

The Mathematical Theory of FEMs

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Chapter 0 Basic Concepts

§0.1 Weak Formulation of BVPs

2-pt BVPs
$$\begin{cases} -\frac{d^2 u}{dx^2} = f & \text{in } (0,1) \\ u(0) = 0, \quad u'(1) = 0 \end{cases} \quad (0.1.1)$$

Weak Formulation Find $u \in V = \{v \in L^2(0,1) \mid a(v,v) \equiv \int_0^1 v'v'dx < +\infty \text{ and } v(0)=0\}$ s.t.
Variational
$$a(u,v) \equiv \int_0^1 u'v'dx = \int_0^1 f v dx \quad \forall v \in V. \quad (0.1.3)$$

"(0.1.1) \Rightarrow (0.1.3)" Let u be solution, v — any (sufficiently smooth) function

$$\begin{aligned} (f, v) &= \int_0^1 f v dx = \int_0^1 -u'' v dx = \int_0^1 u'v'dx - u'v \Big|_0^1 = a(u,v) - u'(1)v(1) \\ &= a(u,v) \quad \text{if } v(1)=0. \end{aligned}$$

Question $u'(x) = ?$ $\left\{ \begin{array}{l} \text{classic} \\ ? \end{array} \right.$

Thrm (0.1.4) $f \in C^0[0,1], u \in C^2[0,1]$ satisfies (0.1.3) \Rightarrow u solves (0.1.1)

Proof ~~$\forall v \in C^1[0,1]$~~ (0.1.3) $\xrightarrow[\text{by parts}]{\text{integration}}$ $(f + u'', v) = 0 \quad \forall v \in V \cap C^1[0,1]$ and $v(1)=0$
 $(f + u'', v) = u'(1)v(1)$

$$\Rightarrow f+u'' \equiv 0 \quad \left[\begin{array}{l} \text{If not, } \exists [x_0, x_1] \subset [0,1] \text{ s.t. } f+u'' > 0 \text{ in } [x_0, x_1] \\ \text{choose } v = \begin{cases} (x-x_0)^2(x-x_1)^2 & x \in [x_0, x_1] \\ 0 & \text{otherwise} \end{cases} \end{array} \right. \Rightarrow \begin{cases} (f+u'', v) \neq 0 \\ v(1) = 0 \end{cases} \text{ contradiction}$$

Take $v(x) = x \Rightarrow u'(1) = 0$
 $u \in V \Rightarrow u(0) = 0$

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Remark $u(x) = 0$ essential Dirichlet
 $u'(x) = 0$ natural Neumann

Question Well-posedness of (0.1.3)?

§0.2 Ritz-Galerkin Approximation

$S \subset V$ — a finite dimensional subspace

RG Approx. Find $u_S \in S$ s.t.

$$a(u_S, v) = (f, v) \quad \forall v \in S \quad (0.2.1)$$

~~Thm (0.2.2) Given $f \in L^2[0,1]$, (0.2.1) has a unique solution.~~

Proof $S = \text{span} \{ \phi_i \}_{i=1}^n \Rightarrow u_S = \sum_j U_j \phi_j$

$$\Rightarrow KU = F, \quad K = (K_{ij})_{n \times n}, \quad K_{ij} = a(\phi_j, \phi_i)$$

$$U = (U_j)_{n \times 1}, \quad F = (F_i) \quad F_i = (f, \phi_i)$$

~ stiffness matrix

Remark (1) K is symmetric,

(2) K is positive definite, i.e., $\langle KV, V \rangle \geq 0 \quad \forall V \in \mathbb{R}^n$
and " $\langle KV, V \rangle = 0 \Rightarrow V = 0$ ".

Proof $V = (V_j)$, let $v = \sum_j V_j \phi_j$

$$\Rightarrow \langle KV, V \rangle = V^T KV = a(v, v) \geq 0 \quad \forall v$$

~~$\neq 0 \Rightarrow v \neq 0$~~ $\langle KV, V \rangle = 0 \Rightarrow a(v, v) = \int_0^1 (v')^2 dx = 0$

$$\Rightarrow v' \equiv 0 \text{ in } (0, 1) \quad v(0) = 0?$$

$$\Rightarrow v = \text{constant} \implies v \equiv 0 \text{ in } (0, 1) \Rightarrow V = 0$$

Thm(0.2.2) Given $f \in L^2[0, 1]$, (0.2.1) has a unique solution.

Proof (i) (K is sym pos. def.) $\Rightarrow KU = F$ has a unique sol. \Rightarrow (0.2.1) has

(ii) a finite dimensional prob. is equivalent to that $KV = 0$ has only trivial sol.

§0.3 Error Estimates

exact sol. $a(u, v) = (f, v) \quad \forall v \in V$
approx. $a(u_s, v) = (f, v) \quad \forall v \in S \subset V$ } $\Rightarrow a(u - u_s, v) = 0 \quad \forall v \in S$
error eqn. or orthogonal property

the energy norm $\|v\|_E = \sqrt{a(v, v)} = \sqrt{\int_0^1 (v')^2 dx}$

the Schwarz inequality $|a(u, v)| \leq \|u\|_E \|v\|_E \quad \forall u, v \in V$

2nd Lecture Review

- (1) 2-pts BVPs $(1) \Rightarrow (2)$ and $(2) \Rightarrow (1)$ if (2) is smooth
- (2) Variational Problem $\begin{cases} u \in V \\ a(u, v) = f(v) \quad \forall v \in V \end{cases}$
- BCs: natural, essential

- (3) R-G Approximation $\begin{cases} u_s \in S \subset V \\ a(u_s, v) = f(v) \quad \forall v \in S = \text{span}\{\phi_i\}_{i=1}^n \end{cases}$
- system of AEs $KU = F$
- K is sym. pos. def.

Let $Y \in \mathbb{R}^n$ and $v = Y_1 \phi_1 + \dots + Y_n \phi_n$

$$Y^T K Y = a(v, v)$$

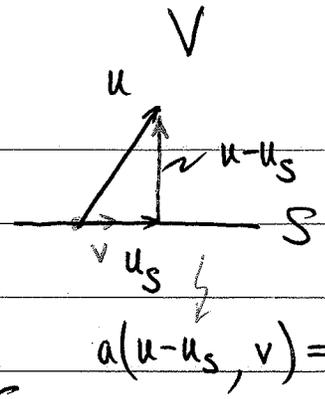
Thm (0.3.3) $\|u - u_S\|_E = \min_{v \in S} \|u - v\|_E$

~~Proof~~

Proof

$$\|u - u_S\|_E \leq \|u - v\|_E \quad \forall v \in S$$

$$\|u - u_S\|_E^2 = a(u - u_S, u - u_S) \stackrel{\text{orthogonality}}{=} a(u - u_S, u - v) \quad \forall v \in S$$
$$\leq \|u - u_S\|_E \|u - v\|_E \quad \forall v \in S$$



$$a(u - u_S, v) = 0 \quad \forall v \in S$$

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L-norm error estimate (a "duality" argument)

the dual problem: $\begin{cases} -w'' = u - u_S & \text{in } (0, 1) \\ w(0) = w(1) = 0 \end{cases} \Rightarrow a(w, v) = (u - u_S, v) \quad \forall v \in V$

$$\Rightarrow \|u - u_S\|_E^2 = a(w, u - u_S) = a(w - v, u - u_S) \quad \forall v \in S$$

$$\leq \|w - v\|_E \|u - u_S\|_E$$

$$\Rightarrow \|u - u_S\|_E \leq \|u - u_S\|_E \frac{\|w - v\|_E}{\|u - u_S\|_E}$$

$$= \|u - u_S\|_E \frac{\|w - v\|_E}{\|w''\|}$$

Assume that $\inf_{v \in S} \|w - v\|_E \leq \epsilon \|w''\|$?

Thm (0.3.5) $\|u - u_S\| \leq \epsilon^2 \|u''\| = \epsilon^2 \|f\|$

Proof

$$\|u - u_S\| \leq \epsilon \|u''\| \frac{\epsilon \|w''\|}{\|w''\|} = \epsilon^2 \|u''\|$$

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- S:
- (1) polynomials of degree n
 - (2) piecewise polynomials (spline, FE, etc.)
 - (3) trigonometric functions
 - (4) wavelet ...

§ 0.4 Piecewise Polynomials Spaces - Finite Element Method

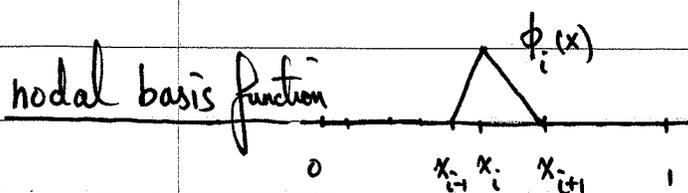
a partition: $0 = x_0 < x_1 < \dots < x_n = 1$, $I_i = [x_{i-1}, x_i]$ and $h_i = x_i - x_{i-1}$

$$S = \{ v \in C^0[0,1] \mid v|_{I_i} \text{ is a linear poly. } (i=1, \dots, n) \text{ and } v(0)=0 \} \subset V$$

2 DoF at each interval

$$\dim S = n \cdot 2 - (n-1) - 1 = n$$

of intervals # of interior nodes B.C.



$$\phi_i(x) \in S \text{ and } \phi_i(x_j) = \delta_{ij} = \begin{cases} 1 & x_j = x_i \\ 0 & x_j \neq x_i \end{cases}$$

$$\Rightarrow \phi_i(x) = \begin{cases} \frac{x - x_{i+1}}{x_i - x_{i+1}} & x \in I_i \\ \frac{x - x_{i-1}}{x_i - x_{i-1}} & x \in I_{i+1} \\ 0 & x \notin I_i \cup I_{i+1} \end{cases}$$

Properties

$$(1) \begin{cases} -\phi_i''(x) = 0 & \text{in } (x_{i-1}, x_i) \cup (x_i, x_{i+1}) \\ \phi_i(x_{i-1}) = 0, \phi_i(x_i) = 1, \phi_i(x_{i+1}) = 0 \end{cases}$$

$$(2) \{ \phi_i(x) \}_{i=1}^n \text{ is linearly indep.}$$

$$\sum_i c_i \phi_i(x) \equiv 0 \text{ in } [0,1] \Rightarrow c_j = \sum_i c_i \phi_i(x_j) = 0$$

$$\Rightarrow S = \text{span} \{ \phi_i(x) \}_{i=1}^n$$

interpolant

Given $v \in C^0[0,1]$, define the interpolant v_I of v as

$$\left. \begin{array}{l} (1) v_I \in S \\ (2) v_I(x_i) = v(x_i) \end{array} \right\} \Rightarrow v_I(x) = \sum_i v(x_i) \phi_i(x)$$

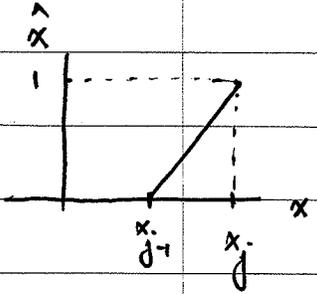
Thm. (0.4.5) Let $h = \max_{1 \leq i \leq n} h_i$. Then for $u \in C^2[0,1] \cap V$

$$\|u - u_I\|_E \leq Ch \|u''\|.$$

Proof Let $e = u - u_I$,

$$\|e\|_E^2 \leq Ch^2 \|u''\|^2 \iff \sum_j \int_{x_{j-1}}^{x_j} e(x)^2 dx \leq \sum_j \int_{x_{j-1}}^{x_j} u''(x)^2 dx \cdot Ch^2$$

$$\iff \int_{x_{j-1}}^{x_j} e(x)^2 dx \leq c (x_j - x_{j-1})^2 \int_{x_{j-1}}^{x_j} u''(x)^2 dx = ch_j^2 \int_{x_{j-1}}^{x_j} e''(x)^2 dx$$



$$\hat{x}: [x_{j-1}, x_j] \rightarrow [0, 1] \quad \hat{x} = \frac{x - x_{j-1}}{x_j - x_{j-1}} \quad \text{or} \quad x = x_{j-1} + h_j \hat{x}: [0, 1] \rightarrow [x_{j-1}, x_j]$$

~~$e(x)$~~ $e(x) = e(x_{j-1} + h_j \hat{x}) = \hat{e}(\hat{x})$

$$e'(x) = \frac{de(x)}{dx} = \frac{d\hat{e}(\hat{x})}{d\hat{x}} \cdot \frac{d\hat{x}}{dx} = \hat{e}'(\hat{x}) \frac{1}{h_j}$$

$$e''(x) = \frac{d^2e(x)}{dx^2} = \frac{1}{h_j} \frac{d\hat{e}'(\hat{x})}{d\hat{x}} = \frac{1}{h_j} \hat{e}''(\hat{x}) \frac{d\hat{x}}{dx} = \frac{1}{h_j^2} \hat{e}''(\hat{x}).$$

$$dx = h_j d\hat{x}$$

$$\Rightarrow \int_0^1 \hat{e}'(\hat{x})^2 \frac{1}{h_j^2} h_j d\hat{x} \leq ch_j^2 \int_0^1 \hat{e}''(\hat{x})^2 \frac{1}{h_j^4} h_j d\hat{x}$$

$$\iff \int_0^1 \hat{e}'(\hat{x})^2 d\hat{x} \leq c \int_0^1 \hat{e}''(\hat{x})^2 d\hat{x} \quad (\text{the scaling argument})$$

$$\hat{e}(0) = \hat{e}(1) = 0 \xrightarrow{\text{Rolle's Thm}} \exists \xi \in (0, 1) \text{ s.t. } \hat{e}'(\xi) = 0$$

$$\Rightarrow \hat{e}'(\hat{x}) = \int_{\xi}^{\hat{x}} \hat{e}''(y) dy$$

(7)

$$|\hat{e}'(\hat{x})| = \left| \int_{\xi}^{\hat{x}} \hat{e}''(y) dy \right| \leq \left| \int_{\xi}^{\hat{x}} 1^2 dy \right|^{\frac{1}{2}} \left| \int_{\xi}^{\hat{x}} \hat{e}''(y)^2 dy \right|^{\frac{1}{2}}$$

$$= |\hat{x} - \xi|^{\frac{1}{2}} \left| \int_{\xi}^{\hat{x}} \hat{e}''(y)^2 dy \right|^{\frac{1}{2}} \leq |\hat{x} - \xi|^{\frac{1}{2}} \left| \int_0^1 \hat{e}''(y)^2 dy \right|^{\frac{1}{2}}$$

$$\int_0^1 \hat{e}'(\hat{x})^2 d\hat{x} \leq \int_0^1 |\hat{x} - \xi| d\hat{x} \int_0^1 \hat{e}''(y)^2 dy$$

$$\leq \sup_{\xi \in (0,1)} \int_0^1 |\hat{x} - \xi| d\hat{x} \cdot \int_0^1 \hat{e}''(\hat{x})^2 d\hat{x} = \frac{1}{2} \int_0^1 \hat{e}''(\hat{x})^2 d\hat{x}.$$

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Corollary (0.4.7) $\|u - u_S\| + h \|u - u_S\|_E \leq ch^2 \|u''\|.$

Remark (0.4.8) $\mathcal{I} : C^0[0,1] \rightarrow S$ by $\mathcal{I}v = v_{\mathcal{I}}$ defines a linear operator and \mathcal{I} is a projection ($\mathcal{I}^2 = \mathcal{I}$).

§0.5 Relationship to Difference Methods

For ϕ_i described above,

$$K = \begin{pmatrix} & & & 0 \\ & & & & \\ & K_{i-1,i} & K_{i,i} & K_{i,i+1} & \\ & & & & \\ 0 & & & & \end{pmatrix}$$

$$K_{i,i} = \frac{1}{h_i} + \frac{1}{h_{i+1}} \quad i=1, \dots, n-1; \quad K_{nn} = \frac{1}{h_n}$$

$$K_{i-1,i} = -\frac{1}{h_{i-1}} = K_{i,i-1}$$

$$K_{i,i+1} = -\frac{1}{h_{i+1}} = K_{i+1,i}$$

$$F_i = (f, \phi_i) = \int_{x_{i-1}}^{x_{i+1}} f \phi_i dx \quad \text{if } f(x) = f(x_i) + f'(\xi_i)(x - x_i)$$

$$= f(x_i) \frac{1}{2}(h_i + h_{i+1}) + \frac{1}{2}(h_i + h_{i+1}) O(h) \sim O(h^2) \text{ if } 1 - \frac{h_i}{h_{i+1}} = O(h)$$

the i^{th} eq

$$\frac{1}{(h_i + h_{i+1})/2} \left(\frac{U_{i+1} - U_i}{h_{i+1}} - \frac{U_i - U_{i-1}}{h_i} \right) = \frac{F_i}{(h_i + h_{i+1})/2} = f(x_i) + O(h)$$

$$= \frac{d^2 U(x_i)}{dx^2} + O(h)$$

$h_i = h_{i+1}$

$$\frac{U_{i+1} - 2U_i + U_{i-1}}{h^2} = f(x_i) + O(h^2)$$

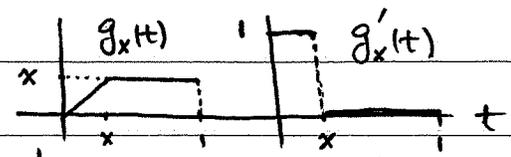
Remark For general ~~mesh~~ mesh, it is 2nd-order in both L^2 and L^∞ norms. even though the difference equations are formally consistent to 1st-order.

Advantages systematic, easy handling BCs, math. profound, clean notation,

§0.6 Computer Implementation of FEMs

§0.7 Local Estimates

DEs
$$\begin{cases} -u''(x) = f(x) & x \in (0,1) \\ u(0) = 0, u'(0) = 0 \end{cases}$$



Green's Function
$$g_x(t) = \begin{cases} t & t \leq x \\ x & t \geq x \end{cases}$$
 where x is a given pt in $[0,1]$

$$\begin{cases} -g_x''(t) = \delta(x) & \bar{t} \in (0,1) \\ g_x(0) = 0, g_x'(1) = 0 \end{cases}$$
 general def. of Green's function

• For any $v \in V$, $v(x) = a(v, g_x(t))$

Proof
$$\begin{aligned} a(v, g_x) &= \int_0^1 v(t) g_x'(t) dt = \int_0^x v(t) g_x'(t) dt + \int_x^1 v(t) g_x'(t) dt \\ &= v(t) g_x'(t) \Big|_0^x - \int_0^x v(t) g_x''(t) dt + v g_x' \Big|_x^1 - \int_x^1 v g_x'' dt \\ &= v(x) g_x'(x^-) - v(0) g_x'(0) + v(1) g_x'(1) - v(x) g_x'(x^+) \\ &= v(x) (g_x'(x^-) - g_x'(x^+)) = v(x) \quad \# \end{aligned}$$

$$\Rightarrow u(x) - u_S(x) = a(u - u_S, g_x) = a(u - u_S, g_x - v) \quad \forall v \in S.$$

Let $S = \text{span} \{ \phi_i(x) \}_{i=1}^n$ defined in the previous section

$$\Rightarrow g_{x_i} \in S$$

$$\Rightarrow (u - u_S)(x_i) = a(u - u_S, g_{x_i}) = 0 \quad \forall i = 1, \dots, n$$

$$\Rightarrow \boxed{u_S(x) \equiv u_I(x)}$$

Thrm $\|u - u_I\|_{\max} \leq ch^2 \|u''\|_{\max}$

$\|f\|_{\max} = \max_{x \in [0,1]} |f(x)|$

Proof Let $e(x) = u(x) - u_I(x)$

On I_i $e(x_{i-1}) = e(x_i) = 0$

$$\begin{aligned} \Rightarrow |e(x)| &= \left| \int_{x_{i-1}}^x e'(y) dy \right| \leq \left(\int_{x_{i-1}}^x 1 dy \right)^{\frac{1}{2}} \left(\int_{x_{i-1}}^x e'(y)^2 dy \right)^{\frac{1}{2}} \\ &\leq (x - x_{i-1})^{\frac{1}{2}} \left(\int_{x_{i-1}}^{x_i} e'(y)^2 dy \right)^{\frac{1}{2}} \\ &\leq h_i^{\frac{1}{2}} \left(\int_{x_{i-1}}^{x_i} e'(y)^2 dy \right)^{\frac{1}{2}} \\ &\leq h_i^{\frac{1}{2}} ch_i \left(\int_{x_{i-1}}^{x_i} u''(y)^2 dy \right)^{\frac{1}{2}} \\ &\leq ch_i^2 \max_{x \in I_i} |u''| \leq ch_i^2 \|u''\|_{\max}. \end{aligned}$$

Or $e(x) = \frac{u''(\xi_i)}{2!} (x - x_{i-1})(x - x_i) \quad \exists \xi_i \in (x_{i-1}, x_i)$

$$\begin{aligned} \max_{x \in I_i} |e(x)| &\leq \max_{x \in I_i} \frac{1}{2} (x - x_{i-1})(x - x_i) \max_{x \in I_i} |u''(\xi_i)| \\ &= \frac{1}{8} h_i^2 \max_{x \in I_i} |u''(x)| \end{aligned}$$

$$\Rightarrow \|e(x)\|_{\max} \leq \frac{1}{8} h^2 \|u''\|_{\max}.$$