

**Study Guide # 3****You also need Study Guides # 1 and # 2 for the Final Exam**

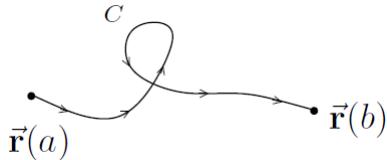
- 0.** Line integral of a vector field  $\vec{\mathbf{F}}(x, y, z) = P(x, y, z)\vec{\mathbf{i}} + Q(x, y, z)\vec{\mathbf{j}} + R(x, y, z)\vec{\mathbf{k}}$  along an *oriented* curve  $C$ , parameterized by  $\vec{\mathbf{r}}(t) = \langle x(t), y(t), z(t) \rangle$  and  $a \leq t \leq b$ , is

$$\int_C \vec{\mathbf{F}} \cdot d\vec{\mathbf{r}} = \int_C (\vec{\mathbf{F}} \cdot \vec{\mathbf{T}}) ds = \int_C P dx + Q dy + R dz = \int_a^b \vec{\mathbf{F}}(\vec{\mathbf{r}}(t)) \cdot \vec{\mathbf{r}}'(t) dt$$

where  $\vec{\mathbf{T}}(t) = \vec{\mathbf{r}}'/|\vec{\mathbf{r}}'|$  is the unit tangent vector.

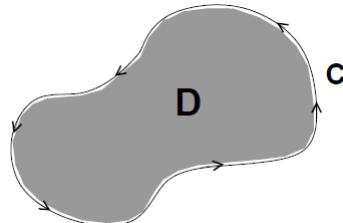
(dependent of orientation of  $C$ , other properties and applications of line integrals of  $\vec{\mathbf{F}}$ )

- 1.** FUNDAMENTAL THEOREM OF CALCULUS FOR LINE INTEGRALS:  $\int_C \nabla f \cdot d\vec{\mathbf{r}} = f(\vec{\mathbf{r}}(b)) - f(\vec{\mathbf{r}}(a))$ :



- 2.** A vector field  $\vec{\mathbf{F}}(x, y) = P(x, y)\vec{\mathbf{i}} + Q(x, y)\vec{\mathbf{j}}$  is *conservative* (i.e.  $\vec{\mathbf{F}} = \nabla f$ ) if  $\frac{\partial Q}{\partial x} = \frac{\partial P}{\partial y}$ ;  
how to determine a potential function  $f$  if  $\vec{\mathbf{F}} = \nabla f$ .

- 3.** GREEN'S THEOREM:  $\int_C P(x, y) dx + Q(x, y) dy = \iint_D \left( \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dA$  ( $C$  = boundary of  $D$ ):



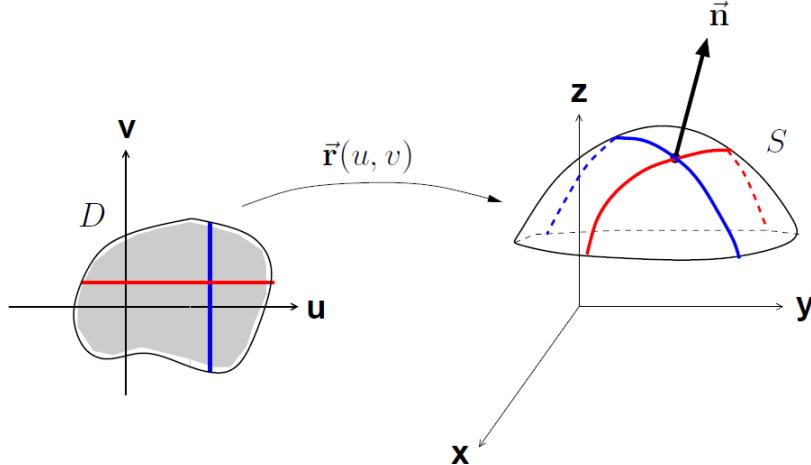
- 4.** DEL OPERATOR:  $\nabla = \frac{\partial}{\partial x}\vec{\mathbf{i}} + \frac{\partial}{\partial y}\vec{\mathbf{j}} + \frac{\partial}{\partial z}\vec{\mathbf{k}}$ ; if  $\vec{\mathbf{F}}(x, y, z) = P(x, y, z)\vec{\mathbf{i}} + Q(x, y, z)\vec{\mathbf{j}} + R(x, y, z)\vec{\mathbf{k}}$ , then

$$\text{curl } \vec{\mathbf{F}} = \nabla \times \vec{\mathbf{F}} = \begin{vmatrix} \vec{\mathbf{i}} & \vec{\mathbf{j}} & \vec{\mathbf{k}} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ P & Q & R \end{vmatrix} \quad \text{and} \quad \text{div } \vec{\mathbf{F}} = \nabla \cdot \vec{\mathbf{F}} = \frac{\partial P}{\partial x} + \frac{\partial Q}{\partial y} + \frac{\partial R}{\partial z}$$

Properties of curl and divergence:

- (i) If  $\operatorname{curl} \vec{\mathbf{F}} = \vec{0}$ , then  $\vec{\mathbf{F}}$  is a conservative vector field ( $\vec{\mathbf{F}} = \nabla f$ ) in a simply-connected domain.
- (ii) If  $\operatorname{curl} \vec{\mathbf{F}} = \vec{0}$ , then  $\vec{\mathbf{F}}$  is *irrotational*; if  $\operatorname{div} \vec{\mathbf{F}} = 0$ , then  $\vec{\mathbf{F}}$  is *incompressible*.
- (iii) *Laplace's Equation:*  $\nabla^2 f = \operatorname{div}(\nabla f) = \frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2} + \frac{\partial^2 f}{\partial z^2} = 0$ .
- (iv) For functions with continuous partials,  $\operatorname{curl}(\nabla f) = \vec{0}$ , and  $\operatorname{div}(\operatorname{curl} \vec{\mathbf{F}}) = 0$ .

**5.** Parametric surface  $S$ :  $\vec{\mathbf{r}}(u, v) = \langle x(u, v), y(u, v), z(u, v) \rangle$ , where  $(u, v) \in D$ :



Normal vector to surface  $S$ :  $\vec{\mathbf{n}} = \vec{\mathbf{r}}_u \times \vec{\mathbf{r}}_v$ ; tangent planes and normal lines to parametric surfaces.

**6.** Surface area of a surface  $S$ :

- (i)  $A(S) = \iint_D |\vec{\mathbf{r}}_u \times \vec{\mathbf{r}}_v| dA$
- (ii) If  $S$  is the graph of  $z = h(x, y)$  above  $D$ , then  $A(S) = \iint_D \sqrt{1 + (\partial h / \partial x)^2 + (\partial h / \partial y)^2} dA$ ;

Remark:  $dS = |\vec{\mathbf{r}}_u \times \vec{\mathbf{r}}_v| dA$  = differential of surface area; while  $d\vec{\mathbf{S}} = (\vec{\mathbf{r}}_u \times \vec{\mathbf{r}}_v) dA$

**7.** The surface integral of  $f$  over the surface  $S$ :

- (i)  $\iint_S f(x, y, z) dS = \iint_D f(\vec{\mathbf{r}}(u, v)) |\vec{\mathbf{r}}_u \times \vec{\mathbf{r}}_v| dA$ .
- (ii) If  $S$  is the graph of  $z = h(x, y)$  above  $D$ , then  

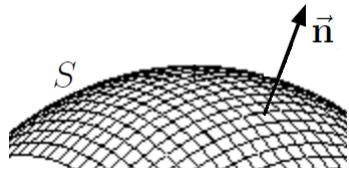
$$\iint_S f(x, y, z) dS = \iint_D f(x, y, h(x, y)) \sqrt{1 + (\partial h / \partial x)^2 + (\partial h / \partial y)^2} dA.$$

**8.** The surface integral of  $\vec{\mathbf{F}}$  over the surface  $S$  (recall,  $d\vec{\mathbf{S}} = (\vec{\mathbf{r}}_u \times \vec{\mathbf{r}}_v) dA$ ):

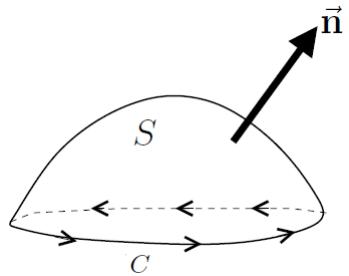
$$\iint_S \vec{\mathbf{F}} \cdot d\vec{\mathbf{S}} = \iint_D \vec{\mathbf{F}} \cdot (\vec{\mathbf{r}}_u \times \vec{\mathbf{r}}_v) dA = \iint_S (\vec{\mathbf{F}} \cdot \vec{\mathbf{n}}) dS = \text{flux of } \vec{\mathbf{F}} \text{ across the surface } S.$$

If  $S$  is the graph of  $z = h(x, y)$  above  $D$ , with  $\vec{\mathbf{n}}$  oriented upward, and  $\vec{\mathbf{F}} = \langle P, Q, R \rangle$ , then

$$\iint_S \vec{\mathbf{F}} \cdot d\vec{\mathbf{S}} = \iint_D \left( -P \frac{\partial h}{\partial x} - Q \frac{\partial h}{\partial y} + R \right) dA$$

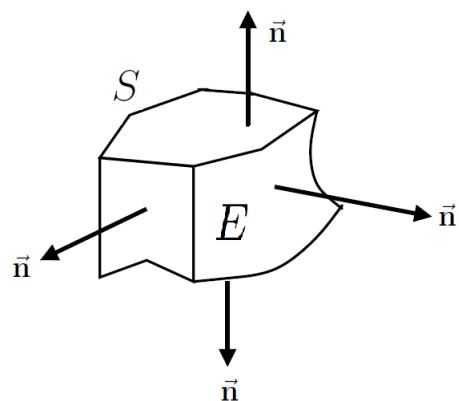


**9. STOKES' THEOREM:**  $\int_C \vec{F} \cdot d\vec{r} = \iint_S \text{curl } \vec{F} \cdot d\vec{S}$  (recall,  $\text{curl } \vec{F} = \nabla \times \vec{F}$ ).



$\int_C \vec{F} \cdot d\vec{r} = \text{circulation}$  of  $\vec{F}$  around \$C\$.

**10. THE DIVERGENCE THEOREM/GAUSS' THEOREM:**  $\iint_S \vec{F} \cdot d\vec{S} = \iiint_E \text{div } \vec{F} \, dV$   
 (recall,  $\text{div } \vec{F} = \nabla \cdot \vec{F}$ ).

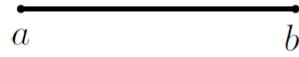


## 11. Summary of Line Integrals and Surface Integrals:

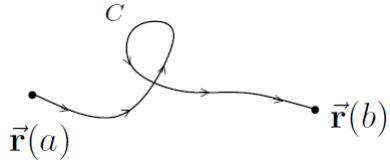
LINE INTEGRALS	SURFACE INTEGRALS
$C : \vec{r}(t)$ , where $a \leq t \leq b$	$S : \vec{r}(u, v)$ , where $(u, v) \in D$
$ds =  \vec{r}'(t)  dt =$ differential of arc length	$dS =  \vec{r}_u \times \vec{r}_v  dA =$ differential of surface area
$\int_C ds =$ length of $C$	$\iint_S dS =$ surface area of $S$
$\int_C f(x, y, z) ds = \int_a^b f(\vec{r}(t))  \vec{r}'(t)  dt$ (independent of orientation of $C$ )	$\iint_S f(x, y, z) dS = \iint_D f(\vec{r}(u, v))  \vec{r}_u \times \vec{r}_v  dA$ (independent of normal vector $\vec{n}$ )
$d\vec{r} = \vec{r}'(t) dt$	$d\vec{S} = (\vec{r}_u \times \vec{r}_v) dA$
$\int_C \vec{F} \cdot d\vec{r} = \int_a^b \vec{F}(\vec{r}(t)) \cdot \vec{r}'(t) dt$ (depends on orientation of $C$ )	$\iint_S \vec{F} \cdot d\vec{S} = \iint_D \vec{F}(\vec{r}(u, v)) \cdot (\vec{r}_u \times \vec{r}_v) dA$ (depends on normal vector $\vec{n}$ )
$\int_C \vec{F} \cdot d\vec{r} = \int_C (\vec{F} \cdot \vec{T}) ds$ The <i>circulation</i> of $\vec{F}$ around $C$	$\iint_S \vec{F} \cdot d\vec{S} = \iint_S (\vec{F} \cdot \vec{n}) dS$ The <i>flux</i> of $\vec{F}$ across $S$ in direction $\vec{n}$

## 12. Integration Theorems:

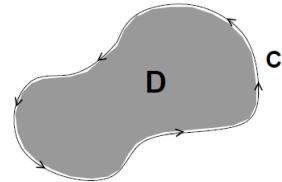
FUNDAMENTAL THEOREM OF CALCULUS:  $\int_a^b F'(x) dx = F(b) - F(a)$



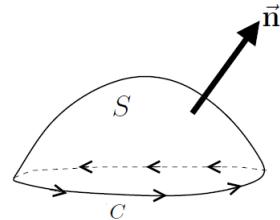
FUNDAMENTAL THEOREM OF CALCULUS FOR LINE INTEGRALS:  $\int_a^b \nabla f \cdot d\vec{r} = f(\vec{r}(b)) - f(\vec{r}(a))$



GREEN'S THEOREM:  $\iint_D \left( \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dA = \int_C P(x, y) dx + Q(x, y) dy$



STOKES' THEOREM:  $\iint_S \text{curl } \vec{F} \cdot d\vec{S} = \int_C \vec{F} \cdot d\vec{r}$



DIVERGENCE THEOREM:  $\iiint_E \text{div } \vec{F} dV = \iint_S \vec{F} \cdot d\vec{S}$

