

Homework 5 for MA527 by Youyi Bi (PID: 00256 8069P)

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34.4 P.151

3. Answer:

obviously, $\vec{y}' = \begin{bmatrix} 0 & 1 \\ -9 & 0 \end{bmatrix} \vec{y}$, $\det \begin{vmatrix} -\lambda & 1 \\ -9 & -\lambda \end{vmatrix} = \lambda^2 + 9 = 0$

$\Rightarrow \lambda_1 = 3i, \lambda_2 = -3i$

Because λ_1, λ_2 are pure imaginary, $p = \lambda_1 + \lambda_2 = 0, q = \lambda_1 \lambda_2 > 0$
 hence the critical point is ^{the} type of center, and stable.

For $\lambda_1 = 3i$, $-(3i)x_1 + x_2 = 0 \Rightarrow \vec{x}_1 = [1 \ 3i]^T$

For $\lambda_2 = -3i$, $-(-3i)x_1 + x_2 = 0 \Rightarrow \vec{x}_2 = [1 \ -3i]^T$

hence

$$\vec{y} = c_1 \begin{bmatrix} 1 \\ 3i \end{bmatrix} e^{3it} + c_2 \begin{bmatrix} 1 \\ -3i \end{bmatrix} e^{-3it}$$

$$\Rightarrow \begin{cases} y_1 = c_1 e^{3it} + c_2 e^{-3it} \\ y_2 = 3c_1 i e^{3it} - 3c_2 i e^{-3it} \end{cases}, \text{ According to Euler Formula } e^{ix} = \cos x + i \sin x$$

we obtain

$$y_1 = c_1 (\cos 3t + i \sin 3t) + c_2 (\cos 3t - i \sin 3t)$$

$$= (c_1 + c_2) \cos 3t + (c_1 - c_2) i \sin 3t, \text{ let } A = c_1 + c_2, B = (c_1 - c_2) i$$

then $y_1 = A \cos 3t + B \sin 3t$

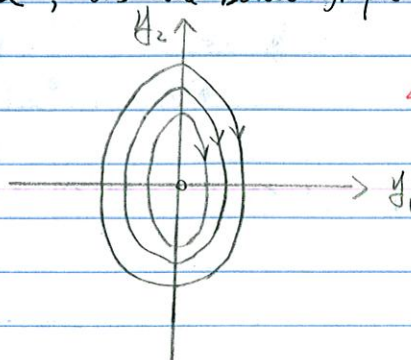
and $y_2 = 3c_1 i (\cos 3t + i \sin 3t) - 3c_2 i (\cos 3t - i \sin 3t)$

$$= (3c_1 i - 3c_2 i) \cos 3t + (-3c_1 - 3c_2) \sin 3t$$

$$= 3B \cos 3t - 3A \sin 3t, \text{ and clearly, } y_1^2 + \left(\frac{y_2}{3}\right)^2 = \text{const}$$

To determine the direction of ~~the~~ the graph, \vec{y}' at $\begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ -9 & 0 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ -9 \end{bmatrix}$

hence, it's clockwise, as the below graph showing:



5. Answer:

$$\vec{y}' = \begin{bmatrix} -2 & 2 \\ -2 & -2 \end{bmatrix} \vec{y}, \quad \det \begin{vmatrix} -2-\lambda & 2 \\ -2 & -2-\lambda \end{vmatrix} = (\lambda+2)^2 + 4 = \lambda^2 + 4\lambda + 8 = 0$$

$$\Rightarrow \lambda_1 = -2+2i, \quad \lambda_2 = -2-2i$$

Because $p = \lambda_1 + \lambda_2 = -4 < 0$, $q = \lambda_1 \lambda_2 = 4 + 4 > 0$

hence the type of critical point is spiral, stable and attractive

$$\text{For } \lambda_1 = -2+2i, \quad (-2 - (-2+2i))x_1 + 2x_2 = 0 \Rightarrow \vec{x}_1 = \begin{bmatrix} 1 \\ i \end{bmatrix}$$

$$\text{For } \lambda_2 = -2-2i, \quad (-2 - (-2-2i))x_1 + 2x_2 = 0 \Rightarrow \vec{x}_2 = \begin{bmatrix} 1 \\ -i \end{bmatrix}$$

$$\text{hence } \vec{y} = c_1 \begin{bmatrix} 1 \\ i \end{bmatrix} e^{(-2+2i)t} + c_2 \begin{bmatrix} 1 \\ -i \end{bmatrix} e^{(-2-2i)t}$$

$$= c_1 e^{-2t} \begin{bmatrix} e^{2it} \\ i e^{2it} \end{bmatrix} + c_2 e^{-2t} \begin{bmatrix} e^{-2it} \\ -i e^{-2it} \end{bmatrix}$$

$$\Rightarrow \begin{cases} y_1 = e^{-2t} (c_1 e^{2it} + c_2 e^{-2it}) \\ y_2 = e^{-2t} (c_1 i e^{2it} - c_2 i e^{-2it}) \end{cases} \text{ According to Euler Formula, } e^{ix} = \cos x + i \sin x$$

$$\Rightarrow y_1 = e^{-2t} ((c_1 + c_2) \cos 2t + (c_1 - c_2) i \sin 2t) \text{ Let } A = c_1 + c_2, B = (c_1 - c_2) i$$

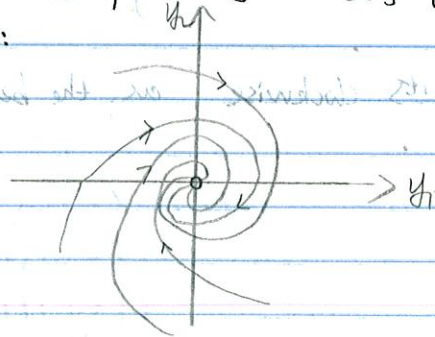
$$\text{then } y_1 = e^{-2t} (A \cos 2t + B \sin 2t)$$

$$y_2 = e^{-2t} ((c_1 - c_2) i \cos 2t - (c_1 + c_2) \sin 2t)$$

$$= e^{-2t} (B \cos 2t - A \sin 2t)$$

To determine the direction of the spiral, \vec{y}' at $\begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} -2 & 2 \\ -2 & -2 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} -2 \\ -2 \end{bmatrix}$

then the graph is as below:



7. Answer:

$$\vec{y}' = \begin{bmatrix} 1 & 2 \\ 2 & 1 \end{bmatrix} \vec{y}, \det \begin{vmatrix} 1-\lambda & 2 \\ 2 & 1-\lambda \end{vmatrix} = (\lambda-1)^2 - 4 = \lambda^2 - 2\lambda - 3 = (\lambda-3)(\lambda+1) = 0$$

$$\Rightarrow \lambda_1 = 3, \lambda_2 = -1$$

Because $p = \lambda_1 + \lambda_2 = 2 > 0$, $q = \lambda_1 \lambda_2 < 0$

hence the type of the critical point is saddle and unstable.

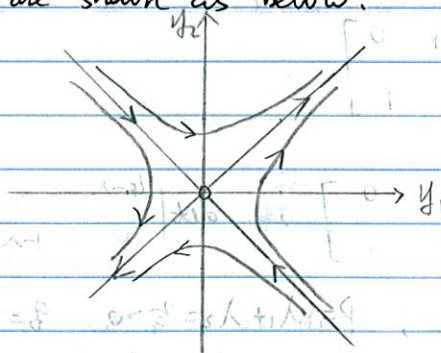
$$\text{For } \lambda_1 = 3, -2x_1 + 2x_2 = 0 \Rightarrow \vec{x}_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$\text{For } \lambda_2 = -1, 2x_1 + 2x_2 = 0 \Rightarrow \vec{x}_2 = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

$$\text{hence } \vec{y} = c_1 \begin{bmatrix} 1 \\ 1 \end{bmatrix} e^{3t} + c_2 \begin{bmatrix} 1 \\ -1 \end{bmatrix} e^{-t}$$

$$\Rightarrow \begin{cases} y_1 = c_1 e^{3t} + c_2 e^{-t} \\ y_2 = c_1 e^{3t} - c_2 e^{-t} \end{cases}$$

The trajectories are shown as below:



11. Answer:

$$\begin{cases} y_1 = y \\ y_2 = y_1' = y' \\ y_3 = y_2' = y'' = -2y' - 2y \end{cases} \Rightarrow \vec{y}' = \begin{bmatrix} 0 & 1 \\ -2 & -2 \end{bmatrix} \vec{y}$$

$$\det \begin{vmatrix} 0-\lambda & 1 \\ -2 & -2-\lambda \end{vmatrix} = \lambda^2 + 2\lambda + 2 = 0 \Rightarrow \lambda_1 = -1+i, \lambda_2 = -1-i$$

Because $p = \lambda_1 + \lambda_2 = -2 < 0$, $q = \lambda_1 \lambda_2 = 2 > 0$

hence, the trajectories are spirals and stable, and attractive.

$$\text{For } \lambda_1 = -1+i, (1-i)x_1 + x_2 = 0 \Rightarrow \vec{x}_1 = \begin{bmatrix} 1 \\ -1 \end{bmatrix} + i \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$$\text{For } \lambda_2 = -1-i, (1+i)x_1 + x_2 = 0 \Rightarrow \vec{x}_2 = \begin{bmatrix} 1 \\ -1 \end{bmatrix} + i \begin{bmatrix} 0 \\ -1 \end{bmatrix}$$

$$y = y_1 = c_1 e^{(-1+i)t} + c_2 e^{(-1-i)t}$$

$$= e^{-t} [(c_1 + c_2) \cos t + (c_1 - c_2)i \sin t]$$

$$\text{Let } A = c_1 + c_2, B = (c_1 - c_2)i$$

$$\Rightarrow y = e^{-t} (A \cos t + B \sin t)$$

§4.5 P159.

4. Answer:

$$f_1 = 4y_1 - y_1^2 = y_1(4 - y_1) = 0 \Rightarrow y_1 = 0 \text{ or } y_1 = 4$$

$$f_2 = y_2 = 0$$

hence we have two critical points $(0, 0)$ and $(4, 0)$

$$\text{And } \nabla \vec{f} = \begin{bmatrix} 4 - 2y_1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$\nabla \vec{f}(0, 0) = \begin{bmatrix} 4 & 0 \\ 0 & 1 \end{bmatrix}, \det \begin{vmatrix} 4 - \lambda & 0 \\ 0 & 1 - \lambda \end{vmatrix} = (\lambda - 4)(\lambda - 1) = 0$$

$$\Rightarrow \lambda_1 = 1, \lambda_2 = 4, p = \lambda_1 + \lambda_2 = 5 > 0, q = \lambda_1 \lambda_2 = 4 > 0$$

$$\nabla \vec{f}(4, 0) = \begin{bmatrix} -4 & 0 \\ 0 & 1 \end{bmatrix} \Rightarrow \lambda_1 = -4, \lambda_2 = 1$$

$$p = \lambda_1 + \lambda_2 = -3 < 0, q = \lambda_1 \lambda_2 = -4 < 0$$

Hence, proper node at $(0, 0)$, ~~is~~ unstable

saddle point at $(4, 0)$, unstable

7. Answer:

$$f_1 = -y_1 + y_2 - y_2^2 = 0, f_2 = -y_1 - y_2 = 0$$

$$\Rightarrow 2y_2 - y_2^2 = 0 \Rightarrow y_2 = 0 \text{ or } y_2 = 2$$

then we have two critical points $(0, 0)$, $(-2, 2)$

$$\text{And } \nabla \vec{f} = \begin{bmatrix} -1 & 1-2y_2 \\ -1 & -1 \end{bmatrix}$$

$$\nabla \vec{f}(0,0) = \begin{bmatrix} -1 & 1 \\ -1 & -1 \end{bmatrix}, \det \begin{vmatrix} -1-\lambda & 1 \\ -1 & -1-\lambda \end{vmatrix} = \lambda^2 + 2\lambda + 2 = 0$$

$$\lambda_1 = -1+i, \lambda_2 = -1-i, P = \lambda_1 + \lambda_2 = -2 < 0, Q = \lambda_1 \lambda_2 = 2 > 0$$

$$\nabla \vec{f}(-2,2) = \begin{bmatrix} -1 & -3 \\ -1 & -1 \end{bmatrix}, \det \begin{vmatrix} -1-\lambda & -3 \\ -1 & -1-\lambda \end{vmatrix} = \lambda^2 + 2\lambda - 3 = 0$$

$$\lambda_1 = 1, \lambda_2 = -3, P = \lambda_1 + \lambda_2 = -2 < 0, Q = \lambda_1 \lambda_2 = -3 < 0$$

Hence, spiral point at $(0, 0)$, stable and attractive
 saddle point at $(-2, 2)$, unstable

11. Answer:

$$y_1 = y$$

$$y_2 = y_1' = y'$$

$$y_3 = y_2' = y'' = -\cos y$$

$$\Rightarrow \begin{cases} y_1' = y_2 \\ y_2' = -\cos y_1 \end{cases}$$

$$f_1 = y_2 = 0, f_2 = -\cos y_1 = 0 \Rightarrow y_1 = \frac{\pi}{2} \pm 2n\pi, \text{ or } y_1 = -\frac{\pi}{2} \pm 2n\pi$$

then we have two sets of critical points:

$$\left(\frac{\pi}{2} \pm 2n\pi, 0\right) \text{ and } \left(-\frac{\pi}{2} \pm 2n\pi, 0\right)$$

$$\text{And } \nabla \vec{f} = \begin{bmatrix} 0 & 1 \\ \sin y_1 & 0 \end{bmatrix}$$

$$\nabla \vec{f}\left(\frac{\pi}{2} \pm 2n\pi, 0\right) = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}, \det \begin{vmatrix} -\lambda & 1 \\ 1 & -\lambda \end{vmatrix} = \lambda^2 - 1 = 0$$

$$\Rightarrow \lambda_1 = 1, \lambda_2 = -1, P = \lambda_1 + \lambda_2 = 0, Q = \lambda_1 \lambda_2 = -1 < 0$$

$$\vec{f}^{\rightarrow}\left(-\frac{z}{2} \pm 2n\pi, 0\right) = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}, \det \begin{vmatrix} -\lambda & 1 \\ -1 & -\lambda \end{vmatrix} = \lambda^2 + 1 = 0$$

$$\Rightarrow \lambda_1 = i, \lambda_2 = -i$$

$$p = \lambda_1 + \lambda_2 = 0, \quad q = \lambda_1 \lambda_2 = 1 > 0$$

Hence, Saddle points at $\left(\frac{z}{2} \pm 2n\pi, 0\right)$, unstable

centers at $\left(-\frac{z}{2} \pm 2n\pi, 0\right)$, stable

§4.6 P163.

3. Answer:

$$\vec{y}' = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \vec{y} + \begin{bmatrix} 1 \\ -3 \end{bmatrix} e^{3t}$$

For the homogeneous system,

$$\det \begin{vmatrix} -\lambda & 1 \\ 1 & -\lambda \end{vmatrix} = \lambda^2 - 1 = 0 \Rightarrow \lambda_1 = 1, \lambda_2 = -1$$

$$\lambda_1 = 1, \quad -x_1 + x_2 = 0 \Rightarrow \vec{x}_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$\lambda_2 = -1, \quad x_1 + x_2 = 0 \Rightarrow \vec{x}_2 = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

$$\text{hence, } \vec{y}_h = c_1 \begin{bmatrix} 1 \\ 1 \end{bmatrix} e^t + c_2 \begin{bmatrix} 1 \\ -1 \end{bmatrix} e^{-t}$$

$$\text{Let } \vec{y}_p = e^{3t} \vec{v} + t e^{3t} \vec{u}$$

$$\begin{aligned} \vec{y}_p' &= 3e^{3t} \vec{v} + (1+3t)e^{3t} \vec{u} \\ &= A(e^{3t} \vec{v} + t e^{3t} \vec{u}) + \begin{bmatrix} 1 \\ -3 \end{bmatrix} e^{3t} \end{aligned}$$

$$\Rightarrow 3\vec{v} + (1+3t)\vec{u} = A\vec{v} + tA\vec{u} + \begin{bmatrix} 1 \\ -3 \end{bmatrix}$$

$$\Rightarrow t(A - 3I)\vec{u} = \vec{0}, \text{ then } \begin{bmatrix} -3 & 1 \\ 1 & -3 \end{bmatrix} \vec{u} = \vec{0} \Rightarrow \vec{u} = \vec{0}$$

$$\text{and } (A-3I)\vec{v} = \vec{u} - \begin{bmatrix} 1 \\ -3 \end{bmatrix} = \begin{bmatrix} -1 \\ 3 \end{bmatrix}$$

$$\text{then } \begin{bmatrix} -3 & 1 \\ 1 & -3 \end{bmatrix} \vec{v} = \begin{bmatrix} -1 \\ 3 \end{bmatrix}$$

$$\Rightarrow \begin{cases} -3v_1 + v_2 = -1 \\ v_1 - 3v_2 = 3 \end{cases} \Rightarrow \begin{cases} v_1 = 0 \\ v_2 = -1 \end{cases} \quad \vec{v} = \begin{bmatrix} 0 \\ -1 \end{bmatrix}$$

$$\text{Hence } \vec{y} = \vec{y}_h + \vec{y}_p = c_1 \begin{bmatrix} 1 \\ 1 \end{bmatrix} e^t + c_2 \begin{bmatrix} 1 \\ -1 \end{bmatrix} e^{-t} + \begin{bmatrix} 0 \\ -1 \end{bmatrix} e^{3t}$$

$$\Rightarrow \begin{cases} y_1 = c_1 e^t + c_2 e^{-t} \\ y_2 = c_1 e^t - c_2 e^{-t} - e^{3t} \end{cases}$$

11. Answer:

$$\vec{y}' = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \vec{y} + \begin{bmatrix} 6 \\ -1 \end{bmatrix} e^{2t}$$

For the homogeneous system, $\det \begin{vmatrix} -\lambda & 1 \\ 1 & -\lambda \end{vmatrix} = 0 \Rightarrow \lambda^2 - 1 = 0, \lambda_1 = -1, \lambda_2 = 1$

$$\lambda_1 = -1, x_1 + x_2 = 0 \Rightarrow \vec{v}_1 = \begin{bmatrix} 1 \\ -1 \end{bmatrix}, \lambda_2 = 1, -x_1 + x_2 = 0 \Rightarrow \vec{v}_2 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$\text{hence } \vec{y}_h = c_1 \begin{bmatrix} 1 \\ -1 \end{bmatrix} e^{-t} + c_2 \begin{bmatrix} 1 \\ 1 \end{bmatrix} e^t$$

$$\text{Let } \vec{y}_p = e^{2t} \vec{v} + t e^{2t} \vec{u}$$

$$\begin{aligned} \vec{y}_p' &= 2e^{2t} \vec{v} + (1+2t)e^{2t} \vec{u} \\ &= A(e^{2t} \vec{v} + t e^{2t} \vec{u}) + \begin{bmatrix} 6 \\ -1 \end{bmatrix} e^{2t} \end{aligned}$$

$$\Rightarrow 2\vec{v} + (1+2t)\vec{u} = A\vec{v} + tA\vec{u} + \begin{bmatrix} 6 \\ -1 \end{bmatrix}$$

$$\Rightarrow t(A-2I)\vec{u} = \vec{0}, \text{ then } \begin{bmatrix} -2 & 1 \\ 1 & -2 \end{bmatrix} \vec{u} = \vec{0} \Rightarrow \vec{u} = \vec{0}$$

$$\text{and } (A - 2I)\vec{v} = \vec{u} = \begin{bmatrix} 6 \\ -1 \end{bmatrix} = \begin{bmatrix} -6 \\ 1 \end{bmatrix}$$

$$\begin{cases} -2v_1 + v_2 = -6 \\ v_1 + 2v_2 = 1 \end{cases} \Rightarrow \begin{cases} v_1 = \frac{11}{3} \\ v_2 = \frac{4}{3} \end{cases}$$

$$\text{Hence } \vec{y} = \vec{y}_h + \vec{y}_p$$

$$= c_1 \begin{bmatrix} 1 \\ -1 \end{bmatrix} e^{-t} + c_2 \begin{bmatrix} 1 \\ 1 \end{bmatrix} e^t + \begin{bmatrix} \frac{11}{3} \\ \frac{4}{3} \end{bmatrix} e^{2t}$$

$$\Rightarrow y_1 = c_1 e^{-t} + c_2 e^t + \frac{11}{3} e^{2t}$$

$$y_2 = -c_1 e^{-t} + c_2 e^t + \frac{4}{3} e^{2t}$$

$$\text{And } y_1(0) = 1, y_2(0) = 0$$

$$\Rightarrow \begin{cases} c_1 + c_2 + \frac{11}{3} = 1 \\ -c_1 + c_2 + \frac{4}{3} = 0 \end{cases} \Rightarrow \begin{cases} c_1 = -\frac{2}{3} \\ c_2 = -2 \end{cases}$$

$$y_1 = -\frac{2}{3} e^{-t} - 2e^t + \frac{11}{3} e^{2t}$$

$$y_2 = \frac{2}{3} e^{-t} - 2e^t + \frac{4}{3} e^{2t}$$

Because $e^t = \cosht + \sinht$, $e^{-t} = \cosht - \sinht$, it can also be written

$$\text{as: } y_1 = -\frac{2}{3} (\cosht - \sinht) - 2(\cosht + \sinht) + \frac{11}{3} e^{2t}$$

$$= -\frac{8}{3} \cosht - \frac{4}{3} \sinht + \frac{11}{3} e^{2t}$$

$$y_2 = \frac{2}{3} (\cosht - \sinht) - 2(\cosht + \sinht) + \frac{4}{3} e^{2t}$$

$$= -\frac{4}{3} \cosht - \frac{8}{3} \sinht + \frac{4}{3} e^{2t}$$