

Study Guide # 3

You also need Study Guides # 1 and # 2 for the Final Exam

1. Line integral of a function  $f(x, y, z)$  along  $C$ , parameterized by  $x = x(t)$ ,  $y = y(t)$ ,  $z = z(t)$  and  $a \leq t \leq b$ , is

$$\int_C f(x, y, z) ds = \int_a^b f(x(t), y(t), z(t)) \sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2 + \left(\frac{dz}{dt}\right)^2} dt.$$

(independent of orientation of  $C$ , other properties and applications of line integrals of  $f$ )

**Remarks:**

(a)  $\int_C f(x, y, z) ds$  is sometimes called the “line integral of  $f$  with respect to arc length”

(b)  $\int_C f(x, y, z) dx = \int_a^b f(x(t), y(t), z(t)) x'(t) dt$

(c)  $\int_C f(x, y, z) dy = \int_a^b f(x(t), y(t), z(t)) y'(t) dt$

(d)  $\int_C f(x, y, z) dz = \int_a^b f(x(t), y(t), z(t)) z'(t) dt$

2. Line integral of vector field  $\mathbf{F}(x, y, z)$  along  $C$ , parameterized by  $\mathbf{r}(t)$  and  $a \leq t \leq b$ , is given by

$$\int_C \mathbf{F} \cdot d\mathbf{r} = \int_a^b \mathbf{F}(\mathbf{r}(t)) \cdot \mathbf{r}'(t) dt.$$

(depends on orientation of  $C$ , other properties and applications of line integrals of  $f$ )

3. Connection between line integral of vector fields and line integral of functions:

$$\int_C \mathbf{F} \cdot d\mathbf{r} = \int_C (\mathbf{F} \cdot \mathbf{T}) ds$$

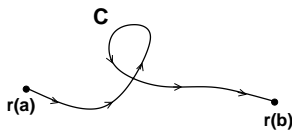
where  $\mathbf{T}$  is the unit tangent vector to the curve  $C$ .

4. If  $\mathbf{F}(x, y, z) = P(x, y, z)\mathbf{i} + Q(x, y, z)\mathbf{j} + R(x, y, z)\mathbf{k}$ , then

$$\int_C \mathbf{F} \cdot d\mathbf{r} = \int_C P(x, y, z) dx + Q(x, y, z) dy + R(x, y, z) dz;$$

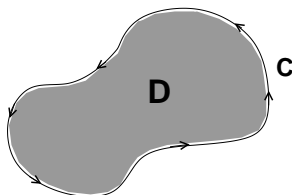
Work =  $\int_C \mathbf{F} \cdot d\mathbf{r}$ .

5. FUNDAMENTAL THEOREM OF CALCULUS FOR LINE INTEGRALS:  $\int_C \nabla f \cdot d\mathbf{r} = f(\mathbf{r}(b)) - f(\mathbf{r}(a))$ :



6. A vector field  $\mathbf{F}(x, y) = P(x, y)\mathbf{i} + Q(x, y)\mathbf{j}$  is *conservative* (i.e.  $\mathbf{F} = \nabla f$ ) if  $\frac{\partial Q}{\partial x} = \frac{\partial P}{\partial y}$ . If  $\mathbf{F}(\mathbf{x}) = \nabla f(\mathbf{x})$ , then  $f_x = P$  and  $f_y = Q$ . Start out with integrating one of the equation and use the other to get the constant. Similarly, a vector field  $\mathbf{F}(x, y, z) = P(x, y, z)\mathbf{i} + Q(x, y, z)\mathbf{j} + R(x, y, z)\mathbf{k}$  is *conservative* (i.e.  $\mathbf{F} = \nabla f$ ) if  $\frac{\partial^2 P}{\partial y \partial z} = \frac{\partial^2 Q}{\partial x \partial z} = \frac{\partial^2 R}{\partial x \partial y}$ .

7. GREEN'S THEOREM:  $\int_C P(x, y) dx + Q(x, y) dy = \iint_D \left( \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dA$  ( $C =$  boundary of  $D$ ):



As a consequence of Green's Theorem one has

$$\frac{1}{2} \int_C x dy - y dx = \int_C x dy = - \int_C y dx = \text{Area}(D)$$

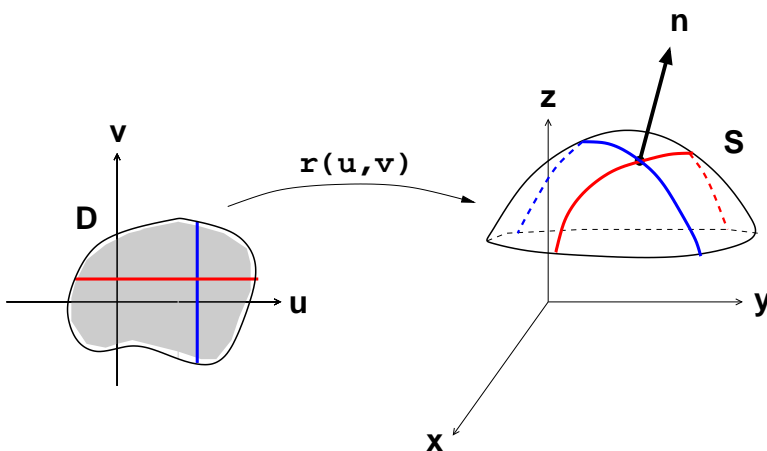
8. Del Operator:  $\frac{\partial}{\partial x} \mathbf{i} + \frac{\partial}{\partial y} \mathbf{j} + \frac{\partial}{\partial z} \mathbf{k}$ ; if  $\mathbf{F}(x, y, z) = P(x, y, z)\mathbf{i} + Q(x, y, z)\mathbf{j} + R(x, y, z)\mathbf{k}$ , then

$$\text{curl } \mathbf{F} = \nabla \times \mathbf{F} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ P & Q & R \end{vmatrix} \quad \text{and} \quad \text{div } \mathbf{F} = \nabla \cdot \mathbf{F} = \frac{\partial P}{\partial x} + \frac{\partial Q}{\partial y} + \frac{\partial R}{\partial z}$$

Note that  $\text{curl}(\nabla f) = 0$ . Some properties of curl and divergence:

- (i) If  $\text{curl } \mathbf{F} = \mathbf{0}$ , then  $\mathbf{F}$  is a conservative vector field (i.e.,  $\mathbf{F}(\mathbf{x}) = \nabla f(\mathbf{x})$ ).
- (ii) If  $\text{curl } \mathbf{F} = \mathbf{0}$ , then  $\mathbf{F}$  is *irrotational*; if  $\text{div } \mathbf{F} = 0$ , then  $\mathbf{F}$  is *incompressible*.

9. Parametric surface  $S$ :  $\mathbf{r}(u, v) = \langle x(u, v), y(u, v), z(u, v) \rangle$ , where  $(u, v) \in D$ :



Normal vector to surface  $S$  :  $\mathbf{n} = \mathbf{r}_u \times \mathbf{r}_v$ ; tangent planes and normal lines to parametric surfaces.

**10.** Surface area of a surface  $S$ :

(i)  $A(S) = \iint_D dS = \iint_D |\mathbf{r}_u \times \mathbf{r}_v| dA$

(ii) If  $S$  is the graph of  $z = h(x, y)$  above  $D$ , then  $A(S) = \iint_D \sqrt{1 + \left(\frac{\partial h}{\partial x}\right)^2 + \left(\frac{\partial h}{\partial y}\right)^2} dA$ .

(iii) If  $S$  is the surface of revolution obtained from  $y = f(x)$  revolving about the  $x$ -axis,  $a \leq x \leq b$ , then

$$\mathbf{r}(x, \theta) = \langle x, f(x) \cos \theta, f(x) \sin \theta \rangle, \quad D = \{(x, \theta) \mid a \leq x \leq b, 0 \leq \theta \leq 2\pi\}.$$

Then

$$|\mathbf{r}_x \times \mathbf{r}_\theta| = f(x) \sqrt{1 + [f'(x)]^2}$$

Then the area of  $S$  becomes:

$$A(s) = \int_0^{2\pi} \int_a^b f(x) \sqrt{1 + [f'(x)]^2} dx d\theta = 2\pi \int_a^b f(x) \sqrt{1 + [f'(x)]^2} dx.$$

Remark:  $dS = |\mathbf{r}_u \times \mathbf{r}_v| dA$  = differential of surface area; while  $d\mathbf{S} = (\mathbf{r}_u \times \mathbf{r}_v) dA$

**11.** The surface integral of  $f(x, y, z)$  over the surface  $S$ :

(i)  $\iint_S f(x, y, z) dS = \iint_D f(\mathbf{r}(u, v)) |\mathbf{r}_u \times \mathbf{r}_v| dA$ .

(ii) If  $S$  is the graph of  $z = h(x, y)$  above  $D$ , then

$$\iint_S f(x, y, z) dS = \iint_D f(x, y, h(x, y)) \sqrt{1 + \left(\frac{\partial h}{\partial x}\right)^2 + \left(\frac{\partial h}{\partial y}\right)^2} dA.$$

**12.** Recall,

$$\mathbf{n} = \frac{\mathbf{r}_u \times \mathbf{r}_v}{|\mathbf{r}_u \times \mathbf{r}_v|}, \quad d\mathbf{S} = (\mathbf{r}_u \times \mathbf{r}_v) dA = \frac{\mathbf{r}_u \times \mathbf{r}_v}{|\mathbf{r}_u \times \mathbf{r}_v|} (|\mathbf{r}_u \times \mathbf{r}_v| dA) = \mathbf{n} dS.$$

The surface integral of  $\mathbf{F}$  over the surface  $S$

$$\iint_S \mathbf{F} \cdot d\mathbf{S} = \iint_D \mathbf{F}(\mathbf{r}(u, v)) \cdot (\mathbf{r}_u \times \mathbf{r}_v) dA = \iint_S (\mathbf{F} \cdot \mathbf{n}) dS$$

If  $S$  is the graph of  $z = h(x, y)$  above  $D$ , with  $\mathbf{n}$  oriented upward, and  $\mathbf{F} = \langle P, Q, R \rangle$ , then

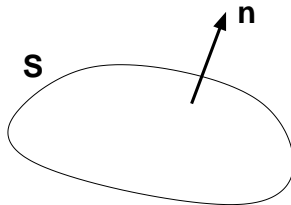
$$\iint_S \mathbf{F} \cdot d\mathbf{S} = \iint_D \left( -P \frac{\partial h}{\partial x} - Q \frac{\partial h}{\partial y} + R \right) dA.$$

(i) Connection between surface integral of a vector field and a function:

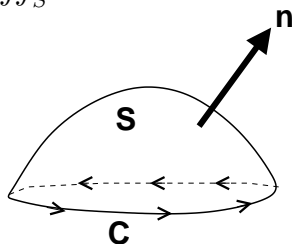
$$\iint_S \mathbf{F} \cdot d\mathbf{S} = \iint_S (\mathbf{F} \cdot \mathbf{n}) dS.$$

The above gives another way to compute  $\iint_S \mathbf{F} \cdot d\mathbf{S}$ .

(ii)  $\iint_S \mathbf{F} \cdot d\mathbf{S} = \iint_S (\mathbf{F} \cdot \mathbf{n}) dS = \underline{\text{flux}}$  of  $\mathbf{F}$  across the surface  $S$ .



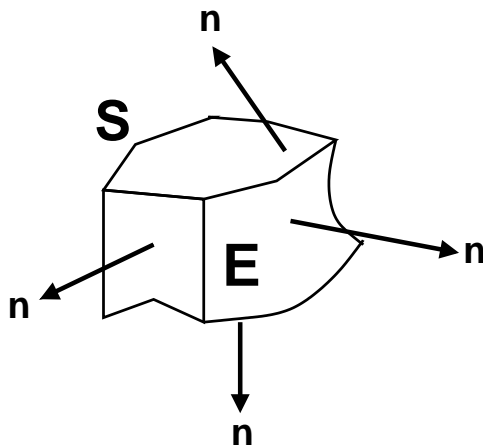
**13. STOKES' THEOREM:**  $\int_C \mathbf{F} \cdot d\mathbf{r} = \iint_S \text{curl } \mathbf{F} \cdot d\mathbf{S}$  (recall,  $\text{curl } \mathbf{F} = \nabla \times \mathbf{F}$ ).



$\int_C \mathbf{F} \cdot d\mathbf{r} = \text{circulation of } \mathbf{F} \text{ around } C.$

**14. THE DIVERGENCE THEOREM/GAUSS' THEOREM:**  $\iint_S \mathbf{F} \cdot d\mathbf{S} = \iiint_E \text{div } \mathbf{F} \, dV$

(recall,  $\text{div } \mathbf{F} = \nabla \cdot \mathbf{F}$ ).



**15.** Summary of Line Integrals and Surface Integrals:

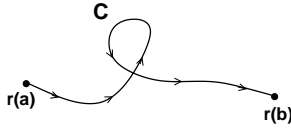
LINE INTEGRALS	SURFACE INTEGRALS
$C : \mathbf{r}(t)$ , where $a \leq t \leq b$	$S : \mathbf{r}(u, v)$ , where $(u, v) \in D$
$ds =  \mathbf{r}'(t)  dt =$ differential of arc length	$dS =  \mathbf{r}_u \times \mathbf{r}_v  dA =$ differential of surface area
$\int_C ds =$ length of $C$	$\iint_S dS =$ surface area of $S$
$\int_C f(x, y, z) ds = \int_a^b f(\mathbf{r}(t))  \mathbf{r}'(t)  dt$ (independent of orientation of $C$ )	$\iint_S f(x, y, z) dS = \iint_D f(\mathbf{r}(u, v))  \mathbf{r}_u \times \mathbf{r}_v  dA$ (independent of normal vector $\mathbf{n}$ )
$d\mathbf{r} = \mathbf{r}'(t) dt$	$d\mathbf{S} = (\mathbf{r}_u \times \mathbf{r}_v) dA$
$\int_C \mathbf{F} \cdot d\mathbf{r} = \int_a^b \mathbf{F}(\mathbf{r}(t)) \cdot \mathbf{r}'(t) dt$ (depends on orientation of $C$ )	$\iint_S \mathbf{F} \cdot d\mathbf{S} = \iint_D \mathbf{F}(\mathbf{r}(u, v)) \cdot (\mathbf{r}_u \times \mathbf{r}_v) dA$ depends on normal vector $\mathbf{n} = \frac{\mathbf{r}_u \times \mathbf{r}_v}{ \mathbf{r}_u \times \mathbf{r}_v }$
$\int_C \mathbf{F} \cdot d\mathbf{r} = \int_C (\mathbf{F} \cdot \mathbf{T}) ds$ The <i>circulation</i> of $\mathbf{F}$ around $C$	$\iint_S \mathbf{F} \cdot d\mathbf{S} = \iint_S (\mathbf{F} \cdot \mathbf{n}) dS$ The <i>flux</i> of $\mathbf{F}$ across $S$ in direction $\mathbf{n}$

## 16. Integration Theorems:

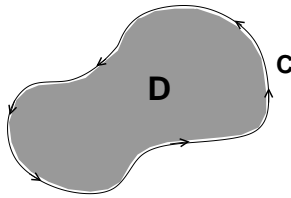
FUNDAMENTAL THEOREM OF CALCULUS:  $\int_a^b F'(x) dx = F(b) - F(a)$

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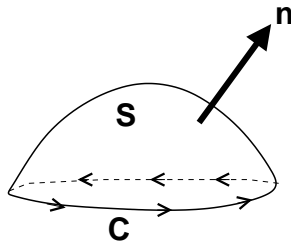
FUNDAMENTAL THEOREM OF CALCULUS FOR LINE INTEGRALS:  $\int_a^b \nabla f \cdot d\mathbf{r} = f(\mathbf{r}(b)) - f(\mathbf{r}(a))$



GREEN'S THEOREM:  $\iint_D \left( \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dA = \int_C P(x, y) dx + Q(x, y) dy$



STOKES' THEOREM:  $\iint_S \text{curl } \mathbf{F} \cdot d\mathbf{S} = \int_C \mathbf{F} \cdot d\mathbf{r}$



DIVERGENCE THEOREM:  $\iiint_E \text{div } \mathbf{F} dV = \iint_S \mathbf{F} \cdot d\mathbf{S}$

