

5.6 - 2

If $B = M^{-1}AM$ then A and B have same eigenvalues. If x is an eigenvector of A , then $M^{-1}x$ is the corresponding eigenvector of B . We like B (or T) to be relative to eigenvectors as basis, (check with $M = \begin{pmatrix} \cos x & -\sin x \\ \sin x & \cos x \end{pmatrix}$)

Spectral Theorem

A real symm. $\Rightarrow A = Q \Lambda Q^T$ Λ diag, Orth
 A complex hermitian $\Rightarrow A = U \Lambda U^T$ Λ diag, Unitary

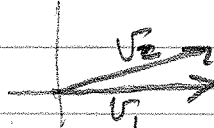
In general (p 296) we have:

There is a unitary M so that $M^{-1}AM = T$ is triangular.

Remark Why are symmetric matrices better?

Any matrix may be approximated by one with distinct roots, so diagonalizable. Book notes (p 297) that in symmetric case, the corresponding U s are ON columns, and so in the limit we expect an ON basis of eigenvectors.

But now lets compare the "close matrices" A not diagonalizable $\begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$ B diagonalizable $\begin{pmatrix} 0 & \epsilon \\ 0 & \epsilon \end{pmatrix}$. $0, \epsilon$ e values
 vector for $0: \begin{pmatrix} 1 \\ 0 \end{pmatrix}$ vector for $\epsilon: \begin{pmatrix} 1 \\ \epsilon \end{pmatrix}$

What happens in limit

 In limit $v_1 \rightarrow 0$
 $v_2 \rightarrow v_1 \rightarrow 0$

$\begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$ $v_1 = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$ $v_2 = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$

How to get Slar form (p 296),
 Given A , find one ^(unit) e-vector x_1 (this is guaranteed)

Put x_1 in first column of U and check

$$U_1^T A U_1 = \Lambda_1; \quad A \begin{pmatrix} x_1 & * & * & - \end{pmatrix} = \begin{pmatrix} x_1 & * & * & - \end{pmatrix} \begin{pmatrix} \lambda_1 & & & \\ & \lambda_2 & & \\ & & \lambda_3 & \\ & & & \lambda_4 \end{pmatrix}$$

U_1 is 1st approximation, U_1 is unitary

Now take U_2 as

$$U_2 = \left(\begin{array}{c|ccc} 1 & 0 & 0 & - \\ \hline 0 & & & \\ 0 & & & \\ 0 & & & \end{array} \right), \quad M_2 \text{ to be determined}$$

We will make U_2 unitary, but a key observation is that we won't touch the first row or column -

so $U_1 U_2$ has the same first column as U_1 ! we haven't changed x_1 !

So if we work on the $(n-1) \times (n-1)$ submatrix of A , we get an eval'd λ_2 e-vector x_2 , which we make an n -vector x_2 with first coordinate zero;

$$U_2 = \left(\begin{array}{c|ccc} 1 & 0 & 0 & - \\ \hline 0 & & & \\ 0 & & & \\ 0 & & & \end{array} \right) \leftarrow \text{fill out } U_2 \text{ unitary}$$

$$\text{Then } U_2^{-1} A U_2 = \begin{bmatrix} \lambda_1 & * & * & \\ 0 & \lambda_2 & & \\ 0 & & \lambda_3 & \\ 0 & & & \lambda_4 \end{bmatrix}; \quad A_1 = U_1$$

\leftarrow This becomes T in the end.

Def A is normal if $AA^* = A^*A$

Check $\begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$ is not normal

No accident! Spectral theorem holds iff A is normal
(half of this is easy to see).

Jordan form If A has s l. ind eigenvectors
then to each λ_i is a block

$$J_i = \begin{bmatrix} \lambda_i & & 0 \\ & \lambda_i & \\ 0 & & \lambda_i \end{bmatrix}$$

Recall the three 3×3 matrices I gave at the beginning of this chapter, all of whom had $-\lambda^3$ as the characteristic polynomial.

Interpretation

$$J = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix}$$

$$AM = MJ, \quad MJ = (x_1 \ x_2 \ x_3) \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix}$$

This means

$$A(x_1 \ x_2 \ x_3) = \begin{pmatrix} x_1 & -x_1 & x_1 \\ x_1 & x_2 & x_2 \\ x_1 & x_2 & x_3 \end{pmatrix} \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix}$$

$$(Ax_1 \ Ax_2 \ Ax_3) = (0 \ x_1 \ x_2)$$

$$\text{so } Ax_1 = 0, \quad Ax_2 = x_1, \quad Ax_3 = x_2$$

$$A^2 = \begin{pmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}, \quad A^3 = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

In general

$$\left(J_i \right)^k = \begin{bmatrix} \lambda & 1 & 0 \\ 0 & \lambda & \\ 0 & 0 & \lambda \end{bmatrix}^k = \begin{bmatrix} \lambda^k & k\lambda^{k-1} & \\ 0 & \lambda^k & \\ 0 & 0 & \lambda^k \end{bmatrix} = \left(\lambda I + \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix} \right)^k$$

± like book account on p 301

$$\begin{pmatrix} u_1 \\ u_2 \\ u_3 \end{pmatrix}' = \begin{pmatrix} \lambda & 1 & 0 \\ 0 & \lambda & 1 \\ 0 & 0 & \lambda \end{pmatrix} \begin{pmatrix} u_1 \\ u_2 \\ u_3 \end{pmatrix} \quad \frac{du}{dt} = Ju \rightarrow$$

solution is $u(t) = e^{Jt} u(0)$. So to see third column of e^{Jt} , take $u(0) = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$. Then we have

$$u_3' = \lambda u_3 \Rightarrow u_3 = e^{\lambda t} \quad (\text{since } u(0) = 1)$$

$$\text{Then } u_2' = \lambda u_2 + u_3 = \lambda u_2 + e^{\lambda t} \Rightarrow u_2 = t e^{\lambda t}$$

$$\text{and similarly } u_1 = \frac{1}{2} t^2 e^{\lambda t}$$

Some hw

$$P196 \#1 \quad F_4 = \begin{pmatrix} 1 & 1 & 1 & 1 \\ 1 & -1 & -1 & -1 \\ 1 & 1 & -1 & -1 \\ 1 & -1 & 1 & 1 \end{pmatrix} \quad \neq 4 = \begin{pmatrix} 16 & 0 & 0 & 0 \\ 0 & 16 & 0 & 0 \\ 0 & 0 & 16 & 0 \\ 0 & 0 & 0 & 16 \end{pmatrix}$$

p196 #11 $y = F_4 c$ We compute directly first:

$$\begin{pmatrix} 1 & 1 & 1 & 1 \\ 1 & -1 & -1 & -1 \\ 1 & 1 & -1 & -1 \\ 1 & -1 & 1 & 1 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 2 \\ 0 \\ 2 \\ 0 \end{pmatrix}$$

Follow steps on p 195

$$\begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \rightarrow \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \begin{matrix} \text{even} \\ \text{odd} \end{matrix} \rightarrow \begin{pmatrix} 1 & -1 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 2 \\ 0 \end{pmatrix} \begin{matrix} y_0' \\ y_1' \end{matrix} \text{ then back} \\ = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \begin{matrix} y_0'' \\ y_1'' \end{matrix}$$

as on p 194 bottom (or 3w)

$$y_0 = y_0' + (i)^0 y_0'' = 2$$

$$y_1 = y_1' + (i)^1 y_1'' = 0$$

$$y_2 = y_0 + 2 = y_0' - (i)^0 y_0'' = 2$$

$$y_3 = 0$$

p196 #18 If the columns are e-vectors of P , then PF has as columns $(f_0, d_1 f_1, d_2 f_2, d_3 f_3)$. So we look at this as see that $\lambda_0 = 1$. For the second col of PF we get (left side) $\begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \end{pmatrix}$ so $\lambda_1 = 0$. Similarly $\lambda_2 = i^2 = -1$, $\lambda_3 = i^3 = -i$.

cols
 (f_0, f_1, f_2, f_3)

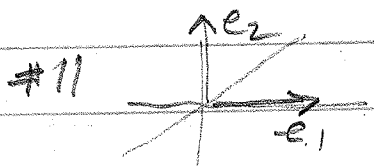
P 302

#2 Anything of the form $M \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} M^{-1}$

If $M = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} = M^{-1}$ we get $\begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix}$

Then try $M = \begin{pmatrix} 1 & 1 \\ 0 & 2 \end{pmatrix}$ so $M^{-1} = \frac{1}{2} \begin{pmatrix} 2 & -1 \\ 0 & 1 \end{pmatrix}$ and

$$M \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} M^{-1} = \begin{pmatrix} 1 & -1 \\ 0 & -1 \end{pmatrix} \quad (\text{I think!})$$



$$T e_1 = e_2$$

$$T e_2 = e_1$$

so Matrix of T is

$$A = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

With respect to $(\overset{V_1}{1}, \overset{V_1}{1})$ and $(\overset{V_2}{1}, \overset{V_2}{-1})$ we have $T V_1 = V_1$,

$T V_2 = -V_2$ so the matrix with respect to the V 's is

$$B = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

Using notation from p 295, we get

$$M = \begin{bmatrix} \text{I} \end{bmatrix}_{V \text{ frame } \leftarrow \text{ my word}} = \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix}; M^{-1} = \frac{1}{2} \begin{pmatrix} -1 & 1 \\ 1 & 1 \end{pmatrix} = \begin{pmatrix} \frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & \frac{1}{2} \end{pmatrix}$$

✓ so $A = M B M^{-1} = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} \frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & \frac{1}{2} \end{pmatrix}$

Ignore p 305 38

Hint for 41c (think of off-diagonal entries)