

17.3 Conservative Vector Fields and the Fundamental Theorem of Line Integrals

a vector field \vec{F} is conservative if it is the gradient of some potential function $\vec{F} = \vec{\nabla} \phi$

if given ϕ , \vec{F} is to find

but if given \vec{F} , how do we know if \vec{F} is conservative?

and if \vec{F} is conservative, how to find ϕ ?

let $\vec{F} = \langle f, g \rangle$ be a conservative vector field

then we know $\vec{F} = \langle f, g \rangle = \vec{\nabla} \phi = \left\langle \frac{\partial \phi}{\partial x}, \frac{\partial \phi}{\partial y} \right\rangle$

$$\text{so } f = \frac{\partial \phi}{\partial x}$$

$$g = \frac{\partial \phi}{\partial y}$$



we also know that

$$\frac{\partial}{\partial y} \left(\underbrace{\frac{\partial \phi}{\partial x}}_f \right) = \frac{\partial}{\partial x} \left(\underbrace{\frac{\partial \phi}{\partial y}}_g \right) \rightarrow \phi_{yx} = \phi_{xy}$$

So, this means, if $\vec{F} = \langle f, g \rangle$ is conservative, then $\frac{\partial f}{\partial y} = \frac{\partial g}{\partial x}$
 $f_y = g_x$

example $\vec{F} = \langle x, y \rangle$

$$\begin{matrix} f \\ g \end{matrix}$$

$$\text{is } f_y = g_x ? \quad f_y = \frac{\partial}{\partial y}(x) = 0 \quad g_x = \frac{\partial}{\partial x}(y) = 0$$

Yes, so $\vec{F} = \langle x, y \rangle$ is conservative.

example $\vec{F} = \langle -y, x \rangle$

$$\begin{matrix} f \\ g \end{matrix}$$

$$\text{is } f_y = g_x ? \quad f_y = -1, \quad g_x = 1$$

no, so \vec{F} is NOT conservative

example $\vec{F} = \langle x+y, x \rangle$

$$\begin{matrix} f & \nearrow \\ & & g \end{matrix}$$

$$\text{is } f_y = g_x? \quad f_y = 1, \quad g_x = 1$$

yes, so \vec{F} is conservative.

If we know $\vec{F} = \langle f, g \rangle$ is conservative $\rightarrow \vec{F} = \vec{\nabla} \phi$

how do we find ϕ ?

let's use $\vec{F} = \langle x+y, x \rangle$ as an example

$$\vec{F} = \langle x+y, x \rangle = \vec{\nabla} \phi = \left\langle \frac{\partial \phi}{\partial x}, \frac{\partial \phi}{\partial y} \right\rangle$$

$$\text{so, } \frac{\partial \phi}{\partial x} = x+y \quad (1)$$

$$\frac{\partial \phi}{\partial y} = x \quad (2)$$

$$\textcircled{1}: \frac{\partial \phi}{\partial x} = x + y$$

integrate with respect to x

$$\phi = \int (x+y) dx = \frac{1}{2}x^2 + xy + a(y) \quad \textcircled{3}$$

variable
treat as constant

now let's take the partial deriv. of this ϕ with respect to y and compare to $\textcircled{2}$

$$\rightarrow \frac{\partial \phi}{\partial y} = x + \frac{da}{dy} = x \quad \text{from } \textcircled{2} \quad \frac{\partial \phi}{\partial y} = x$$

$$\text{so } \frac{da}{dy} = 0 \rightarrow a = \text{constant} = C$$

now sub that into $\textcircled{1}$

$$\boxed{\phi(x,y) = \frac{1}{2}x^2 + xy + C}$$

some function that can depend on y only (or is a constant)

because if this function were to have x , then its derivative would show up if $\frac{\partial \phi}{\partial x}$ ($\textcircled{1}$) because a does not on x , it vanishes in $\frac{\partial \phi}{\partial x}$ ($\textcircled{1}$)

check: is $\vec{\nabla} \phi = \vec{F} = \langle x+y, x \rangle$?

$$\vec{\nabla} \left(\frac{1}{2}x^2 + xy + c \right) = \langle x+y, x \rangle \text{ so, yes, therefore } \phi \text{ is correct.}$$

what about 3D $\vec{F} = \langle f, g, h \rangle$?

how to check if it is conservative?

and if so, how to find ϕ ?

let $\vec{F} = \langle f, g, h \rangle$ be a conservative vector field

$$\text{then } \vec{F} = \langle f, g, h \rangle : \vec{\nabla} \phi = \langle \frac{\partial \phi}{\partial x}, \frac{\partial \phi}{\partial y}, \frac{\partial \phi}{\partial z} \rangle$$

$$\text{so, } f = \frac{\partial \phi}{\partial x} \quad \text{we know } \frac{\partial}{\partial y} \left(\frac{\partial \phi}{\partial x} \right) = \frac{\partial}{\partial x} \left(\frac{\partial \phi}{\partial y} \right) \rightarrow f_y = g_x$$

$$g = \frac{\partial \phi}{\partial y} \quad \frac{\partial}{\partial z} \left(\frac{\partial \phi}{\partial y} \right) = \frac{\partial}{\partial y} \left(\frac{\partial \phi}{\partial z} \right) \rightarrow g_z = h_y$$

$$h = \frac{\partial \phi}{\partial z} \quad \frac{\partial}{\partial x} \left(\frac{\partial \phi}{\partial z} \right) = \frac{\partial}{\partial z} \left(\frac{\partial \phi}{\partial x} \right) \rightarrow f_z = h_x$$



So, if $\vec{F} = \langle f, g, h \rangle$ is conservative,

then $f_y = g_x$
 $f_z = h_x$
 $g_z = h_y$

$\left. \begin{matrix} f_y = g_x \\ f_z = h_x \\ g_z = h_y \end{matrix} \right\}$ all three must be satisfied

example $\vec{F} = \langle x^2 - ze^y, y^3 - xze^y, z^4 - xe^y \rangle$

$f \qquad \qquad g \qquad \qquad h$

is $f_y = g_x$? $f_y = -ze^y$, $g_x = -ze^y$ yes

is $f_z = h_x$? $f_z = -e^y$, $h_x = -e^y$ yes

is $g_z = h_y$? $g_z = -xe^y$, $h_y = -xe^y$ yes

so, \vec{F} is conservative and $\vec{F} = \vec{\nabla} \phi$

we find ϕ using a very similar process used in last example



$$\vec{F} = \langle x^2 - ze^y, y^3 - xze^y, z^4 - xe^y \rangle = \vec{\nabla} \phi = \langle \phi_x, \phi_y, \phi_z \rangle$$

$$\phi_x = x^2 - ze^y \quad ①$$

$$\phi_y = y^3 - xze^y \quad ②$$

$$\phi_z = z^4 - xe^y \quad ③$$

integrate ① with respect to $x \rightarrow \phi = \int (x^2 - ze^y) dx$

$$\phi = \frac{1}{3}x^3 - xze^y + a(y, z) \quad ④$$

function of y and z
or a constant
(deriv. with x is 0 so
is not in ϕ_x)

differentiate ④ with respect to y and compare to ②

$$\phi_y = -xe^y + \frac{\partial a}{\partial y} = \underbrace{y^3 - xze^y}_{\text{from } ②} \rightarrow \frac{\partial a}{\partial y} = y^3$$

differentiate ④ with respect to z and compare to ③

$$\phi_z = -xe^y + \frac{\partial a}{\partial z} = \underbrace{z^4 - xe^y}_{\text{from } ④} \rightarrow \frac{\partial a}{\partial z} = z^4$$



now we find $a(y, z)$ from $\underbrace{\frac{\partial a}{\partial y} = y^3}$ and $\frac{\partial a}{\partial z} = z^4$

$$a = \int y^3 dy$$

$$a = \frac{1}{4}y^4 + b(z)$$

some function
of z

differentiate with respect to z and compare to $\frac{\partial a}{\partial z}$

$$\frac{\partial a}{\partial z} = \frac{db}{dz} = z^4 \rightarrow b = \frac{1}{5}z^5 + C$$

\hookdownarrow constant

$$\text{so, } a = \frac{1}{4}y^4 + \frac{1}{5}z^5 + C \text{ sub this into } \phi \quad (4)$$

and we get

$$\phi(x, y, z) = \frac{1}{3}x^3 - xze^y + \frac{1}{4}y^4 + \frac{1}{5}z^5 + C$$

if unsure, find its gradient and check if $\vec{\nabla}\phi = \vec{F}$

why do we care if \vec{F} is conservative and why do we care about ϕ ?

because if \vec{F} is conservative ($\vec{F} = \vec{\nabla} \phi$)

then $\int_C \vec{F} \cdot \vec{T} ds$ is independent of the path C

(the only things that matter are the starting and ending locations of C)

why? $\int_C \vec{F} \cdot \vec{T} ds = \int_C \vec{F} \cdot \vec{r}' dt = \int_C \vec{F} \cdot d\vec{r}$

let $\vec{F} = \langle f, g \rangle$ and $\vec{r}(t) = \langle x, y \rangle$ $a \leq t \leq b$

if $\vec{F} = \vec{\nabla} \phi$

then $\int_C \vec{F} \cdot \vec{r}' dt = \int_C \vec{\nabla} \phi \cdot \underbrace{\left\langle \frac{dx}{dt}, \frac{dy}{dt} \right\rangle}_{\vec{F}'} dt = \int_C \left\langle \frac{\partial \phi}{\partial x}, \frac{\partial \phi}{\partial y} \right\rangle \cdot \left\langle \frac{dx}{dt}, \frac{dy}{dt} \right\rangle dt$



$$= \int_C \left(\frac{\partial \phi}{\partial x} \frac{dx}{dt} + \frac{\partial \phi}{\partial y} \frac{dy}{dt} \right) dt$$

$\underbrace{\frac{d\phi}{dt}}$ why?

$$= \int_C \frac{d\phi}{dt} dt$$

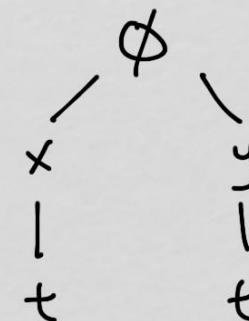
$$= \int_C d\phi$$

$$= \phi(B) - \phi(A)$$

↑ start
end location
of path C

↖ end location
of path C

$\phi(x, y) = \phi \underbrace{(x(t), y(t))}_{\text{from parametrization}} \text{ of } \vec{r}(t)$



ϕ is ultimately a function of t
step down tree: $\frac{d\phi}{dt} = \frac{\partial \phi}{\partial x} \frac{dx}{dt} + \frac{\partial \phi}{\partial y} \frac{dy}{dt}$

notice this says nothing about how we actually go from A to B



this result is called the

Fundamental Theorem of Line Integrals

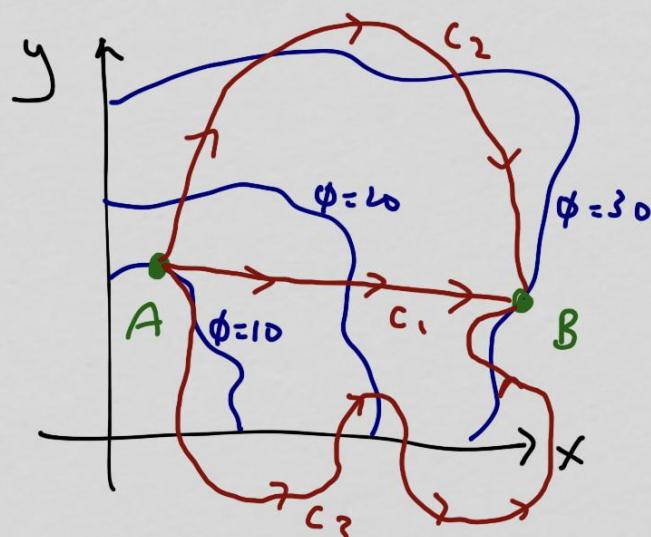
$$\text{if } \vec{F} = \nabla \phi$$

$$\text{then } \int_C \vec{F} \cdot d\vec{r} = \phi(B) - \phi(A)$$

regardless of the actual path C

B: ending location A: starting location

graphically, this means that only the values of ϕ at start and end matter



ALL three paths shown give
the same

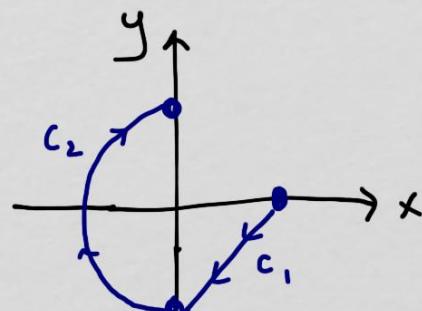
$$\int_C \vec{F} \cdot d\vec{r} = \phi(B) - \phi(A)$$
$$= 30 - 10 = 20$$

path is irrelevant if \vec{F}
is conservative

example $\int_C \vec{F} \cdot d\vec{r}$ $\vec{F} = \langle x+y, x \rangle$

C : line segment from $(1, 0)$ to $(0, -1)$

then along the left half of $x^2 + y^2 = 1$ to $(0, 1)$



let's first do this as a regular line integral

$$C_1: \vec{r}_1(t) = \langle 1-t, -t \rangle \quad 0 \leq t \leq 1$$

$$C_2: \vec{r}_2(t) = \langle -\sin t, -\cos t \rangle \quad 0 \leq t \leq \pi$$

$$\begin{aligned} \int_C \vec{F} \cdot d\vec{r} &= \int_0^1 \underbrace{\langle 1-2t, 1-t \rangle}_{\vec{F} \text{ using } x, y \text{ of } \vec{F},} \cdot \underbrace{\langle -1, -1 \rangle}_{\vec{r}'_1} dt + \int_0^\pi \underbrace{\langle -\sin t - \cos t, -\sin t \rangle}_{\vec{F} \text{ w/ } x, y \text{ of } \vec{F}_2} \cdot \underbrace{\langle -\cos t, \sin t \rangle}_{\vec{r}'_2} dt \\ &= \int_0^1 (3t - 2) dt + \int_0^\pi (\underbrace{\sin t \cos t + \cos^2 t - \sin^2 t}_{\substack{\text{subs.} \\ u = \sin t}} \underbrace{\frac{1 + \cos 2t}{2}}_{\frac{1 - \cos 2t}{2}}) dt = \dots = -\frac{1}{2} \end{aligned}$$



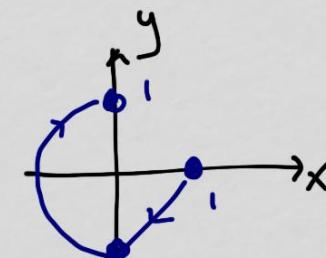
using the Fundamental Theorem of Line Integrals :

first, find ϕ such that $\nabla \phi = \vec{F} = \langle x+y, x \rangle$

from earlier example, $\phi = \frac{1}{2}x^2 + xy + C$

then $\int_C \vec{F} \cdot d\vec{r} = \phi(B) - \phi(A)$

$$\begin{matrix} \nearrow & \uparrow \\ (0, 1) & (1, 0) \\ \times & \times \\ y & y \end{matrix}$$



$$= \left[\frac{1}{2}(0)^2 + (0)(1) + C \right] - \left[\frac{1}{2}(1)^2 + (1)(0) + C \right] = \boxed{-\frac{1}{2}}$$

since \vec{F} is conservative, we could also pick an easier path

if we wanted evaluate $\int_C \vec{F} \cdot d\vec{r}$ as a regular line integral

