

Continuous example

Exponential law case: Let

- $X \sim \mathcal{E}(1)$ and $Y \sim \mathcal{E}(1)$
- $X \perp\!\!\!\perp Y$

We set $S = X + Y$.

Then

CRL of X given S is $\mathcal{U}([0, S])$.

Step 1): Computing $E[\psi(x) | S]$

We will use a formula from our set of examples: if f is the joint density of (x, s) , then

$$E[\psi(x) | S] = g(s)$$

where

$$g(s) = \frac{\int \psi(x) f(x, s) dx}{\int f(x, s) dx}$$

Step 0: Compute f . Here

$$X \sim \mathcal{E}(1), Y \sim \mathcal{E}(1), X \perp\!\!\!\perp Y$$

In order to compute f , we evaluate

$$\mathbb{E}[h(X, S)] = \mathbb{E}[h(X, X+Y)]$$

→ generic C_0

$$= \int_{\mathbb{R}^2} h(x, x+y) e^{-x} \mathbb{1}_{\mathbb{R}_+}(x) e^{-y} \mathbb{1}_{\mathbb{R}_+}(y) dx dy$$

$$= \int_0^\infty \int_0^\infty h(x, x+y) e^{-(x+y)} dx dy$$

Recall

$$\mathbb{E}[h(x, y)] = \int_0^\infty \int_0^\infty h(x, x+y) e^{-\overset{\Delta}{x+y}} dx dy$$

$$\text{cv: } \omega = x \qquad s = x+y \qquad \begin{matrix} x = \omega \\ y = s - \omega \end{matrix}$$

$$\text{Domain: } 0 \leq \omega \leq s < \infty$$

$$\text{Jacobian: } J = \left| \det \begin{pmatrix} 1 & 0 \\ -1 & 1 \end{pmatrix} \right| = 1$$

Then

$$\begin{aligned} \mathbb{E}[h(x, y)] &= \int_0^\infty ds e^{-s} \int_0^s h(\omega, s) d\omega \\ &= \int_0^\infty \int_0^\infty h(\omega, s) e^{-s} \mathbb{1}_{(0 \leq \omega \leq s < \infty)} d\omega ds \end{aligned}$$

$$f(x, \Delta) = e^{-s} \mathbb{1}_{(0 \leq x \leq \Delta)}$$

For a test function, $E[\psi(x)|s] = g(s)$ with

$$\begin{aligned} g(s) &= \frac{\int \psi(x) f(x, \Delta) dx}{\int f(x, \Delta) dx} \\ &= \frac{\int_{\mathbb{R}} \psi(x) e^{-s} \mathbb{1}_{(0 \leq x \leq \Delta)} dx}{\int_{\mathbb{R}} e^{-s} \mathbb{1}_{(0 \leq x \leq \Delta)} dx} \\ &= \frac{e^{-s} \int_0^{\Delta} \psi(x) dx}{e^{-s} \Delta} = \frac{1}{\Delta} \int_0^{\Delta} \psi(x) dx \end{aligned}$$

Conclusion: $E[\psi(x) | S] = \frac{1}{S} \int_0^S \psi(x) dx$ ^{a.s.}

Question: is this well defined? \rightarrow Yes, since

(i) $P(S=0) = \int_0^0 \lambda e^{-\lambda} dx = 0$ cdf of S

(ii) $P(S=\infty) = 1 - \lim_{x \rightarrow \infty} F(x) = 0$

Back to CRL

(i) For fixed ψ , the quantity

$$\omega \mapsto \frac{1}{S(\omega)} \int_0^{\infty} \psi(x) \mathbb{1}(x \leq S(\omega)) dx$$

is measurable

(ii) If ω fixed, the function
 $\psi \in C_b(\mathbb{R}) \mapsto \frac{1}{S(\omega)} \int_0^{S(\omega)} \psi(x) dx$
defines a distribution with density

$$f(x) = \frac{1}{S(\omega)} \mathbb{1}_{[0, S(\omega)]}(x)$$

we get a $\mathcal{U}([0, S(\omega)])$ distribution

Thus $\mathcal{U}([0, S])$ defines a CRL
for $\mathcal{L}(X|S)$.

Continuous example

Proof: The joint density of (X, S) is given by

$$f(x, s) = e^{-s} \mathbf{1}_{\{0 \leq x \leq s\}}.$$

Let then $\psi \in \mathcal{B}_b(\mathbb{R}_+)$. Thanks to Example 5, we have

$$\mathbf{E}[\psi(X)|S] = u(S),$$

with

$$u(s) = \frac{\int_{\mathbb{R}_+} \psi(x) f(x, s) dx}{\int_{\mathbb{R}_+^2} f(x, s) dx} = \frac{1}{s} \int_0^s \psi(x) dx.$$

Proof

In addition, $S \neq 0$ almost surely, and thus if $A \in \mathcal{B}(\mathbb{R})$ we have:

$$\mathbf{E}[\psi(X)|S] = \frac{\int_0^S \psi(x) dx}{S}.$$

Considering the state space as $= \mathbb{R}_+$, $\mathcal{S} = \mathcal{B}(\mathbb{R}_+)$ and setting

$$\mu(\omega, f) = \frac{1}{S(\omega)} \int_0^{S(\omega)} \psi(x) dx,$$

one can verify that we have defined a **conditional regular law**.

Existence of the CRL

Theorem 29.

Let

- X a random variable on $(\Omega, \mathcal{F}_0, P)$.
- Taking values in a space of the form $(\mathbb{R}^n, \mathcal{B}(\mathbb{R}^n))$.
- $\mathcal{G} \subset \mathcal{F}_0$ a σ -algebra.

Then the CRL of X given \mathcal{G} exists.

Proof: nontrivial and omitted.

Computation rules for CRL

(1) If $\mathcal{G} = \sigma(Y)$, with Y random variable with values in \mathbb{R}^m , we have

$$\mu(\omega, f) = \tilde{\mu}(Y(\omega), f),$$

and one can define a CRL of X given Y as a family $\{\tilde{\mu}(y, \cdot); y \in \mathbb{R}^m\}$ of probabilities on \mathbb{R}^n , such that for all $f \in C_b(\mathbb{R}^n)$ the function Fact: $\mu(y, \cdot) = \mathcal{L}(X|Y=y)$

$$y \mapsto \mu(y, f)$$

is measurable.

(2) If Y is a discrete r.v, this can be reduced to:

$$\mu(y, A) = \mathbf{P}(X \in A | Y = y) = \frac{\mathbf{P}(X \in A, Y = y)}{\mathbf{P}(Y = y)}.$$

Computation rules for CRL (2)

- (3) When one knows the CRL, quantities like the following (for $\phi \in \mathcal{B}(\mathbb{R}^n)$) can be computed:

$$\mathbf{E}[\phi(X)|\mathcal{G}] = \int_{\mathbb{R}^n} \phi(x) \mu(\omega, dx)$$

$$\mathbf{E}[\phi(X)|Y] = \int_{\mathbb{R}^n} \phi(x) \mu(Y, dx).$$

- (4) ~~The CRL is not unique.~~

However if N_1, N_2 are 2 CRL of X given \mathcal{G}

\hookrightarrow we have ω -almost surely:

$$N_1(\omega, f) = N_2(\omega, f) \quad \text{for all } f \in C_b(\mathbb{R}^n).$$