## Study Guide # 2

- **1.** Double integrals; Midpoint Rule for rectangle :  $\iint_R f(x,y) dA \approx \sum_{i=1}^m \sum_{j=1}^n f(\overline{x_i}, \overline{y_j}) \Delta A;$
- **2.** Type I region  $D: \left\{ \begin{array}{l} g_1(x) \leq y \leq g_2(x) \\ a \leq x \leq b \end{array} \right.$ ; Type II region  $D: \left\{ \begin{array}{l} h_1(y) \leq x \leq h_2(y) \\ c \leq y \leq d \end{array} \right.$ ; iterated integrals over Type I and II regions:  $\iint_D f(x,y) \, dA = \int_a^b \int_{g_1(x)}^{g_2(x)} f(x,y) \, dy \, dx \text{ and }$   $\iint_D f(x,y) \, dA = \int_c^d \int_{h_1(y)}^{h_2(y)} f(x,y) \, dx \, dy, \text{ respectively; Reversing Order of Integration (regions of the property of$
- **3.** Integral inequalities:  $mA \leq \iint_D f(x,y) dA \leq MA$ , where  $A = \text{area of } D \text{ and } m \leq f(x,y) \leq M$  on D.
- **4.** Change of Variables Formula in Polar Coordinates: if  $D: \begin{cases} h_1(\theta) \leq r \leq h_2(\theta) \\ \alpha \leq \theta \leq \beta \end{cases}$ , then  $\iint_D f(x,y) \, dA = \int_{\alpha}^{\beta} \int_{h_1(\theta)}^{h_2(\theta)} f(r\cos\theta, \ r\sin\theta) \, r \, dr \, d\theta.$

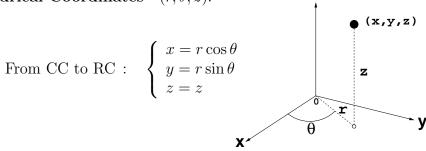
that are both Type I and Type II); properties of double integrals.

- **5.** Applications of double integrals:
  - (a) Area of region D is  $A(D) = \iint_D dA$
  - (b) Volume of solid under graph of z = f(x, y), where  $f(x, y) \ge 0$ , is  $V = \iint_D f(x, y) dA$
  - (c) Mass of D is  $m = \iint_D \rho(x, y) dA$ , where  $\rho(x, y) = \text{density}$  (per unit area); sometimes write  $m = \iint_D dm$ , where  $dm = \rho(x, y) dA$ .
  - (d) Moment about the x-axis  $M_x = \iint_D y \, \rho(x,y) \, dA$ ; moment about the y-axis  $M_y = \iint_D x \, \rho(x,y) \, dA$ .
  - (e) Center of mass  $(\overline{x}, \overline{y})$ , where  $\overline{x} = \frac{M_y}{m} = \frac{\iint_D x \, \rho(x, y) \, dA}{\iint_D \rho(x, y) \, dA}$ ,  $\overline{y} = \frac{M_x}{m} = \frac{\iint_D y \, \rho(x, y) \, dA}{\iint_D \rho(x, y) \, dA}$

<u>Remark</u>: centroid = center of mass when density is constant (this is useful).

**6.** Elementary solids  $E \subset \mathbb{R}^3$  of Type 1, Type 2, Type 3; triple integrals over solids E:  $\iiint_E f(x,y,z) \, dV = \iint_D \int_{u(x,y)}^{v(x,y)} f(x,y,z) \, dz \, dA \text{ for } E = \{(x,y) \in D, \ u(x,y) \leq z \leq v(x,y)\};$  volume of solid E is  $V(E) = \iiint_E dV$ ; applications of triple integrals, mass of a solid, moments about the coordinate planes  $M_{xy}$ ,  $M_{xz}$ ,  $M_{yz}$ , center of mass of a solid  $(\overline{x}, \overline{y}, \overline{z})$ .

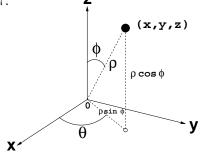
7. Cylindrical Coordinates  $(r, \theta, z)$ :



Going from RC to CC use  $x^2 + y^2 = r^2$  and  $\tan \theta = \frac{y}{x}$  (make sure  $\theta$  is in correct quadrant).

**8. Spherical Coordinates**  $(\rho, \theta, \phi)$ , where  $0 \le \phi \le \pi$ :

From SC to RC : 
$$\begin{cases} x = (\rho \sin \phi) \cos \theta \\ y = (\rho \sin \phi) \sin \theta \\ z = \rho \cos \phi \end{cases}$$



Going from RC to SC use  $x^2 + y^2 + z^2 = \rho^2$ ,  $\tan \theta = \frac{y}{x}$  and  $\cos \phi = \frac{z}{\rho}$ .

9. Triple integrals in Cylindrical Coordinates:  $\begin{cases} x = r \cos \theta \\ y = r \sin \theta \\ z = z \end{cases}, \quad dV = r dz dr d\theta$ 

$$\iiint_{E} f(x, y, z) \ dV = \iiint_{E} f(r \cos \theta, r \sin \theta, z) r \, dz \, dr \, d\theta$$

**10.** Triple integrals in Spherical Coordinates:  $\begin{cases} x = (\rho \sin \phi) \cos \theta \\ y = (\rho \sin \phi) \sin \theta \end{cases}, \quad dV = \rho^2 \sin \phi \ d\rho \ d\phi \ d\theta$  $z = \rho \cos \phi$ 

$$\iiint_E f(x, y, z) \ dV = \iiint_E f(\rho \sin \phi \cos \theta, \ \rho \sin \phi \sin \theta, \ \rho \cos \phi) \ \rho^2 \sin \phi \ d\rho \ d\phi \ d\theta$$

$$\uparrow$$

**11.** Vector fields on  $\mathbb{R}^2$  and  $\mathbb{R}^3$ :  $\vec{\mathbf{F}}(x,y) = \langle P(x,y), Q(x,y) \rangle$  and

 $\vec{\mathbf{F}}(x,y,z) = \langle P(x,y,z), Q(x,y,z), R(x,y,z) \rangle;$ 

 $\vec{\mathbf{F}}$  is a conservative vector field if  $\vec{\mathbf{F}} = \nabla f$ , for some real-valued function f.

12. Line integral of a function f(x,y) along C, parameterized by x=x(t), y=y(t) and  $a \le t \le b$ , is

$$\int_C f(x,y) \ ds = \int_a^b f(x(t), y(t)) \sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2} \ dt \ .$$

(independent of orientation of C, other properties and applications of line integrals of f)

## Remarks:

(a)  $\int_C f(x,y) ds$  is sometimes called the "line integral of f with respect to arc length"

(b) 
$$\int_C f(x,y) dx = \int_a^b f(x(t), y(t)) x'(t) dt$$

(c) 
$$\int_C f(x,y) dy = \int_a^b f(x(t), y(t)) y'(t) dt$$

13. Line integral of vector field  $\vec{\mathbf{F}}(x,y)$  along C, parameterized by  $\vec{\mathbf{r}}(t)$  and  $a \leq t \leq b$ , is given by

$$\int_{C} \vec{\mathbf{F}} \cdot d\vec{\mathbf{r}} = \int_{a}^{b} \vec{\mathbf{F}}(\vec{\mathbf{r}}(t)) \cdot \vec{\mathbf{r}}'(t) dt.$$

(depends on orientation of C, other properties and applications of line integrals of f)

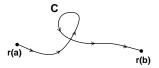
14. Connection between line integral of vector fields and line integral of functions:

$$\int_{C} \vec{\mathbf{F}} \cdot d\vec{\mathbf{r}} = \int_{C} (\vec{\mathbf{F}} \cdot \vec{\mathbf{T}}) \, ds$$

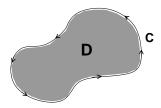
where  $\vec{\mathbf{T}}$  is the unit tangent vector to the curve C.

**15.** If 
$$\vec{\mathbf{F}}(x,y) = P(x,y)\vec{\mathbf{i}} + Q(x,y)\vec{\mathbf{j}}$$
, then  $\int_C \vec{\mathbf{F}} \cdot d\vec{\mathbf{r}} = \int_C P(x,y) dx + Q(x,y) dy$ ; Work  $= \int_C \vec{\mathbf{F}} \cdot d\vec{\mathbf{r}}$ .

**16.** Fundamental Theorem of Calculus for Line Integrals:  $\int_C \nabla f \cdot d\vec{\mathbf{r}} = f(\vec{\mathbf{r}}(b)) - f(\vec{\mathbf{r}}(a))$ :



- **17.** A vector field  $\vec{\mathbf{F}}(x,y) = P(x,y)\vec{\mathbf{i}} + Q(x,y)\vec{\mathbf{j}}$  is conservative (i.e.  $\vec{\mathbf{F}} = \nabla f$ ) if  $\frac{\partial Q}{\partial x} = \frac{\partial P}{\partial y}$ ; how to determine a potential function f if  $\vec{\mathbf{F}}(\vec{\mathbf{x}}) = \nabla f(\vec{\mathbf{x}})$ .
- **18.** Green's Theorem:  $\int_C P(x,y) dx + Q(x,y) dy = \iint_D \left( \frac{\partial Q}{\partial x} \frac{\partial P}{\partial y} \right) dA$  (C = boundary of D):



**19.** DEL OPERATOR:  $\nabla = \frac{\partial}{\partial x} \vec{\mathbf{i}} + \frac{\partial}{\partial y} \vec{\mathbf{j}} + \frac{\partial}{\partial z} \vec{\mathbf{k}}$ ; if  $\vec{\mathbf{F}}(x, y, z) = P(x, y, z) \vec{\mathbf{i}} + Q(x, y, z) \vec{\mathbf{j}} + R(x, y, z) \vec{\mathbf{k}}$ , then

$$\operatorname{curl} \vec{\mathbf{F}} = \nabla \times \vec{\mathbf{F}} = \begin{vmatrix} \vec{\mathbf{i}} & \vec{\mathbf{j}} & \vec{\mathbf{k}} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ P & Q & R \end{vmatrix} \quad \text{and} \quad \operatorname{div} \vec{\mathbf{F}} = \nabla \cdot \vec{\mathbf{F}} = \frac{\partial P}{\partial x} + \frac{\partial Q}{\partial y} + \frac{\partial R}{\partial z}$$

Properties of curl and divergence:

- (i) If curl  $\vec{\mathbf{F}} = \vec{\mathbf{0}}$ , then  $\vec{\mathbf{F}}$  is a conservative vector field (i.e.,  $\vec{\mathbf{F}}(\vec{\mathbf{x}}) = \nabla f(\vec{\mathbf{x}})$ ).
- (ii) If curl  $\vec{\mathbf{F}} = \vec{\mathbf{0}}$ , then  $\vec{\mathbf{F}}$  is *irrotational*; if div  $\vec{\mathbf{F}} = 0$ , then  $\vec{\mathbf{F}}$  is *incompressible*.

(iii) Laplace's Equation: 
$$\nabla^2 f = \frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2} + \frac{\partial^2 f}{\partial z^2} = 0.$$