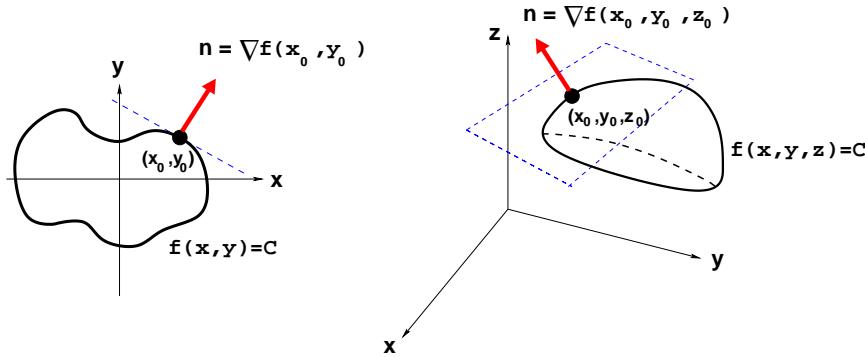


Study Guide # 2

- 1.** Gradient vector for $f(x, y)$: $\nabla f(x, y) = \left\langle \frac{\partial f}{\partial x}, \frac{\partial f}{\partial y} \right\rangle$, properties of gradients; gradient points in direction of maximum rate of increase of f ; $\nabla f(x_0, y_0) \perp$ level curve $f(x, y) = C$ and, in the case of 3 variables, $\nabla f(x_0, y_0, z_0) \perp$ level surface $f(x, y, z) = C$:



- 2.** Directional derivative of $f(x, y)$ at (x_0, y_0) in the direction \vec{u} : $D_{\vec{u}}f(x_0, y_0) = \nabla f(x_0, y_0) \cdot \vec{u}$, where \vec{u} must be a unit vector; tangent planes to level surfaces $f(x, y, z) = C$ (a normal vector at (x_0, y_0, z_0) is $\vec{n} = \nabla f(x_0, y_0, z_0)$).
- 3.** Relative/local extrema; critical points ($\nabla f = \vec{0}$ or ∇f does not exist); *2nd Derivatives Test*: A critical points is a local min if $D = f_{xx}f_{yy} - f_{xy}^2 > 0$ and $f_{xx} > 0$, local max if $D > 0$ and $f_{xx} < 0$, saddle if $D < 0$; absolute extrema; Max-Min Problems; **Lagrange Multipliers**: Extremize $f(\vec{x})$ subject to a constraint $g(\vec{x}) = C$, solve the system: $\nabla f = \lambda \nabla g$ and $g(\vec{x}) = C$.
- 4.** Double integrals; Midpoint Rule for rectangle : $\iint_R f(x, y) dA \approx \sum_{i=1}^m \sum_{j=1}^n f(\bar{x}_i, \bar{y}_j) \Delta A$;
- 5.** Type I region D : $\begin{cases} g_1(x) \leq y \leq g_2(x) \\ a \leq x \leq b \end{cases}$; Type II region D : $\begin{cases} h_1(y) \leq x \leq h_2(y) \\ c \leq y \leq d \end{cases}$;
 iterated integrals over Type I and II regions: $\iint_D f(x, y) dA = \int_a^b \int_{g_1(x)}^{g_2(x)} f(x, y) dy dx$ and
 $\iint_D f(x, y) dA = \int_c^d \int_{h_1(y)}^{h_2(y)} f(x, y) dx dy$, respectively; Reversing Order of Integration (regions that are both Type I and Type II); properties of double integrals.
- 6.** Integral inequalities: $mA \leq \iint_D f(x, y) dA \leq MA$, where A = area of D and $m \leq f(x, y) \leq M$ on D .

7. Change of Variables Formula in Polar Coordinates: if $D : \begin{cases} h_1(\theta) \leq r \leq h_2(\theta) \\ \alpha \leq \theta \leq \beta \end{cases}$, then

$$\iint_D f(x, y) dA = \int_{\alpha}^{\beta} \int_{h_1(\theta)}^{h_2(\theta)} f(r \cos \theta, r \sin \theta) r dr d\theta.$$

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8. Applications of double integrals:

(a) Area of region D is $A(D) = \iint_D dA$

(b) Volume of solid under graph of $z = f(x, y)$, where $f(x, y) \geq 0$, is $V = \iint_D f(x, y) dA$

(c) Mass of D is $m = \iint_D \rho(x, y) dA$, where $\rho(x, y)$ = density (per unit area); sometimes write
 $m = \iint_D dm$, where $dm = \rho(x, y) dA$.

(d) Moment about the x -axis $M_x = \iint_D y \rho(x, y) dA$; moment about the y -axis $M_y = \iint_D x \rho(x, y) dA$.

(e) Center of mass (\bar{x}, \bar{y}) , where $\bar{x} = \frac{M_y}{m} = \frac{\iint_D x \rho(x, y) dA}{\iint_D \rho(x, y) dA}$, $\bar{y} = \frac{M_x}{m} = \frac{\iint_D y \rho(x, y) dA}{\iint_D \rho(x, y) dA}$

Remark: centroid = center of mass when density is constant (this is useful).

9. Elementary solids $E \subset \mathbb{R}^3$ of Type 1, Type 2, Type 3; triple integrals over solids E : $\iiint_E f(x, y, z) dV$;

volume of solid E is $V(E) = \iiint_E dV$; applications of triple integrals, mass of a solid, moments about the coordinate planes M_{xy} , M_{xz} , M_{yz} , center of mass of a solid $(\bar{x}, \bar{y}, \bar{z})$.
