

#5

$$A = \begin{pmatrix} 0 & 1 & 2 & 0 \\ 0 & 2 & 4 & 0 \\ 0 & -3 & -6 & 0 \end{pmatrix}$$

$$r(A) = ?$$

$$\rightarrow \begin{pmatrix} 0 & 1 & 2 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

$$r(A) = 1$$

B

#6

$$A = \begin{pmatrix} 1 & 0 & 1 \\ 0 & 2 & 0 \\ 3 & 0 & 3 \end{pmatrix} \quad \lambda(A) = ?$$

$$0 = \begin{vmatrix} 1-\lambda & 0 & 1 \\ -0 & 2-\lambda & 0 \\ 3 & 0 & 3-\lambda \end{vmatrix} = (2-\lambda) \begin{vmatrix} 1-\lambda & 1 \\ 3 & 3-\lambda \end{vmatrix}$$

$$= (2-\lambda) \left[(\lambda-1)(\lambda-3) - 3 \right]$$

$$\lambda^2 - 4\lambda = \lambda(\lambda-4)$$

$$\lambda = 0, 2, 4$$

F

#7

$$A = \begin{pmatrix} 0 & -1 & 0 \\ -1 & 1 & -1 \\ 0 & -1 & 0 \end{pmatrix}$$

$$\lambda(A) = 2, 0, \textcircled{-1}$$

$$\underline{A\vec{x} = \lambda\vec{x}}$$

$$\vec{x} \neq \vec{0}$$

$$A+I = \begin{pmatrix} 1 & -1 & 0 \\ \textcircled{-1} & 2 & -1 \\ 0 & -1 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

C

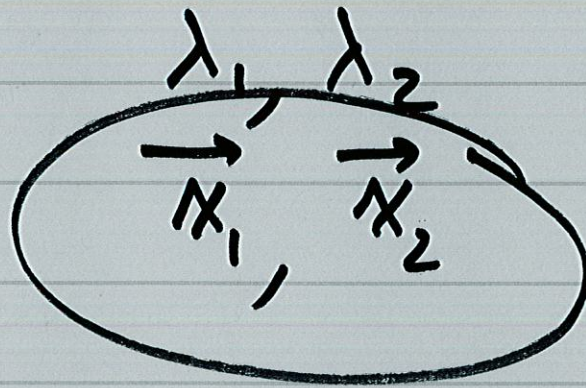
$$\rightarrow \begin{pmatrix} 1 & -1 & 0 \\ 0 & 1 & -1 \\ 0 & \textcircled{-1} & \textcircled{1} \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\begin{cases} x_1 - x_2 = 0 \\ x_2 - x_3 = 0 \end{cases}$$

$$\underline{x_2 = s}$$

$$\vec{x} = \begin{pmatrix} s \\ s \\ s \end{pmatrix} = s \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$$

diagonalize $A_{2 \times 2}$



$$\lambda_1 = \lambda_2$$

$$X = [\vec{x}_1, \vec{x}_2]$$

$$AX = X \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix}$$

$$X^{-1}AX = \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix}$$

#8 $\vec{y}' = \begin{pmatrix} 3 & 0 \\ 1 & 2 \end{pmatrix} \vec{y}$, $\vec{y}_1 = \begin{pmatrix} 0 \\ e^{2t} \end{pmatrix}$, $\vec{y}_2 = ?$

$0 = \begin{vmatrix} 3-\lambda & 0 \\ 1 & 2-\lambda \end{vmatrix} = (\lambda-3)(\lambda-2) \Rightarrow \lambda_1 = 2, \lambda_2 = 3$

$\lambda_1 = 2$ $x_1 = 0$ $\vec{x} = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$ $\vec{y}_1 = e^{2t} \begin{pmatrix} 0 \\ 1 \end{pmatrix}$

$\lambda_2 = 3$ $\begin{pmatrix} 0 & 0 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$ $x_1 = x_2$ $\vec{x} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$

$\vec{y}_2 = e^{3t} \begin{pmatrix} 1 \\ 1 \end{pmatrix}$

F. $e^{2t} \begin{pmatrix} 0 \\ 1 \end{pmatrix} + e^{3t} \begin{pmatrix} 1 \\ 1 \end{pmatrix}$

$\frac{e^{2t} \begin{pmatrix} 1 \\ 0 \end{pmatrix} + e^{3t} \begin{pmatrix} 0 \\ 1 \end{pmatrix}}{e^{2t} \begin{vmatrix} 0 & e^{3t} \\ e^{2t} & e^{3t} \end{vmatrix}} = -e^{st} \neq 0$

#9 $\vec{y}' = \begin{pmatrix} 1 & 3 \\ 4 & 2 \end{pmatrix} \vec{y}$ $(0,0)$ -

$$\lambda = \frac{3 \pm \sqrt{9+40}}{2} = \frac{3 \pm 7}{2}$$

$$0 = \begin{vmatrix} 1-\lambda & 3 \\ 4 & 2-\lambda \end{vmatrix} = (\lambda-1)(\lambda-2) - 12$$

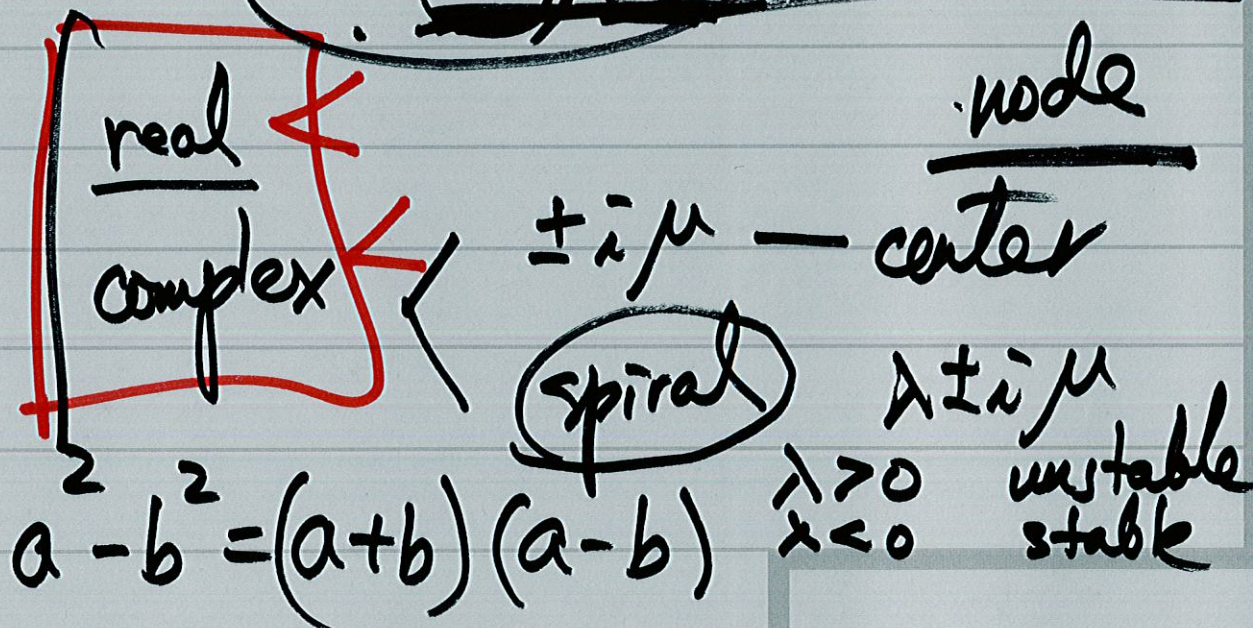
$$= \lambda^2 - 3\lambda - 10$$

$= \underline{-2}, \underline{5}$ - saddle pt

#10 $\vec{y}' = \begin{pmatrix} 6 & 9 \\ 1 & 6 \end{pmatrix} \vec{y}$ $(0,0)$

$$0 = \begin{vmatrix} 6-\lambda & 9 \\ 1 & 6-\lambda \end{vmatrix} = (\lambda-6)^2 - 9 = (\lambda-3)(\lambda-9)$$

$\lambda = \underline{3}, \underline{9}$ node unstable



$$\begin{pmatrix} x' \\ y' \end{pmatrix} = \begin{pmatrix} f_1(x, y) \\ f_2(x, y) \end{pmatrix}$$

critical pts

$$\begin{cases} f_1(x, y) = 0 \\ f_2(x, y) = 0 \end{cases}$$

(x_0, y_0)

$$\vec{\nabla} f(x_0, y_0) = \begin{pmatrix} \frac{\partial f}{\partial x} \\ \frac{\partial f}{\partial y} \end{pmatrix}_{(x_0, y_0)}$$

#11
$$\begin{pmatrix} x' \\ y' \end{pmatrix} = \begin{pmatrix} \frac{3xy}{1+x^2+y^2} - \frac{1+x^2}{1+y^2} \\ x^2 - y^2 \end{pmatrix}$$

(1,1)

$\frac{\partial f_1}{\partial x} \Big|_{(1,1)}$

$$\frac{3y(1+x^2+y^2) - 2x \cdot 3xy}{(1+x^2+y^2)^2}$$

$$- \frac{2x(1+y^2) - 0}{(1+y^2)^2} \Big|_{(1,1)}$$

$$\frac{\partial f_1}{\partial y} \Big|_{(1,1)} = \frac{1}{3} + 1 = \frac{4}{3}$$

$$= \frac{9-6}{9} - \frac{4}{4} = \frac{1}{3} - 1 = -\frac{2}{3}$$

$\frac{\partial f_2}{\partial x} \Big|_{(1,1)} = 2x \Big|_{(1,1)} = 2, \quad \frac{\partial f_2}{\partial y} = -2y \rightarrow -2$

$$\begin{vmatrix} -\frac{2}{3} - \lambda & \frac{4}{3} \\ 2 & -2 - \lambda \end{vmatrix} = \left(\lambda + \frac{2}{3}\right)(\lambda + 2) - \frac{8}{3} = \lambda^2 + \frac{8}{3}\lambda - \frac{4}{3}$$

$$\nabla f(1,1) = \begin{pmatrix} -\frac{2}{3} & \frac{4}{3} \\ 2 & -2 \end{pmatrix}$$

$$0 = |A - \lambda I| = \lambda^2 + \frac{8}{3}\lambda - \frac{4}{3}$$

$$\lambda = \frac{-\frac{8}{3} \pm \sqrt{\left(\frac{8}{3}\right)^2 + \frac{16}{3}}}{2}$$

real distinct

roots

$$\underline{\lambda_1 < 0}$$

$$\underline{\lambda_2 > 0}$$

saddle pt.

unstable.

#12

$$\begin{pmatrix} x' \\ y' \end{pmatrix} = \begin{pmatrix} y \\ \sin x \end{pmatrix}$$

$$\underline{\underline{(0,0)}}$$

$$\begin{cases} y=0 \\ \sin x=0 \end{cases} \quad x=k\pi$$

$$\nabla f(0,0) = \begin{pmatrix} 0 & 1 \\ \cos x & 0 \end{pmatrix}_{(0,0)}$$

$$= \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

$$0 = \begin{vmatrix} \lambda & 1 \\ 1 & -\lambda \end{vmatrix} = \lambda^2 - 1 \Rightarrow \lambda = \pm 1$$

saddle pt
unstable

#13

$$\vec{x}' = A\vec{x} + \begin{pmatrix} 2e^{-t} \\ 2 \end{pmatrix}$$

$$X(t) = \begin{pmatrix} e^{-3t} & e^{-t} \\ -e^{-3t} & e^{-t} \end{pmatrix}$$

$$\vec{u}' = X^{-1} \vec{g}$$

$$X^{-1} = \frac{1}{2e^{-4t}} \begin{pmatrix} e^{-t} & -e^{-t} \\ e^{-3t} & e^{-3t} \end{pmatrix}$$

$$\vec{u}' = \frac{1}{2e^{-4t}} \begin{pmatrix} 2e^{-2t} & -2e^{-t} \\ 2e^{-4t} + 2e^{-3t} \end{pmatrix} = \begin{pmatrix} e^{2t} & -e^{3t} \\ 1 + e^t \end{pmatrix}$$

$$\vec{u} = \begin{pmatrix} \frac{1}{2}e^{2t} - \frac{1}{3}e^{3t} \\ t + e^t \end{pmatrix} + \begin{pmatrix} c_1 \\ c_2 \end{pmatrix}$$

$X\vec{u}$

$$= \begin{pmatrix} \frac{1}{2}e^{-t} + te^{-t} + \frac{2}{3} \\ -\frac{1}{2}e^{-t} + te^{-t} + \frac{4}{3} \end{pmatrix}$$

$$\vec{x} = X \vec{u} = X \vec{c} + X \begin{pmatrix} \frac{1}{2}e^{2t} - \frac{1}{3}e^{3t} \\ t + e^t \end{pmatrix}$$

$$= \begin{pmatrix} \frac{1}{2}e^{-t} - \frac{1}{3} + te^{-t} + 1 \\ -\frac{1}{2}e^{-t} + \frac{1}{3} + te^{-t} + 1 \end{pmatrix}$$

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