

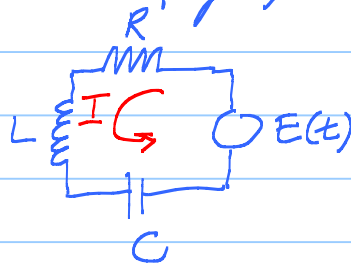
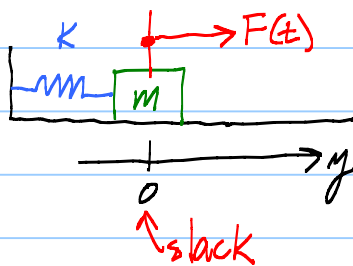
Lecture 17 3.4 Vibrations

[HW16 due in MyLab tonight
Exam 1 Tues, Oct 5 8-9pm
in UC = Univ. Church

Monday: Review. See practice probs (1-12) at our home page at

www.math.purdue.edu/~bell/MA266

and all Exam 1 info (Exam cover page, map, seating chart, ...)



$$F_{\text{Net}} = ma$$

$$\underbrace{-Ky}_{\text{Hooke's}} - \underbrace{cv}_{\text{Friction}} + \underbrace{F(t)}_{\text{external force}} = ma$$

$$m \frac{d^2 y}{dt^2} + c \frac{dy}{dt} + Ky = F(t) \quad \leftarrow \text{Non-homogeneous if } F \neq 0.$$

Case: No friction, no ext force:

$$m \ddot{y} + Ky = 0 \quad \leftarrow t \text{ missing. } p = \frac{dy}{dt}$$
$$\frac{d^2 y}{dt^2} = \frac{dp}{dt} = \frac{dp}{dy} \frac{dy}{dt} = \underbrace{p \frac{dp}{dy}}_p$$

$$mp \frac{dp}{dy} + Ky = 0. \quad \text{Separable}$$

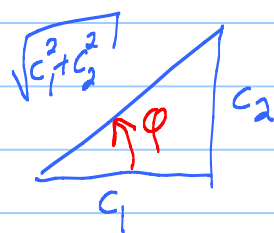
Better: $mr^2 + k = 0$

$$r^2 = -\frac{k}{m}$$

$$r = \pm \sqrt{\frac{k}{m}} i$$

Gen^l solⁿ: $y = c_1 \cos \underbrace{\sqrt{\frac{k}{m}} t}_{\omega_0} + c_2 \sin \underbrace{\sqrt{\frac{k}{m}} t}_{\omega_0}$

Classic important trick:

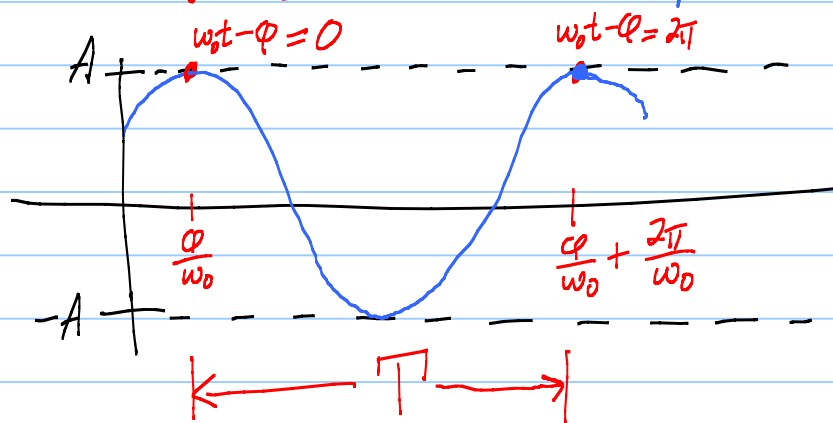
$$y = \underbrace{\sqrt{c_1^2 + c_2^2}}_A \left(\underbrace{\frac{c_1}{\sqrt{c_1^2 + c_2^2}}}_{\cos \phi} \cos \omega_0 t + \underbrace{\frac{c_2}{\sqrt{c_1^2 + c_2^2}}}_{\sin \phi} \sin \omega_0 t \right)$$


$= A \cos(\omega_0 t - \phi)$

← Easy to graph

$\phi = \tan^{-1} \frac{c_2}{c_1}$ ← "phase shift"

$A = \sqrt{c_1^2 + c_2^2}$ ← "amplitude"



$T = \text{"period"} = \frac{2\pi}{\omega_0}$

Frequency = $f = \frac{1}{T} = \frac{\omega_0}{2\pi}$

Trig identities: $e^{(\alpha + \beta)i} = e^{\alpha i} e^{\beta i} = (\cos \alpha + i \sin \alpha)(\cos \beta + i \sin \beta)$

$\underline{\cos(\alpha + \beta)} + i \underline{\sin(\alpha + \beta)} = \underline{[\cos \alpha \cos \beta - \sin \alpha \sin \beta]} + i \underline{[\cos \alpha \sin \beta + \cos \beta \sin \alpha]}$

Simple harmonic motion: (Undamped)

Damping: $m\ddot{y} + c\dot{y} + ky = 0$

$$mr^2 + cr + k = 0$$

Roots: $r_1, r_2 = \frac{-c \pm \sqrt{c^2 - 4mk}}{2m}$

Case r_1, r_2 real and $\neq$: $c^2 - 4mk > 0$

$$r_1 = \frac{-c}{2m} - \frac{\sqrt{c^2 - 4mk}}{2m} < 0 \leftarrow \text{no brainer}$$

Claim: $r_2 < 0$ too. Hmmm.

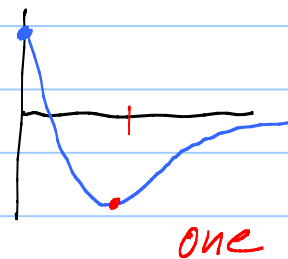
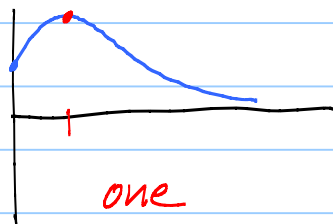
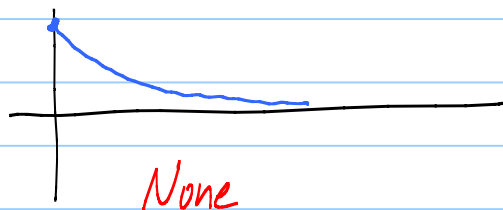
$$c^2 > c^2 - 4mk > 0 \quad \sqrt{c^2} = c$$

So $c > \sqrt{c^2 - 4mk} > 0$

$$r_2 = \frac{-c + \sqrt{c^2 - 4mk}}{2m} < 0 \text{ too.}$$

Consequently, sol's $y = c_1 e^{r_1 t} + c_2 e^{r_2 t}$ fizzle out fast!

How many humps? None, or at most one:



Overdamped case. (Good shock absorbers.)

Case $r_1 = r_2$: $c^2 - 4mk = 0$

$$r_1 = r_2 = \frac{-c}{2m}$$

$$y = c_1 \underbrace{e^{-(\frac{c}{2m})t}} + c_2 \underbrace{t e^{-(\frac{c}{2m})t}}$$

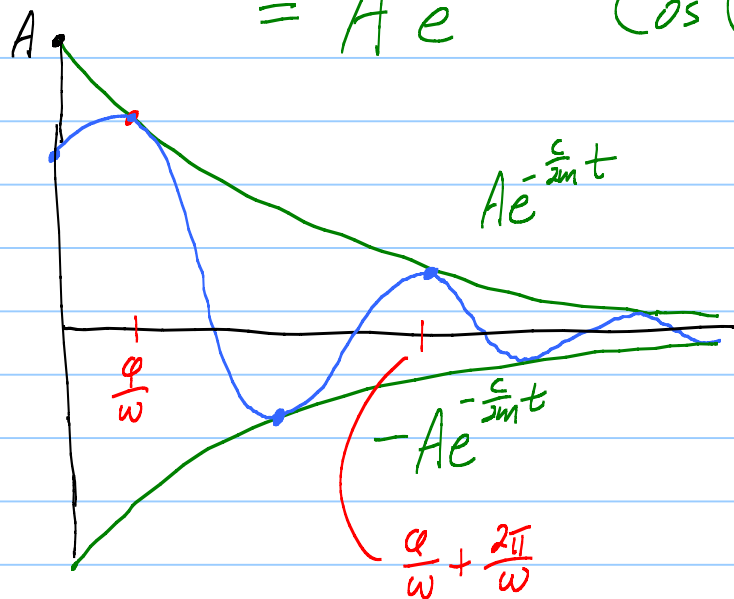
tends to zero rapidly as $t \rightarrow \infty$
Critically damped case. (Shock absorbers about to go.)

Same condition: No humps, or at most one.

Case r_1, r_2 complex $= \frac{-c}{2m} \pm \underbrace{\frac{\sqrt{c^2 - 4mk}}{2m}}_w i$
 $(c^2 - 4km < 0)$

$$y = c_1 e^{-\frac{c}{2m}t} \cos wt + c_2 e^{-\frac{c}{2m}t} \sin wt$$

$$= A e^{-\frac{c}{2m}t} \cos(wt - \phi)$$

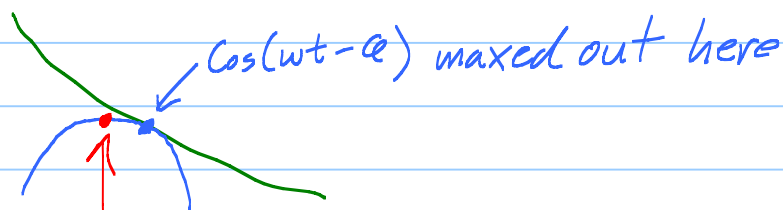


Shock absorbers shot!

$\frac{2\pi}{\omega}$ is a "pseudo period"

Underdamped case.

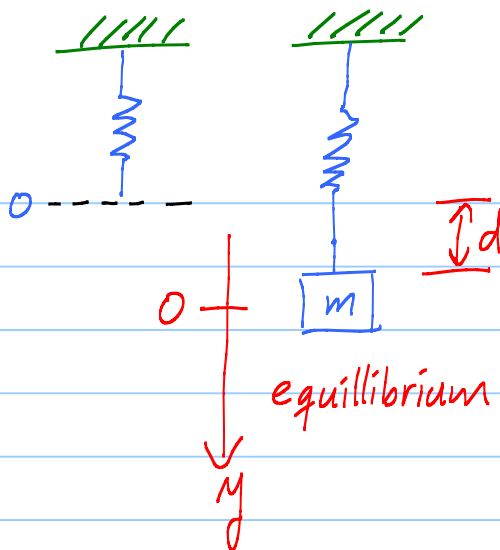
Top of humps?



max! slightly before top of cos fun

Vertical springs:

slack



Hooke's; $kd = mg$

$$F = ma$$

$$-cv + mg - k(d+y) = m \frac{d^2 y}{dt^2}$$

Cancel!

$$\underbrace{-kd}_{\text{Cancel!}} - ky$$

Get same ODE
as sideways!