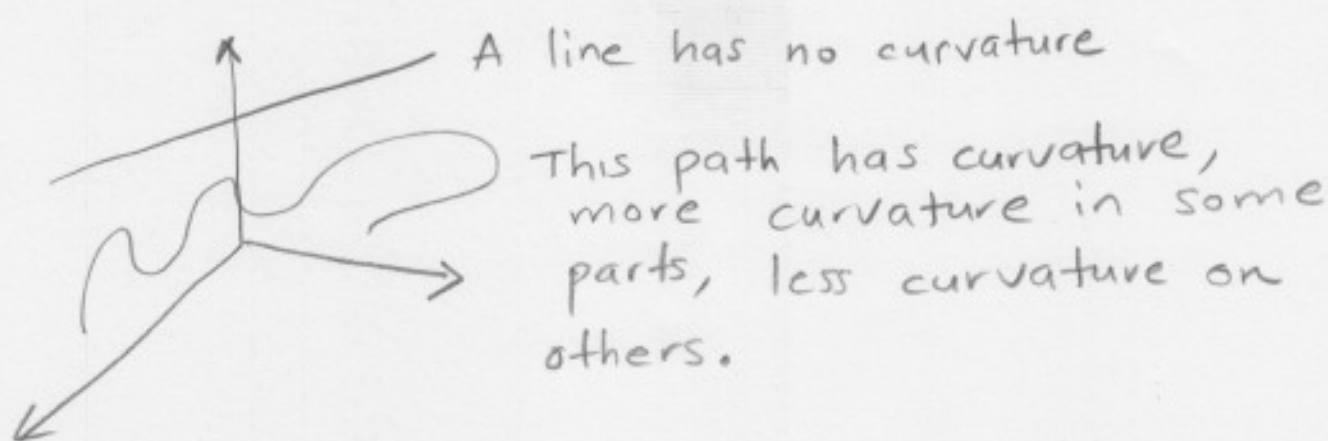
$$\Rightarrow \frac{dt}{ds} = \frac{1}{ds/dt}$$

$$= \frac{\vec{r}'(t)}{\|\vec{r}'(t)\|}$$

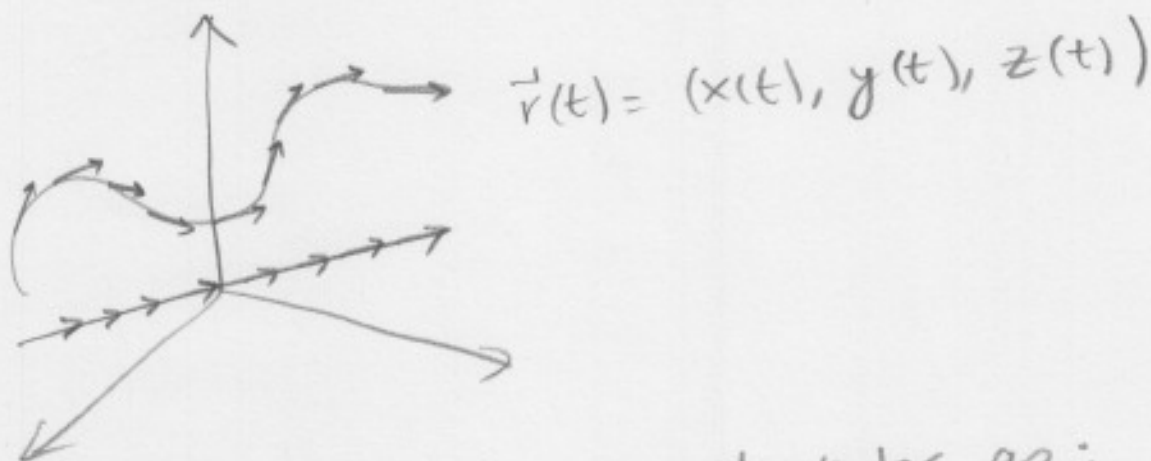
$$\text{Hence, } \|\vec{R}'(s)\| = \left\| \frac{\vec{r}'(t)}{\|\vec{r}'(t)\|} \right\| = 1.$$

As explained in class, an application of the arc length parametrization is to study "curvature" of paths. Our textbook, in later chapters, also deals with "curvature" of surfaces.

Curvature



Question : How do we measure curvature?



We define the tangent unit vector as;

$$\vec{T}(t) = \frac{\vec{r}'(t)}{\|\vec{r}'(t)\|}$$

$\vec{T}(t)$ is a unit vector in the same direction as the velocity vector. In a line, $\vec{T}(t)$ is always the same and hence $\frac{d}{dt} \vec{T}(t) = 0$, which says there is no curvature. Thus, we can measure curvature by looking at the derivative of $\vec{T}(t)$, which tell us how the tangent vector $\vec{T}(t)$ is changing. But, given

a path C , we have learned that we can parametrize with different formulas $\vec{r}(t)$ because we can travel along C with different velocities. Indeed, if we travel with $\vec{r}(t) = (1+2t, 1+2t, 1+2t)$, we are traveling with velocity $\vec{r}'(t) = (2, 2, 2)$ and speed $\|\vec{r}'(t)\| = \sqrt{12}$. But we can travel the same line with $\vec{R}(s) = (1 + \frac{s}{\sqrt{3}}, 1 + \frac{s}{\sqrt{3}}, 1 + \frac{s}{\sqrt{3}})$, and hence with velocity $\vec{R}'(s) = (\frac{1}{\sqrt{3}}, \frac{1}{\sqrt{3}}, \frac{1}{\sqrt{3}})$ and speed $\|\vec{R}'(s)\| = 1$. Hence $\vec{R}(s)$ is the parametrization with respect to arc length. Indeed, if we apply the procedure in page 142 to $\vec{r}(t) = (1+2t, 1+2t, 1+2t)$ we have

$$s(t) = \int_0^t \|\vec{r}'(\tau)\| d\tau = \int_0^t \sqrt{12} d\tau = \sqrt{12} t. \text{ So, } s(t) = \sqrt{12} t$$

and $t(s) = \frac{s}{\sqrt{12}}$. Hence:

$$\begin{aligned} \vec{R}(s) &= \vec{r}(t(s)) = \vec{r}\left(\frac{s}{\sqrt{12}}\right) = \left(1 + \frac{2s}{\sqrt{12}}, 1 + \frac{2s}{\sqrt{12}}, 1 + \frac{2s}{\sqrt{12}}\right) \\ &= \left(1 + \frac{s}{\sqrt{3}}, 1 + \frac{s}{\sqrt{3}}, 1 + \frac{s}{\sqrt{3}}\right). \end{aligned}$$

Therefore, in order to avoid ambiguity, we can use the unit speed path to measure curvature.

Since there is only one unit speed path, we can

define

now define:

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Definition: Given a path parametrized with respect to arc length, $\vec{r}(s)$, we define the function, $K(s)$, the curvature at s , as follows:

$$K(s) = \left\| \frac{d}{ds} \vec{T}(s) \right\|$$

$$\Rightarrow K(s) = \left\| \frac{d}{ds} \vec{r}'(s) \right\| ; \text{ since } \vec{T}(s) = \frac{\vec{r}'(s)}{\|\vec{r}'(s)\|} \text{ and } \|\vec{r}'(s)\| = 1, \text{ since } \vec{r}(s) \text{ is the unit speed path}$$

$$\Rightarrow \boxed{K(s) = \|\vec{r}''(s)\|}$$

Ex. If $\vec{r}(t)$ is given in terms of some parameter t and $\vec{r}'(t)$ is never $\vec{0}$, show that:

$$K = \frac{\|\vec{r}'(t) \times \vec{r}''(t)\|}{\|\vec{r}'(t)\|^3}$$

Solution: We consider the tangent unit vector:

$$\vec{T}(s(t))$$

Using the chain rule:

$$\frac{d\vec{T}}{dt} = \frac{d\vec{T}}{ds} \cdot \frac{ds}{dt} = \frac{d\vec{T}}{ds} \|\vec{r}'(t)\| ; \text{ since } s'(t) = \|\vec{r}'(t)\|$$

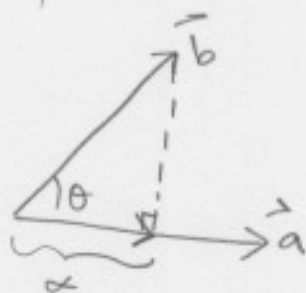
Therefore:

$$\|\vec{T}'(t)\| = \|\vec{r}'(t)\| \left\| \frac{d\vec{T}}{ds} \right\|$$

Hence:

$$\left\| \frac{d\vec{T}}{ds} \right\| = K = \frac{\|\vec{T}'(t)\|}{\|\vec{r}'(t)\|}$$

We need to compute $\vec{T}'(t)$. We first recall our formula to compute projections:

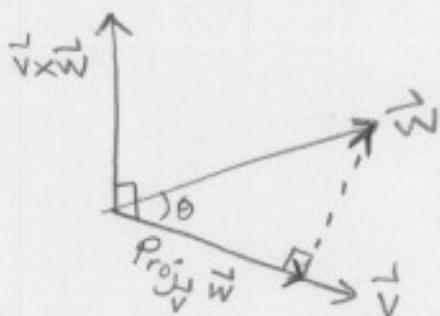


$$\cos \theta = \frac{\alpha}{\|\vec{b}\|}$$

$$\begin{aligned} \alpha &= \cos \theta \|\vec{b}\| \\ &= \frac{\vec{a} \cdot \vec{b}}{\|\vec{a}\| \|\vec{b}\|} \|\vec{b}\| = \frac{\vec{a} \cdot \vec{b}}{\|\vec{a}\|} \end{aligned}$$

$$\text{Proj}_{\vec{a}} \vec{b} = \alpha \frac{\vec{a}}{\|\vec{a}\|} = \frac{\vec{a} \cdot \vec{b}}{\|\vec{a}\| \|\vec{a}\|} \vec{a} = \left(\frac{\vec{a} \cdot \vec{b}}{\|\vec{a}\|^2} \right) \vec{a} \quad (1)$$

Let \vec{v} and \vec{w} any two vectors, we can use (1) to obtain a formula for $\|\vec{v} \times \vec{w}\|$:



We compute:

$$\begin{aligned} \|\vec{v} \times \vec{w}\| &= \|\vec{v}\| \|\vec{w}\| \sin \theta ; \text{ from Chapter 4} \\ \text{Proj}_{\vec{v}} \vec{w} + (\vec{w} - \text{Proj}_{\vec{v}} \vec{w}) &= \vec{w} \end{aligned} \quad (2)$$

$$\|\vec{w}\| \sin \theta = \|\vec{w} - \text{Proj}_{\vec{v}} \vec{w}\|; \quad \text{see right triangle in previous picture}$$

$$= \left\| \vec{w} - \left(\frac{\vec{v} \cdot \vec{w}}{\|\vec{v}\|^2} \right) \vec{v} \right\|; \quad \text{From (1)}$$

From (2):

$$\begin{aligned} \|\vec{v} \times \vec{w}\| &= \|\vec{v}\| \cdot \|\vec{w}\| \sin \theta \\ &= \|\vec{v}\| \left\| \vec{w} - \left(\frac{\vec{v} \cdot \vec{w}}{\|\vec{v}\|^2} \right) \vec{v} \right\| \end{aligned}$$

We have found:

$$\|\vec{v} \times \vec{w}\| = \|\vec{v}\| \left\| \vec{w} - \left(\frac{\vec{v} \cdot \vec{w}}{\|\vec{v}\|^2} \right) \vec{v} \right\| \quad (3)$$

We will use the following:

Lemma: Let $p(t) = (x(t), y(t), z(t))$. Then:

$$\frac{d}{dt} \left(\frac{p(t)}{\|p(t)\|} \right) = \frac{p'(t)}{\|p(t)\|} - \frac{p(t) \cdot p'(t)}{\|p(t)\|^3} p(t)$$

$$\frac{d}{dt} \left(\frac{p(t)}{\|p(t)\|} \right) = \frac{d}{dt} \left(\frac{x(t)}{(x^2+y^2+z^2)^{1/2}}, \frac{y(t)}{(x^2+y^2+z^2)^{1/2}}, \frac{z(t)}{(x^2+y^2+z^2)^{1/2}} \right)$$

$$\frac{d}{dt} \left[x(t) (x^2+y^2+z^2)^{-1/2} \right] = x'(t) (x^2+y^2+z^2)^{-1/2} - \frac{1}{2} x(t) (x^2+y^2+z^2)^{-3/2} (2xx' + 2yy' + 2zz')$$

$$= \frac{x'(t)}{\|p(t)\|} - \frac{x(t)}{\|p(t)\|^3} p(t) \cdot p'(t)$$

Similarly:

$$\frac{d}{dt} \left[y(t) (x^2 + y^2 + z^2)^{-1/2} \right] = \frac{y'}{\|p(t)\|} - \frac{y(t)}{\|p(t)\|^3} p(t) \cdot p'(t)$$

and

$$\frac{d}{dt} \left[z(t) (x^2 + y^2 + z^2)^{-1/2} \right] = \frac{z'}{\|p(t)\|} - \frac{z(t)}{\|p(t)\|^3} p(t) \cdot p'(t)$$

Putting together the terms in the vector form we obtain:

$$\frac{d}{dt} \left(\frac{p(t)}{\|p(t)\|} \right) = \frac{p'(t)}{\|p(t)\|} - p(t) \cdot p'(t) \frac{p(t)}{\|p(t)\|^3}$$

We now apply the previous Lemma to $\vec{T}(t) = \frac{\vec{r}'(t)}{\|\vec{r}'(t)\|}$; that is, $p(t)$ will be $\vec{r}'(t)$:

$$\frac{d}{dt} \left(\frac{\vec{r}'(t)}{\|\vec{r}'(t)\|} \right) = \frac{\vec{r}''(t)}{\|\vec{r}'(t)\|} - \frac{\vec{r}'(t) \cdot \vec{r}''(t)}{\|\vec{r}'(t)\|^3} \vec{r}'(t)$$

Hence

$$\|\vec{T}'(t)\| = \frac{1}{\|\vec{r}'(t)\|} \cdot \left\| \vec{r}''(t) - \frac{\vec{r}'(t) \cdot \vec{r}''(t)}{\|\vec{r}'(t)\|^2} \vec{r}'(t) \right\|$$

$$= \frac{1}{\|\vec{r}'(t)\|} \cdot \frac{\|\vec{r}'(t) \times \vec{r}''(t)\|}{\|\vec{r}'(t)\|}; \quad \text{using (3) with } \vec{v} = \vec{r}'(t), \vec{w} = \vec{r}''(t)$$

$$= \frac{\|\vec{r}'(t) \times \vec{r}''(t)\|}{\|\vec{r}'(t)\|^2}$$

We now go back to finish our Ex. in page 146. We have, See page 147, that:

$$\begin{aligned}
k &= \frac{\|\vec{T}'(t)\|}{\|\vec{r}'(t)\|} \\
&= \frac{\|\vec{v}'(t) \times \vec{v}''(t)\|}{\|\vec{v}'(t)\|^2} ; \text{ we have just computed } \|\vec{T}'(t)\| \\
&= \frac{\|\vec{v}'(t) \times \vec{r}''(t)\|}{\|\vec{v}'(t)\|^3}
\end{aligned}$$

Given any parametrization $\vec{r}(t)$, we have obtained a formula for the curvature in terms of t :

$$k(t) = \frac{\|\vec{r}'(t) \times \vec{r}''(t)\|}{\|\vec{r}'(t)\|^3} \quad \blacksquare$$