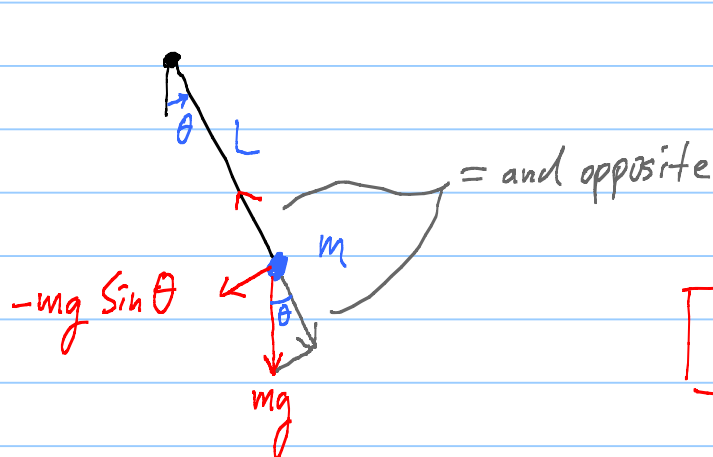


Lesson 13 on 4.5

9,10,11 due tonight, 12,13,14 next Wed.

Exam 1 on Thurs., Oct 1 8-9 pm in WTHR 200
covers Lessons 1-14

Damped pendulum: stiff string



$\vec{F} = m\vec{a}$ in tangential dir.
 $-mg \sin \theta = m(L\ddot{\theta})$
 $-c\dot{\theta}$
 ↑
 friction

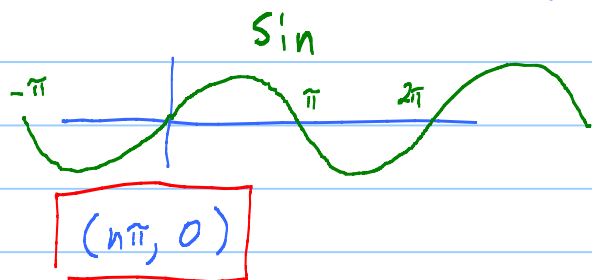
$$mL\ddot{\theta} + c\dot{\theta} + mg \sin \theta = 0$$

Prob: $\ddot{\theta} = -\sin \theta - \dot{\theta}$

Let $\begin{cases} x_1 = \theta(t) \\ x_2 = \dot{\theta}(t) \end{cases} \quad \begin{cases} x_1' = \dot{\theta} = x_2 \\ x_2' = \ddot{\theta} = -\sin \theta - \dot{\theta} \\ \quad \quad \quad = -\sin x_1 - x_2 \end{cases}$

$\begin{cases} x_1' = x_2 \quad \leftarrow f \\ x_2' = -\sin x_1 - x_2 \quad \leftarrow g \end{cases}$

Step 1 Crt. Pts. $\begin{cases} f=0 \\ g=0 \end{cases} \quad \begin{aligned} x_2 &= 0 \checkmark \\ -\sin x_1 - x_2 &= 0 \end{aligned}$



$\sin x_1 = 0$
 ↑
 happens when
 $x_1 = n\pi$
 $n = 0, \pm 1, \pm 2, \dots$

Step 2: Linearize at Crt. Pts.

Jacobian matrix = $J = \begin{bmatrix} \frac{\partial f}{\partial x} & \frac{\partial f}{\partial y} \\ \frac{\partial g}{\partial x} & \frac{\partial g}{\partial y} \end{bmatrix} \quad \begin{aligned} f &= x_1 \\ g &= -\sin x_1 - x_2 \end{aligned}$

Linearized syst. $\vec{x}' = A\vec{x}$ where

$$A = J \Big|_{(x_0, y_0)} \leftarrow \text{Crt. Pt. new origin}$$

$$A = \begin{bmatrix} 0 & 1 \\ -\cos x_1 & -1 \end{bmatrix} \Big|_{(n\pi, 0)}$$

Case: n even (including $n=0$) $\cos(\text{even})\pi = 1$

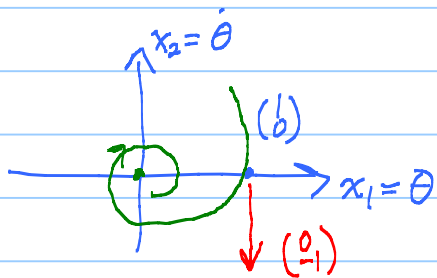
$$A = \begin{bmatrix} 0 & 1 \\ -1 & -1 \end{bmatrix} \quad \text{e-vals} \quad \begin{aligned} (-\lambda)(-1-\lambda)+1 &= 0 \\ \lambda^2 + \lambda + 1 &= 0 \end{aligned}$$

$$\lambda = -\frac{1}{2} \pm \frac{\sqrt{3}}{2}i \quad \text{complex}$$

Spiral

$$\uparrow \text{Re } \lambda < 0 \quad \underline{\underline{\text{in}}}$$

W or CCW? $\vec{x}'$ at $\begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{bmatrix} 0 & 1 \\ -1 & -1 \end{bmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ -1 \end{pmatrix}$



$$\begin{cases} \tilde{x} = x - x_0 \\ \tilde{y} = y - y_0 \end{cases}$$

rename x, y

Case: Odd mult π . $\cos(\text{odd})\pi = -1$

$$A = \begin{bmatrix} 0 & 1 \\ 1 & -1 \end{bmatrix}$$

$\uparrow$
 $-\cos n\pi$

$$\text{e-vals} \quad \begin{aligned} (-\lambda)(-1-\lambda)-1 &= 0 \\ \lambda^2 + \lambda - 1 &= 0 \end{aligned}$$

$$\lambda = -\frac{1}{2} \pm \frac{\sqrt{5}}{2}$$

opp. sign
Saddle pt., Unstable

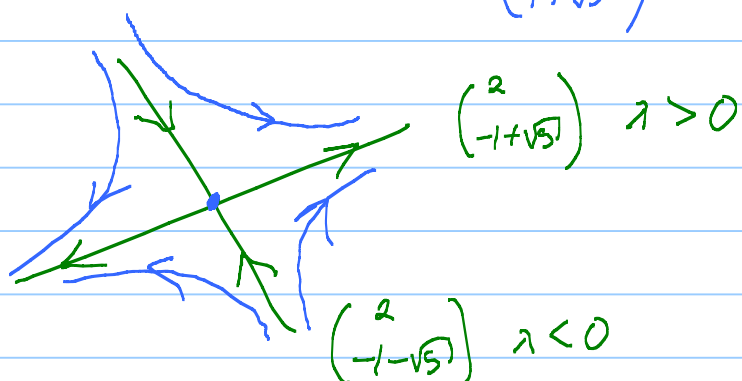
For $\lambda = -\frac{1}{2} - \frac{\sqrt{5}}{2}$: $(A - \lambda I)\vec{q} = \vec{0}$

$$\begin{bmatrix} 0 - (-\frac{1}{2} - \frac{\sqrt{5}}{2}) & 1 \\ \text{eee} & \text{eee} \end{bmatrix} \begin{bmatrix} q_1 \\ q_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\leadsto \begin{bmatrix} \frac{1}{2} + \frac{\sqrt{5}}{2} & 1 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} q_1 \\ q_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\vec{a} = \begin{pmatrix} 1 \\ -(\frac{1}{2} + \frac{\sqrt{5}}{2}) \end{pmatrix} \text{ or better } \begin{pmatrix} 2 \\ -1-\sqrt{5} \end{pmatrix}$$

For $\lambda = -\frac{1}{2} + \frac{\sqrt{5}}{2} > 0$ Get $\begin{pmatrix} 2 \\ -1+\sqrt{5} \end{pmatrix}$



(p plane demo)

4.6 Non-homogeneous syst

$$\vec{x}' = A\vec{x} \leftarrow \text{homog}$$

$$\vec{x}' = A\vec{x} + \vec{g} \leftarrow \text{non-homog}$$

EX: $\vec{x}' = \begin{pmatrix} -3 & 1 \\ 1 & -3 \end{pmatrix} \vec{x} + \underbrace{\begin{pmatrix} 1 \\ 2 \end{pmatrix}}_{\vec{g}} e^{2t}$

Step 1: Get homog solⁿ $\vec{x}_c = c_1 \begin{pmatrix} 1 \\ 1 \end{pmatrix} e^{-2t} + c_2 \begin{pmatrix} 1 \\ -1 \end{pmatrix} e^{-4t}$

Gen^l Solⁿ to non-homog = $\vec{x}_c + \vec{x}_p$

$\uparrow$ gen^l solⁿ to homog $\uparrow$ one particular solⁿ to non-homog

Step 2: Try $\vec{x}_p = \vec{b} e^{2t} \leftarrow \text{safe! } 2 \text{ is not an e-val!}$

Plug in: $\vec{x}_p' = \overset{\text{want}}{2} \vec{b} e^{2t} = A\vec{x}_p + \vec{g}$

$$2\vec{b} e^{2t} = A\vec{b} e^{2t} + \begin{pmatrix} 1 \\ 2 \end{pmatrix} e^{2t} \quad \text{Cancel } e^{2t}'s$$

$$2\vec{b} = A\vec{b} + \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

$$A\vec{b} - \underbrace{2\vec{b}}_{2I\vec{b}} = -\begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

$$(A - 2I) \vec{b} = \begin{pmatrix} -1 \\ -2 \end{pmatrix}$$

$\det \neq 0$ because not e-val

$$\left[\begin{array}{cc|c} \underbrace{-3-2}_{-5} & 1 & -1 \\ 1 & \underbrace{-3-2}_{-5} & -2 \end{array} \right]$$

Cramer's Rule:

$$b_1 = \frac{\det \begin{bmatrix} -1 & 1 \\ -2 & -5 \end{bmatrix}}{\det \begin{bmatrix} -5 & 1 \\ 1 & -5 \end{bmatrix}} = \frac{7}{24}$$

$$b_2 = \frac{\det \begin{bmatrix} -5 & -1 \\ 1 & -2 \end{bmatrix}}{\det \begin{bmatrix} -5 & 1 \\ 1 & -5 \end{bmatrix}} = \frac{11}{24}$$

$$\text{So } \vec{x}_p = \begin{pmatrix} 7/24 \\ 11/24 \end{pmatrix} e^{2t}$$

$$\text{Genl Sol}^n \quad \vec{x} = c_1 \begin{pmatrix} 1 \\ 1 \end{pmatrix} e^{-2t} + c_2 \begin{pmatrix} 1 \\ -1 \end{pmatrix} e^{-4t} + \begin{pmatrix} 7/24 \\ 11/24 \end{pmatrix} e^{2t}$$

$$\begin{cases} x_1 = c_1 e^{-2t} + c_2 e^{-4t} + \frac{7}{24} e^{2t} \\ x_2 = c_1 e^{-2t} - c_2 e^{-4t} + \frac{11}{24} e^{2t} \end{cases}$$