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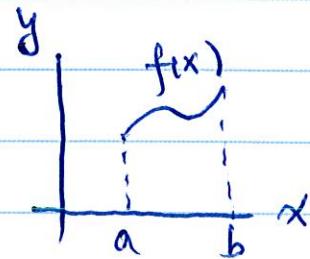
Chapter 13 Vector-Valued Functions and Motion in Space

§13.1 Curves in Space and Their Tangents

Representations of a curve in \mathbb{R}^2

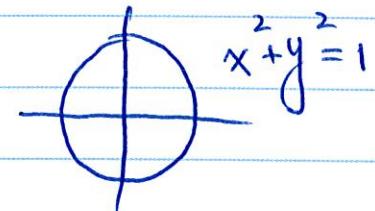
- graph $y = f(x) \quad x \in [a, b]$

$$C = \{(x, f(x)) \mid x \in [a, b]\}$$



- level curve $f(x, y) = k - \text{const.}$

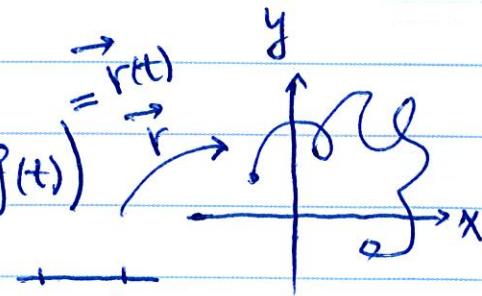
$$C = \{f(x, y) = k \mid (x, y) \in A\}$$



- parametric curve

$$(x, y) = (f(t), g(t))$$

$$C = \{(f(t), g(t)) \mid t \in [a, b]\}$$



Path in \mathbb{R}^3 $(x, y, z) = (f(t), g(t), z(t)) \quad t \in I = [a, b]$

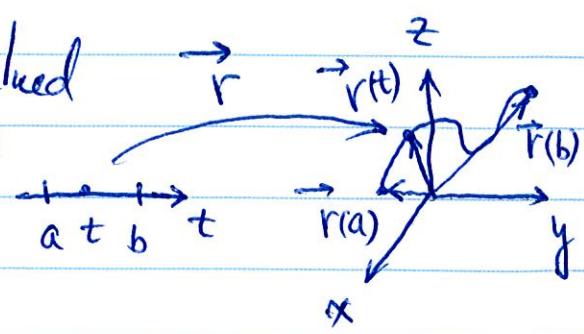
$$= \vec{r}(t)$$

parametric curve

$$C = \{(f(t), g(t), z(t)) \mid t \in I\}$$

Ex. 1 Graph $\vec{r}(t) = (\cos t, \sin t, t)$

vector-valued
function



(2)

Limits and Continuity

• Limit

$$\vec{r}(t) = (f(t), g(t), h(t)) \text{ on } D \text{ and } \vec{L} = (L_1, L_2, L_3)$$

$$\lim_{t \rightarrow t_0} \vec{r}(t) = \vec{L} \iff \forall \varepsilon > 0, \exists \delta > 0, \text{ s.t. } \forall t \in D$$

$$0 < |t - t_0| < \delta \Rightarrow |\vec{r}(t) - \vec{L}| < \varepsilon$$

$$\iff \lim_{t \rightarrow t_0} \vec{r}(t) = (\lim_{t \rightarrow t_0} f(t), \lim_{t \rightarrow t_0} g(t), \lim_{t \rightarrow t_0} h(t))$$

$$= (L_1, L_2, L_3)$$

Ex. 2 $\lim_{t \rightarrow \frac{\pi}{2}} (\cos t, \sin t, t) = ?$

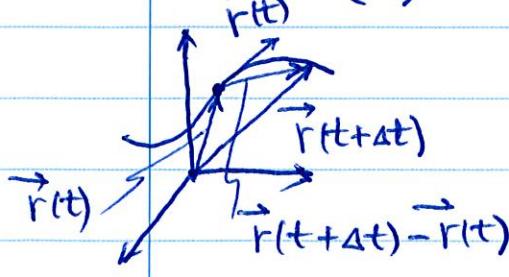
• Continuity

$$\vec{r}(t) \text{ is cont. at } t_0 \in D \iff \lim_{t \rightarrow t_0} \vec{r}(t) = \vec{r}(t_0)$$

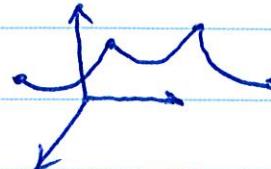
Derivatives and Motion

- Derivative $\vec{r}(t)$ has a derivative ($\vec{r}'(t)$ differentiable) at t

$$\vec{r}'(t) \iff \vec{r}'(t) = \frac{d\vec{r}(t)}{dt} = (f'(t), g'(t), h'(t))$$



piecewise
smooth



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Velocity $\vec{r}(t)$ — position vector of a moving particle
and Acceleration

$\vec{v}(t) = \vec{r}'(t)$ — velocity vector

$|\vec{v}(t)|$ — speed

$\vec{a}(t) = \vec{v}'(t) = \vec{r}''(t)$ — acceleration

$\frac{\vec{v}(t)}{|\vec{v}(t)|}$ — direction of motion

Ex. 4

Differential Rules

$$(1) \vec{c} - \text{const}, \quad \vec{c}' = \vec{0}, \quad (2) \left(f(t) \vec{u}(t) \right)' = f' \vec{u} + f \vec{u}'$$

$$(3) \left(\vec{u} \pm \vec{v} \right)' = \vec{u}' \pm \vec{v}', \quad (4) \left(\vec{u} \cdot \vec{v} \right)' = \vec{u}' \cdot \vec{v} + \vec{u} \cdot \vec{v}'$$

$$(5) \left(\vec{u} \times \vec{v} \right)' = \vec{u}' \times \vec{v} + \vec{u} \times \vec{v}', \quad (6) \frac{d}{dt} \vec{u}(f(t)) = \boxed{0} \vec{u}'(f(t)) f'(t)$$

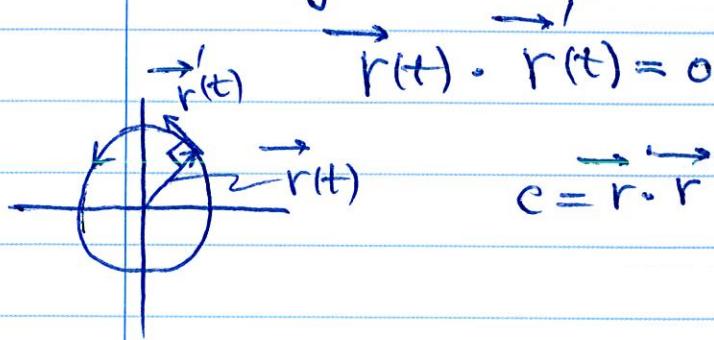
Proof of (4)

$$\text{Proof of (5)} \quad \left(\vec{u} \times \vec{v} \right)' = \lim_{t \rightarrow 0} \frac{1}{h} \left[\begin{array}{c} \vec{u}(t+h) \times \vec{v}(t+h) \\ - \vec{u}(t) \times \vec{v}(t+h) \end{array} \right] - \left[\begin{array}{c} \vec{u}(t) \times \vec{v}(t) \\ + \vec{u}(t) \times \vec{v}(t+h) \end{array} \right]$$

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Vector Functions of Const Length

$$\left| \vec{r}(t) \right| = \text{const.}$$



$$c = \vec{r} \cdot \vec{r} \Rightarrow 0 = (\vec{r} \cdot \vec{r})' = 2 \vec{r} \cdot \vec{r}'$$

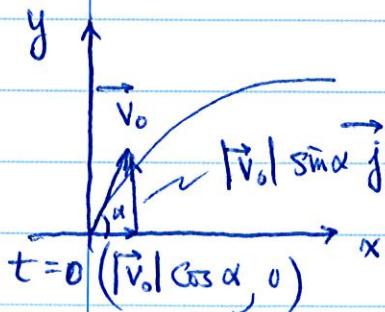
§ 13.2 Integrals of Vector Functions; Projectile Motion

$$\int \vec{r}(t) dt = \left(\int f(t) dt, \int g(t) dt, \int h(t) dt \right)$$

Ex. 1, 2, 3

A classical example of $\vec{r}(t)$ in the derivation of the projectile motion.

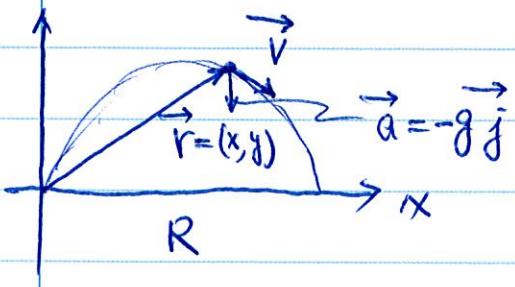
Ideal Projectile Motion



$$\vec{v}_0 = \left(|\vec{v}_0| \cos \alpha, |\vec{v}_0| \sin \alpha \right)$$

$$= (v_0 \cos \alpha, v_0 \sin \alpha)$$

$$\vec{r}_0 = (0, 0)$$



$$m \ddot{\vec{r}}(t) = -mg \vec{j}$$

$$\Rightarrow \vec{r}'(t) = -(gt) \vec{j} + \vec{v}_0$$

$$\Rightarrow \vec{r}(t) = -\frac{1}{2}gt^2 \vec{j} + \vec{v}_0 t + \vec{r}_0$$

(5)

$$\vec{r}(t) = -\frac{1}{2}gt^2 \vec{j} + v_0 t \cos \alpha \vec{i} + v_0 t \sin \alpha \vec{j}$$

$$\left\{ \begin{array}{l} x(t) = v_0 t \cos \alpha \\ y(t) = v_0 t \sin \alpha - \frac{1}{2}gt^2 \end{array} \right.$$

$$t = \frac{x}{v_0 \cos \alpha} \Rightarrow y = -\left(\frac{g}{2v_0^2 \cos^2 \alpha}\right)x^2 + (\tan \alpha)x$$

\swarrow
parabola

Maximum height $y_{\max} = \frac{(v_0 \sin \alpha)^2}{2g} \Leftarrow 0 = \frac{dy}{dx}$

Flight time $t = \frac{2v_0 \sin \alpha}{g} \Leftarrow y=0 = v_0 t \sin \alpha - \frac{1}{2}gt^2$

Range $R = \frac{v_0^2}{g} \sin 2\alpha \Leftarrow \text{Max } x(\text{flight time}) = R$

Ex. 4 Given $\vec{r}_0 = (0, 0)$, $v_0 = 500 \text{ m/sec}$, $\alpha = 60^\circ$

Find $\vec{r}(10) = ?$

Projectile Motion with Wind Gusts $a = 8.8 \text{ ft/sec}$

Ex. 5 Given $\vec{v}_0 = (v_0 \cos \alpha, v_0 \sin \alpha) - (a, 0)$

$\vec{r}_0 = (0, 3)$, $v_0 = 152 \text{ ft/sec}$, $\alpha = 20^\circ$

Find (a) $\vec{r}(t) = ?$

(b) $y_{\max} = ?$

(c) $R = ?$ Flight time = ?

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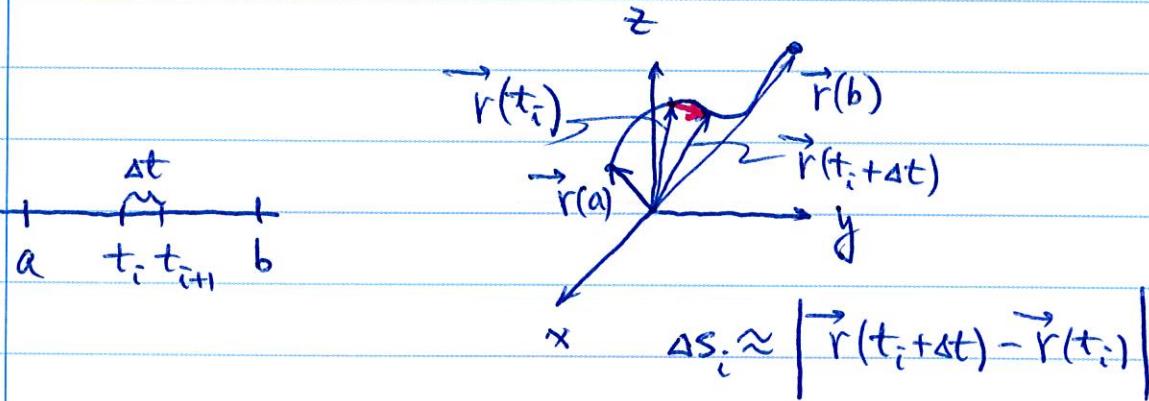
§13.3 Arc Length in Space

$$\vec{r}(t) = (x(t), y(t), z(t)) \quad t \in [a, b] \quad \text{traced exactly once}$$

length

$$L = \int_a^b |\vec{v}| dt$$

$$= \int_a^b \sqrt{x'^2 + y'^2 + z'^2} dt = \int_C ds$$



$$L = \lim \sum_i |\vec{r}(t_{i+1}) - \vec{r}(t_i)|$$

Ex. 1

Arc Length Parameter with Base Point P(t_0)

$$s(t) = \int_{t_0}^t |\vec{v}(\tau)| d\tau$$

Ex. 2

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Speed on a Smooth Curve

Speed $\frac{ds}{dt} = \frac{d}{dt} \int_{t_0}^t |\vec{v}(\tau)| d\tau = |\vec{v}(t)| > 0$

\Rightarrow arclength s is an increasing function of t

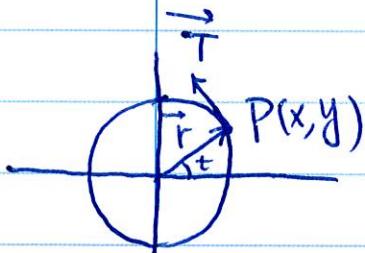
Unit Tangent Vector

$$\vec{T} = \frac{\vec{v}}{|\vec{v}|} = \frac{\vec{r}'(t)}{|\vec{r}'(t)|} \text{ tangent to the curve}$$

Ex. 3

~~Ex/Ex~~

$$\vec{r} = (\cos t, \sin t)$$



$$\vec{v} = (-\sin t, \cos t) \Rightarrow \vec{T} = \vec{v}$$

$$\frac{d\vec{r}}{dt}$$

In general $? = \frac{d\vec{r}}{ds} = \frac{d\vec{r}}{dt} \cdot \left(\frac{dt}{ds} \right) = \vec{v} \left(\frac{1}{\frac{ds}{dt}} \right) = \frac{\vec{v}}{|\vec{v}|} = \vec{T}(t)$

§13.4 Curvature and Normal Vector of a Curve

How a curve turns or bends

Curvature of a Plane Curve

As a particle moves along a smooth curve in the plane

$\vec{T} = \frac{d\vec{r}}{ds}$ turns as the curve bends.

unit tangent vector

the rate at which \vec{T} turns

per unit length along the curve

curvature

$$K = \left| \frac{d\vec{T}}{ds} \right|$$

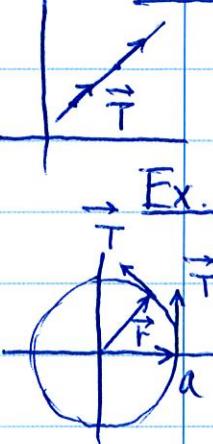
$$\boxed{K = \frac{1}{\|\vec{v}\|} \left| \frac{d\vec{T}}{dt} \right| = \left| \frac{d\vec{T}}{dt} \cdot \frac{dt}{ds} \right| = \left| \frac{d\vec{T}}{dt} \right| \frac{1}{\left| \frac{ds}{dt} \right|} = \frac{1}{\|\vec{v}\|} \left| \frac{d\vec{T}}{dt} \right|}$$

Ex. 1 $\vec{r}(t) = \vec{C} + t\vec{v}$ $\xrightarrow{\text{const.}}$ $\vec{r}'(t) = \vec{v}$ and $\vec{T} = \frac{\vec{v}}{\|\vec{v}\|}$ const

$$K = \frac{1}{\|\vec{v}\|} \left| \frac{d\vec{T}}{dt} \right| = 0$$

Ex. 2 $\vec{r}(t) = (a\cos t, a\sin t)$ $t \in [0, 2\pi]$

$$K \stackrel{?}{=} \frac{1}{a}$$



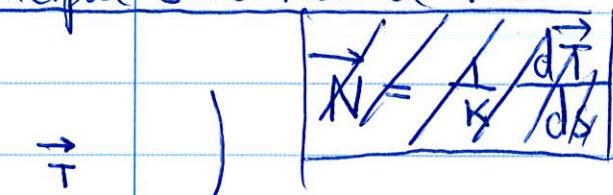
$$s(t) = \int_0^t \left| \vec{r}'(\tau) \right| d\tau = at \Rightarrow \frac{ds}{dt} = a$$

$$\vec{T} = \vec{r}'(t) / \left| \vec{r}'(t) \right| = \frac{1}{a} (-a\sin t, a\cos t) = (-\sin t, \cos t) \quad \vec{N} = \frac{1}{K} \frac{d\vec{T}}{ds} = -\frac{\vec{r}(t)}{a} \perp \vec{T}$$

$$\frac{d\vec{T}}{ds} = \frac{d\vec{T}}{dt} \cdot \frac{dt}{ds} = \frac{1}{a} \frac{d\vec{T}}{dt} = \frac{-1}{a} (\cos t, \sin t) = -\frac{1}{a^2} \vec{r}(t)$$

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Principal Unit Normal Vector at $\kappa \neq 0$



$$N = \frac{1}{\kappa} \frac{dT}{ds}$$

$$\|T\| = 1 \Rightarrow T(s) \cdot T'(s) = 0 \Leftrightarrow T(s) \perp \frac{dT}{ds}$$

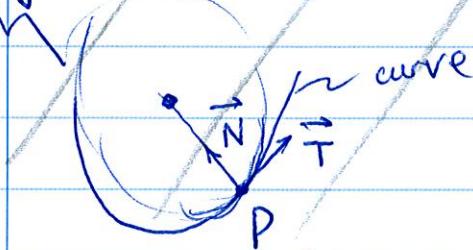
$$N = \frac{1}{\kappa} \frac{dT}{ds} = \frac{\frac{dT}{dt}}{\left\| \frac{dT}{dt} \right\|}$$

definition

Ex. 3 $\vec{r}(t) = (\cos 2t, \sin 2t)$

$$\vec{T} = ? \quad \vec{N} = ?$$

Circle of Curvature for Plane Curves (see p749)



Curvature and Normal Vectors in Space Curves

$$\kappa = \left\| \frac{dT}{ds} \right\| = \frac{1}{\|v\|} \left\| \frac{dT}{dt} \right\|, \quad \vec{N} = \frac{1}{\kappa} \frac{dT}{ds} = \frac{\frac{dT}{dt}}{\left\| \frac{dT}{dt} \right\|}$$

Ex. 5 $\vec{r}(t) = (a \cos t, a \sin t, bt), \quad a, b > 0, \quad a^2 + b^2 \neq 0$

$$\kappa = ? \quad \vec{N} = ?$$

§13.5 Tangential and Normal Components of Acceleration

Traveling along a space curve

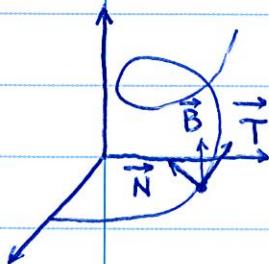
- Cartesian $\vec{i}, \vec{j}, \vec{k}$ — not truly relevant

- ~~TNB~~ TNB frame or Frenet frame

$$\vec{T} = \frac{\vec{v}}{|\vec{v}|} \quad \text{forward moving direction}$$

$$\vec{N} = \pm \frac{d\vec{T}}{ds} \quad \text{turning direction}$$

binormal vector $\vec{B} = \vec{T} \times \vec{N}$ Tendency to "twist" out of the plane $\text{span}\{\vec{T}, \vec{N}\}$



- tangential and normal components of acceleration

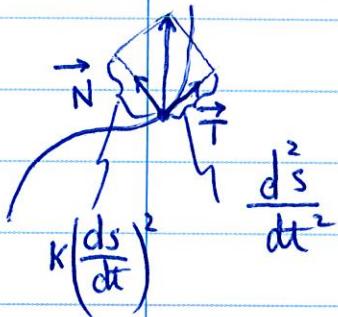
$$\vec{a} = a_T \vec{T} + a_N \vec{N}$$

$$a_T = \frac{d^2 s}{dt^2} = \frac{d}{dt} |\vec{v}| \quad \text{tangential components of acceleration}$$

$$a_N = \kappa \left(\frac{ds}{dt} \right)^2 = \kappa |\vec{v}|^2 \quad \text{normal component}$$

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$$\begin{aligned}\vec{a} &= \frac{d}{dt} \vec{v} \\ &= \frac{d}{dt} \left(\vec{T} \frac{ds}{dt} \right) \\ &= \frac{d^2 s}{dt^2} \vec{T} + \frac{ds}{dt} \cdot \frac{d\vec{T}}{dt} \\ &= \frac{d^2 s}{dt^2} \vec{T} + \left(\frac{ds}{dt} \right)^2 \frac{d\vec{T}}{ds} = \frac{d^2 s}{dt^2} \vec{T} + \kappa \left(\frac{ds}{dt} \right)^2 \vec{N}.\end{aligned}$$



$$a_N = \kappa \left(\frac{ds}{dt} \right)^2 = \sqrt{|\vec{a}|^2 - a_T^2}$$

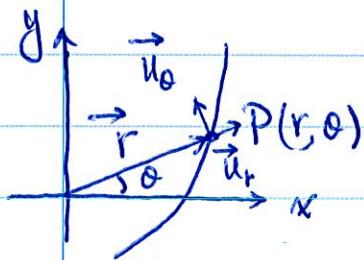
Ex. 1 $\vec{r}(t) = (\cos t + t \sin t, \sin t - t \cos t) \quad t > 0$

$$\vec{a} = a_T \vec{T} + a_N \vec{N} = ? \text{ without computing } \vec{T} \text{ & } \vec{N}$$

$$a_T = \frac{d}{dt} |\vec{v}|, \quad a_N = \sqrt{|\vec{a}|^2 - a_T^2}$$

§13.6 Velocity and Acceleration in Polar Coordinates

Motion in Polar and Cylindrical Coordinates



$$\vec{u}_r = (\cos \theta, \sin \theta) = \cos \theta \vec{i} + \sin \theta \vec{j}$$

$$\vec{u}_\theta = (-\sin \theta, \cos \theta)$$

$$\vec{u}_r \perp \vec{u}_\theta$$

$$\vec{r} = r \vec{u}_r$$

$$\|\vec{u}_r\| = \|\vec{u}_\theta\| = 1$$

$$\begin{cases} \frac{d\vec{u}_r}{d\theta} = \vec{u}_\theta \\ \frac{d\vec{u}_\theta}{d\theta} = -\vec{u}_r \end{cases} \Rightarrow \begin{cases} \frac{d\vec{u}_r}{dt} = \frac{d\vec{u}_r}{d\theta} \cdot \frac{d\theta}{dt} = \dot{\theta} \vec{u}_\theta \\ \frac{d\vec{u}_\theta}{dt} = -\dot{\theta} \vec{u}_r \end{cases}$$

$$\vec{v} = \dot{\vec{r}} = \dot{r} \vec{u}_r + r \dot{\theta} \vec{u}_\theta$$

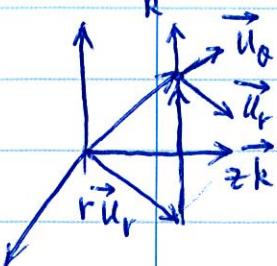
$$\vec{a} = \ddot{\vec{r}} = (\ddot{r} - r \dot{\theta}^2) \vec{u}_r + \left(\dot{r} \dot{\theta} \vec{u}_\theta + r \ddot{\theta} \vec{u}_\theta + r \dot{\theta} \vec{u}_r \right) (\ddot{r} + 2\dot{r}\dot{\theta}) \vec{u}_\theta$$

R³

$$\vec{r} = r \vec{u}_r + z \vec{k}$$

$$\vec{v} = \dot{r} \vec{u}_r + r \dot{\theta} \vec{u}_\theta + \dot{z} \vec{k}$$

$$\vec{a} = (\ddot{r} - r \dot{\theta}^2) \vec{u}_r + (r \ddot{\theta} + 2\dot{r}\dot{\theta}) \vec{u}_\theta + \ddot{z} \vec{k}$$



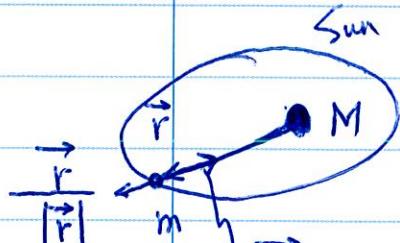
$$\vec{u}_r \times \vec{u}_\theta = \vec{k}, \quad \vec{u}_\theta \times \vec{k} = \vec{u}_r, \quad \vec{k} \times \vec{u}_r = \vec{u}_\theta$$

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Planets Move in Planes

$$G \approx 6.6726 \times 10^{-11} \text{ N m}^2 \text{ kg}^{-2}$$

universal gravitational constant



$$\vec{F} = -\frac{GmM}{|\vec{r}|^2} \cdot \frac{\vec{r}}{|\vec{r}|}$$

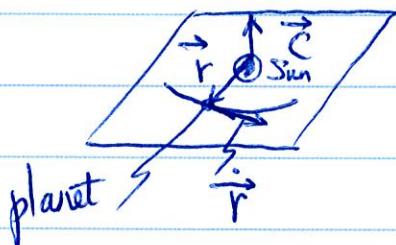
$$\vec{F} = m\vec{a} \Rightarrow \ddot{\vec{r}} = -\frac{GmM}{|\vec{r}|^3} \vec{r} \Rightarrow \ddot{\vec{r}} \times \vec{r} = \vec{0}$$

$$\frac{d}{dt} (\vec{r} \times \dot{\vec{r}}) = \dot{\vec{r}} \times \dot{\vec{r}} + \vec{r} \times \ddot{\vec{r}} = \vec{0}$$

↓

$$\vec{r} \times \dot{\vec{r}} = \vec{c} \text{ — const.} \Rightarrow \vec{r} \text{ & } \dot{\vec{r}} \text{ lie in a plane } \perp \vec{c}$$

\Rightarrow the planet moves in a fixed plane



Kepler's First Law (Ellipse Law) $r = |\vec{r}|$

$$r = \frac{(1+e)r_0}{1+e \cos \theta} \quad \text{— ellipse equation in polar coordinates}$$

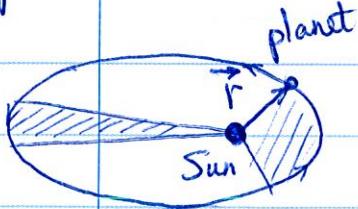
where $e = \frac{r_0 v_0^2}{GM} - 1$ eccentricity

r_0 — min distance
 v_0 — speed at min distance

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Kepler's 2nd Law

the radius vector from the sun to a planet \vec{r} sweeps out equal area in equal times.



$$\vec{C} = \vec{r} \times \dot{\vec{r}} = r(r\dot{\theta})\vec{k}$$

$$= [r(r\dot{\theta})]_{t=0} \vec{k} = r_0 v_0 \vec{k}$$

$$\Rightarrow r_0 v_0 \vec{k} = r^2 \dot{\theta} \vec{k} \Rightarrow r^2 \dot{\theta} = r_0 v_0$$

$$dA = \frac{1}{2} r^2 d\theta \Rightarrow \frac{dA}{dt} = \frac{1}{2} r_0 v_0 = \text{const}$$

(Section 11.5)



Kepler's 3rd Law

T - the planet's orbital period

$$\frac{T^2}{a^3} = \frac{4\pi^2}{GM}$$

a - semi major axis