

6.3 Ecological Models: Predators and Competitors (part 1)

Predator: thing that eats prey (e.g. hawks)

Prey: thing that predator eats (e.g. squirrels)

predator-prey system: x : prey y : predator

$$\frac{dx}{dt} = ax - pxy = (a - py)x$$

a, b, p, g positive

$$\frac{dy}{dt} = -by + gxy = (-b + gx)y$$

constants

the xy terms are interaction terms \rightarrow how species interact

w/ each other

if $p = g = 0$, $\frac{dx}{dt} = ax \rightarrow$ simple exponential growth

$\frac{dy}{dt} = -by \rightarrow$ decay

if $p \cdot b \neq 0$

$$\frac{dx}{dt} = (a - py)x$$

rate of growth decreased by y

$$\frac{dy}{dt} = (-b + \delta x)y \quad \text{rate increased by } x$$

example

$$\frac{dx}{dt} = x - 0.5xy = f \quad x: \text{prey}$$

y : predator

$$\frac{dy}{dt} = -0.75y + 0.25xy = g$$

cp: $x' = y' = 0 \rightarrow$ pop. not changing

$$x - 0.5xy = 0 \rightarrow x(1 - 0.5y) = 0$$

$$\boxed{x = 0}, \quad \boxed{y = 2}$$

both eggs = 0

$$-0.75y + 0.25xy \rightarrow 0.25y(-3 + x) = 0$$

$$\boxed{y = 0}, \quad \boxed{x = 3}$$

$(0, 0), (3, 2)$ coexistence

both die out

which is stable?

linearize about each CP

$$\text{Jacobian: } J = \begin{bmatrix} f_x & f_y \\ g_x & g_y \end{bmatrix} = \begin{bmatrix} 1-0.5y & -0.5x \\ 0.25y & -0.75+0.25x \end{bmatrix}$$

near each CP: $(0,0), (3,2)$

linear sys:

$$\begin{bmatrix} u' \\ v' \end{bmatrix} = J \begin{bmatrix} u \\ v \end{bmatrix}$$

$$\begin{aligned} u &= x - x_0 \\ v &= y - y_0 \end{aligned} \quad \left(\begin{array}{l} u, y_0 \text{ of CP} \end{array} \right)$$

near $(0,0)$

$$\begin{bmatrix} u' \\ v' \end{bmatrix} = \underbrace{\begin{bmatrix} 1 & 0 \\ 0 & -0.75 \end{bmatrix}}_{\lambda=1, -0.75} \begin{bmatrix} u \\ v \end{bmatrix}$$

$\lambda=1, -0.75$ saddle pt. unstable

unless start w/ $x=0, y=0$

$t \rightarrow 0$ will NOT go here

(they don't die out)

near (3,2)

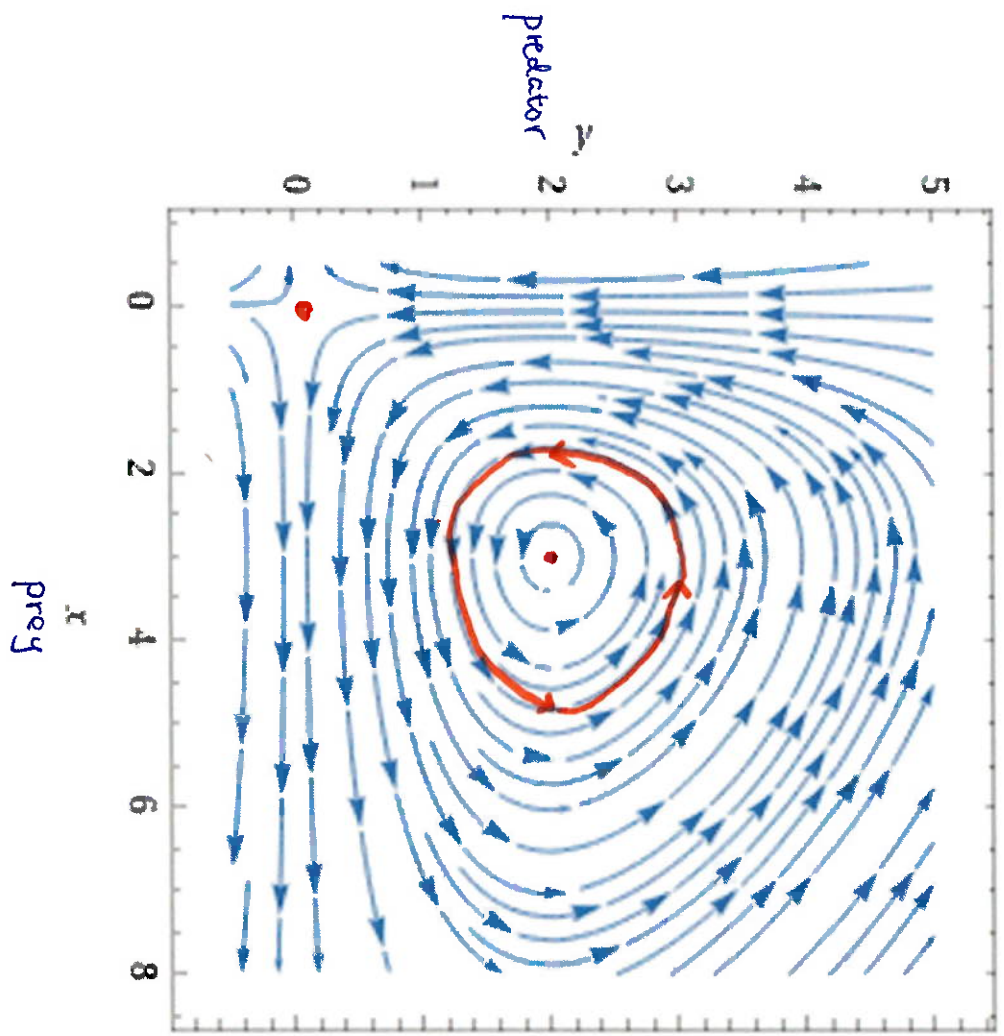
$$\begin{bmatrix} u' \\ v' \end{bmatrix} = \begin{bmatrix} 0 & -1.5 \\ 0.5 & 0 \end{bmatrix} \begin{bmatrix} u \\ v \end{bmatrix}$$

λ : purely imaginary

center, stable

BUT, remember this
is a case where
the linearized sys
may "lie"

$$\frac{dx}{dt} = x - 0.5xy$$
$$\frac{dy}{dt} = -0.75y + 0.25xy$$



Example

$$\frac{dx}{dt} = x - 0.5x^2 - 0.5xy$$

$$\frac{dy}{dt} = -0.25y + 0.5xy$$

w/o interaction:

$$\frac{dx}{dt} = x - 0.5x^2 = x(1 - 0.5x)$$

if $x=2$, $x'=0$
prey pop. capped at 2

$$\frac{dy}{dt} = -0.25y \text{ just decays}$$

CP: (0,0), (2,0), (1/2, 3/2)

$$J = \begin{bmatrix} 1-x-0.5y & -0.5x \\ 0.5y & -0.25+0.5x \end{bmatrix}$$

$$\text{at } (0,0) \quad J = \begin{bmatrix} 1 & 0 \\ 0 & -0.25 \end{bmatrix}$$

saddle pt, unstable

$$\text{at } (2,0) \quad J = \begin{bmatrix} -1 & -1 \\ 0 & 0.75 \end{bmatrix}$$

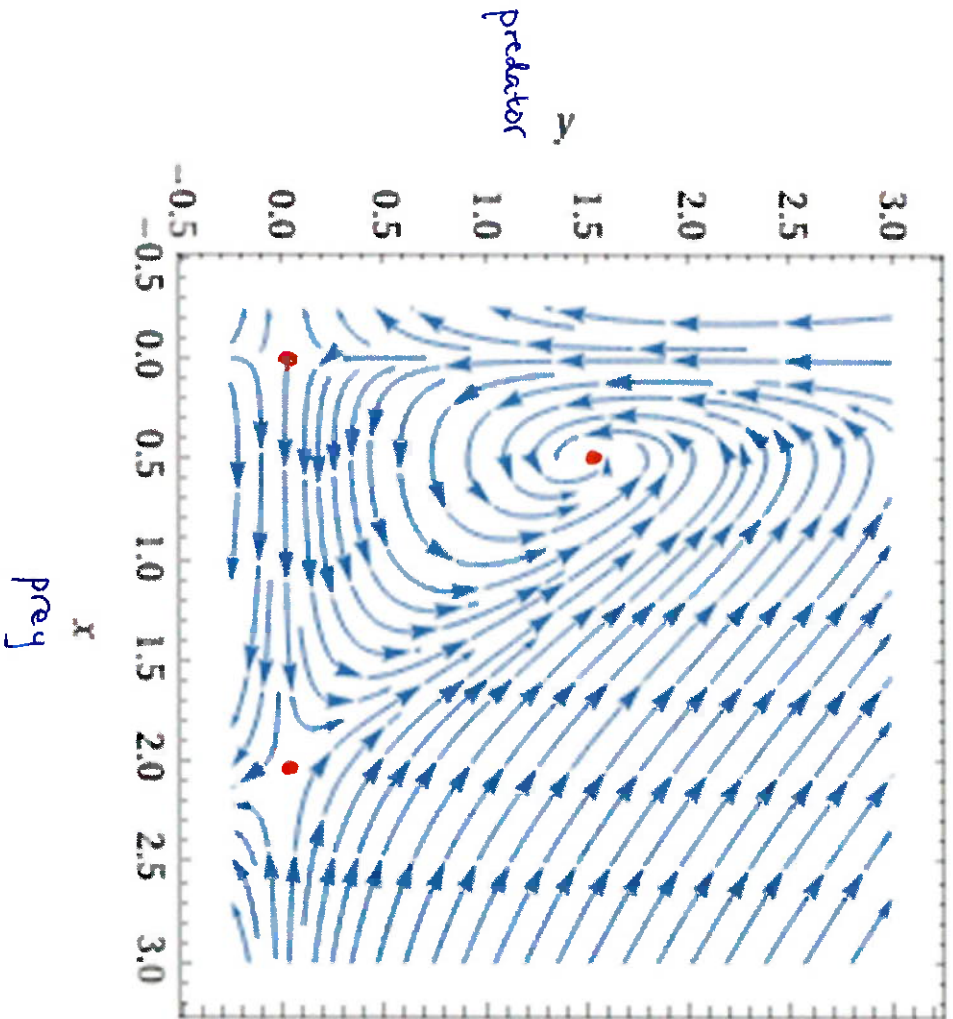
saddle pt, unstable

$$\text{at } (1/2, 3/2) \quad J = \begin{bmatrix} -0.25 & -0.25 \\ 0.15 & 0 \end{bmatrix}$$

$\lambda = -0.125 \pm 0.415i$
AS spiral

$$\frac{dx}{dt} = x - 0.5x^2 - 0.5xy$$

$$\frac{dy}{dt} = -0.25y + 0.5xy$$



example

$$\frac{dx}{dt} = -x + \frac{1}{2}x^2 - \frac{1}{2}xy$$

$$\frac{dy}{dt} = y^2 - 4y + xy$$

example

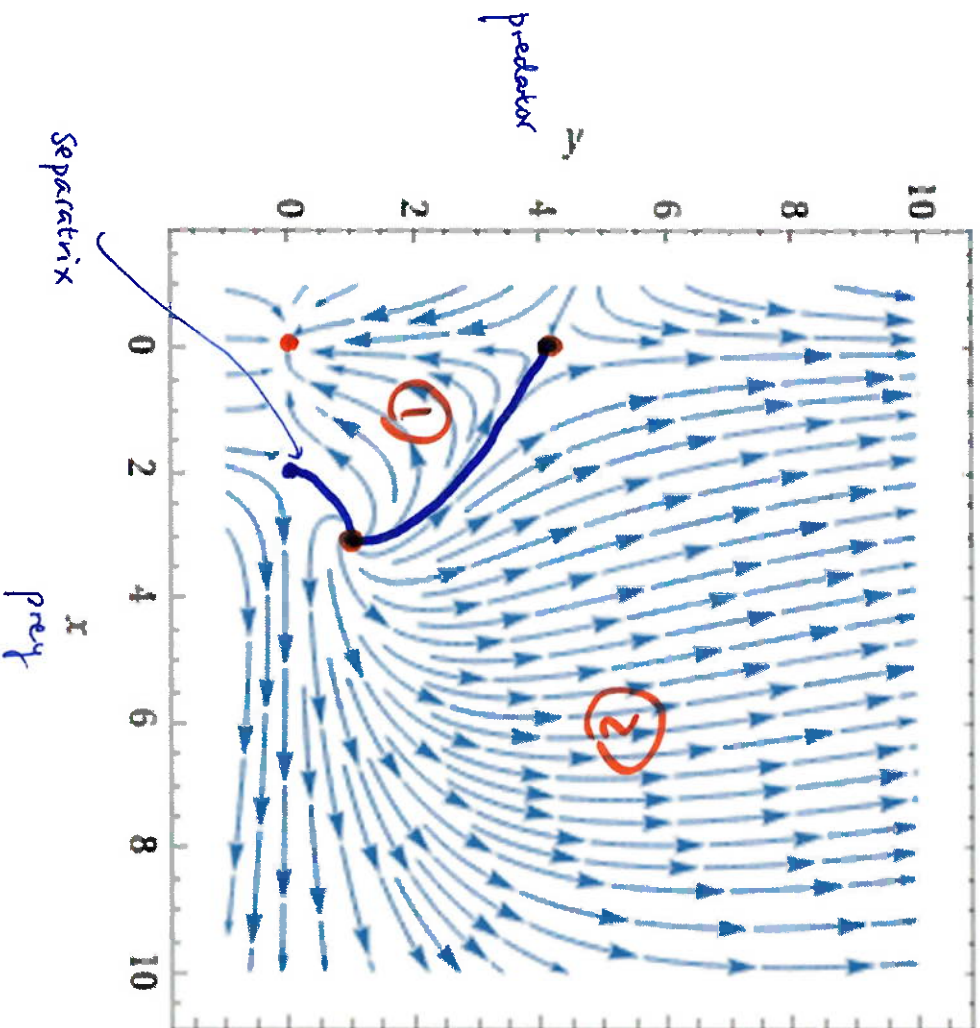
$$\frac{dx}{dt} = 14x - \frac{1}{2}x^2 - xy$$

$$\frac{dy}{dt} = 16y - \frac{1}{2}y^2 - xy$$

next time: competition system

$$\frac{dx}{dt} = -x + \frac{1}{2}x^2 - \frac{1}{2}xy$$

$$\frac{dy}{dt} = y^2 - 4y + xy$$



- ① : both die out
- ② : pops. explode

$$\frac{dx}{dt} = 14x - \frac{1}{2}x^2 - xy$$

$$\frac{dy}{dt} = 16y - \frac{1}{2}y^2 - xy$$

