Stable homotopy theory and geometry

Paul VanKoughnett

October 24, 2014

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Building topological spaces

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- X is described entirely by **attaching maps** $S^{n-1} \to X^{(n-1)}$, where $X^{(n-1)}$ is the *n*-dimensional part of X.
- Even simpler: $S^{n-1} \rightarrow X^{(n-1)}/X^{(n-2)}$, a bouquet of (n-1)-spheres; or $S^{n-1} \rightarrow X^{(n-2)}/X^{(n-3)}$, a bouquet of (n-2)-spheres; or ...

Homotopy

Two of these spaces are equivalent if the attaching maps of one can be deformed into the attaching maps of the other.

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Homotopy

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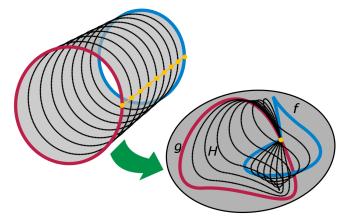
Definition

Given two maps $f, g : X \to Y$, a **homotopy** $f \sim g$ is map $H : X \times [0,1] \to Y$ with $H|_{X \times \{0\}} = f$, and $H|_{X \times \{1\}} = Y$.

 $[X, Y] = \{ maps \ X \to Y \} / homotopy \}$

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Remark

Always take spaces to come equipped with a fixed basepoint; maps preserve basepoint; homotopies don't move basepoint.

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- Is it? How many other complexes like this are there?

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Homotopy groups

Definition

The *n*th **homotopy group** of a space X is

$$\pi_n X := [S^n, X].$$

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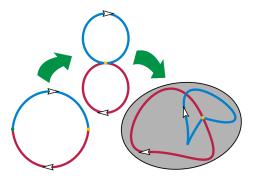
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Why are they groups?

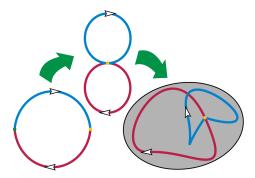
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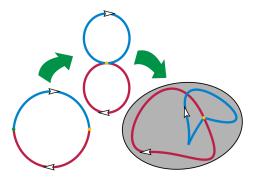
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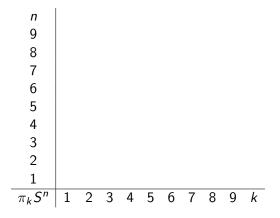
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 π_0 is just a set. π_n is abelian for $n \ge 2$ (why?).

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Homotopy groups of spheres



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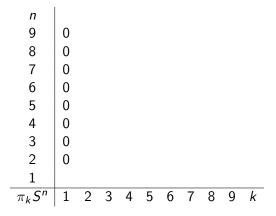
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Examples

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Homotopy groups of spheres



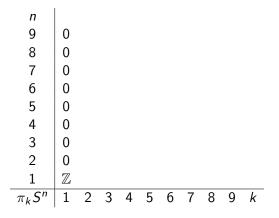
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Homotopy groups of spheres

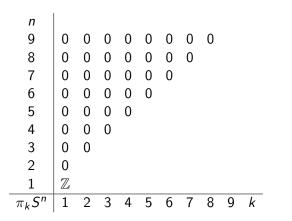


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Homotopy groups of spheres



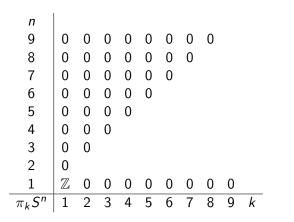
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A tool: suspension

Definition

The **suspension** of a space X is

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There are suspension maps

$$E:[X,Y] \to [\Sigma X,\Sigma Y]$$

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Theorem (Freudenthal suspension theorem)

The suspension map

$$E:\pi_kS^n\to\pi_{k+1}S^{n+1}$$

is a surjection for k = 2n - 1 and an isomorphism for k < 2n - 1.

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Using the suspension theorem

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$$\mathbb{Z} = \pi_1 S^1 \twoheadrightarrow \pi_2 S^2 \xrightarrow{\sim} \pi_3 S^3 \xrightarrow{\sim} \cdots$$

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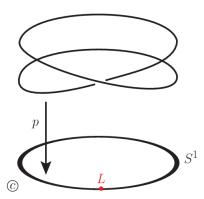
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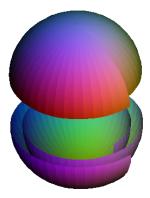
 $\pi_n S^n$ is cyclic... and must be \mathbb{Z} , because the *degree* of a map is homotopy invariant.

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$$\pi_n S^n = \mathbb{Z}$$

Degree two maps:





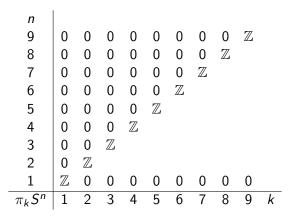
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Homotopy groups of spheres



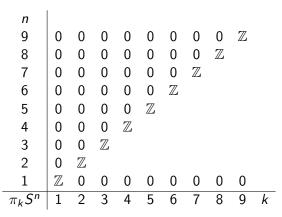
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Homotopy groups of spheres



Is everything else zero? NO!

The Hopf fibration

• S^3 is the unit sphere in \mathbb{C}^2 , with coordinates z, w.

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- The fiber over two points are two linked circles.

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Homotopy groups of spheres

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$\pi_k S^n$	1	2	3	4	5	6	7	8	9	k

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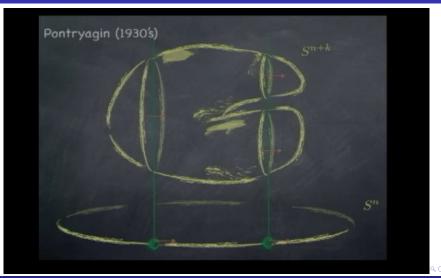
Stable homotopy theory and geometry,

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- The degree of a map $S^n \rightarrow S^n$ is an integer, because its fibers are signed 0-manifolds.
- The 'degree' of a map S^k → Sⁿ should just be its fiber a stably framed (n − k)-manifold.



Stably framed manifolds

Definition

A stably framed manifold is a manifold M^n with an embedding $i: M^n \hookrightarrow \mathbb{R}^{n+k}$, $k \gg 0$, and a trivialization of the normal bundle $N_i M \cong M \times \mathbb{R}^k$.

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Definition

A **framed cobordism** of *n*-dimensional stably framed manifolds M, N is an (n + 1)-manifold W with $\partial W \cong M \sqcup N$, together with a stable framing on W extending those on M and N.

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Pontryagin-Thom

The Pontryagin-Thom isomorphism

 $\Omega_n^{\text{fr}} := \{\text{stably framed } n\text{-manifolds}\}/\text{framed cobordism}$

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Pontryagin-Thom

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Homotopy elements can be described as framed *n*-manifolds!

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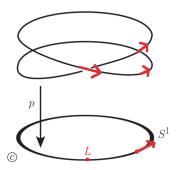
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0-manifolds: $\pi_n S^n$

A 0-manifold in \mathbb{R}^n is a set of points. A framing is a sign attached to each point: orient their normal bundles either with or against the orientation of \mathbb{R}^n .

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Stable homotopy theory and geometry

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A 1-manifold is just a circle. A framing on S¹ → ℝⁿ⁺¹ is determined by how a basis for ℝⁿ rotates as you go around the circle.

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- Framings are classified by π₁SO(n) = Z/2 for n ≥ 3 (and Z for n ≥ 2).
- The Hopf map S³ → S² corresponds to S¹ → S³ together with a basis for its normal bundle that twists once.



• One way to make cobordisms is through surgery.

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2-manifolds: $\pi_{n+2}S^n$

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- Pontryagin: whether or not we can do framed surgery on a 1-cycle is determined by a map

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But H₁(M; Z/2) is positive-dimensional if M has genus ≥ 1, so ker φ is always nonzero, so any M is framed-cobordant to a sphere. ∴ π_{n+2}Sⁿ = 0, n ≫ 0.

Pontryagin's mistake

$\phi: H_1(M; \mathbb{Z}/2) \to \mathbb{Z}/2$

is not a linear map, but a *quadratic* map. Even if we can do surgery on two-cycles, we might not be able to on their sum.



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Whether or not we can do framed surgery on *M* depends on the nature of this quadratic map. We can conclude that

$$\pi_{n+2}S^2\cong \mathbb{Z}/2, n\gg 0.$$

A representative for the nontrivial class is given by the product of two nontrivially framed circles.

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