Study Guide # 2

- 1. Relative/local extrema; critical points ($\nabla f = \vec{\mathbf{0}}$ or ∇f does not exist); 2^{nd} Derivatives Test: A critical points is a local min if $D = f_{xx}f_{yy} f_{xy}^2 > 0$ and $f_{xx} > 0$, local max if D > 0 and $f_{xx} < 0$, saddle if D < 0; absolute extrema; Max-Min Problems; **Lagrange Multipliers:** Extremize $f(\vec{\mathbf{x}})$ subject to a constraint $g(\vec{\mathbf{x}}) = C$, solve the system: $\nabla f = \lambda \nabla g$ and $g(\vec{\mathbf{x}}) = C$.
- **2.** Double integrals; Midpoint Rule for rectangle : $\iint_R f(x,y) dA \approx \sum_{i=1}^m \sum_{j=1}^n f(\overline{x_i}, \overline{y_j}) \Delta A;$
- **3.** Type I region $D: \begin{cases} g_1(x) \leq y \leq g_2(x) \\ a \leq x \leq b \end{cases}$; Type II region $D: \begin{cases} h_1(y) \leq x \leq h_2(y) \\ c \leq y \leq d \end{cases}$; iterated integrals over Type I and II regions: $\iint_D f(x,y) \, dA = \int_a^b \int_{g_1(x)}^{g_2(x)} f(x,y) \, dy \, dx \text{ and}$ $\iint_D f(x,y) \, dA = \int_c^d \int_{h_1(y)}^{h_2(y)} f(x,y) \, dx \, dy, \text{ respectively; Reversing Order of Integration (regions that are both Type I and Type II); properties of double integrals.$
- **4.** Integral inequalities: $mA \leq \iint_D f(x,y) dA \leq MA$, where A = area of D and $m \leq f(x,y) \leq M$ on D.
- **5.** Change of Variables Formula in Polar Coordinates: if $D: \begin{cases} h_1(\theta) \leq r \leq h_2(\theta) \\ \alpha \leq \theta \leq \beta \end{cases}$, then $\iint_D f(x,y) \, dA = \int_{\alpha}^{\beta} \int_{h_1(\theta)}^{h_2(\theta)} f(r\cos\theta, r\sin\theta) r \, dr \, d\theta.$
- **6.** Applications of double integrals:
 - (a) Area of region D is $A(D) = \iint_D dA$
 - (b) Volume of solid under graph of z = f(x, y), where $f(x, y) \ge 0$, is $V = \iint_D f(x, y) dA$
 - (c) Mass of D is $m = \iint_D \rho(x, y) dA$, where $\rho(x, y) = \text{density}$ (per unit area); sometimes write $m = \iint_D dm$, where $dm = \rho(x, y) dA$.
 - (d) Moment about the x-axis $M_x = \iint_D y \, \rho(x,y) \, dA$; moment about the y-axis $M_y = \iint_D x \, \rho(x,y) \, dA$.
 - (e) Center of mass $(\overline{x}, \overline{y})$, where $\overline{x} = \frac{M_y}{m} = \frac{\iint_D x \, \rho(x, y) \, dA}{\iint_D \rho(x, y) \, dA}$, $\overline{y} = \frac{M_x}{m} = \frac{\iint_D y \, \rho(x, y) \, dA}{\iint_D \rho(x, y) \, dA}$

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Remark: centroid = center of mass when density is constant (this is useful).

7. Elementary solids
$$E \subset \mathbb{R}^3$$
 of Type 1, Type 2, Type 3; triple integrals over solids E :
$$\iiint_E f(x,y,z) \, dV = \iint_D \int_{u(x,y)}^{v(x,y)} f(x,y,z) \, dz \, dA \text{ for } E = \{(x,y) \in D, \ u(x,y) \leq z \leq v(x,y)\};$$

volume of solid E is $V(E) = \iiint_E dV$; applications of triple integrals, mass of a solid, moments about the coordinate planes M_{xy} , M_{xz} , M_{yz} , center of mass of a solid $(\overline{x}, \overline{y}, \overline{z})$.

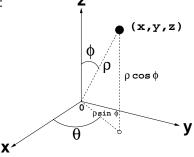
8. Cylindrical Coordinates (r, θ, z) :

From CC to RC :
$$\begin{cases} x = r \cos \theta \\ y = r \sin \theta \\ z = z \end{cases}$$

Going from RC to CC use $x^2 + y^2 = r^2$ and $\tan \theta = \frac{y}{x}$ (make sure θ is in correct quadrant).

9. Spherical Coordinates (ρ, θ, ϕ) , where $0 \le \phi \le \pi$:

From SC to RC :
$$\begin{cases} x = (\rho \sin \phi) \cos \theta \\ y = (\rho \sin \phi) \sin \theta \\ z = \rho \cos \phi \end{cases}$$



Going from RC to SC use $x^2 + y^2 + z^2 = \rho^2$, $\tan \theta = \frac{y}{x}$ and $\cos \phi = \frac{z}{\rho}$.

10. Triple integrals in Cylindrical Coordinates: $\begin{cases} x = r \cos \theta \\ y = r \sin \theta \\ z = z \end{cases}, \quad dV = r dz dr d\theta$

$$\iiint_{E} f(x, y, z) \ dV = \iiint_{E} f(r \cos \theta, r \sin \theta, z) r \, dz \, dr \, d\theta$$

11. Triple integrals in Spherical Coordinates: $\begin{cases} x = (\rho \sin \phi) \cos \theta \\ y = (\rho \sin \phi) \sin \theta \end{cases}, \quad dV = \rho^2 \sin \phi \ d\rho \ d\phi \ d\theta$ $= \lim_E f(x, y, z) \ dV = \iiint_E f(\rho \sin \phi \cos \theta, \rho \sin \phi \sin \theta, \rho \cos \phi) \rho^2 \sin \phi \ d\rho \ d\phi \ d\theta$

$$\iiint_E f(x, y, z) \ dV = \iiint_E f(\rho \sin \phi \cos \theta, \ \rho \sin \phi \sin \theta, \ \rho \cos \phi) \ \rho^2 \sin \phi \ d\rho \ d\phi \ d\theta$$

12. Vector fields on \mathbb{R}^2 and \mathbb{R}^3 : $\vec{\mathbf{F}}(x,y) = \langle P(x,y), Q(x,y) \rangle$ and $\vec{\mathbf{F}}(x,y,z) = \langle P(x,y), Q(x,y), R(x,y) \rangle$; $\vec{\mathbf{F}}$ is a conservative vector field if $\vec{\mathbf{F}} = \nabla f$, for some real-valued function f.

13. Line integral of a function f(x,y) along C, parameterized by x=x(t), y=y(t) and $a \le t \le b$, is

$$\int_C f(x,y) \ ds = \int_a^b f(x(t), y(t)) \sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2} \ dt.$$

(independent of orientation of C, other properties and applications of line integrals of f)

Remarks:

- (a) $\int_C f(x,y) ds$ is sometimes called the "line integral of f with respect to arc length"
- (b) $\int_C f(x,y) dx = \int_a^b f(x(t), y(t)) x'(t) dt$
- (c) $\int_C f(x,y) dy = \int_a^b f(x(t), y(t)) y'(t) dt$

14. Line integral of vector field $\vec{\mathbf{F}}(x,y)$ along C, parameterized by $\vec{\mathbf{r}}(t)$ and $a \leq t \leq b$, is given by

$$\int_{C} \vec{\mathbf{F}} \cdot d\vec{\mathbf{r}} = \int_{a}^{b} \vec{\mathbf{F}}(\vec{\mathbf{r}}(t)) \cdot \vec{\mathbf{r}}'(t) dt.$$

(depends on orientation of C, other properties and applications of line integrals of f)

15. Connection between line integral of vector fields and line integral of functions:

$$\int_{C} \vec{\mathbf{F}} \cdot d\vec{\mathbf{r}} = \int_{C} (\vec{\mathbf{F}} \cdot \vec{\mathbf{T}}) \, ds$$

where $\vec{\mathbf{T}}$ is the unit tangent vector to the curve C.

- **16.** If $\vec{\mathbf{F}}(x,y) = P(x,y)\vec{\mathbf{i}} + Q(x,y)\vec{\mathbf{j}}$, then $\int_C \vec{\mathbf{F}} \cdot d\vec{\mathbf{r}} = \int_C P(x,y) dx + Q(x,y) dy$; Work $= \int_C \vec{\mathbf{F}} \cdot d\vec{\mathbf{r}}$.
- 17. If S is the graph of z = f(x, y) above D, then the surface area of S is

$$A(S) = \iint_{D} \sqrt{1 + (\partial f/\partial x)^{2} + (\partial f/\partial y)^{2}} dA.$$