

## Erratum to the paper:

# Fast structured direct spectral methods for differential equations with variable coefficients, I. The one-dimensional case

By Jie Shen, Yingwei Wang and Jianlin Xia

1. In Eq.(2.14), the “ $2(N+1)$ ” should be “ $2N$ ” in the last column of the matrix. Also, in Eq.(2.15), the “ $N+1$ ” should be  $N$ .

$$(2.14) \quad \begin{pmatrix} 0 & 1 & 0 & 3 & 0 & 5 & \cdots & 0 \\ & 0 & 4 & 0 & 8 & 0 & \cdots & 2N \\ & & 0 & 6 & 0 & 10 & \cdots & 0 \\ & & & 0 & 8 & 0 & \cdots & 2N \\ & & & & 0 & 10 & \ddots & 0 \\ & & & & & \ddots & \ddots & \vdots \\ & & & & & & \ddots & 2N \\ & & & & & & & 0 \end{pmatrix}_{(N+1) \times (N+1)}$$

$$(2.15) \quad A_2|_{j,j+1:N} = \begin{cases} (1, 0, 3, 0, 5, \dots, 0), & j = 1, \\ 2(j, 0, j+2, 0, j+4, \dots, 0), & j > 1, j: \text{ odd}, \\ 2(j, 0, j+2, 0, \dots, N), & j > 1, j: \text{ even}. \end{cases}$$

2. In Eq.(2.17), the  $\tilde{F}$  and  $\tilde{F}^*$  should be interchanged to make it consistent with the definition of Forward and Backward discrete Chebyshev transforms (*FDCT* and *BDCT*).

The transforms between the spectral space  $\tilde{\mathbf{u}}$  and the physical space  $\mathbf{u} = (u(x_j))_{j=0}^N$  can be performed by

$$(2.17) \quad \tilde{\mathbf{u}} = \tilde{F}\mathbf{u}, \quad \mathbf{u} = \tilde{F}^*\tilde{\mathbf{u}},$$

where  $\tilde{F}$  and  $\tilde{F}^*$  are the FDCT and BDCT matrices, respectively.

Also, the Eq.(2.18) should be

$$(2.18) \quad A\tilde{\mathbf{u}} = \hat{\mathbf{f}}, \quad A = A_3(\tilde{F}\mathcal{D}_\alpha\tilde{F}^* - A_2\tilde{F}\mathcal{D}_\beta\tilde{F}^*A_2)A_1.$$