## MA 511, Session 37

## **Quadratic Forms and Quadrics**

Consider the general quadratic form in n variables  $f(x_1, \ldots, x_n) = \sum_{i=1}^n \sum_{j=1}^n a_{ij} x_i x_j = x^T A x,$ where  $A = (a_{ij}).$ 

Example: Let

$$f(x_1, x_2, x_3) = x^T \begin{pmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{pmatrix} x$$
$$= x_1^2 + 2x_1x_2 + 3x_1x_3 + 4x_2x_1 + 5x_2^2$$
$$+ 6x_2x_3 + 7x_3x_1 + 8x_3x_2 + 9x_3^2.$$

The matrix A that represents the quadratic form  $f(x) = x^T A x$  is not unique. We <u>always</u> take the (unique) symmetric one obtained by replacing  $a_{ij}$  and  $a_{ji}$  by their average. In the example,

$$f(x) = x^T \begin{pmatrix} 1 & 3 & 5 \\ 3 & 5 & 7 \\ 5 & 7 & 9 \end{pmatrix} x$$

as well.

## **Definition:** The quadratic form is

(i) <u>positive definite</u> if f(x) > 0 for  $x \neq 0$ ;

- (ii) <u>positive semi-definite</u> if  $f(x) \ge 0$  for  $x \ne 0$ ;
- (iii) <u>negative definite</u> if f(x) < 0 for  $x \neq 0$ ;
- (iv) <u>negative semi-definite</u> if  $f(x) \leq 0$  for  $x \neq 0$ ;

(v) <u>indefinite</u> if f(x) > 0 for some x and f(x) < 0 for some x.

**Theorem:** The following statements are equivalent for a real symmetric matrix.

(i) A is positive definite;

(ii) All eigenvalues  $\lambda_k$  of A are positive.

(iii) All upper left submatrices  $A_k$  of A have positive determinants.

(iv) All pivots  $d_k$  in the Gaussian elimination (without row exchanges) are positive.

(v) There is a matrix R with linearly independent columns such that  $A = R^T R$ .

<u>Proof</u>: Let us show that (i)  $\Leftrightarrow$  (ii):

We assume first that  $x^T A x > 0$  for all  $x \neq 0$ . Let  $v_j$  be an eigenvector of A with the eigenvalue  $\lambda_j$ . Then  $v_j^T A v_j = \lambda_j ||v_j||^2 > 0$ , hence  $\lambda_j > 0$ .

Conversely, assume that all  $\lambda_k$  are positive. Let  $Q^T A Q = \Lambda$  be diagonal, Q orthogonal, and let  $y = Q^T x$ . Then  $x \neq 0$  implies  $y \neq 0$ . Hence

$$x^T A x = y^T \Lambda y = \lambda_1 y_1^2 + \dots + \lambda_n y_n^2 > 0.$$

Now we show that (ii)  $\Rightarrow$  (v):

Assume  $Q^T A Q = \Lambda$  is diagonal and let

$$\sqrt{\Lambda} = \begin{pmatrix} \sqrt{\lambda_1} & 0 \dots 0 & & \\ 0 & \sqrt{\lambda_2} & \dots & 0 \\ & & \vdots & \\ 0 & 0 & \dots & \sqrt{\lambda_n} \end{pmatrix}, \quad R = \sqrt{\Lambda} Q^T.$$

Then, we can readily see that  $(\sqrt{\Lambda})^2 = \Lambda$ , and thus  $A = Q\Lambda Q^T = (Q\sqrt{\Lambda})(\sqrt{\Lambda}Q^T) = R^T R$ , as needed.

Finally we show that  $(v) \Rightarrow (i)$ :

 $A = R^T R$  is symmetric, since  $A^T = (R^T R)^T = R^T R = A$ . Since R is invertible (full rank), we know that given  $x \in \mathbb{R}^n$ ,  $x = 0 \Leftrightarrow Rx = 0$ . Thus,  $x^T A x = x^T R^T R x = (Rx)^T (Rx) = ||Rx||^2 > 0$  unless Rx = 0, that is unless x = 0.

**Remark:** It follows from (ii) that positive definite matrices have positive determinants.

(iii) and (iv) are equivalent since det  $A_k = d_1 \cdots d_k$ . (iii) follows from (ii) applied to  $A_k$ . Note that  $A_k$ is positive definite when A is positive definite. Conversely, if (iv) holds, then  $A = LDL^T$  (see p.51) where L is lower diagonal with 1's on the diagonal, and D is the pivot matrix. Let  $L_t = tL + (1-t)\mathbb{I}$  be a line segment in the space of lower diagonal matrices with 1's on the diagonal connecting  $\mathbb{I}$  and L. Then  $A_t = L_t DL_t^T$  is symmetric and det  $A_t = \det D > 0$ . All eigenvalues of  $A_0 = D$  are positive, and  $A_t$  cannot have a zero eigenvalue. Hence eigenvalues cannot change sign and should remain positive for any  $A_t$ , including  $A_1 = A$ . We can simplify the quadratic form very noticeably by introducing an appropriate change of variables. Since A is symmetric there is an orthogonal matrix Q such that  $Q^T A Q = \Lambda$  is diagonal. Let  $y = Q^T x$ . Then, since  $A = Q \Lambda Q^T$ , we have  $x^T A x = x^T Q \Lambda Q^T x = y^T \Lambda y = \lambda_1 y_1^2 + \dots + \lambda_n y_n^2$ ,

This is a <u>pure quadratic</u> form, i.e. one without any cross product terms.

Consider now the locus of points in  $\mathbb{R}^n$  such that  $f(x) = x^T A x = a^2$ . Recall that orthogonal matrices geometrically preserve angles and distances from the origin. Since the locus of  $\lambda_1 y_1^2 + \cdots + \lambda_n y_n^2 = a^2$   $(a \neq 0)$  is an <u>ellipsoid</u> (an ellipse if n = 2), then so is the original locus  $f(x) = x^T A x = a^2$ .

**Example:** Give a geometric description of the ellipse

$$f(x_1, x_2) = \begin{pmatrix} x_1 & x_2 \end{pmatrix} \begin{pmatrix} 5 & -3 \\ -3 & 5 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = 1.$$

Solution:  $p(\lambda) = (5 - \lambda)^2 - 9 = \lambda^2 - 10\lambda + 16$ =  $(\lambda - 2)(\lambda - 8)$ . So, the eigenvalues of A are  $\lambda_1 = 2$  and  $\lambda_2 = 8$ . We find unit eigenvectors  $v_1$  and  $v_2$  as solutions of, respectively,

$$\begin{pmatrix} 3 & -3 \\ -3 & 3 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

and

$$\begin{pmatrix} -3 & -3 \\ -3 & -3 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}.$$

Thus,  $v_1 = \left(\frac{1}{\sqrt{2}} \ \frac{1}{\sqrt{2}}\right)$ ,  $v_2 = \left(-\frac{1}{\sqrt{2}} \ \frac{1}{\sqrt{2}}\right)$ , for example. Define

$$Q = \begin{pmatrix} \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{pmatrix}, \quad \Lambda = \begin{pmatrix} 2 & 0 \\ 0 & 8 \end{pmatrix}, \quad A = \begin{pmatrix} 5 & -3 \\ -3 & 5 \end{pmatrix}.$$

It then follows that  $Q^T A Q = \Lambda$ . With the change of variables  $y = \begin{pmatrix} y_1 \\ y_2 \end{pmatrix} = Q^T x$ , we see that the given ellipse, the locus of points  $y \in \mathbb{R}^2$  such that  $y^T \Lambda y =$  $2y_1^2 + 8y_2^2 = 1 = x^T A x$ , is the ellipse with major semiaxis  $a = \frac{\sqrt{2}}{2}$  in the direction of  $v_1$  and minor semiaxis  $b = \frac{\sqrt{2}}{4}$  in the (orthogonal) direction of  $v_2$ . Q represents a counterclockwise rotation by  $\frac{\pi}{4}$  from the canonical position, that is  $Q = R_{\frac{\pi}{4}}$ .