Real solutions of Painlevé VI and circular pentagons

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Real solutions of Painlevé VI and special pentagons A. Eremenko and A. Gabrielov



Richard Fuchs was a son of Lazarus Fuchs. Father Fuchs is famous for Fuchsian groups, and several (at least three different kinds of) "Fuchs conditions" in the analytic theory of differential equations.

$$w'' + p(z)w' + q(z)w = 0$$

p, q - rational functions. A singular point a (a pole of p or q) is called *regular* if all solutions satisfy $w(z) = O(z - a)^K$ near a for some real K. The necessary and sufficient condition for this: $p(z) = O(z - a)^{-1}$ and $q(z) = O(z - a)^{-2}$ (Lazarus Fuchs). In this case there are fundamental solutions of the form

$$w_1(z) = (z-a)^{\rho_1}(1+g_1(z)), \quad w_2(z) = (z-a)^{\rho_2}(1+g_2(z)),$$

where g_j are holomorphic, g(a) = 0, and ρ_j are the *exponents* at *a*, solutions of the indicial equation

$$\rho(\rho-1)+p_0\rho+q_0=0,$$

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and we assume that $\rho_1 - \rho_2 > 0$ is not an integer.

To describe the global behavior one uses the **projective monodromy** representation

 $M: \pi_1(\overline{\mathbb{C}} \setminus \text{singularities}) \to PSL(2, \mathbb{C}).$

Question: which monodromy representations can occur? Riemann solved this question completely when the number of singularities n = 3.

When n > 3, parameter count (Poincaré) shows that an equation with prescribed singularities and prescribed monodromy does not exist. But if one introduces *apparent singularities* (with trivial monodromy) then the number of parameters matches. The simplest case occurs when the number of non-apparent singularities is 4 and one singularity is apparent. Richard Fuchs studied in 1905 the following differential equation:

$$w'' - \left(\frac{1}{z-q} + \sum_{j=1}^{3} \frac{\kappa_j - 1}{z - t_j}\right) w' + \left(\frac{p}{z-q} - \sum_{j=1}^{3} \frac{h_j}{z - t_j}\right) w = 0$$

with 5 singularities at $(t_1, t_2, t_3, t_4, q) := (0, 1, x, \infty, q)$. The singularities at t_j have exponents $\{0, \kappa_j\}$, for $1 \le j \le 3$, and the exponents at q are $\{0, 2\}$.

R. Fuchs imposed the following conditions:

a) the singularity at ∞ is regular, and has exponent difference κ_4 , b) the singularity at q is apparent (has trivial monodromy). For given κ_j , $1 \le j \le 4$, and given p, q, x, these conditions determine parameters h_j uniquely.

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Suppose that all κ_j are fixed, and let us move x continuously. How should p(x), q(x) change so that the monodromy of this equation remains unchanged?

Answer: *q* must satisfy the following non-linear ODE:

$$\begin{split} q_{xx} &= \frac{1}{2} \left(\frac{1}{q} + \frac{1}{q-1} + \frac{1}{q-x} \right) q_x^2 - \left(\frac{1}{x} + \frac{1}{x-1} + \frac{1}{q-x} \right) q_x \\ &+ \frac{q(q-1)(q-x)}{2x^2(x-1)^2} \left\{ \kappa_4^2 - \kappa_1^2 \frac{x}{q^2} + \kappa_2^2 \frac{x-1}{(q-1)^2} + (1-\kappa_3^2) \frac{x(x-1)}{(q-x)^2} \right\}, \end{split}$$

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which is called Painlevé VI.

This was the first example of "isomonodromic deformation".

Equation PVI was rediscovered by Painlevé and Gambier who were solving a different problem: to find all equations of the form

y'' = R(y', y, z), R is rational,

without movable singularities.



PAUL PAINLEVÉ

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Examples.

$$y' = a(z)y^2 + b(z)y + c(z)$$
 (Riccati) Has no movable singularities.
 $yy'' + {y'}^2 = 0$, $y(z) = \sqrt{c_1 z + c_2}$. Movable singularity is at $z = -c_2/c_1$.

This classification consists of about 50 types of equations, most of them can be solved in terms of the classical special functions (satisfying linear or first order ODE). Six equations of this classification define new functions, which cannot be expressed in terms of the classical special functions. These are the six Painlevé equations. The sixth one is the most general, in the sense that all others can be obtained from it by certain "confluence" process.

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All solutions of PVI are meromorphic in the universal cover of $C \setminus \{0, 1\}$. The points $x = 0, 1, \infty$ are *fixed singularities* of PVI. The conditions of Cauchy's theorem are violated at the points where $q(x) \in \{0, 1, x, \infty\}$. These points x are removable singularities or poles of q. We call them *special points*. We consider *real* solutions q(x) of PVI with *real* parameters, on an interval of the real line between two adjacent fixed singularities $0, 1, \infty$. WLOG we choose the interval $(1, \infty)$.

We will explain a geometric interpretation of these solutions, and obtain an algorithm which determines the number and mutual position of special points on the interval.

More precisely, the outcome of the algorithm is a sequence of symbols $\{0, 1, x, \infty\}$ which shows the order in which the special points appear on $(1, \infty)$.

Selection of a particular solution q(x)

a) Cauchy initial data: $q(x_0) = q_0, \ q'(x_0) = q'_0.$

b) Specifying the second order linear equation with 5 singularities. c) Prescribing the monodromy representation corresponding to the linear equation. For generic values of PVI parameters and generic monodromies this determines the linear equation $(p_0 \text{ and } q_0)$ uniquely.

We use a different method of assigning the initial conditions, and monodromy representation will be easily computed from our initial conditions. (Initial values p_0, q_0 are difficult to compute directly from the monodromy).

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Fuchsian ODE with real parameters and circular polygons

Suppose that all parameters (singularities, exponents and accessory parameters) in a linear Fuchsian ODE

$$w'' + P(z)w' + Q(z)w = 0$$

are real. Such equations will be called real. Consider the ratio $f = w_1/w_2$ of two linearly independent solutions. This function is meromorphic in the upper half-plane H and is locally univalent there. At a singular point t:

$$f(z) = f(t) + (c + o(1))(z - t)^{\kappa},$$

where κ is the absolute value of the exponent difference at t. If $\kappa = 0$ but the singularity at t is not apparent, then

$$f(z) = f(t) + (c + o(1)) / \log(z - t).$$

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We measure all angles in half-turns instead of radians!

Function f is holomorphic in H, locally univalent in $\overline{H} \setminus \{t_j\}$, maps each interval (t_{j-1}, t_j) into some circle C_j , and has conical singularities at t_j .

Such functions are called *developing maps* (of circular polygons). The formal definition of a circular polygon is

$$Q=(\overline{D},t_1,\ldots,t_n,f),$$

where \overline{D} is a closed disk, $t_j \in \partial D$ are distinct boundary points, and f is a developing map with conical singularities at t_j . The intervals (t_{j-1}, t_j) are called *sides*, the points t_j corners and κ_j are the interior angles at the corners.

Two circular *n*-gons $Q = (\overline{D}, t_1, \ldots, t_n, f)$ and $Q' = (\overline{D'}, t'_1, \ldots, t'_n, f_1)$ are *equal* if there is a conformal homeomorphism $\phi : \overline{D'} \to \overline{D}$ such that $\phi(t'_i) = t_j$ and

$$f_1 = f \circ \phi. \tag{1}$$

Two circular *n*-gons are called *equivalent* if instead of (1) we require only $f_1 = L \circ f \circ \phi$, with some linear-fractional transformation *L*. For polygons which are subsets of the sphere this means that one can be mapped onto another by a linear-fractional transformation.

There is a one-to-one correspondence between the equivalence classes of circular n-gons and normalized Fuchsian equations with all parameters real. The developing map defining a polygon is the ratio of two linearly independent solutions.

this fact was known to Schwarz and possibly to Riemann.



Special pentagons corresponding to the equation of R. Fuchs

This equation with five singularities defines a circular pentagon. But one singularity q is special: it has exponents 0,2 and trivial monodromy.

We say in such case that our pentagon Q has a slit, and call f(q) the *tip of the slit*. Pentagons of this type (with exactly one slit) will be called *special pentagons*.

There is a one-to-one correspondence between real normalized Fuchsian equations with 5 singularities, one of them apparent with exponent difference 2, and equivalence classes of special pentagons.

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Transformation 1. Let $q \in (t_{k-1}, t_k)$, and as the slit vanishes, q collides with s which is either t_k or t_{k-1} . When q = s, we have a quadrilateral without a slit. As x passes s we must have a special pentagon with images of the sides on the same 4 circles, but q and s interchanged their order on ∂H , The slit which was on C_k is now on C_{k+1} , if $s = t_k$, and on C_{k-1} if $s = t_{k-1}$.



Transformation 2. Suppose that $q \in (t_{k-1}, t_k)$, and the slit lengthens. Then eventually it hits the boundary from inside of Q_x , and becomes a cross-cut. The cross-cut splits the pentagon into two parts. Let $s \in \partial H$ be the point where this collision happens (that is $f(q) \to f(s)$ as the slit lengthens).



Transformation 3. When the slit lengthens, hits the boundary from inside, and the special pentagon splits, as in Transformation 2, we assume now that the slit hits a corner $s \in \{t_i\}$.

Examples



In Example 1, when the slit in a) lengthens and hits the boundary, we have $x \to 1$. As the slit in a) shortens, x increases. When the slit vanishes we obtain the limit quadrilateral in picture b); at this point $q(x) = \infty$. Then the new slit grows as in picture c) and when it hits the boundary, $x \to +\infty$. Therefore the solution q(x) has only one special point on $(1, +\infty)$, and it is a pole. We had one transformation of type 1 in this example.



Solutions without special points on $(1, +\infty)$



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Theorem. A real solution satisfying 0 < q(x) < 1 for $1 < x < +\infty$ exists for arbitrary real parameters κ_j . The monodromy of the LDE corresponding to this solution satisfies L_1 and L_2 have a common fixed point with multipliers $e^{2\pi i \kappa_1}$ and $e^{2\pi i \kappa_2}$.

Depending on the κ_j there is either one such isolated solution, or a whole interval of them.

For special values of parameters (1/2, 1/2, 1/2, 1/2) and (1/2, 1/2, 1/2, 3/2) this was recently proved by Z-J. Chen, T.-J. Kuo and C-S. Lin.

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Representation of polygons by nets

Let $Q = (\overline{D}, t_1, \ldots, t_n, f)$ be a circular *n*-gon. C_j is the circle containing $f((t_{j-1}, t_j))$. Circles C_j define a cell decomposition of the sphere which we call the *lower configuration*. The *f*-preimage of the lower configuration is a cell decomposition of the closed disk \overline{D} which is called the *net* of our polygon. Vertices of the net at the corners are labeled by t_i .

Two nets are considered the same if there is an orientation-preserving homeomorphism of \overline{D} sending one net to another and labeled vertices to similarly labeled vertices. Specifying the cells

$$(f(t_1), f(e), f(T))$$

of the lower configuration will define the polygon uniquely. So a polygon is completely determined by the lower configuration, the net and the normalization data.

It is difficult to describe intrinsically all possible nets on a given lower configuration. But in the case when n = 4 and the lower configuration is homeomorphic to a generic quadruple of great circles, one can give such an intrinsic description.



The corresponding cell decomposition of the sphere has the following property:

a) any pair of 2-cells adjacent along a 1-cell consists of a triangle and a quadrilateral.

This property is inherited by the net. Two additional property of the net are:

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b) every interior vertex has degree 4, and every vertex on a side has degree 3, and

c) the degrees of the corners (as vertices of the net) are even.

The last property follows from our assumption that the circles C_j and C_{j+1} are distinct.

One can show that these three properties a), b) and c)

characterize the nets over lower configurations homeomorphic to generic configurations of 4 great circles.

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This permits to construct many examples of nets, circular quadrilaterals and special circular pentagons.

Transformations 1, 2, 3 above can be explicitly performed on the nets.

Lower configurations of four great circles correspond to PSU(2) monodromy representations.

Properties of special points of real PVI solutions strongly depend on the topological type of the lower configuration. For example, *The number of special points is infinite if and only if some two circles of the lower configuration are disjoint. It is infinite in one direction if there is one pair of disjoint circles, and in both directions if there are two such pairs.*

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Classification of generic configurations



Figure: Generic chains A-H. All pairs of circles intersect.



Figure: Generic chains I-O. Some pairs are disjoint.

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