

# Chapter 14 Vector-Valued Functions (4 lectures)

## §14.1 Vector-Valued Functions

- vector-valued function

$$\vec{r}(t) = \boxed{\text{_____}} \langle x(t), y(t), z(t) \rangle = x(t) \vec{i} + y(t) \vec{j} + z(t) \vec{k}$$

aspect of analysis

- domain where  $\vec{r}(t)$  is well-defined

find the domain of  $\vec{r}(t) = \left\langle \frac{t-2}{t+2}, \sin t, \ln(9-t^2) \right\rangle$

#38, 40 (p874)

- limit  $\lim_{t \rightarrow a} \vec{r}(t) = \left\langle \lim_{t \rightarrow a} x(t), \lim_{t \rightarrow a} y(t), \lim_{t \rightarrow a} z(t) \right\rangle$

$$\lim_{t \rightarrow 0} \left\langle (1+t)^3, t e^{-t}, \frac{\sin t}{t} \right\rangle =$$

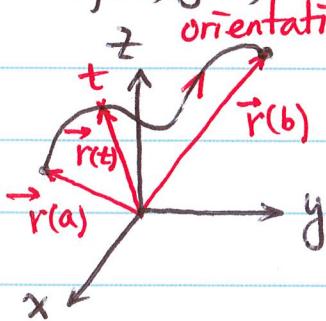
- continuity  $\vec{r}(t)$  is continuous at  $t=a \iff \lim_{t \rightarrow a} \vec{r}(t) = \vec{r}(a)$

## Aspect of geometry

- curves in space

$$C = \left\{ \vec{r}(t) = \langle f(t), g(t), h(t) \rangle \mid t \in I = [a, b] \right\}$$

$$\begin{array}{c} + \\ \longrightarrow \\ a \quad t \quad b \end{array}$$



How to represent curves in plane and space?

- (1) graph
- (2) level curve
- (3) parametric curve

examples (1) line segment from  $P(2, -1, 4)$  to  $Q(3, 0, 6)$

(2) a spiral graph  $\vec{r}(t) = \langle 4 \cos t, \sin t, \frac{t}{2\pi} \rangle$

$$0 \leq t \leq \pi \quad \text{and} \quad -\infty < t < \infty$$

(3) Roller coaster curve  $\vec{r}(t) = \langle \cos t, \sin t, 0.4 \sin 2t \rangle$

(4) Slinky curve  $\vec{r}(t) = \langle (3 + \cos 15t) \cos t, (3 + \cos 15t) \sin t, \sin 15t \rangle$   
 $0 \leq t \leq \pi$

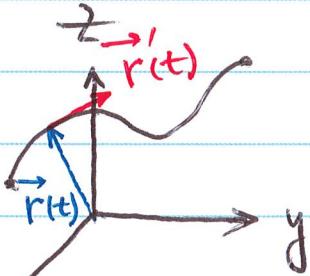
## §14.2 Calculus of Vector-Valued Functions

- derivative  $\vec{r}(t) = \langle f(t), g(t), h(t) \rangle$

$$\vec{r}'(t) = \lim_{\Delta t \rightarrow 0} \frac{\vec{r}(t + \Delta t) - \vec{r}(t)}{\Delta t} ? = \langle f'(t), g'(t), h'(t) \rangle$$

#11, 16

- tangent vector



$$\vec{T}(t) = \frac{\vec{r}'(t)}{\|\vec{r}'(t)\|} \sim \text{unit tangent vector}$$

#24, 28

- derivative rules

$$(1) \frac{d}{dt} \vec{c} = \vec{0} \quad (\text{constant } \vec{c}) ; \quad (2) \left( \vec{u}(t) + \vec{v}(t) \right)' = \vec{u}'(t) + \vec{v}'(t)$$

$$(3) \left[ f(t) \vec{u}(t) \right]' = f'(t) \vec{u}(t) + f(t) \vec{u}'(t); \quad (4) \frac{d}{dt} \vec{u}(f(t)) = \vec{u}'(f(t)) \cdot f'(t)$$

$$(5) \left[ \vec{u} \cdot \vec{v} \right]' = \vec{u}' \cdot \vec{v} + \vec{u} \cdot \vec{v}'; \quad (6) \left[ \vec{u} \times \vec{v} \right]' = \vec{u}' \times \vec{v} + \vec{u} \times \vec{v}'$$

#34, 38, 48

- higher-order derivatives

#56

- integral  $\vec{r}(t) = \langle f(t), g(t), h(t) \rangle$

$$\int \vec{r}(t) dt = \left\langle \int f(t) dt, \int g(t) dt, \int h(t) dt \right\rangle$$

$$\int_a^b \vec{r}(t) dt = \left\langle \int_a^b f(t) dt, \int_a^b g(t) dt, \int_a^b h(t) dt \right\rangle$$

#71, 77

### §14.3 Motion in Space

- position  $\vec{r}(t) = \langle x(t), y(t), z(t) \rangle$

- velocity  $\vec{v}(t) = \vec{r}'(t) = \langle x'(t), y'(t), z'(t) \rangle$

$$\text{speed} \quad |\vec{v}(t)| = \sqrt{x'(t)^2 + y'(t)^2 + z'(t)^2}$$

- acceleration  $\vec{a}(t) = \vec{v}'(t) = \vec{r}''(t)$

#10, 49

- straight-line motion  $\vec{r}(t) = \langle x_0 + at, y_0 + bt, z_0 + ct \rangle, t \geq 0$

- circular motion  $\vec{r}(t) = \langle A \cos t, A \sin t \rangle, t \in [0, 2\pi]$

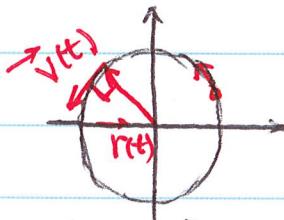
Theorem (motion with constant  $|\vec{r}|$ )

$\vec{r}$  is a path on which  $|\vec{r}|$  is const. (motion on a circle or sphere)  
center at the origin.

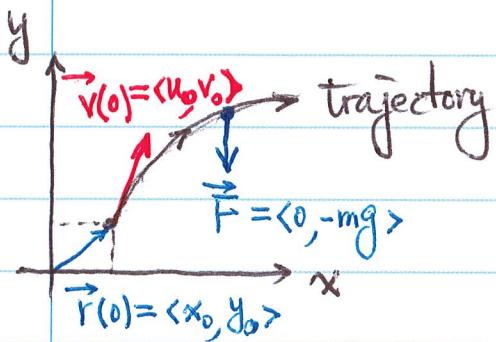
$$\Rightarrow \vec{r} \cdot \vec{v} = 0$$

Proof  $|\vec{r}|^2 = \text{const.}$

$$\Rightarrow 0 = \frac{d}{dt} |\vec{r}|^2 = \frac{d}{dt} (\vec{r} \cdot \vec{r}) = 2 \vec{r} \cdot \vec{v}.$$



- two-dimensional motion in a gravitational field



$$g = 9.8 \text{ m/s}^2 = 32 \text{ ft/s}^2$$

Newton's second law

$$m \vec{a}(t) = \vec{F} = <0, -mg>$$

$$\Rightarrow \vec{a}(t) = <0, -g>$$

$$\begin{cases} \vec{v}'(t) = \vec{a}(t) \\ \vec{v}(0) = <u_0, v_0> \end{cases} \Rightarrow \vec{v}(t) = <u_0, -gt + v_0>$$

$$\begin{cases} \vec{r}'(t) = \vec{v}(t) \\ \vec{r}(0) = <x_0, y_0> \end{cases}$$

$$\Rightarrow \vec{r}(t) = <u_0 t + x_0, -\frac{1}{2} g t^2 + v_0 t + y_0>$$

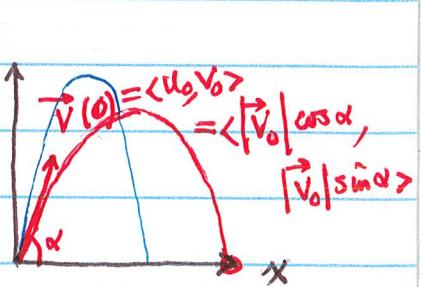
Assume that  $\vec{r}(0) = \langle 0, 0 \rangle$ ,  $\vec{r}(t) = \langle x(t), y(t) \rangle$

- time of flight

it returns to the ground ( $0 = y(t)$ )

$$\Rightarrow 0 = y(t) = -\frac{1}{2}gt^2 + |\vec{v}_0| \sin \alpha t$$

$$\Rightarrow T = 2 |\vec{v}_0| \sin \alpha / g$$



- range of the object

$$x(T) = |\vec{v}_0| \cos \alpha T = \frac{|\vec{v}_0|^2 \sin 2\alpha}{g}$$

- maximum height of the object ( $0 = y'(t)$ )

$$0 = y'(t) = -gt + |\vec{v}_0| \sin \alpha \Rightarrow t = \frac{|\vec{v}_0| \sin \alpha}{g} = \frac{T}{2}$$

$$\Rightarrow y\left(\frac{T}{2}\right) = \frac{|\vec{v}_0|^2 \sin^2 \alpha}{2g}$$

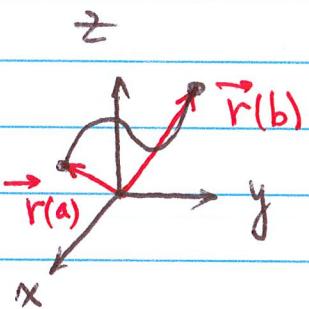
- three-dimensional motion in a gravitational field

$$\vec{m}\vec{a} = \vec{F} = \langle 0, 0, -mg \rangle$$

$$\vec{a} = \langle 0, 0, -g \rangle$$

## §14.4 Length of Curves

curve  $C: \vec{r}(t) = \langle f(t), g(t), h(t) \rangle$   
 $a \leq t \leq b$



- arc length

$$L = \int_a^b \left| \vec{v}(t) \right| dt = \int_a^b \sqrt{f'(t)^2 + g'(t)^2 + h'(t)^2} dt$$

#14.24  
 $C: \text{unit circle } x^2 + y^2 = 1$        $\begin{cases} \vec{r}_1 = \langle \cos t, \sin t \rangle, t \in [0, 2\pi] \\ \vec{r}_2 = \langle \cos 2t, \sin 2t \rangle, t \in [0, \pi] \end{cases}$       arc length

- arc length as a parameter

$$s(t) = \int_a^t \left| \vec{v}(u) \right| du \iff \frac{ds}{dt} = \left| \vec{v}(t) \right| \approx \text{speed.}$$

Example 3 helix  $\vec{r}(t) = \langle 2 \cos t, 2 \sin t, 4t \rangle$  for  $t \geq 0$

(a) Find the arc length function  $s(t)$

(b) use arc length as the parameter to describe the helix.

$$\begin{cases} s = s(t) \implies t = t(s) \\ \vec{r}(t) \implies \vec{r}(t(s)) = \vec{r}(s) \end{cases} \quad \text{--- arc length parametrization}$$

## §14.5 Curvature and Normal Vectors

- curvature (how a curve turns or bends)

(1)  $\vec{r}(t)$  is smooth  $\Leftrightarrow \vec{r}'(t)$  is cont. &  $\vec{r}'(t) \neq 0$



(2)  $C$  is a smooth curve  $\Leftrightarrow C$  has a smooth parametrization

(3) unit tangent vector  $\vec{T}(t) = \frac{\vec{r}'(t)}{|\vec{r}'(t)|}$

(4) curvature of a curve

$$K = \left| \frac{d\vec{T}}{ds} \right| \quad \text{measurement of how quickly the curve changes direction}$$

$$\vec{T}(s) = \vec{T}\left(\frac{s(t)}{s}\right)$$

$$\Rightarrow \frac{d\vec{T}}{dt} = \frac{d\vec{T}}{ds} \cdot \frac{ds}{dt}$$

$$= \left| \frac{d\vec{T}}{dt} / \frac{ds}{dt} \right| = \frac{1}{|\vec{v}|} \left| \frac{d\vec{T}}{dt} \right|$$

$$K = \boxed{\left| \frac{\vec{T}'(t)}{|\vec{r}'(t)|} \right|} = \boxed{\frac{|\vec{v} \times \vec{a}|}{|\vec{v}|^3}} \quad \boxed{\vec{v} = \vec{r}'(t)} \quad \boxed{\vec{a} = \vec{r}''(t)}$$

#12, 14, 16, 22

- principal unit normal vector at  $K \neq 0$

$\vec{T}$

$s$

$\vec{N} = \frac{1}{K} \frac{d\vec{T}}{ds} = \frac{\vec{T}'(t)}{|\vec{T}'(t)|}$

turning direction

$$1 = |\vec{T}| \Rightarrow \vec{T} \cdot \vec{T} = 1$$

$$\Rightarrow 0 = \frac{d}{dt} (\vec{T} \cdot \vec{T}) = 2\vec{T} \cdot \vec{T}'$$

$$\Rightarrow \vec{T} \perp \vec{T}'$$

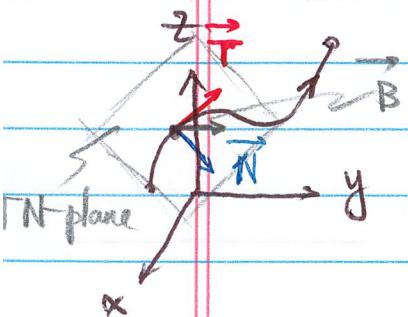
Example 5 the helix  $\vec{r}(t) = \langle a \cos t, a \sin t, bt \rangle$

$$t \in (-\infty, +\infty), a > 0, b > 0$$

$$\vec{N} = ?$$

• unit binormal vector  $\vec{B} = \vec{T} \times \vec{N}$  (Fig. 14.38)

• torsion  $\tau = - \frac{d\vec{B}}{ds} \cdot \vec{N}$  the rate at which the curve twists out of the TN-plane.



$$\begin{aligned} \tau &= - \frac{d\vec{B}}{ds} \cdot \vec{N} \\ &= \frac{(\vec{r}' \times \vec{r}'') \cdot \vec{r}'''}{|\vec{r}' \times \vec{r}''|^2}. \end{aligned}$$

Ex. 8 and 9.