MATH 351, FALL 2017, EXAM #1

<u>Instructions</u>: Work the first problem and then exactly three of the remaining four problems. In order to receive full credit be sure to <u>show all work</u>. Each problem is worth 5 points.

Problem 1. Short answer.

2

2

- **Lefts** (A) Give the precise definition for when a set of vectors $\{\vec{v}_1, \dots, \vec{v}_n\}$ in a vector space V is linearly independent.
 - (B) Give one possible definition of the rank of a system of linear equations.
 - (C) If $T: V \to W$ is a linear transformation show that $T(\vec{0}) = \vec{0}$.

Respond to $\underline{\text{three}}$ of the problems below.

Problem 2. Consider the system of linear equations:

$$\begin{cases} x - y + 2z + u = 1 \\ 2x + y + 2u + 3w = 4 \\ x + z + u + w = 3 \end{cases}$$

- (A) Express the system as an augmented matrix.
- (B) Put the augmented matrix into row reduced echelon form.
- (C) Express the solution set in parametric form.

Problem 3. Let $C(\mathbb{R})$ be the vector space of all continuous, real-valued functions with domain \mathbb{R} .

- (A) Show that the set $C^2(\mathbb{R})$ of all functions whose first and second derivatives exist everywhere is a subspace of $C(\mathbb{R})$.
- (B) Give three examples of functions f such that for each one $\{f, f', f''\}$ is a linearly dependent set. The functions you pick are not allowed to be linear combinations of each other.

Problem 4. Consider the matrix

$$A = \begin{bmatrix} 1 & 3 & 1 \\ 2 & -2 & -1 \\ 6 & 2 & 0 \end{bmatrix}$$

- (A) Find the null space Nul(A).
- (B) Find a non-zero vector \vec{b} such that $A \cdot \vec{x} = \vec{b}$ is consistent.

Problem 5. Let $A \in M_{kn}(\mathbb{R})$ be a $k \times n$ real matrix. If k > n show that $\operatorname{Col}(A) \neq \mathbb{R}^k$. Give as precise of a logical argument as you can.

- 1. A. $\{\vec{v}_i, ..., \vec{v}_n\}$ is linearly independent if no vector m the set can be expressed as a linear combination of the other vectors.
- 1.0B. The rank is the smallest number of linear equations for a linear system with the same solution set

1.C.
$$T(\vec{o}) = T(\vec{o}\cdot\vec{o}) = \vec{o}\cdot T(\vec{o}) = \vec{o}$$
.

2. C. parametric form of solution is
$$\begin{bmatrix} -1 \\ 6 \\ 4 \\ 0 \end{bmatrix} + S \begin{bmatrix} -1 \\ 0 \\ 0 \end{bmatrix} + t \begin{bmatrix} -1 \\ -1 \\ 0 \\ 0 \end{bmatrix}$$

3. A,
$$f \in C^2(\mathbb{R})$$
, then f' exists everywhere, so f is continuous, i.e., $f \in C(\mathbb{R})$ $(f+g)' = f'+g'$, $(f+g)'' = f''+g''$, $(f+g)'' = f''+g''$, $(f+g)'' = f''+g''$, $(f+g)'' = f''+g''$.

Also $(c-f)' = c \cdot f'$, $(c\cdot f)'' = c \cdot f''$.

Therefore $C^2(\mathbb{R})$ is a subspace of $C(\mathbb{R})$.

4. A.
$$\begin{bmatrix} 13 & 1 & 0 \\ 2-2 & -1 & 0 \\ 62 & 0 & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 13 & 1 & 0 \\ 0-8-3 & 0 \\ 0-16-6 & 0 \end{bmatrix}$$

$$\rightarrow \begin{bmatrix} 13 & 1 & 0 \\ 083 & 0 \\ 000 & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & -1/8 & 0 \\ 0 & 1 & 3/8 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$Nu(A) = x_3 \cdot \begin{bmatrix} 1/8 \\ -3/8 \\ 1 \end{bmatrix}$$

4. B.
$$A = \vec{x} = \vec{b}$$
 is consistent

exactly when $\vec{b} \in Gol(A)$
 $Gol(A) = Span \begin{cases} \vec{i} \\ \vec{j} \end{cases} \begin{bmatrix} 3 \\ 2 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \end{bmatrix} \end{cases}$

So any of these vectors will work.

In general $\begin{bmatrix} x \\ y \end{bmatrix} \in Gol(A)$ exactly when

 $2(x+y) = 2$.

S. A has more rows than columns,

\$ 50 +6 RREF w.U have

a zero row. Thus

\[\frac{1}{5} & \frac{1}{5} & \text{Theory stent} \]

Und sing row operations we see that [AI &] is inconsistent for some $\vec{b} \in \mathbb{R}^k$, so $\vec{b} \notin Gl(A)$.