

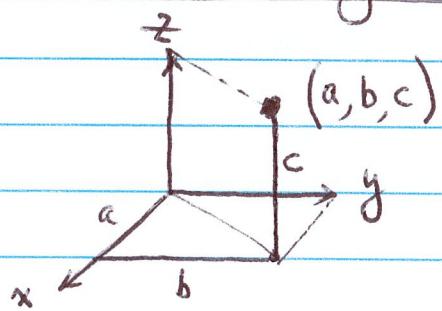
Calculus: Early Transcendentals, 3rd edition
 by Briggs, Cochran, Gillett, Schulz

①

Chapter 13 Vectors and the Geometry of Space

Lesson 1 (Review §13.1 - 13.4)

- three-dimensional rectangular coordinate system



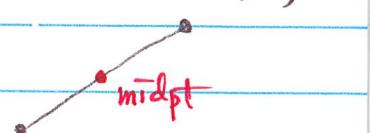
- (1) Equations of a simple planes

$$z = c, \quad x = c, \quad y = c$$

- (2) Distances between two pts (x_1, y_1, z_1) and (x_2, y_2, z_2)

$$d = \sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2 + (z_2 - z_1)^2}$$

$$\text{midpt} = \left(\frac{x_1 + x_2}{2}, \frac{y_1 + y_2}{2}, \frac{z_1 + z_2}{2} \right)$$



- (3) Equation of a sphere/ball

sphere $(x-a)^2 + (y-b)^2 + (z-c)^2 = r^2$

P824 #31, 34

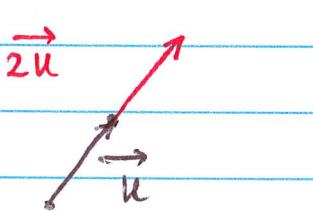
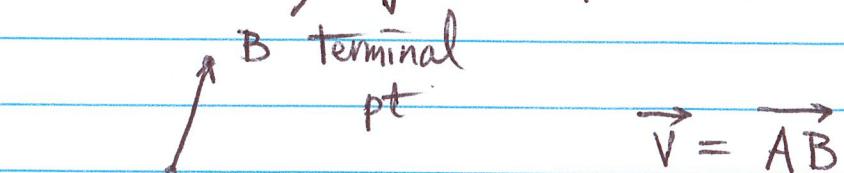
ball $(x-a)^2 + (y-b)^2 + (z-c)^2 \leq r^2$

(2)

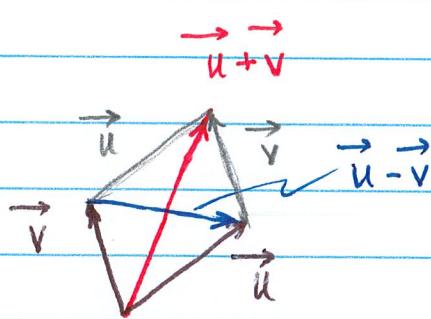
Vectors

magnitude: mass, length, time, ...

vector (magnitude & direction): force, displacement, velocity, ...

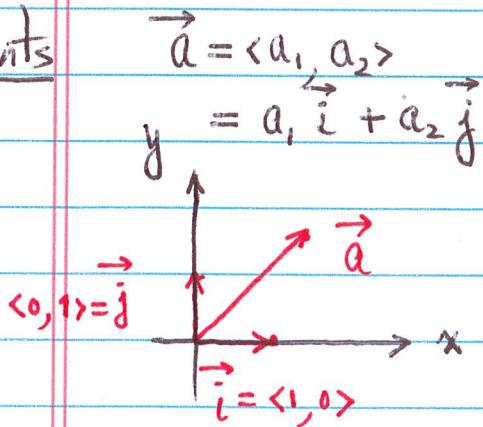


scalar multiplication

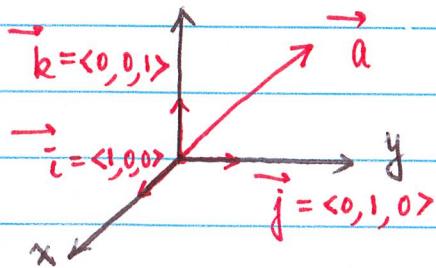


addition & subtraction

components



$$\vec{a} = \langle a_1, a_2, a_3 \rangle = a_1 \vec{i} + a_2 \vec{j} + a_3 \vec{k}$$



$$\text{magnitude } |\vec{a}| = \sqrt{a_1^2 + a_2^2 + a_3^2}, \quad c\vec{a} = \langle ca_1, ca_2, ca_3 \rangle$$

$$\vec{a} \pm \vec{b} = \langle a_1 \pm b_1, a_2 \pm b_2, a_3 \pm b_3 \rangle$$

$$\text{unit vector } \vec{a} / |\vec{a}|$$

(3)

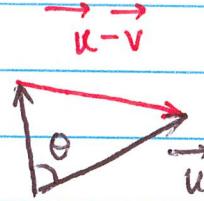
(1) the dot product $\vec{u} = \langle u_1, u_2, u_3 \rangle, \vec{v} = \langle v_1, v_2, v_3 \rangle$

Definition $\vec{u} \cdot \vec{v} = |\vec{u}| |\vec{v}| \cos \theta$

$$\text{angle } \theta = \cos^{-1} \frac{\vec{u} \cdot \vec{v}}{|\vec{u}| |\vec{v}|} \in [0, \pi]$$

orthogonality $\vec{u} \perp \vec{v} \iff \vec{u} \cdot \vec{v} = 0$

Theorem $\vec{u} \cdot \vec{v} = u_1 v_1 + u_2 v_2 + u_3 v_3$

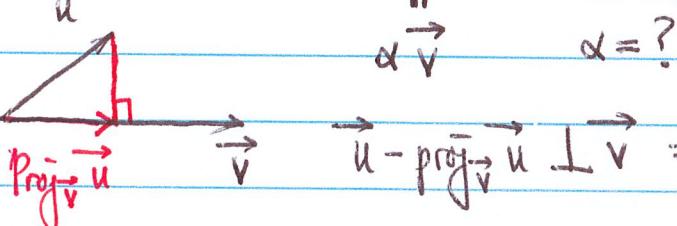


Proof - the law of cosine

$$\begin{aligned} |\vec{u} - \vec{v}|^2 &= |\vec{u}|^2 + |\vec{v}|^2 - 2 |\vec{u}| |\vec{v}| \cos \theta \\ &\quad -2 \vec{u} \cdot \vec{v} \\ &= (u_1 - v_1)^2 + (u_2 - v_2)^2 + (u_3 - v_3)^2 \\ &= (u_1^2 + u_2^2 + u_3^2) + (v_1^2 + v_2^2 + v_3^2) - 2(u_1 v_1 + u_2 v_2 + u_3 v_3) \end{aligned}$$

Orthogonal Projection $\text{proj}_{\vec{v}} \vec{u} = ? = |\vec{u}| \underbrace{\cos \theta}_{\text{length}} \frac{\vec{v}}{|\vec{v}|} = \left(\vec{u} \cdot \frac{\vec{v}}{|\vec{v}|} \right) \frac{\vec{v}}{|\vec{v}|}$

\vec{u} $\parallel \vec{v}$ $\alpha = ?$



$$\vec{u} - \text{proj}_{\vec{v}} \vec{u} \perp \vec{v} \Rightarrow 0 = (\vec{u} - \alpha \vec{v}) \cdot \vec{v} \\ = \vec{u} \cdot \vec{v} - \alpha \vec{v} \cdot \vec{v}$$

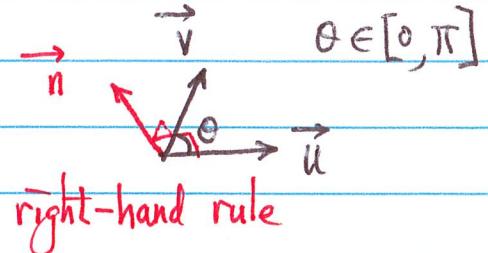
$$\Rightarrow \alpha = \frac{\vec{u} \cdot \vec{v}}{|\vec{v}|^2} = \frac{|\vec{u}| \cos \theta}{|\vec{v}|}$$

(4)

(2) the cross product

cross product $\vec{u} = \langle u_1, u_2, u_3 \rangle, \vec{v} = \langle v_1, v_2, v_3 \rangle$

$$\begin{aligned}\vec{u} \times \vec{v} &= \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ u_1 & u_2 & u_3 \\ v_1 & v_2 & v_3 \end{vmatrix} = \begin{vmatrix} u_2 & u_3 \end{vmatrix} \vec{i} - \begin{vmatrix} u_1 & u_3 \end{vmatrix} \vec{j} + \begin{vmatrix} u_1 & u_2 \end{vmatrix} \vec{k} \\ &= \left(|\vec{u}| |\vec{v}| \sin \theta \right) \vec{n}\end{aligned}$$



Properties (a) $\vec{u} \times \vec{v} \perp \vec{u}, \vec{u} \times \vec{v} \perp \vec{v}$

(b) $|\vec{u} \times \vec{v}| = |\vec{u}| |\vec{v}| \sin \theta = \text{area of parallelogram}$



(c) $\vec{u} \times \vec{v} = 0 \iff \vec{u} \parallel \vec{v}$

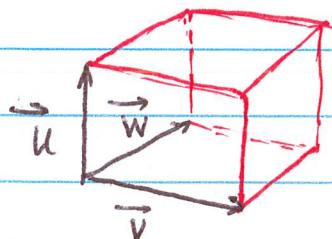
(d) $\vec{u} \times \vec{v} = -\vec{v} \times \vec{u}$

$$\vec{u} \cdot (\vec{v} \times \vec{w}) = (\vec{u} \times \vec{v}) \cdot \vec{w}$$

$$\vec{u} \times (\vec{v} \times \vec{w}) = (\vec{u} \cdot \vec{w}) \vec{v} - (\vec{u} \cdot \vec{v}) \vec{w}$$

(e) $|\vec{u} \cdot (\vec{v} \times \vec{w})| = \begin{vmatrix} u_1 & u_2 & u_3 \\ v_1 & v_2 & v_3 \\ w_1 & w_2 & w_3 \end{vmatrix} = \text{volume of parallelopiped}$

(#62)

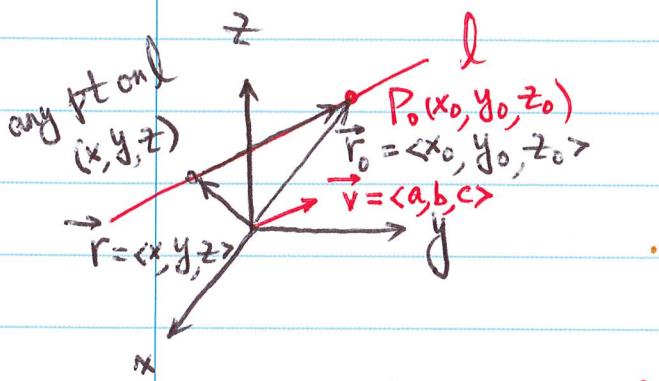


(5)

§13.5 Lines and Planes in Space

• Equation of a Line l

Given (1) a point $P_0(x_0, y_0, z_0)$ on l or [two points
 (2) a vector $\vec{v} = \langle a, b, c \rangle \parallel l$ $P_0(x_0, y_0, z_0)$ and $P_1(x_1, y_1, z_1)$]



↓
 [a pt $P_0(x_0, y_0, z_0)$ on l
 a vector $\vec{P}_0P_1 \parallel l$]

$$\vec{r} = \vec{r}_0 + t\vec{v} \quad (\text{vector equation})$$

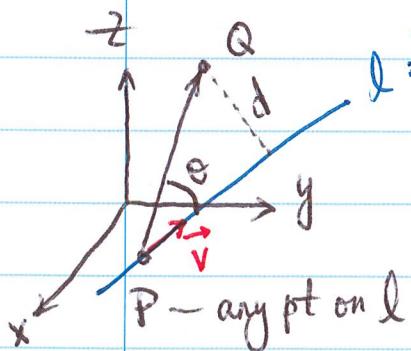
$$\langle x, y, z \rangle = \langle x_0, y_0, z_0 \rangle + t \langle a, b, c \rangle \iff$$

$$\begin{cases} x = x_0 + ta \\ y = y_0 + tb \\ z = z_0 + tc \end{cases}$$

parametric equation.

examples #12, 20, 28, 34, 38

• Distance from a point to a line



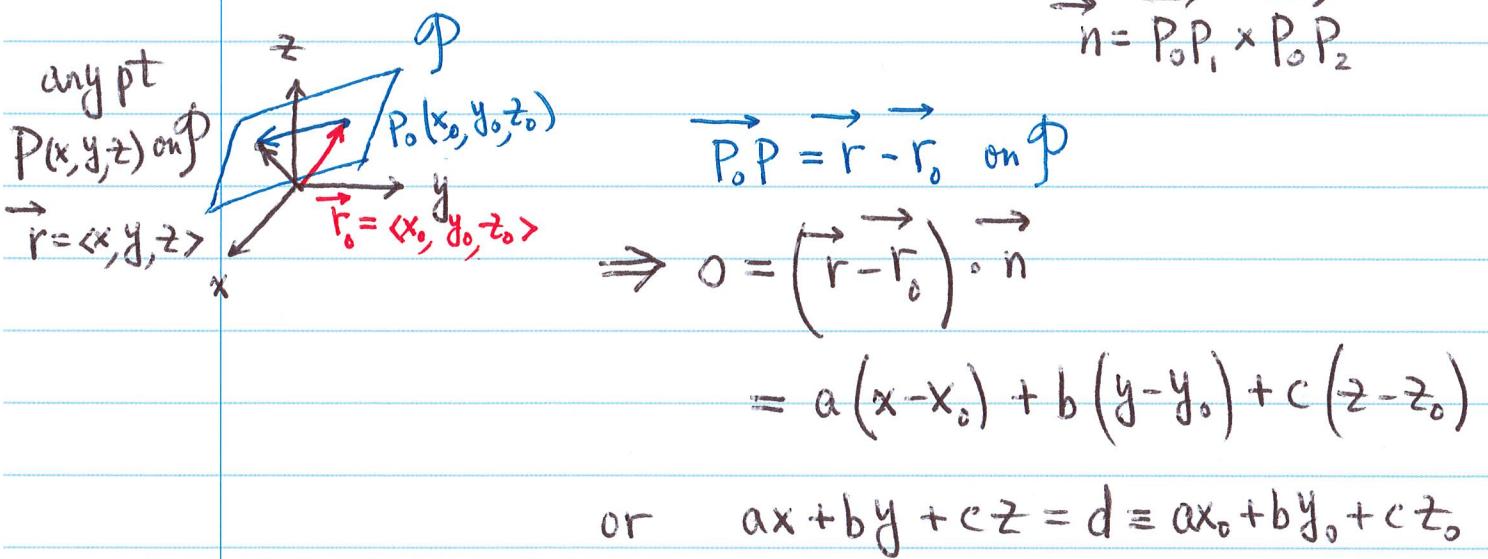
$$d = |\vec{PQ}| \sin\theta$$

$$|\vec{v} \times \vec{PQ}| = |\vec{v}| |\vec{PQ}| \sin\theta = |\vec{v}| d$$

$$\Rightarrow d = \frac{|\vec{v} \times \vec{PQ}|}{|\vec{v}|}$$

• Equation of a plane in \mathbb{R}^3 ϕ

Given { (1) a point $P_0(x_0, y_0, z_0)$ on ϕ or [three pts
 (2) a vector $\vec{n} = \langle a, b, c \rangle \perp \phi$ or P_0, P_1, P_2
 \Downarrow
 $\vec{n} = \overrightarrow{P_0P_1} \times \overrightarrow{P_0P_2}$



examples #46, 66, 74, 79, 87

§ 13.6 Cylinders and Quadratic Surfaces

by Katty Yackman

Def. A trace is the set of points at which a surface intersects a plane that is parallel to one of the coordinate planes.

xy-trace: intersection with $z=0$ (the xy-plane)

yz-trace: intersection with $x=0$ (the yz-plane)

xz-trace: intersection with $y=0$ (the xz-plane)

Note: Intersection with coordinate axes

x-axis: Set $y=0$ and $z=0$

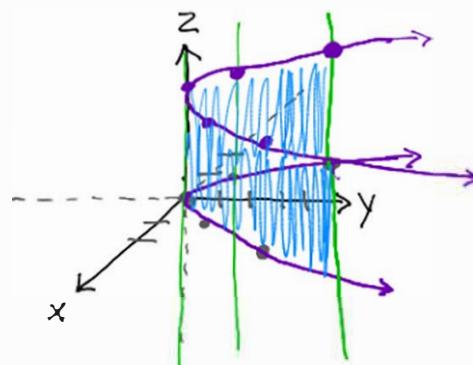
y-axis: Set $x=0$ and $z=0$

z-axis: Set $x=0$ and $y=0$

Def. A cylinder is a surface that consists of all lines that are parallel to a given line and pass through a given curve.

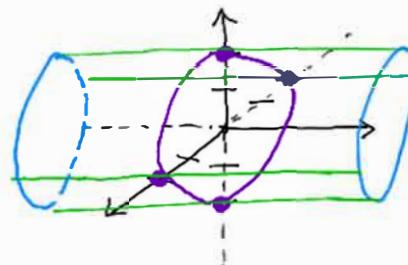
Ex. $y = x^2$

Because there is no restriction on z , this surface consists of all lines parallel to the z-axis that pass through the curve $y = x^2$ (in the xy-plane).



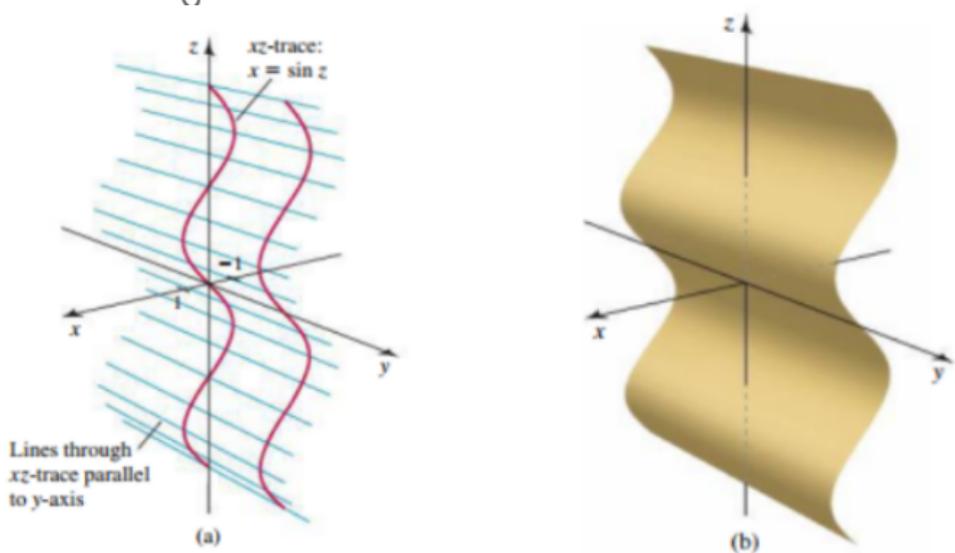
Ex. $x^2 + z^2 = 4$

No restriction on y , so parallel to y-axis through the circle $x^2 + z^2 = 4$ (in the xz-plane).



Ex. $x - \sin z = 0$

See Fig. 13.82 (below) from Pg. 857 of the text.



Def. Quadratic surfaces have the general form

$$Ax^2 + By^2 + Cz^2 + Dxy + Exz + Fyz + Gx + Hy + Iz + J = 0$$

where not all of A, B, C, D, E , and F are 0.

We will focus on a smaller class where
 $D = E = F = 0$.

Note: $\underset{\text{all variables}}{\underbrace{ax + by + cz}} = d$ is a plane

all variables linear \rightarrow Not a quadratic surface.

$\underset{\text{all squared}}{\underbrace{x^2 + y^2 + z^2}} = r^2$ is a sphere

all squared \rightarrow Quadratic Surface

Also, some cylinders are quadratic surfaces
(like $y = x^2$ and $x^2 + z^2 = 4$, but $x = \sin z$ is not).

Def. Ellipsoids have the form $\frac{x^2}{a^2} + \frac{y^2}{b^2} + \frac{z^2}{c^2} = 1$.
All traces are ellipses. A sphere when $a=b=c$.

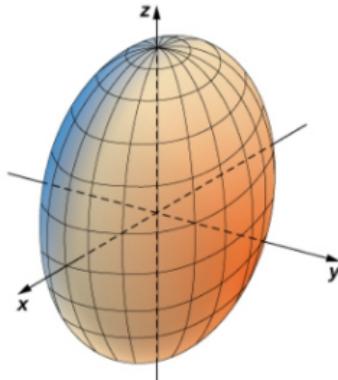
Ellipsoid

$$\frac{x^2}{a^2} + \frac{y^2}{b^2} + \frac{z^2}{c^2} = 1$$

Traces

In plane $z = p$: an ellipse — Ellipsoid
In plane $y = q$: an ellipse — Ellipsoid
In plane $x = r$: an ellipse

If $a = b = c$, then this surface is a sphere.



Elliptic paraboloids have the form $\frac{z}{c} = \frac{x^2}{a^2} + \frac{y^2}{b^2}$.

Traces in two directions are parabolas. In this case, when $y=0$: $\frac{z}{c} = \frac{x^2}{a^2}$ and when $x=0$: $\frac{z}{c} = \frac{y^2}{b^2}$.

Traces in one direction are ellipses. In this case, when $z=c$: $1 = \frac{x^2}{a^2} + \frac{y^2}{b^2}$.

When $z=0$, the "ellipse" is the point $(0,0,0)$.

Enter as
 $\frac{x^2}{a^2} + \frac{y^2}{b^2} = 0$

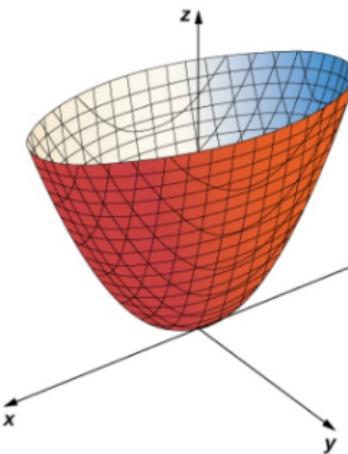
Elliptic Paraboloid

$$z = \frac{x^2}{a^2} + \frac{y^2}{b^2}$$

Traces

In plane $z = p$: an ellipse — Elliptic
In plane $y = q$: a parabola — Paraboloid
In plane $x = r$: a parabola

The axis of the surface corresponds to the linear variable.



Hyperbolic paraboloids have the form $\frac{z}{c} = \frac{x^2}{a^2} - \frac{y^2}{b^2}$

Traces in two directions are parabolas. In this case, when $y=0$: $\frac{z}{c} = \frac{x^2}{a^2}$ and when $x=0$: $\frac{z}{c} = -\frac{y^2}{b^2}$.

Traces in one direction are hyperbolas. In this case, when $z=c$: $1 = \frac{x^2}{a^2} - \frac{y^2}{b^2}$.

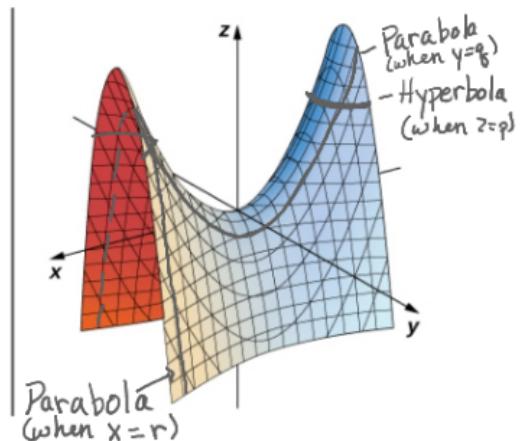
Hyperbolic Paraboloid

$$z = \frac{x^2}{a^2} - \frac{y^2}{b^2}$$

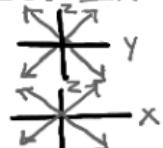
Traces

In plane $z = p$: a hyperbola — Hyperbolic
In plane $y = q$: a parabola — Paraboloid
In plane $x = r$: a parabola — Paraboloid

The axis of the surface corresponds to the linear variable.



(Elliptic) cones have the form $\frac{z^2}{c^2} = \frac{x^2}{a^2} + \frac{y^2}{b^2}$.

Traces in two directions are two lines. In this case, when $x=0$: $\frac{z^2}{c^2} = \frac{y^2}{b^2} \Rightarrow \frac{|z|}{|c|} = \frac{|y|}{|b|} \Rightarrow$  when $y=0$: $\frac{z^2}{c^2} = \frac{x^2}{a^2} \Rightarrow \frac{|z|}{|c|} = \frac{|x|}{|a|} \Rightarrow$ 

Enter the squared versions, not absolute values

Traces in one direction are ellipses. In this case, when $z=c$: $1 = \frac{x^2}{a^2} + \frac{y^2}{b^2}$. Again, when $z=0$, the "ellipse" is the point $(0, 0, 0)$. This point is the center of the cone.

Enter as $\frac{x^2}{a^2} + \frac{y^2}{b^2} = 0$.

Elliptic Cone

$$\frac{x^2}{a^2} + \frac{y^2}{b^2} - \frac{z^2}{c^2} = 0$$

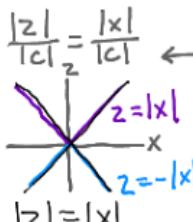
Traces

In plane $z = p$: an ellipse — Elliptic

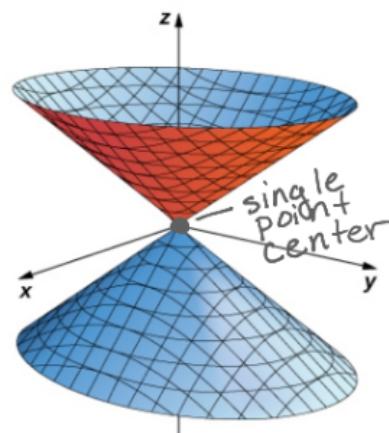
In plane $y = q$: a hyperbola

In plane $x = r$: a hyperbola

In the xz -plane: a pair of lines that intersect at the origin
In the yz -plane: a pair of lines that intersect at the origin



The axis of the surface corresponds to the variable with a negative coefficient. The traces in the coordinate planes parallel to the axis are intersecting lines.



Hyperboloids of one sheet have the form

$$\frac{x^2}{a^2} + \frac{y^2}{b^2} - \frac{z^2}{c^2} = 1.$$

Traces in two directions are hyperbolas. In this case, when $y=0$: $\frac{x^2}{a^2} - \frac{z^2}{c^2} = 1$

$$\text{when } x=0: \frac{y^2}{b^2} - \frac{z^2}{c^2} = 1$$

Traces in one direction are ellipses. In this case, when $z=0$: $\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1$. The center of this ellipse is the center of the surface.

Hyperboloid of One Sheet

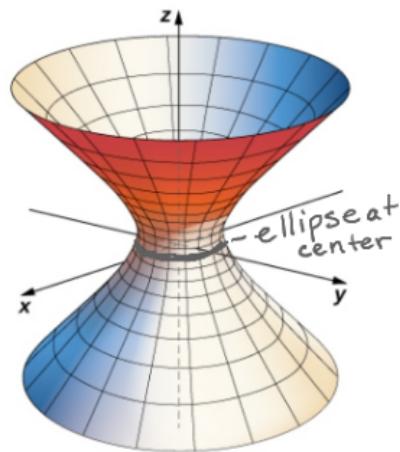
$$\frac{x^2}{a^2} + \frac{y^2}{b^2} - \frac{z^2}{c^2} = 1$$

Traces

In plane $z = p$: an ellipse

In plane $y = q$: a hyperbola
In plane $x = r$: a hyperbola \Rightarrow Hyperboloid

In the equation for this surface, two of the variables have positive coefficients and one has a negative coefficient. The axis of the surface corresponds to the variable with the negative coefficient.



Note: Center could be shifted.

For instance, $(x-2)^2 + (y+1)^2 - (z+2)^2 = 1$.

To determine if cone, hyperboloid of one sheet or hyperboloid of two sheets, check

$x=2$: hyperbola
 $y=-1$: hyperbola
 $z=-2$: ellipse (circle)

} hyperboloid of one sheet.

Hyperboloids of two sheets have the form

$$-\frac{x^2}{a^2} - \frac{y^2}{b^2} + \frac{z^2}{c^2} = 1.$$

Traces in two directions are hyperbolas.

In this case, $x=0$: $-\frac{y^2}{b^2} + \frac{z^2}{c^2} = 1$

$$y=0: -\frac{x^2}{a^2} + \frac{z^2}{c^2} = 1$$

Traces in one direction are ellipses.

$\frac{z^2}{c^2} - 1 = \frac{x^2}{a^2} + \frac{y^2}{b^2} \Rightarrow$ If $\frac{z^2}{c^2} - 1 < 0$, $-c < z < c$, the equation is not valid, so there are no traces.

\Rightarrow When $z = \pm c$, $0 = \frac{x^2}{a^2} + \frac{y^2}{b^2}$, so the "vertices" of the sheets are $(0, 0, c)$ and $(0, 0, -c)$, and the distance between the sheets is $2c$.

Hyperboloid of Two Sheets

$$\frac{z^2}{c^2} - \frac{x^2}{a^2} - \frac{y^2}{b^2} = 1$$

Traces

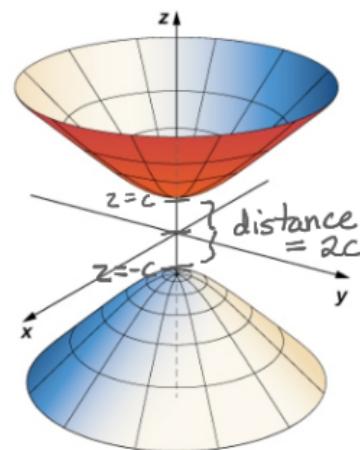
In plane $z = p$: an ellipse or the empty set (no trace),

In plane $y = q$: a hyperbola

In plane $x = r$: a hyperbola

In the equation for this surface, two of the variables have negative coefficients and one has a positive coefficient.

The axis of the surface corresponds to the variable with a positive coefficient. The surface does not intersect the coordinate plane perpendicular to the axis.



Ex. $(x-2)^2 - (y-7)^2 - (z+3)^2 = 1$

$$x=2: -(y-7)^2 - (z+3)^2 = 1$$

$$(y-7)^2 + (z+3)^2 = -1 \quad \text{Not possible}$$

$$y=7: \text{Hyperbola}$$

$$z=-3: \text{Hyperbola}$$

Hyperboloid of two sheets