From the Peierls-Nabarro model to the equation of motion of the dislocation continuum

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Geometric and functional inequalities and recent topics in nonlinear PDEs,
February 28th & March 1st, 2021
Main problem

We study the limit as $\epsilon \to 0$ of the solution $u^\epsilon$ of the following fractional reaction-diffusion PDE:

$$
\begin{cases}
\delta \partial_t u^\epsilon = -(-\Delta)^{\frac{1}{2}} u^\epsilon - \frac{1}{\delta} \mathcal{W}' \left( \frac{u^\epsilon}{\epsilon} \right) & \text{in } \mathbb{R}^+ \times \mathbb{R} \\
u^\epsilon(0, \cdot) = u_0(\cdot) & \text{on } \mathbb{R}
\end{cases}
$$

where $\epsilon, \delta > 0$ are small scale parameters and $\delta = \delta_\epsilon \to 0$ as $\epsilon \to 0$, $\mathcal{W}$ is a multi-well potential with nondegenerate minima at integer points and $u_0$ is non-decreasing.
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where $\epsilon, \delta > 0$ are small scale parameters and $\delta = \delta_\epsilon \to 0$ as $\epsilon \to 0$, $W$ is a multi-well potential with nondegenerate minima at integer points and $u_0$ is non-decreasing.

- If $\epsilon = 1$, (1) is a fractional Allen-Cahn problem (González-Monneau);
- If $\delta = 1$, (1) is a homogenization problem (Monneau-P.);
- We do not assume any assumption about how $\delta$ goes to 0 when $\epsilon \to 0$. 

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Classical Allen-Cahn equation (Chen): for $n \geq 2$,

$$\partial_t u^\delta = \Delta u^\delta - \frac{1}{\delta} W'(u^\delta) \quad \text{in } \mathbb{R}^+ \times \mathbb{R}^n$$

with a suitable initial condition, $u^\delta(0, x) = u_0(x), 0 < u_0 < 1$, where $W$ is a double well potential with minima at 0 and 1.

- $n=1$, works by Fife and co.
- The stationary case previously studied by Modica and Mortola.
When $\Delta$ is replaced by $-(-\Delta)^s u$, $s \in (0, 1)$, the motion of forming interphases in dimension $n \geq 2$ studied by Imbert, Souganidis;

Stationary case, $n \geq 2$: Savin, Valdinoci (non-local version of Modica-Mortola);

In dimension 1, Gonzalez and Monneau studied

$$\delta \partial_t \nu^\delta = -(-\Delta)^{1/2} \nu^\delta - \frac{1}{\delta} W'(\nu^\delta) \quad \text{in } \mathbb{R}^+ \times \mathbb{R}$$

with a well-prepared initial condition. Here $W$ is a multi-well potential.
Dislocations are defect lines in crystalline solids whose motion is directly responsible for the plastic deformation of these materials. Their typical length is of order of $10^{-6} m$ with thickness of order of $10^{-9} m$.

Geometry of an edge dislocation

(a) Dislocation line in a crystal lattice. (b) Schematic representation of a stair-step edge dislocation.
Dislocations can be described at several scales by different models:

1. atomic scale (Frenkel-Kontorova model)
2. microscopic scale (Peierls-Nabarro model)
3. mesoscopic scale (Discrete dislocation dynamics)
4. macroscopic scale (elasto-visco-plasticity with density of dislocations)
We consider a straight dislocation line parallel to $e_3$.

Assumptions

- The dislocation defects are described by the mismatch between the two planes $I_2 = 0$ and $I_2 = -1$.
- The displacement of the crystal is antysymmetric wrt the plane $e_1e_3$.
- Any atoms move only in the direction $e_1$.
- The displacement is independent of $e_3$.
The Peierls-Nabarro model

The P-N model is a *continuous* model where a dislocation is described by means of a scalar phase field defined over the slip plane.

The medium will be $\mathbb{R}^2$, endowed with coordinates $(x, y)$.

The disregistry of the upper half crystal $\{y > 0\}$ relative to the lower half $\{y < 0\}$ is given by $\phi(x)$, which is a transition between 0 and 1:

\[
\begin{align*}
\phi(-\infty) &= 0, & \phi(+\infty) &= 1 \\
\phi' &> 0.
\end{align*}
\]
The total energy is given by

\[ \mathcal{E} = \frac{1}{2} \int_{\mathbb{R} \times \mathbb{R}^+} |\nabla U(x, y)|^2 \, dx \, dy + \int_{\mathbb{R}} W(U(x, 0)) \, dx \]

where \( U : \mathbb{R} \times \mathbb{R}^+ \to \mathbb{R} \) represents (twice) the (scalar) displacement and it is such that \( U(x, 0) = \phi(x) \).

The potential \( W \) satisfies

- \( W(u + 1) = W(u) \quad \forall u \in \mathbb{R} \) (periodicity)
- \( W(\mathbb{Z}) = 0 < W(u) \quad \forall u \in \mathbb{R} \setminus \mathbb{Z} \) (minimum property)
The Peierls-Nabarro model

A critical point of the energy satisfies

\[
\begin{align*}
\Delta U(x, y) &= 0 \quad (x, y) \in \mathbb{R} \times \mathbb{R}^+ \\
\partial_y U(x, 0) &= W'(U(x, 0)) \quad x \in \mathbb{R}
\end{align*}
\]
The Peierls-Nabarro model

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\end{cases}
\]

The system can be rewritten for

\[\phi(x) = U(x, 0)\]

as follows

\[-(-\Delta)^{\frac{1}{2}} \phi = W'(\phi) \quad \text{in} \quad \mathbb{R}\]

where

\[(-\Delta)^{\frac{1}{2}} v = \mathcal{F}^{-1}(|\xi|\mathcal{F}(v)) \quad \text{for any} \quad v \in S(\mathbb{R}^n)\]

and \(\mathcal{F}\) is the Fourier transform. If \(v \in C^{1,1}_{loc}(\mathbb{R}) \cap L^\infty(\mathbb{R})\), \(n = 1\),

\[-(-\Delta)^{\frac{1}{2}} v = PV \frac{1}{\pi} \int_\mathbb{R} \frac{v(y) - v(x)}{(y - x)^2} \, dy\]
In the original PN model:

\[ W(u) = \frac{1}{4} \pi^2 (1 - \cos(2\pi u)) \]

and

\[ \phi(x) = \frac{1}{2} + \frac{1}{\pi} \arctan(2x) \]

The phase transition \( \phi \) (also called layer solution) therefore satisfies

\[
\begin{cases}
-(-\Delta)^{\frac{1}{2}} \phi = W'(\phi) & \text{in } \mathbb{R} \\
\phi' > 0 \\
\phi(-\infty) = 0, \quad \phi(+\infty) = 1, \quad \phi(0) = \frac{1}{2}
\end{cases}
\]
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\end{cases}
\]

- Existence, uniqueness by Cabré, Sòla-Morales. Asymptotic estimates by González, Monneau;
- When \(-(-\Delta)^{\frac{1}{2}}\) is replaced by \(-(-\Delta)^s\), \(s \in (0, 1)\), existence, uniqueness and asymptotic estimates are proven in a series of paper by Cabré, Sire, Dipierro, Figalli, Palatucci, Savin, Valdinoci.
Evolutive PN-model

Suppose that there are $N$ straight edge dislocations lines all lying in the same plane:

After a cross section:
The dynamics for an ensemble of $N$ straight dislocations lines with the same Burgers’ vector and all contained in a single slip plane, moving with self-interactions (no exterior forces) is described by the evolutive version of the Peierls-Nabarro model:

$$\partial_t u = -(-\Delta)^{\frac{1}{2}} u - W'(u) \quad \text{in } \mathbb{R}^+ \times \mathbb{R}.$$
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$$\partial_t u = -(-\Delta)^{1/2} u - W'(u) \quad \text{in } \mathbb{R}^+ \times \mathbb{R}.$$  

with the following initial condition

$$u(0, x) = \sum_{i=1}^{N} \phi \left( x - \frac{y_i^0}{\delta} \right),$$

where $\phi$ is the transition layer introduced before and $0 \leq y_{i+1}^0 - y_i^0 \lesssim 1$. 
Consider the following rescaling

\[ v^\delta(t, x) = u \left( \frac{t}{\delta^2}, \frac{x}{\delta} \right) \]

Then, \( v^\delta \) is solution of the fractional Allen-Cahn type equation:

\[ \delta \partial_t v^\delta = - (-\Delta)^{\frac{1}{2}} v - \frac{1}{\delta} W'(v) \quad \text{in} \quad \mathbb{R}^+ \times \mathbb{R} \]

associated to the well-prepared initial condition:

\[ v^\delta(0, x) = \sum_{i=1}^{N} \phi \left( \frac{x - y_i^0}{\delta} \right). \]
González and Monneau proved that the solution $v^\delta$ converges, as $\delta \to 0$ to the stable minima of $W$, i.e. integers. More precisely,

$$v^\delta(t, x) \to \sum_{i=1}^{N} H(x - y_i(t)),$$

where $H$ is the Heaviside function and the interface points $y_i(t)$, $i = 1, \ldots, N$ evolve in time driven by the following system of ODE’s:

$$\begin{cases}
\dot{y}_i = \frac{c_0}{\pi} \sum_{j \neq i} \frac{1}{y_i - y_j} & \text{in } (0, +\infty) \\
y_i(0) = y_i^0,
\end{cases}$$

(2)

where $c_0 = \left(\int_{\mathbb{R}} (\phi')^2\right)^{-1}$. System (2) corresponds to the classical discrete dislocation dynamics (DDD).
Fractional Allen-Cahn equation
In our paper we consider the case $N \to +\infty$. Precisely,

$$N = N_\varepsilon \simeq \frac{1}{\varepsilon}.$$ 

that is

$$\partial_t u = -(-\Delta)^{\frac{1}{2}} u - W'(u) \quad \text{in } \mathbb{R} \times \mathbb{R}^+,$$ 

$$u(0, x) = \sum_{i=1}^{N_\varepsilon} \phi \left(x - \frac{y_i^0}{\delta}\right),$$

We want to identify at large (macroscopic) scale the evolution model for the dynamics of a density of dislocations.
We consider the following rescaling

\[ u^\epsilon(t, x) = \epsilon u \left( \frac{t}{\epsilon \delta^2}, \frac{x}{\epsilon \delta} \right), \]

then we see that \( u^\epsilon \) is solution of

\[ \delta \partial_t u^\epsilon = -(-\Delta)^{\frac{1}{2}} u^\epsilon - \frac{1}{\delta} W' \left( \frac{u^\epsilon}{\epsilon} \right) \quad \text{in} \ (0, +\infty) \times \mathbb{R} \]

with initial datum

\[ u^\epsilon(0, x) = \sum_{i=1}^{N_\epsilon} \epsilon \phi \left( \frac{x - \epsilon y_i}{\epsilon \delta} \right). \]
More in general, we consider

\[
\begin{cases}
\delta \partial_t u^\varepsilon = -(-\Delta)^{1/2} u^\varepsilon - \frac{1}{\delta} W' \left( \frac{u^\varepsilon}{\varepsilon} \right) & \text{in } \mathbb{R}^+ \times \mathbb{R} \\
u^\varepsilon(0, \cdot) = u_0(\cdot) & \text{on } \mathbb{R}
\end{cases}
\]

where \( \varepsilon, \delta > 0 \) are small scale parameters and \( \delta = \delta_\varepsilon \to 0 \) as \( \varepsilon \to 0 \),

\[
\begin{cases}
W \in C^{2,\beta}(\mathbb{R}) & \text{for some } 0 < \beta < 1 \\
W(u + 1) = W(u) & \text{for any } u \in \mathbb{R} \\
W = 0 & \text{on } \mathbb{Z} \\
W > 0 & \text{on } \mathbb{R} \setminus \mathbb{Z} \\
W''(0) > 0.
\end{cases}
\]

On the function \( u_0 \) we assume

\[
\begin{cases}
u_0 \in C^{1,1}(\mathbb{R}) \\
u_0 \text{ non-decreasing.}
\end{cases}
\]
Main result

\[
\begin{cases}
\delta \partial_t u^\varepsilon = -(-\Delta)^{\frac{1}{2}} u^\varepsilon - \frac{1}{\delta} W' \left( \frac{u^\varepsilon}{\varepsilon} \right) & \text{in } \mathbb{R}^+ \times \mathbb{R} \\
u^\varepsilon(0, \cdot) = u_0(\cdot) & \text{on } \mathbb{R}
\end{cases}
\quad (3)
\]

Theorem

Let \( u^\varepsilon \) be the viscosity solution of (3). Then, as \( \varepsilon \to 0 \), \( u^\varepsilon \) converges locally uniformly in \( (0, +\infty) \times \mathbb{R} \) to the non-decreasing viscosity solution of

\[
\begin{cases}
\partial_t u = -c_0 \partial_x u(-\Delta)^{\frac{1}{2}} u & \text{in } \mathbb{R}^+ \times \mathbb{R} \\
u(0, \cdot) = u_0 & \text{on } \mathbb{R}
\end{cases}
\quad (4)
\]

where \( c_0 = \left( \int_{\mathbb{R}} (\phi')^2 \right)^{-1} \).
Mechanical interpretation of the convergence result

The limit equation

\[
\begin{cases}
\partial_t u = -c_0 \partial_x u (-\Delta)^{1/2} u & \text{in } \mathbb{R}^+ \times \mathbb{R} \\
u(0, \cdot) = u_0 & \text{on } \mathbb{R}
\end{cases}
\]

represents the plastic flow rule for the macroscopic crystal plasticity with density of dislocations.

- \(u\) is the plastic strain
- \(\partial_t u\) is the plastic strain velocity;
- \(\partial_x u\) is the dislocation density;
- \(-(-\Delta)^{1/2} u\) is the internal stress created by the density of dislocations contained in a slip plane.

The theorem says that in this regime, the plastic strain velocity \(\partial_t u\) is proportional to the dislocation density \(u_x\) times the effective stress \(-(-\Delta)^{1/2} u\). This physical law is known as Orowan’s equation.
Equation

\[ \partial_t u = -c_0 \partial_x u (-\Delta)^{\frac{1}{2}} u \]  \hfill (5)

is an integrated form of a model studied by Head for the self-dynamics of a dislocation density represented by \( u_x \)

Equation
\[ \partial_t u = -c_0 \partial_x u (-\Delta)^{\frac{1}{2}} u \] \hspace{1cm} (5)
is an integrated form of a model studied by Head for the self-dynamics of a dislocation density represented by \( u_x \)


Let \( f = u_x \), differentiating (5), we get
\[ \partial_t f = c_0 \partial_x (f \mathcal{H}[f]) \]
where \( \mathcal{H} \) is Hilbert transform defined in Fourier variables by
\[ \mathcal{F}(\mathcal{H}[v])(\xi) = i \text{sgn}(\xi) \mathcal{F}(v)(\xi), \]
for \( v \in S(\mathbb{R}) \). The Hilbert transform has the representation formula
\[ \mathcal{H}[v](x) = \frac{1}{\pi} \text{PV} \int_{\mathbb{R}} \frac{v(y)}{y-x} \, dy \]
and if \( u \in C^{1,\alpha}(\mathbb{R}) \) and \( u_x \in L^p(\mathbb{R}) \) with \( 1 < p < +\infty \), then
\[ -(-\Delta)^{\frac{1}{2}} u = \mathcal{H}[u_x]. \] \hspace{1cm} (6)
The equation of motion of the dislocation continuum

Equation

\[ \partial_t f = c_0 \partial_x (f \mathcal{H}[f]) \]  \hspace{1cm} (7)

is called by Head the equation of motion of the dislocation continuum.
The equation of motion of the dislocation continuum

Equation

$$\partial_t f = c_0 \partial_x (f \mathcal{H}[f])$$

(7)

is called by Head the equation of motion of the dislocation continuum

- Existence of a smooth solution of (7) is proven by Castro and Córdoba under the assumption that the initial datum is strictly positive and in $C^\alpha(\mathbb{R}) \cap L^2(\mathbb{R})$

- Carrillo, Ferreira and Precioso apply transportation methods and show that the solution can be obtained as a gradient flow in the space of probability measures with bounded second moment.
δ = 1, homogenization problem studied by R. Monneau and S.P in any dimension.

Limit equation \( \partial_t u = \overline{H}(\nabla u, -(-\Delta)^{\frac{1}{2}} u) \), where the effective Hamiltonian \( \overline{H} \) is defined through a cell problem.

When \( n = 1, \overline{H}(p, L) \approx c_o |p|L \).

δ = 0, corresponds to the (DDD). The passage from the discrete model (DDD) to continuum models has been studied by Forcadel, Imbert and Monneau and more recently by van Meurs, Peletier, Pozar.
Let $v \in C^{1,1}(\mathbb{R})$. Assume for simplicity that $v$ is strictly increasing. Let $\epsilon > 0$ be a small parameter. Let us define the points $x_i$ as follows,

$$v(x_i) = \epsilon i, \quad i = M_\epsilon, \ldots, N_\epsilon$$

where $M_\epsilon := \left\lfloor \frac{\inf_{\mathbb{R}} v + \epsilon}{\epsilon} \right\rfloor$ and $N_\epsilon = \left\lceil \frac{\sup_{\mathbb{R}} v - \epsilon}{\epsilon} \right\rceil$. By the monotonicity of $v$ the points $x_i$ are ordered,

$$x_i < x_{i+1} \quad \text{for all } i.$$

Then, we show that

$$\left(-\Delta\right)^{\frac{1}{2}} v(x_i) \simeq -\frac{1}{\pi} \sum_{j \neq i} \frac{\epsilon}{x_i - x_j},$$

where the error goes to 0 when $\epsilon \to 0$. 

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To show it, we consider a small radius $r = r_\epsilon \to 0$ as $\epsilon \to 0$ and we split

$$
\sum_{i \neq i_0} \frac{\epsilon}{x_i - x_{i_0}} = \sum_{i \neq i_0} \left( \frac{\epsilon}{x_i - x_{i_0}} \right)_{|x_i - x_{i_0}| \leq r} + \sum_{i \neq i_0} \frac{\epsilon}{x_i - x_{i_0}} \left( \frac{\epsilon}{x_i - x_{i_0}} \right)_{|x_i - x_{i_0}| > r}.
$$
Heuristics. Approximation of $-(-\Delta)^{1/2}$

To show it, we consider a small radius $r = r_\varepsilon \to 0$ as $\varepsilon \to 0$ and we split

$$
\sum_{i \neq i_0} \frac{\varepsilon}{x_i - x_{i_0}} = \sum_{i \neq i_0} \frac{\varepsilon}{|x_i - x_{i_0}| \leq r} + \sum_{|x_i - x_{i_0}| > r} \frac{\varepsilon}{x_i - x_{i_0}}.
$$

Then, we have

$$
\frac{1}{\pi} \sum \left( \frac{\varepsilon}{|x_j - x_{i_0}|} \right) \approx \frac{1}{\pi} \sum \left( \frac{\varepsilon}{|x_j - x_{i_0}| > r} \right)
$$

$$
= \frac{1}{\pi} \sum \left( \frac{\varepsilon}{|x_j - x_{i_0}| > r} \right)
$$

$$
\approx \frac{1}{\pi} \int_{|x - x_{i_0}| > r} \frac{v_x(x)}{x - x_{i_0}} dx
$$

$$
= \frac{1}{\pi} \int_{|x - x_{i_0}| > r} \left( \frac{v(x) - v(x_{i_0})}{(x - x_{i_0})^2} - \frac{v(x_{i_0} + r) + v(x_{i_0} - r) - 2v(x_{i_0})}{r} \right) dx
$$

$$
\approx -(-\Delta)^{1/2} [v](x_{i_0}).
$$

We can control the error produced in the approximation by choosing $r$ not too small ($r$ such that $\varepsilon/r \to 0$ as $\varepsilon \to 0$).
On the other hand, for \( i \neq i_0 \),

\[
\epsilon(i - i_0) = v(x_i) - v(x_{i_0}) \simeq v_x(x_{i_0})(x_i - x_{i_0})
\]

from which

\[
\sum_{i \neq i_0, |x_i - x_{i_0}| \leq r} \frac{\epsilon}{x_i - x_{i_0}} \simeq v_x(x_{i_0}) \sum_{i \neq i_0, |i - i_0| \leq v_x(x_{i_0}) \frac{r}{\epsilon}} \frac{1}{(i - i_0)}
\]

\[
\simeq v_x(x_{i_0}) \left( \sum_{i \leq i_0} \frac{1}{(i - i_0)} + \sum_{i \geq i_0 + 1} \frac{1}{(i - i_0)} \right)
\]

\[
= v_x(x_{i_0}) \left( -\sum_{k \geq 1} \frac{1}{k} + \sum_{k \geq 1} \frac{1}{k} \right)
\]

\[
= 0.
\]

We can control the error produced by choosing \( r \) sufficiently small (\( r \leq \epsilon^{\frac{1}{2}} \)).
Heuristics. Any function is well-prepared

Let $\phi$ be the transition layer. If $H(x)$ is the Heaviside function, then

$$\phi(x) \simeq H(x) - \frac{1}{\alpha \pi x}, \quad \text{if } |x| >> 1,$$

where $\alpha = W''(0)$. Then, if $v \in C^{1,1}(\mathbb{R})$ is non-decreasing

$$v(x) \simeq \sum_{i=M_\epsilon}^{N_\epsilon} \epsilon \phi \left( \frac{x - x_i}{\epsilon \delta} \right) + \epsilon M_\epsilon,$$

where $\epsilon M_\epsilon \simeq \inf_{\mathbb{R}} v$. Indeed, assume $x = x_{i_0}$ for some $i_0$. Then,

$$\sum_{i=M_\epsilon}^{N_\epsilon} \epsilon \phi \left( \frac{x_{i_0} - x_i}{\epsilon \delta} \right) + \epsilon M_\epsilon = \sum_{i=M_\epsilon}^{i_0-1} \epsilon \phi \left( \frac{x_{i_0} - x_i}{\epsilon \delta} \right) + \epsilon \phi(0) + \sum_{i=i_0+1}^{N_\epsilon} \epsilon \phi \left( \frac{x_{i_0} - x_i}{\epsilon \delta} \right) + \epsilon M_\epsilon$$

$$\simeq \sum_{i=M_\epsilon}^{i_0-1} \epsilon \left( 1 + \frac{\epsilon \delta}{\alpha \pi (x_i - x_{i_0})} \right) + \frac{\epsilon \delta}{\alpha \pi} \sum_{i=i_0+1}^{N_\epsilon} \frac{\epsilon}{x_i - x_{i_0}} + \epsilon M_\epsilon$$

$$= \frac{\epsilon \delta}{\alpha \pi} \sum_{i \neq i_0} \frac{\epsilon}{x_i - x_{i_0}} + \epsilon i_0$$

$$\simeq \frac{\epsilon \delta}{\alpha} \left( -(-\Delta)^{\frac{1}{2}} [v](x_{i_0}) \right) + \epsilon i_0$$

$$\simeq \epsilon i_0$$

$$= v(x_{i_0}).$$
Assume that the limit function $u$ is smooth and $\partial_x u > 0$. 
Assume that the limit function $u$ is smooth and $\partial_x u > 0$.

Then, we can define $x_i(t)$ as the unique solution of

$$u(t, x_i(t)) = \epsilon i.$$
Next we consider as ansatz for $u$ the approximation of $u$ given by

$$
\Phi(t, x) := N \sum_{i=1}^{M} \phi_{x_i} - \sum_{i=1}^{M} \delta_{x_i} + M.
$$

Plugging the ansatz into the PDE

$$
\delta \partial_t u = -(-\Delta)^{1/2} u - \delta W_0 u,
$$

we get

$$
\dot{x}_i(t) = -\frac{\partial_t u(t, x_i(t))}{\partial_x u(t, x_i(t))}.
$$

**Heuristics. Proof of convergence**

Assume that the limit function $u$ is smooth and $\partial_x u > 0$.

Then, we can define $x_i(t)$ as the unique solution of

$$
u(t, x_i(t)) = \epsilon i.
$$

Differentiate,

$$
\partial_t u(t, x_i(t)) + \partial_x u(t, x_i(t)) \dot{x}_i(t) = 0,
$$

from which

$$
\dot{x}_i(t) = -\frac{\partial_t u(t, x_i(t))}{\partial_x u(t, x_i(t))}.
$$
Assume that the limit function \( u \) is smooth and \( \partial_x u > 0 \).

Then, we can define \( x_i(t) \) as the unique solution of
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from which
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Next we consider as ansatz for \( u^\epsilon \) the approximation of \( u \) given by
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  \Phi^\epsilon(t, x) := \sum_{i=M_\epsilon}^{N_\epsilon} \epsilon \phi \left( \frac{x - x_i(t)}{\epsilon \delta} \right) + \epsilon M_\epsilon.
\]
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Assume that the limit function \( u \) is smooth and \( \partial_x u > 0 \). Then, we can define \( x_i(t) \) as the unique solution of

\[
\begin{align*}
\partial_t u(t, x_i(t)) + \partial_x u(t, x_i(t)) x_i'(t) &= 0,
\end{align*}
\]

Differentiate,

\[
\begin{align*}
\partial_t u(t, x_i(t)) + \partial_x u(t, x_i(t)) x_i'(t) &= 0,
\end{align*}
\]

Next, we consider as ansatz for \( u \) the approximation of \( u \) given by

\[
\begin{align*}
\mathcal{M}^\varepsilon + \left( \frac{\varepsilon}{(\varepsilon)^! x - x} \right) \phi \bigg|_{\varepsilon N}^{\varepsilon = 0} = (x_i(t), \phi)
\end{align*}
\]

Plugging the ansatz into the PDE \( \delta \partial_t u = -((t)^! x, t) n_x \partial_{x_i} \rho + ((t)^! x, t) n_t \rho \)

From which

\[
\begin{align*}
0 = (t)^! x ((t)^! x, t) n_x \rho + ((t)^! x, t) n_t \rho
\end{align*}
\]

Differentiate,

\[
\begin{align*}
(\varepsilon)^! = ((t)^! x, t) n
\end{align*}
\]

Then, we can define \( x_i(t) \) as the unique solution of

\[
\begin{align*}
\mathcal{M}^\varepsilon + \left( \frac{\varepsilon}{(\varepsilon)^! x - x} \right) \phi \bigg|_{\varepsilon N}^{\varepsilon = 0} = (x_i(t), \phi)
\end{align*}
\]

Assume that the limit function \( u \) is smooth and \( n_x \rho < n_t \rho < 0 \).
Therefore,

\[ \partial_t u(t, x_i(t)) = -c_0 \partial_x u(t, x_i(t))(-\Delta)^{\frac{1}{2}} u(t, x_i(t)). \]

Passing to the limit as \( \epsilon \to 0 \) we see that \( u \) solves

\[ \partial_t u = -c_0 \partial_x (-\Delta)^{\frac{1}{2}} u. \]
Therefore,

\[
\partial_t u(t, x_i(t)) = -c_0 \partial_x u(t, x_i(t))(-\Delta)^{\frac{1}{2}} u(t, x_i(t)).
\]

Passing to the limit as \( \epsilon \to 0 \) we see that \( u \) solves

\[
\partial_t u = -c_0 \partial_x u(-\Delta)^{\frac{1}{2}} u.
\]

Notice that if we define

\[
y_i(\tau) := \frac{x_i(\epsilon \tau)}{\epsilon}
\]

then the \( y_i \)'s solve

\[
\dot{y}_i(\tau) = \dot{x}_i(\epsilon \tau) \sim \frac{c_0}{\pi} \sum_{j \neq i} \frac{\epsilon}{x_i - x_j} = \frac{c_0}{\pi} \sum_{j \neq i} \frac{1}{y_i - y_j},
\]

which is the (DDD).
Proof of convergence

In the formal proof we prove that:

- The limit function is $u$ is viscosity solution of the limit equation when testing with test functions with derivative in $x$ different than 0;
- For all $t \geq 0$, $\lim_{x \to -\infty} u(t, x) = \inf_{\mathbb{R}} u_0$ and $\lim_{x \to +\infty} u(t, x) = \sup_{\mathbb{R}} u_0$, that is the mass of the non-negative function $\partial_x u(t, x)$ is conserved: for all $t \geq 0$,
  \[
  \| \partial_x u(t, \cdot) \|_{L^1(\mathbb{R})} = \| \partial_x u_0 \|_{L^1(\mathbb{R})}.
  \]
- By a comparison argument, we conclude that $u$ is the non-decreasing viscosity solution of the limit equation.