

Lesson 31 Systems

2nd order ODE $\longleftrightarrow$ 2x2 system

EX: $u'' + 5u' + \underbrace{(1+\varepsilon u^2)}_K u = \cos \omega t$
 $\uparrow$ $m=1$ $\uparrow$ $c=5$

ode45 demands
that you convert
to a 2x2 system

Step 1: Let $x_1(t) = u(t)$

Step 2: Let $x_2(t) = u'(t)$

System: $\frac{dx_1}{dt} = \sim \leftarrow \text{easy!}$
 $\frac{dx_2}{dt} = \sim$

$$\boxed{\frac{dx_1}{dt} = u' = x_2}$$

$$\frac{dx_2}{dt} = u'' = \left[-5u' - (1+\varepsilon u^2)u + \cos \omega t \right] \leftarrow \text{from ODE}$$
$$= -5x_2 - (1+\varepsilon x_1^2)x_1 + \cos \omega t$$

Get 2x2 system: $\begin{cases} \frac{dx_1}{dt} = x_2 \\ \frac{dx_2}{dt} = -5x_2 - x_1 - \varepsilon x_1^3 + \cos \omega t \end{cases}$

Important problem: $\begin{cases} \frac{dx_1}{dt} = 5x_1 - x_2 \\ \frac{dx_2}{dt} = 3x_1 + x_2 \end{cases}$ 2x2 linear homog
first order system
with const coeff

Fancy notation: $\vec{x} = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$. $\vec{x}' = \begin{pmatrix} \dot{x}_1 \\ \dot{x}_2 \end{pmatrix}$

$$\vec{x}' = \begin{bmatrix} 5 & -1 \\ 3 & 1 \end{bmatrix} \vec{x} = A \vec{x}$$

High school method gave $\vec{x} = c_1 \begin{pmatrix} A \\ B \end{pmatrix} e^{r_1 t} + c_2 \begin{pmatrix} C \\ D \end{pmatrix} e^{r_2 t}$

Big idea: Try solⁿs of form $\vec{x} = \begin{pmatrix} a_1 \\ a_2 \end{pmatrix} e^{rt}$. $\begin{cases} x_1 = a_1 e^{rt} \\ x_2 = a_2 e^{rt} \end{cases}$
 $= \vec{a} e^{rt}$

Want

$$\begin{cases} \frac{dx_1}{dt} = 5x_1 - x_2 \\ \frac{dx_2}{dt} = 3x_1 + x_2 \end{cases}$$

$$\begin{cases} r a_1 e^{rt} \overset{\text{want!}}{=} 5a_1 e^{rt} - a_2 e^{rt} \\ r a_2 e^{rt} = 3a_1 e^{rt} + a_2 e^{rt} \end{cases}$$

$$\begin{cases} r a_1 = 5a_1 - a_2 \\ r a_2 = 3a_1 + a_2 \end{cases}$$

$$\begin{cases} 0 = (5-r)a_1 - a_2 \\ 0 = 3a_1 + (1-r)a_2 \end{cases}$$

Hmmm. Don't want $\vec{a} = \vec{0}$ solⁿ.
If Cramer's rule works, get
only the zero solⁿ =

$$a_1 = \frac{\det \begin{bmatrix} 0 & 3 \\ 0 & 3 \end{bmatrix}}{\det \begin{bmatrix} 5-r & -1 \\ 3 & 1-r \end{bmatrix}} = 0$$

Must have

$$\det \begin{bmatrix} 5-r & -1 \\ 3 & 1-r \end{bmatrix} = 0$$

$$(5-r)(1-r) - (-1)3 = 0$$

$$r^2 - 6r + 8 = 0$$

$$(r-4)(r-2) = 0$$

$$\vec{x}' = A \vec{x}$$

$$r \vec{a} e^{rt} = (A \vec{a}) e^{rt}$$

$$\boxed{r \vec{a} = A \vec{a}} \quad \begin{array}{l} \leftarrow r \text{ eigenvalue} \\ \vec{a} \text{ eigenvector} \end{array}$$

$$A \vec{a} - r \vec{a} = \vec{0}$$

$$(A - rI) \vec{a} = \vec{0} \quad I = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

$$\boxed{\det(A - rI) = 0}$$

$\uparrow$ solutions r are e.vals

$$r = 2, 4$$

Next, find $\vec{a}$ that goes with each r .

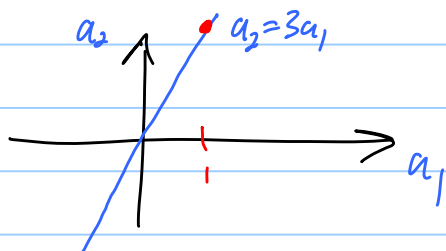
$$\begin{cases} 0 = (5-r)a_1 - a_2 \\ 0 = 3a_1 + (1-r)a_2 \end{cases} \quad \bigg| \quad (A - rI)\vec{a} = 0$$

Case $r=2$:

$$\begin{cases} (5-2)a_1 - a_2 = 0 \\ 3a_1 + (1-2)a_2 = 0 \end{cases}$$

$$\begin{cases} 3a_1 - a_2 = 0 \\ 3a_1 - a_2 = 0 \end{cases} \leftarrow \text{sometimes eqn 2 = const. (eqn 1)}$$

One eqn: $3a_1 - a_2 = 0 \leftarrow \infty$ many solⁿs $\underline{\underline{a_2 = 3a_1}}$
a line of solⁿs.



Take $a_1 = 1$
 $a_2 = 3 \cdot 1 = 3$

Get one non-zero $\vec{a}$ that works: $\vec{a} = \begin{pmatrix} 1 \\ 3 \end{pmatrix}$

Found solⁿ $\vec{x} = \vec{a}e^{rt} = \begin{pmatrix} 1 \\ 3 \end{pmatrix}e^{2t}$

Case $r=4$: Get $\vec{x} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}e^{4t}$

Superposition principle: If $\vec{x}_1$ and $\vec{x}_2$ solve homog linear system $\vec{x}' = A\vec{x}$, so does $c_1\vec{x}_1 + c_2\vec{x}_2$.

Why: $\vec{x}_1' = A\vec{x}_1$

Let $\vec{x} = c_1\vec{x}_1 + c_2\vec{x}_2$.

$\vec{x}_2' = A\vec{x}_2$

Then $\vec{x}' = c_1\vec{x}_1' + c_2\vec{x}_2'$

$$= c_1 A \vec{x}_1 + c_2 A \vec{x}_2$$

$$\vec{x}' = A [\underbrace{c_1 \vec{x}_1 + c_2 \vec{x}_2}_{\vec{x}}] \quad \checkmark$$

Big question: Is $c_1 \begin{pmatrix} 1 \\ 3 \end{pmatrix} e^{2t} + c_2 \begin{pmatrix} 1 \\ 1 \end{pmatrix} e^{4t}$ the gen^l solⁿ to my system? E: U Thm plus superposition princ tells me yes, if I can solve any IVP $\vec{x}(t_0) = \begin{pmatrix} A \\ B \end{pmatrix}$.

Check: $\vec{x}(t_0) = c_1 \begin{pmatrix} 1 \\ 3 \end{pmatrix} e^{2t_0} + c_2 \begin{pmatrix} 1 \\ 1 \end{pmatrix} e^{4t_0} \stackrel{\text{want}}{=} \begin{pmatrix} A \\ B \end{pmatrix}$

$$\begin{cases} c_1 e^{2t_0} + c_2 e^{4t_0} = A \\ c_1 3e^{2t_0} + c_2 e^{4t_0} = B \end{cases}$$

If Cramer's Rule works, get c_1, c_2 no matter what A, B are!

$$\rightarrow \begin{bmatrix} e^{2t_0} & e^{4t_0} \\ 3e^{2t_0} & e^{4t_0} \end{bmatrix} \begin{pmatrix} c_1 \\ c_2 \end{pmatrix} = \begin{pmatrix} A \\ B \end{pmatrix}$$

$$\det = e^{6t_0} - 3e^{6t_0} = \underbrace{-2e^{6t_0}}_{\text{never zero!}}$$

Need $\det [] \neq 0$

Yes, we have gen^l solⁿ!

Bad news. Get double root r . Or complex roots.

Defⁿ: For 2×2 system $\vec{x}' = A$. $\vec{x}_1, \vec{x}_2$ solⁿs.

$X = [\vec{x}_1, \vec{x}_2]$ with $\det X \neq 0$, then

X is a Fundamenta Matrix.

$W = W[\vec{x}_1, \vec{x}_2] = \det X$ is the Wronskian.

$$X = \left[\begin{pmatrix} 1 \\ 3 \end{pmatrix} e^{2t}, \begin{pmatrix} 1 \\ 1 \end{pmatrix} e^{4t} \right] = \begin{bmatrix} e^{2t} & e^{4t} \\ 3e^{2t} & e^{4t} \end{bmatrix}$$

Gen^l solⁿ to $\vec{x}' = A \vec{x}$ is $\vec{x} = c_1 \vec{x}_1 + c_2 \vec{x}_2$

$$\vec{x} = X \begin{pmatrix} c_1 \\ c_2 \end{pmatrix} = X \vec{c}$$

Next time: Complex e. vals $r = a \pm bi$

Get complex e. vect $\vec{a}$ for $r = a + bi$.

Then $\vec{x} = \vec{a} e^{(a+bi)t}$ is a complex solⁿ.

Aha! Real and imag parts are vector solⁿs too!

Wronskian is $\neq 0$. Get real gen^l solⁿ!