

Practice Exam for Second Midterm

Please be neat and show all work. Write each answer in the provided box. Return this entire booklet to your instructor. **No books. No notes. No calculators.**

Student Name (print):

Student ID:

Circle your class: Div 7, Sec 3 (9:00) Div 8, Sec 2 (10:30)

| Problem # | Max pts. | Earned points |
|------------------|-----------|---------------|
| 1 | 4 | |
| 2 | 4 | |
| 3 | 4 | |
| 4 | 4 | |
| 5 | 4 | |
| 6 | 4 | |
| 7 | 4 | |
| 8 | 4 | |
| 9 | 6 | |
| 10 | 6 | |
| Section I | 44 | |

| | | |
|--------------------|------------|--|
| 11 | 6 | |
| 12 | 4 | |
| 13 | 4 | |
| 14 | 6 | |
| 15 | 4 | |
| Section II | 24 | |
| 16 | 10 | |
| 17 | 8 | |
| 18 | 6 | |
| 19 | 8 | |
| Section III | 32 | |
| TOTAL | 100 | |

SECTION I: SHORT PROBLEMS

Show all your work. Write your answer **clearly** in the provided box. **No partial credit on this part.**

1.(4 points) Let $\mathbf{v}_1 = \begin{bmatrix} 0 \\ -2 \\ -2 \end{bmatrix}$, $\mathbf{v}_2 = \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix}$. Let θ be the angle between \mathbf{v}_1 and \mathbf{v}_2 . Find $\cos \theta$.

$$\theta = \boxed{}$$

2.(4 points) Let $A = \begin{bmatrix} 5 & 4 & 2 & 1 \\ 2 & 3 & 1 & -2 \\ -5 & -7 & -3 & 9 \\ 1 & -2 & -1 & 4 \end{bmatrix}$. Compute $\det(A)$.

$$|A| = \boxed{}$$

3.(4 points) Let W be the subspace of \mathbb{R}^4 spanned by $\left\{ \begin{bmatrix} 1 \\ 2 \\ 1 \\ 2 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 0 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \\ 1 \\ 1 \end{bmatrix} \right\}$. Find an orthogonal basis of the space that is orthogonal to W ; i.e., W^\perp .

4.(4 points) A linear transformation $L: \mathbb{R}^5 \rightarrow \mathbb{R}^3$ defined by $L \begin{pmatrix} a_1 \\ a_2 \\ a_3 \\ a_4 \\ a_5 \end{pmatrix} = \begin{bmatrix} a_1 - 2a_2 + 5a_3 - 3a_5 \\ 5a_1 + 2a_2 - 6a_3 + a_4 \\ 2a_3 + 2a_5 - 2a_1 - a_4 \end{bmatrix}$.

(a) **(2 points)** Find the standard matrix A representing L .

$$A = \boxed{\phantom{\begin{bmatrix} & & & & \\ & & & & \\ & & & & \end{bmatrix}}$$

(b) **(2 points)** Find $L \begin{pmatrix} 1 \\ -1 \\ 2 \\ -2 \\ 1 \end{pmatrix}$.

$$\boxed{\phantom{\begin{bmatrix} \\ \\ \\ \end{bmatrix}}}$$

5.(4 points) Find a, b, c such that the matrix $A = \begin{bmatrix} 1 & 0 & -1 \\ a & b & c \\ 0 & 1 & -1 \end{bmatrix}$ has eigenvalue 0,1,2.

$$a = \boxed{} \quad b = \boxed{} \quad c = \boxed{}$$

6.(4 points) E is a 4×4 matrix of the form $E = \begin{bmatrix} 1 & 1 & 1 & 1 \\ y & x & z & w \\ 2 & 3 & 2 & 3 \\ a & b & c & d \end{bmatrix}$, and $\det(E) = 5$.

Let $F = \begin{bmatrix} -5a & -5b & -5c & -5d \\ 2y & 2x & 2z & 2w \\ 2 - 3y & 3 - 3x & 2 - 3z & 3 - 3w \\ 1 & 1 & 1 & 1 \end{bmatrix}$. Compute $\det(F)$.

$$\det(F) = \boxed{}$$

7.(3 points) Let A and B be 3×3 matrices with $\det(A) = 5$ and $\det(B) = 2$. Set

$$C = B^3 \cdot A^{-1} \cdot (A^T)^4 \cdot (3B) \cdot (B^T)^{-1}. \quad \text{Compute } \det(C).$$

$$\det(C) = \boxed{}$$

8.(3 points) Given a matrix $A = \begin{bmatrix} -3 & 1 & -1 \\ -7 & 5 & -1 \\ -6 & 6 & -2 \end{bmatrix}$, we know that there are a non-singular matrix P and a diagonal matrix D such that $P^{-1}AP = D$. Find such a matrix D .

$$D = \boxed{\phantom{\begin{bmatrix} & & \\ & & \\ & & \end{bmatrix}}}$$

9.(6 points) Let $A = \begin{bmatrix} 2 & 3 & -4 \\ 0 & -4 & 2 \\ 1 & -1 & 5 \end{bmatrix}$.

(a) **(4 points)** Find $\text{adj } A$.

$$\text{adj } A = \boxed{\phantom{\begin{bmatrix} & & \\ & & \\ & & \end{bmatrix}}}$$

(b) **(2 points)** Find A^{-1} .

$$A^{-1} = \boxed{\phantom{\begin{bmatrix} & & \\ & & \\ & & \end{bmatrix}}}$$

10.(6 points) The plane W in space \mathbb{R}^4 is defined by the equations $x + 2y + z + 2w = 0$, $2x + y + 2z + w = 0$, or we can view W as a subspace of \mathbb{R}^4 ,

$$W = \left\{ \begin{bmatrix} x \\ y \\ z \\ w \end{bmatrix}, x + 2y + z + 2w = 0, 2x + y + 2z + w = 0 \right\}.$$

(a) **(3 points)** Find an orthogonal basis for W .

$$\boxed{\phantom{\begin{bmatrix} & & & \\ & & & \\ & & & \\ & & & \end{bmatrix}}}$$

(b) **(3 points)** Find the distance d between $\mathbf{b} = \begin{bmatrix} 4 \\ 3 \\ 2 \\ 1 \end{bmatrix}$ and W .

$$d = \boxed{}$$

SECTION II: MULTIPLE CHOICE–NO PARTIAL CREDIT

For Problems 11 through 15, circle **only one** (the correct) answer for each part. **No Partial credit.**

11.(6 points) Determine whether the following are true or false:

- | | | |
|---|------|-------|
| (a) (1 points) If A, B are $n \times n$ matrices, then $\det(A + B) = \det(A) + \det(B)$. | True | False |
| (b) (1 points) All eigenvalues of a real symmetry matrix are real and distinct. | True | False |
| (c) (1 points) Real symmetry matrices are all diagonalizable. | True | False |
| (d) (1 points) Every inner product space has an orthogonal basis. | True | False |
| (e) (1 points) Two similar matrices share the same eigenvalues. | True | False |
| (f) (1 points) If A is a real orthogonal matrix, then then $(\det(A))^2 = 1$ | True | False |

12.(4 points) If A is a 3×3 matrix with eigenvalues $0, 3, -2$ whose associated eigenvectors are

$$\begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}, \quad \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix}, \quad \begin{bmatrix} 2 \\ 2 \\ 0 \end{bmatrix},$$

respectively, then A^3 has an eigenvalue λ whose associated eigenvector is \mathbf{v} .

- A. $\lambda = 9, \mathbf{v} = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$.
- B. $\lambda = 0, \mathbf{v} = \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix}$.
- C. $\lambda = 27, \mathbf{v} = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$.
- D. $\lambda = -2, \mathbf{v} = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$.
- E. $\lambda = -8, \mathbf{v} = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$.

13.(4 points) If A is a 4×4 matrix and $\det(A) = 3$, then what is $\det((\text{adj } A)^{-1})$?

- A. $\frac{1}{27}$.
- B. 3.
- C. $\frac{1}{3}$.
- D. 1.
- E. 27.

14.(6 points) Determine if each of the following matrix is diagonalizable.

(a) **(2 points)** $\begin{bmatrix} 1 & 0 & 5 \\ 0 & 3 & 4 \\ 5 & 4 & 3 \end{bmatrix}$. True False

(b) **(2 points)** $\begin{bmatrix} 2 & 2 \\ 0 & 2 \end{bmatrix}$. True False

(c) **(2 points)** $\begin{bmatrix} 2 & 0 & 0 \\ 0 & 1 & 2 \\ 0 & 0 & 1 \end{bmatrix}$. True False

15.(4 points) Let W be a subspace of \mathbb{R}^3 with an orthogonal basis $\left\{ \mathbf{v}_1 = \begin{bmatrix} 1 \\ 2 \\ 2 \end{bmatrix}, \mathbf{v}_2 = \begin{bmatrix} 2 \\ -2 \\ 1 \end{bmatrix} \right\}$.

We can write $\mathbf{u} = \begin{bmatrix} 5 \\ 1 \\ 1 \end{bmatrix}$ as $\mathbf{u} = \mathbf{u}_1 + \mathbf{u}_2$, where $\mathbf{u}_1 \in W$, $\mathbf{u}_2 \in W^\perp$. What are $\mathbf{u}_1, \mathbf{u}_2$?

A. $\mathbf{u}_1 = \begin{bmatrix} 1 \\ 2 \\ 2 \end{bmatrix}$, $\mathbf{u}_2 = \begin{bmatrix} 4 \\ -1 \\ -1 \end{bmatrix}$.

B. $\mathbf{u}_1 = \begin{bmatrix} 3 \\ 0 \\ 3 \end{bmatrix}$, $\mathbf{u}_2 = \begin{bmatrix} 2 \\ 1 \\ -2 \end{bmatrix}$.

C. $\mathbf{u}_1 = \begin{bmatrix} 2 \\ -2 \\ 1 \end{bmatrix}$, $\mathbf{u}_2 = \begin{bmatrix} 3 \\ 3 \\ 0 \end{bmatrix}$.

D. $\mathbf{u}_1 = \begin{bmatrix} 5 \\ 1 \\ 1 \end{bmatrix}$, $\mathbf{u}_2 = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$.

E. $\mathbf{u}_1 = \begin{bmatrix} 5 \\ 1 \\ 0 \end{bmatrix}$, $\mathbf{u}_2 = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$.

SECTION III: MULTI-STEP PROBLEMS – PARTIAL CREDIT

Show all work (**no work - no credit!**) and display computing steps. Write clearly.

16.(10 points) Given four vectors $\mathbf{u}_1 = \begin{bmatrix} 1 \\ -3 \\ 5 \\ 1 \end{bmatrix}$, $\mathbf{u}_2 = \begin{bmatrix} 5 \\ -5 \\ 9 \\ 7 \end{bmatrix}$, $\mathbf{u}_3 = \begin{bmatrix} 7 \\ -1 \\ 3 \\ 11 \end{bmatrix}$, $\mathbf{u}_4 = \begin{bmatrix} 4 \\ -2 \\ 4 \\ 6 \end{bmatrix}$, $\mathbf{b} =$

$\begin{bmatrix} 2 \\ 4 \\ 12 \\ 22 \end{bmatrix}$, we set

$$W = \text{span}\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3, \mathbf{u}_4\}, A = [\mathbf{u}_1 \ \mathbf{u}_2 \ \mathbf{u}_3]$$

(a) (3 points) Find an orthonormal basis for W .

(b) (3 points) Find an orthonormal basis for W^\perp .

(c) (2 points) Find $\mathbf{u}_1 = \text{Proj}_W \mathbf{b} \in W$, $\mathbf{u}_2 = \text{Proj}_{W^\perp} \mathbf{b} \in W^\perp$.

$$\mathbf{u}_1 = \begin{bmatrix} \\ \\ \\ \end{bmatrix} \quad \mathbf{u}_2 = \begin{bmatrix} \\ \\ \\ \end{bmatrix}$$

(d) (2 points) Find the least square solution $\hat{\mathbf{x}}$ for the system $A\mathbf{x} = \mathbf{b}$.

$$\hat{\mathbf{x}} = \begin{bmatrix} \\ \\ \\ \end{bmatrix}$$

17.(8 points)

- (a) **(4 points)** Given three vectors $\mathbf{v}_1 = \begin{bmatrix} 1 \\ -3 \\ 2 \end{bmatrix}$, $\mathbf{v}_2 = \begin{bmatrix} 0 \\ -1 \\ 1 \end{bmatrix}$, $\mathbf{v}_3 = \begin{bmatrix} -2 \\ 6 \\ -5 \end{bmatrix}$, let $S = \{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$ and $L: \mathbb{R}^3 \rightarrow \mathbb{R}^5$ be a linear transformation defined by

$$L(\mathbf{v}_1) = \begin{bmatrix} 5 \\ 5 \\ -2 \\ 8 \\ -2 \end{bmatrix}, L(\mathbf{v}_2) = \begin{bmatrix} 2 \\ 2 \\ 1 \\ 4 \\ -1 \end{bmatrix}, L(\mathbf{v}_3) = \begin{bmatrix} -12 \\ -11 \\ 2 \\ -19 \\ 3 \end{bmatrix}.$$

- (i) **(1 points)** Use the determinant to check whether S is a basis for \mathbb{R}^3 . Justify your answer.

- (ii) **(3 points)** Let $\mathbf{v} = \begin{bmatrix} -3 \\ 7 \\ -5 \end{bmatrix}$. Find $L(\mathbf{v})$.

$$L(\mathbf{v}) =$$

- (b) **(4 points)** Given three vectors $\mathbf{v}'_1 = [1 \ 2 \ 2]$, $\mathbf{v}'_2 = [3 \ 1 \ 0]$, $\mathbf{v}'_3 = [1 \ 1 \ 1]$, let $S' = \{\mathbf{v}'_1, \mathbf{v}'_2, \mathbf{v}'_3\}$ and $L': \mathbb{R}_3 \rightarrow \mathbb{R}_4$ be a linear transformation defined by

$$L'(\mathbf{v}'_1) = [0 \ -1 \ 7 \ 3], L'(\mathbf{v}'_2) = [-6 \ -1 \ 2 \ 3], L'(\mathbf{v}'_3) = [-1 \ -1 \ 4 \ 2].$$

- (i) **(1 points)** Use the determinant to check whether S' is a basis for \mathbb{R}_3 . Justify your answer.

- (ii) **(3 points)** Let $\mathbf{v}' = [0 \ -3 \ -4]$. Find $L'(\mathbf{v}')$.

$$L'(\mathbf{v}') =$$

18.(6 points)

Given a system

$$\begin{cases} 2x + 3y - z = 1 \\ 3x + 5y + 2z = 8 \\ x - 2y - 3z = -1 \end{cases},$$

solve the system by the Cramer's rule.

$$x = \boxed{} \quad y = \boxed{} \quad z = \boxed{}$$

19.(8 points) Let

$$A = \begin{bmatrix} 3 & 1 & 1 \\ 1 & 3 & 1 \\ 1 & 1 & 3 \end{bmatrix}.$$

(a) **(3 points)** Find all eigenvalues of A .

(b) **(3 points)** Find three linearly independent eigenvectors of A .

(c) **(2 points)** Find an orthogonal matrix P and a diagonal matrix D such that $P^T A P = D$.

$P =$

$D =$