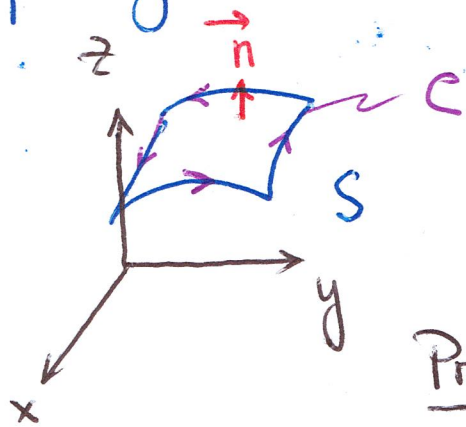


§16.8 Stokes's Theorem

Stokes's Theorem Let S be an oriented piecewise-smooth surface that is bounded by a simple, closed, piecewise-smooth boundary curve C with positive orientation. Let $\vec{F}$ be a vector field whose components have continuous partial derivatives on an open region in $\mathbb{R}^3$ that contains S . $\vec{F}(x, y, z) = \langle P(x, y, z), Q(x, y, z), R(x, y, z) \rangle$

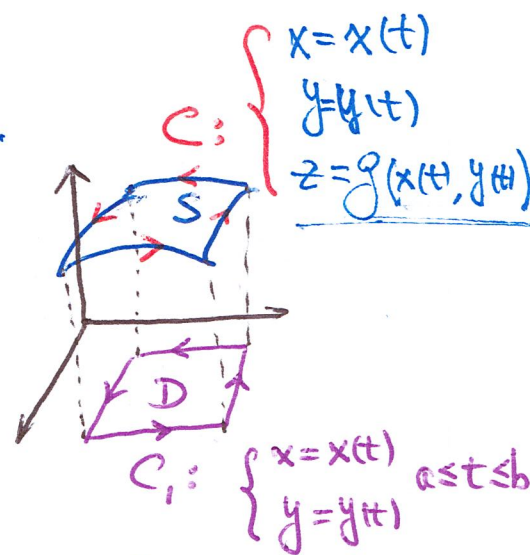


$$\oint_{C=\partial S} \vec{F} \cdot d\vec{r} = \iint_S \nabla \times \vec{F} \cdot d\vec{S}$$

Proof of S: $z = g(x, y), (x, y) \in D$

$$S: \vec{r}(x, y) = \langle x, y, g(x, y) \rangle$$

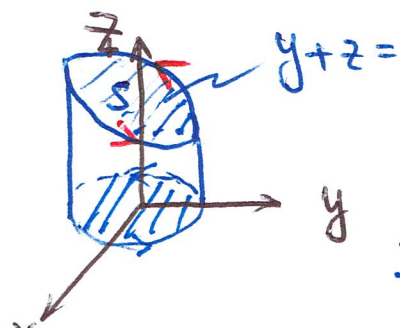
$$\iint_S \nabla \times \vec{F} \cdot d\vec{S} = \iint_D \nabla \times \vec{F} \cdot \left\langle -\frac{\partial g}{\partial x}, -\frac{\partial g}{\partial y}, 1 \right\rangle dx dy \quad (x, y) \in D$$



$$\int_C \vec{F} \cdot d\vec{r} = \int_a^b \vec{F}(x(t), y(t), g(x(t), y(t))) \cdot \left\langle x'(t), y'(t), \frac{\partial g}{\partial x} x'(t) + \frac{\partial g}{\partial y} y'(t) \right\rangle dt$$

$\vec{r}(t) = \langle x(t), y(t) \rangle$

Ex. 1 Evaluate $\mathbf{I} = \int_C \vec{F} \cdot d\vec{r}$, where $\vec{F}(x, y, z) = \langle -y^2, x, z^2 \rangle$ and C is the curve of intersection of the plane $y + z = 2$ and the cylinder $x^2 + y^2 = 1$.

 $C: \vec{r}(t) = \langle \cos t, \sin t, 2 - \sin t \rangle \quad t: 0 \rightarrow 2\pi$

$$\mathbf{I} = \int_0^{2\pi} \langle -\sin^2 t, \cos t, (2 - \sin t)^2 \rangle \cdot \langle -\sin t, \cos t, -\cos t \rangle dt$$

$$\mathbf{I} = \iint_S (\nabla \times \vec{F}) \cdot d\vec{S} = \iint_D \langle 0, 0, 1 + 2y \rangle \cdot \langle 0, 1, 1 \rangle dx dy$$

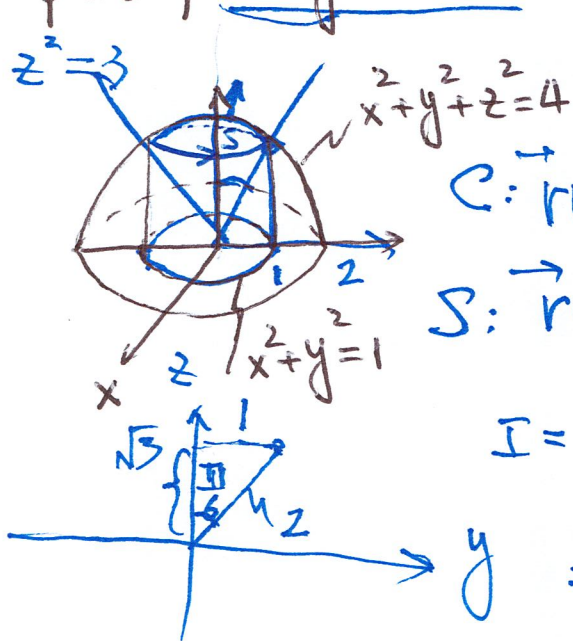
$$= \iint_D (1 + 2y) dx dy = \int_0^{2\pi} \int_0^1 (1 + 2r \sin \theta) r dr d\theta$$

$S: \vec{r}(x, y) = \langle x, y, 2 - y \rangle$

$D: \{(x, y) \mid x^2 + y^2 \leq 1\}$

$$\nabla \times \vec{F} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ -y^2 & x & z^2 \end{vmatrix} = \langle 0, 0, 1 + 2y \rangle$$

Ex. 2 Use Stokes' ~~Theorem~~ Theorem to compute $\iint_S \nabla \times \vec{F} \cdot d\vec{S} = \mathbf{I}$, where $\vec{F} = \langle xz, yz, xy \rangle$ and S is the part of $x^2 + y^2 + z^2 = 4$ that lies inside the cylinder $x^2 + y^2 = 1$ and above the xy -plane.



(1) $\mathbf{I} = \int_C \vec{F} \cdot d\vec{r} = \int_0^{2\pi} \langle \cos t \cdot \sqrt{3}, \sqrt{3} \sin t, \cos t \sin t \rangle \cdot \langle -\sin t, \cos t, 0 \rangle dt$

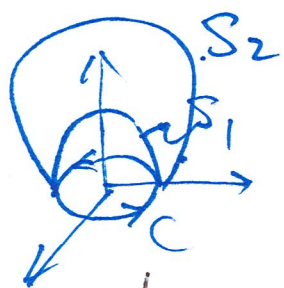
$C: \vec{r}(t) = \langle \cos t, \sin t, \sqrt{3} \rangle, t: 0 \rightarrow 2\pi = \sqrt{3} \int_0^{2\pi} (\cos t \sin t + \sin t \cos t) dt = 0$

$S: \vec{r}(\varphi, \theta) = \langle 2 \sin \varphi \cos \theta, 2 \sin \varphi \sin \theta, 2 \cos \varphi \rangle, 0 \leq \theta \leq 2\pi, 0 \leq \varphi \leq \frac{\pi}{6}$

$\mathbf{I} = \iint_D \langle x - y, x - y, 0 \rangle \cdot 2 \sin \varphi \vec{r}(\varphi, \theta) d\varphi d\theta \quad D = [0, \frac{\pi}{6}] \times [0, 2\pi]$

$= \int_0^{\frac{\pi}{6}} \int_0^{2\pi} 2(x^2 - y^2) \cdot 2 \sin \varphi d\varphi d\theta = \int_0^{\frac{\pi}{6}} \int_0^{2\pi} 16 \sin^3 \varphi (\cos 2\theta) d\varphi d\theta$

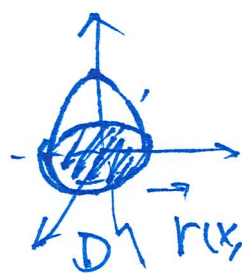
- $\underline{S_1}$ and $\underline{S_2}$ are surfaces having the same orientation, and $\underline{\partial S_1 = \partial S_2 = C}$



$$\oint_{\underline{S_1}} (\nabla \times \vec{F}) \cdot d\vec{S} \implies \oint_{\underline{S_2}} \nabla \times \vec{F} \cdot d\vec{S}$$

Examples Use Stokes's Theorem to evaluate $\oint_S \nabla \times \vec{F} \cdot d\vec{S} = I$

#2 (P1139) $\vec{F} = \langle x^2 \sin z, y^2, xy \rangle$, S is the part of $z = 1 - x^2 - y^2$ that lies above the xy -plane, oriented upward.



$$I = \iint_S \langle x^2 \sin(1 - x^2 - y^2), y^2, xy \rangle \cdot \langle +2x, 2y, 1 \rangle dx dy$$

$$= \iint_D (2x^3 \sin(1 - x^2 - y^2) + 2y^3 + xy) dx dy$$

$$= 0$$

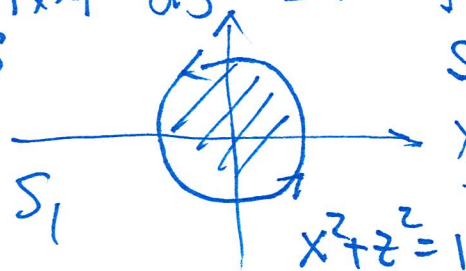
$$I = \iint_D \nabla \times \langle 0, y^2, xy \rangle \cdot \langle 0, 0, 1 \rangle dx dy = \iint_D \langle x, y, 0 \rangle \cdot \langle 0, 0, 1 \rangle dx dy = 0$$

#6 (P1139) $\vec{F} = \langle e^{xy}, e^{xz}, x^2 z \rangle$, S is the half of $4x^2 + y^2 + 4z^2 = 4$ that lies to the right of the xz -plane, oriented in the direction of the positive y -axis.

$$\oint_S \nabla \times \vec{F} \cdot d\vec{S} = \iint_D \nabla \times \vec{F} \cdot d\vec{S} = \iint_D \langle *, -2xz, * \rangle \cdot \langle 0, 1, 0 \rangle dx dz$$

$$\begin{vmatrix} i & j & k \\ \partial_x & \partial_y & \partial_z \\ e^{xy} & e^{xz} & x^2 z \end{vmatrix} = \langle *, -2xz, * \rangle$$

$$= 2 \iint_D xz dx dz$$



$$S_1: \vec{r}(x, z) = \langle x, 0, z \rangle$$

$$(x, z) \in D$$

$$\vec{r}_x \times \vec{r}_z = \langle -\frac{\partial y}{\partial x}, 1, -\frac{\partial y}{\partial z} \rangle = \langle 0, 1, 0 \rangle$$