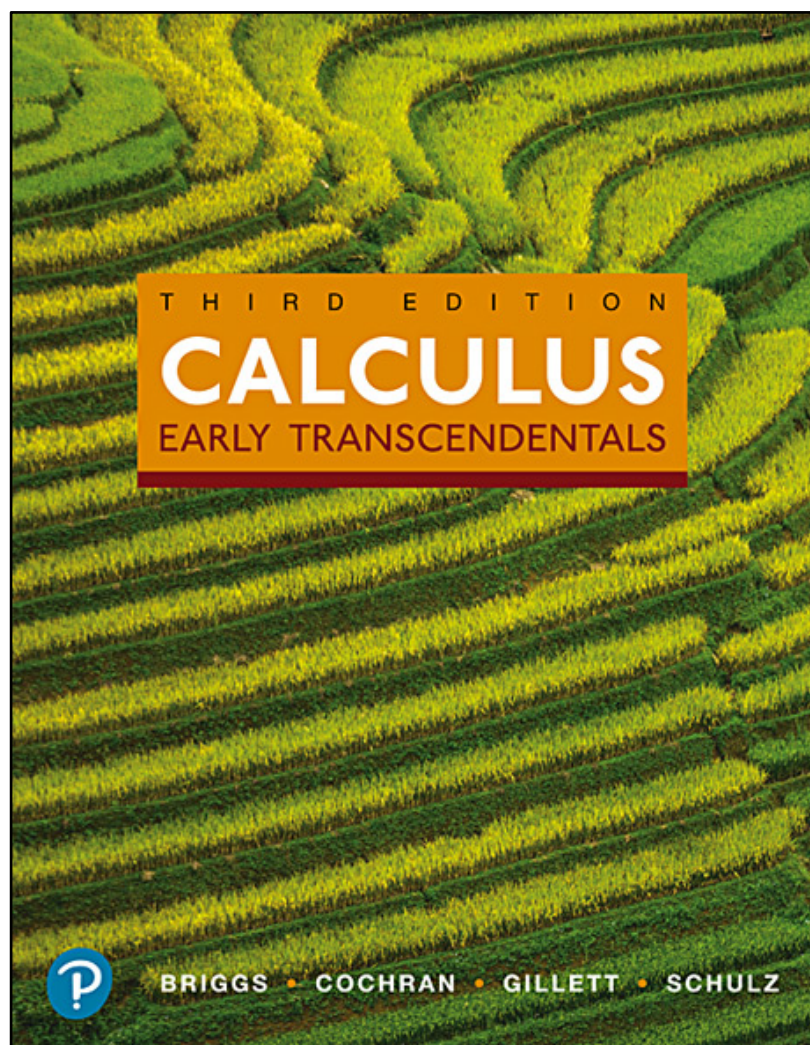


Calculus Early Transcendentals

Third Edition



Chapter 17 Vector Calculus

Lesson	Section	
25	§17.1	Vector Field
26 } 27 }	§17.2	<u>Line Integral</u> $\left\{ \begin{array}{l} \text{scalar-valued function} \\ \text{vector field} \end{array} \right.$
28	§17.3	Conservative VF
29	§17.4	Green's Theorem
30	§17.5	Divergence and Curl
31 } 32 } 33 }	§17.6	<u>Surface Integrals</u>
34 } 35 }	§17.7	<u>Stokes' Theorem</u>
36 } 37 }	§17.8	<u>Divergence Theorem</u>

$\begin{cases} y = f(x) & \text{scalar-valued function} \\ z = f(x, y) & \dots \end{cases}$

$\vec{r}(t) = \langle \underline{x(t)}, \underline{y(t)}, \underline{z(t)} \rangle$ vector-valued function

$\vec{F}(x, y) = \langle f(x, y), g(x, y) \rangle$ vector-valued function

Section 17.1 Vector Fields

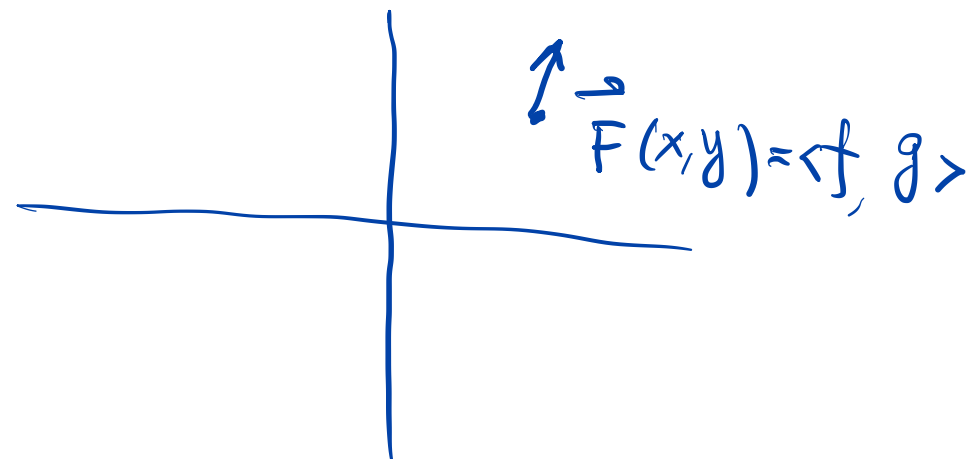
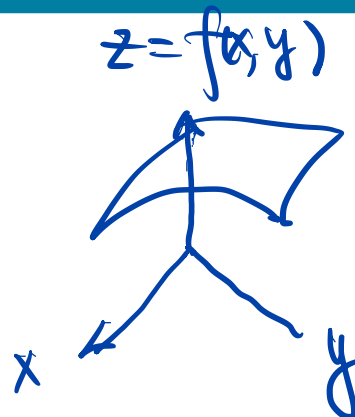
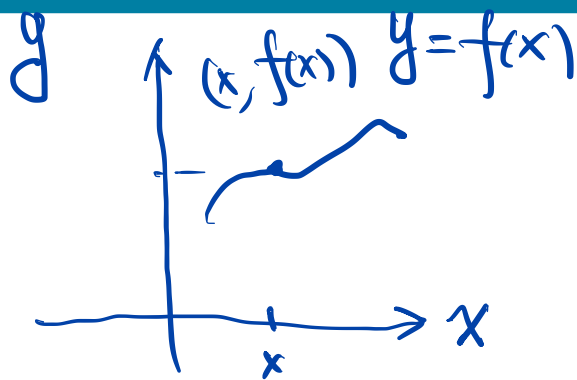


Figure 17.1

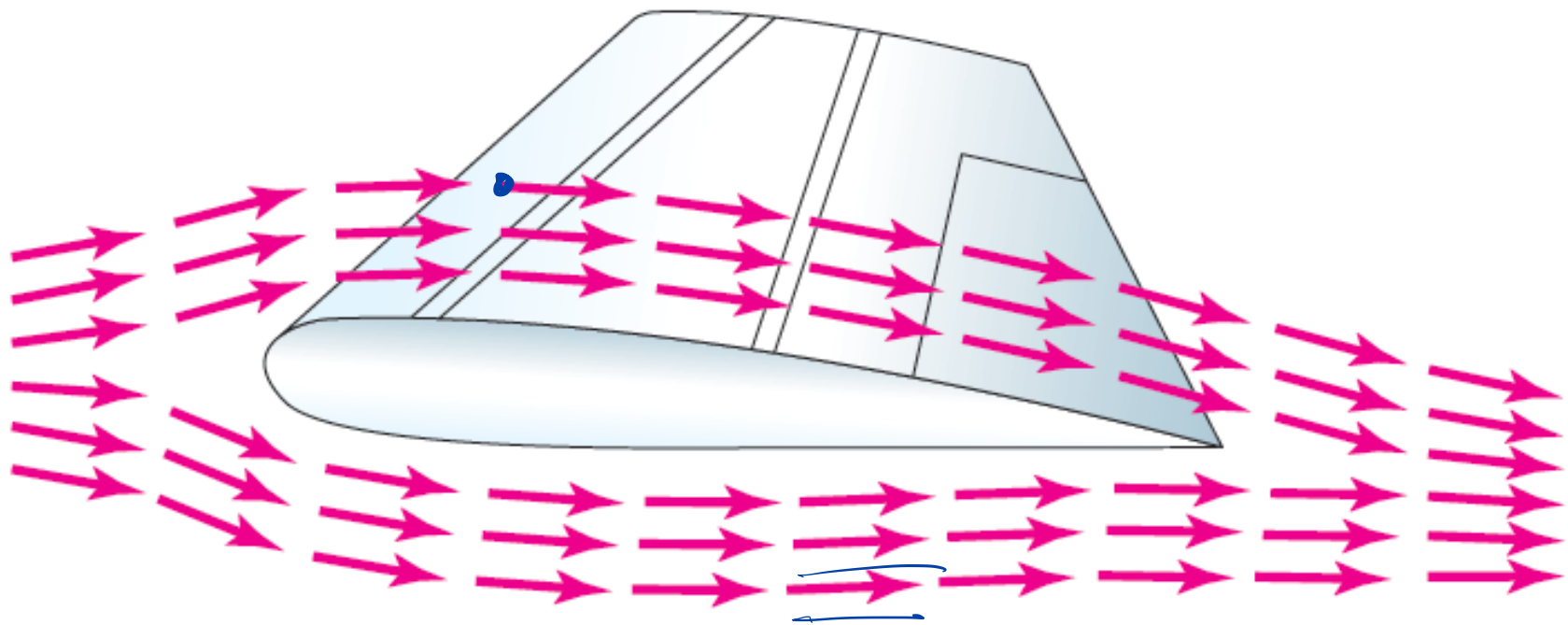


Figure 17.2 (a & b)

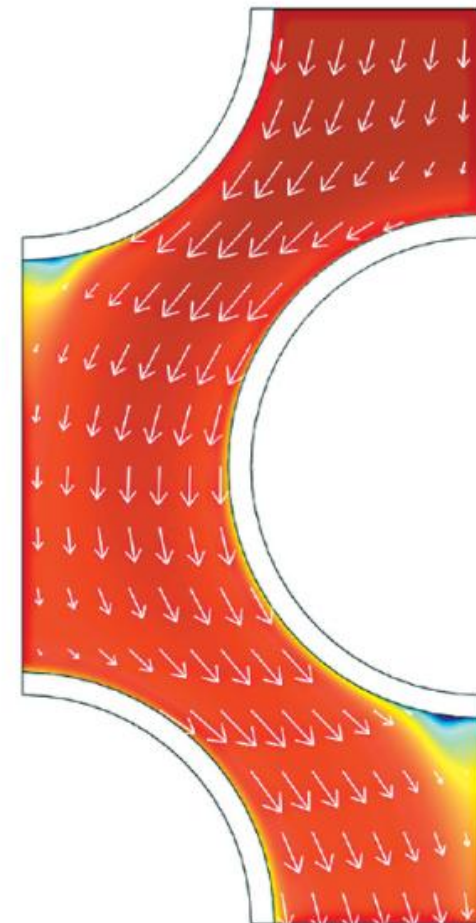
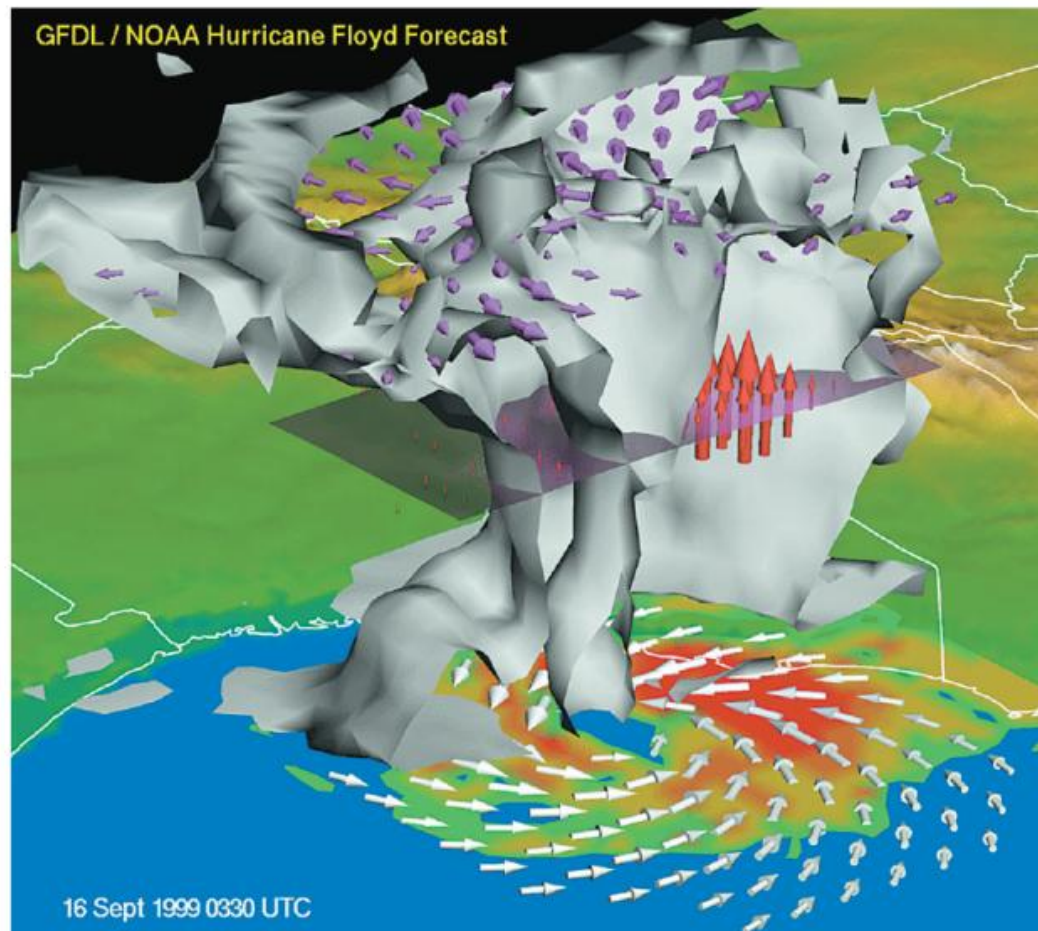
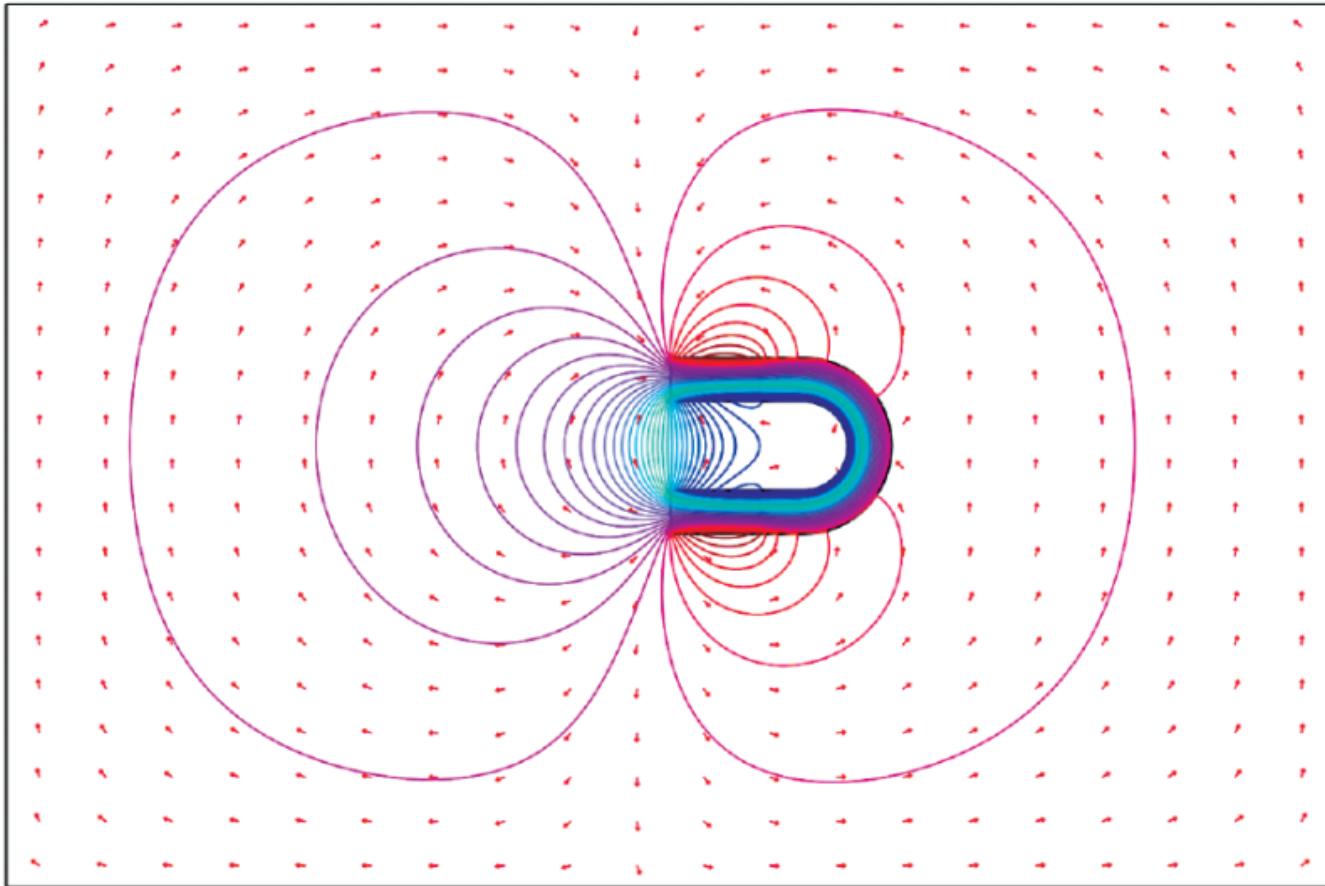


Figure 17.2 (c)



Definition Vector Fields in Two Dimensions

$$\vec{F}(x_1, \dots, x_d) = \langle f_1, \dots, f_d \rangle \quad \underline{\underline{d=c}}$$

Let f and g be defined on a region R of $\mathbb{R}^2$. A **vector field** in

◦ $\mathbb{R}^2$ is a function $\mathbf{F}$ that assigns to each point in R a vector

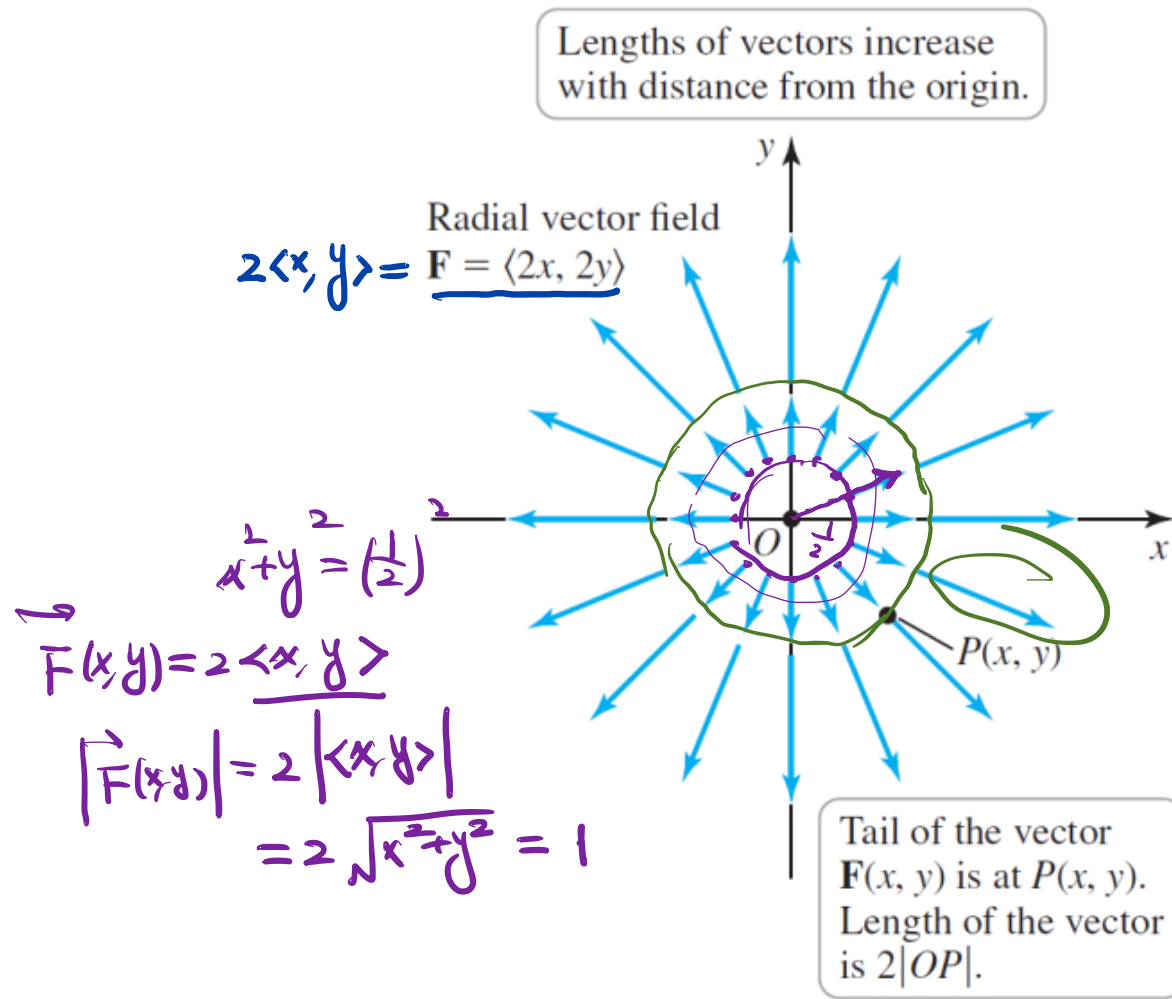
$\langle f(x, y), g(x, y) \rangle$. The vector field is written as

$$\mathbf{F}(x, y) = \langle f(x, y), g(x, y) \rangle \text{ or } R \rightarrow R$$

$$\mathbf{F}(x, y) = f(x, y)\mathbf{i} + g(x, y)\mathbf{j}.$$

A vector field $\mathbf{F} = \langle f, g \rangle$ is continuous or differentiable on a region R of $\mathbb{R}^2$ if f and g are continuous or differentiable on R , respectively.

Figure 17.3



Example 1 Sketch representative vectors of the following VFs:

(a) $\vec{F}(x,y) = \langle 0, x \rangle$ (a shear field); (b) $\vec{F}(x,y) = \langle 1-y^2, 0 \rangle$ for $|y| \leq 1$ (channel flow)

Figure 17.4

(c) $\vec{F}(x,y) = \langle -y, x \rangle$ (a rotation field)

$\vec{F} = \langle 0, x \rangle$ $\left\{ \begin{array}{l} \uparrow x > 0 \\ \downarrow x < 0 \end{array} \right.$

$\vec{F}(x,y) = \langle 0, 1 \rangle$
 $x=1$

$\vec{F}(x,y) = \langle 1-y^2, 0 \rangle$

$\vec{F}(x,y) = \langle -y, x \rangle$

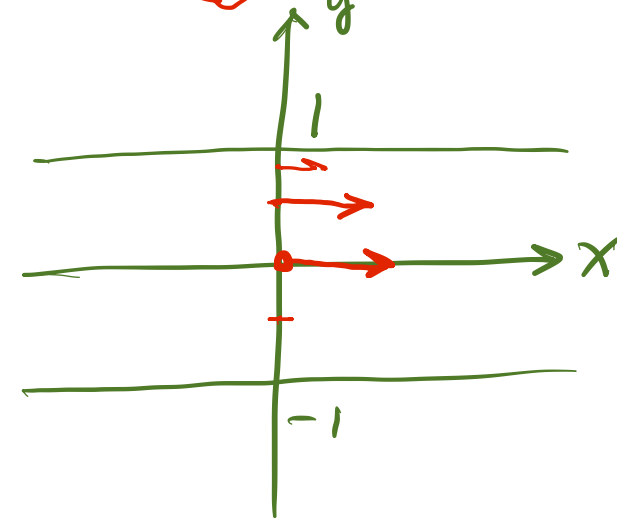
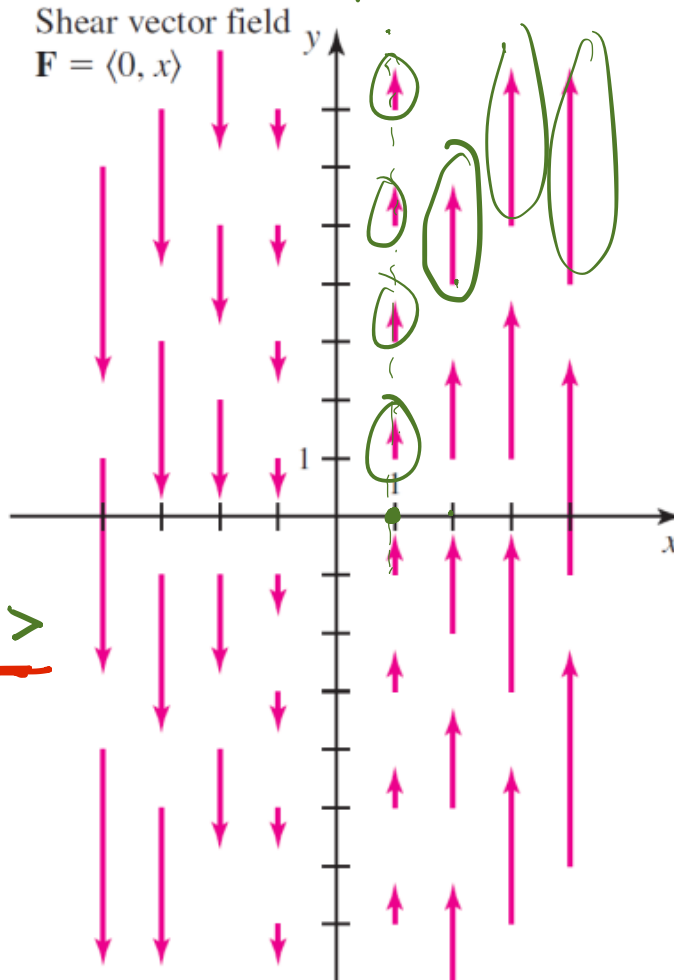
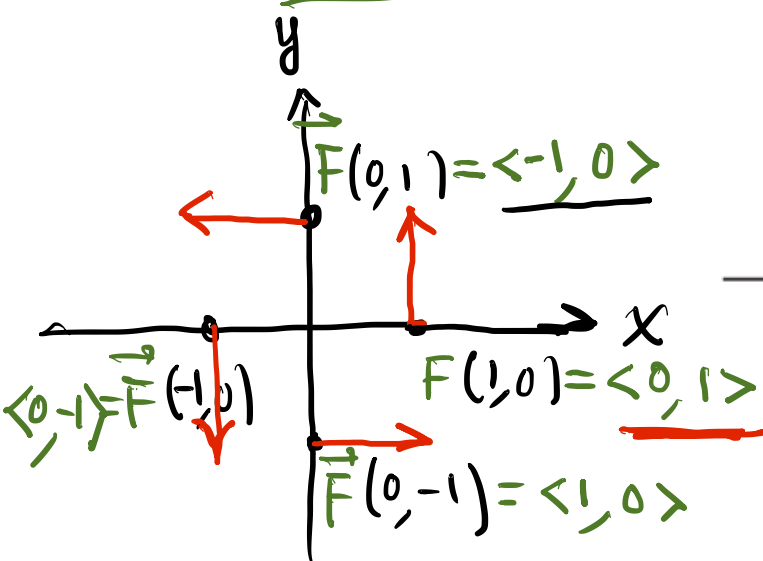


Figure 17.5

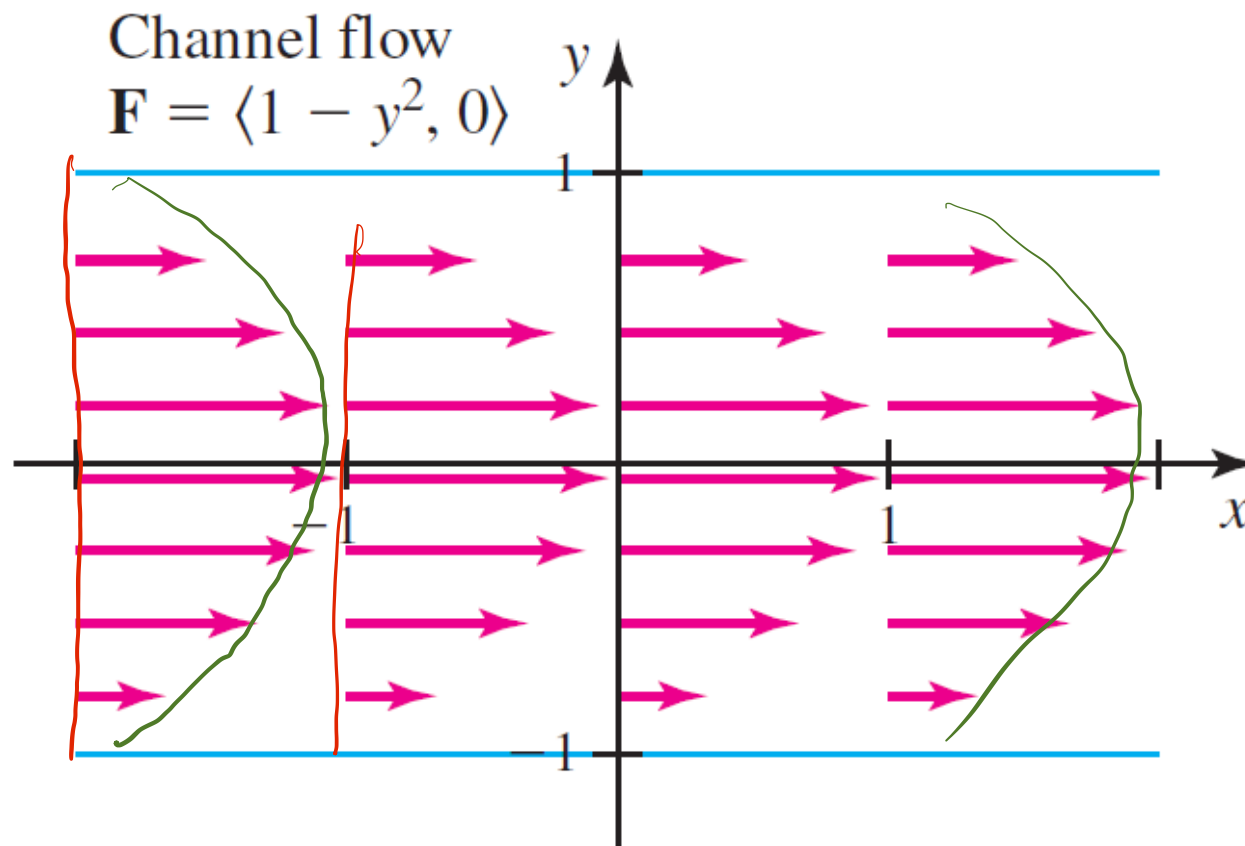


Figure 17.6

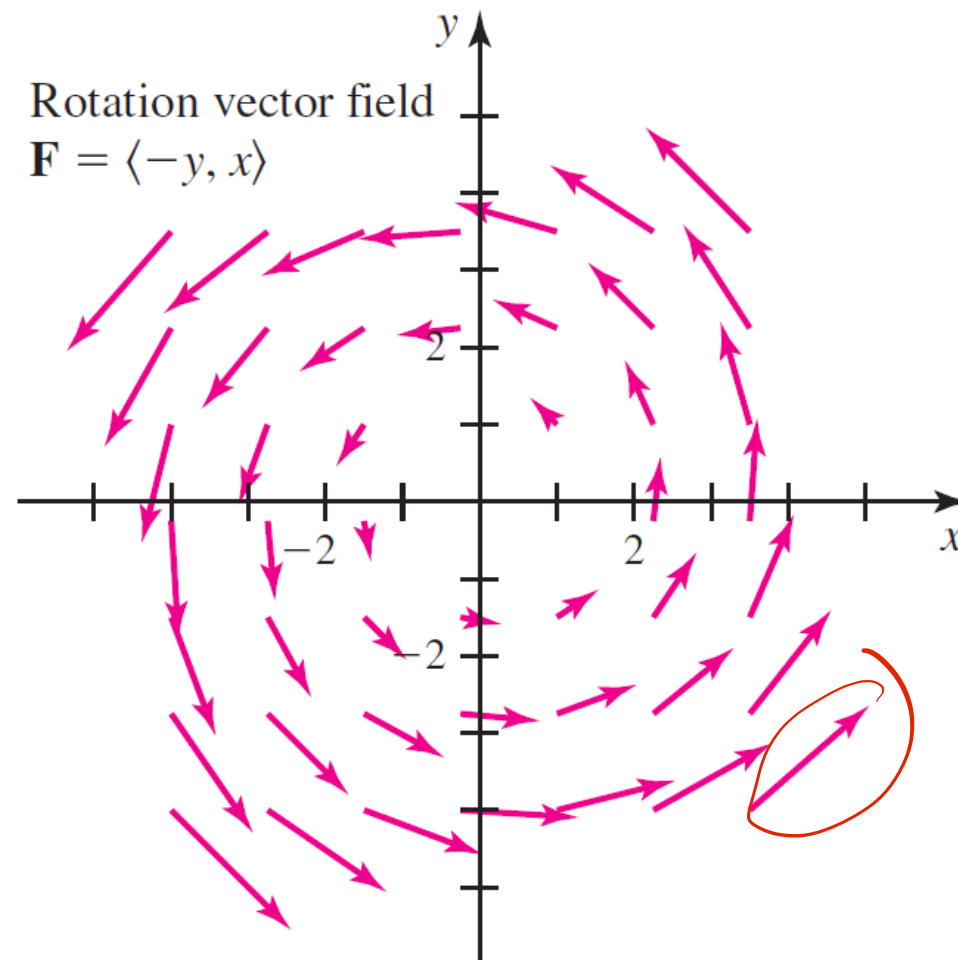
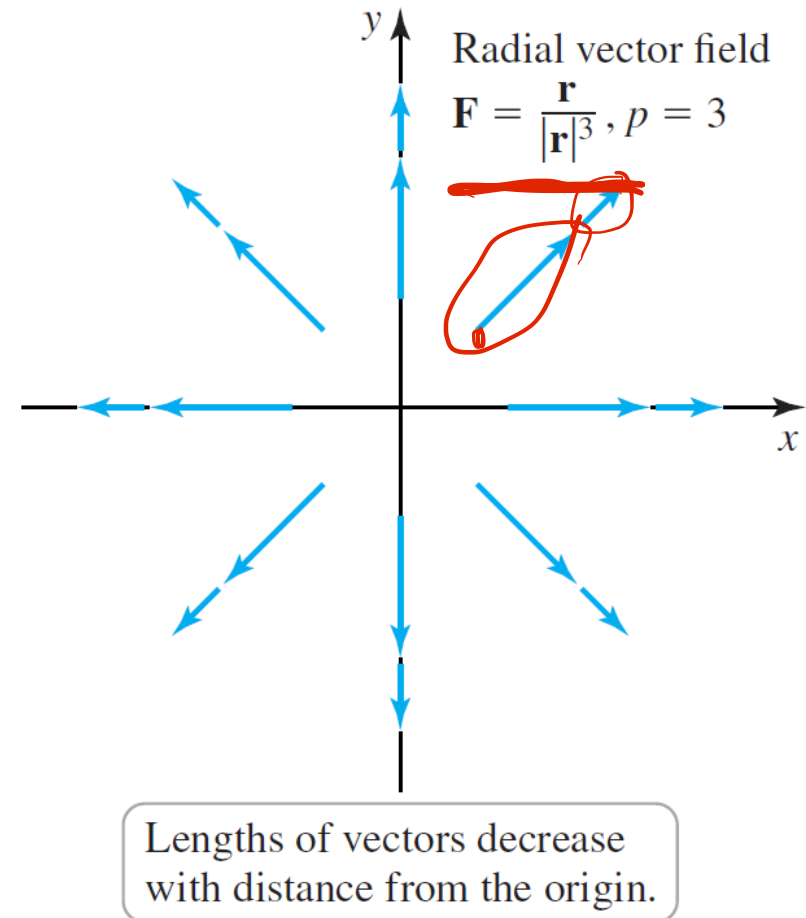
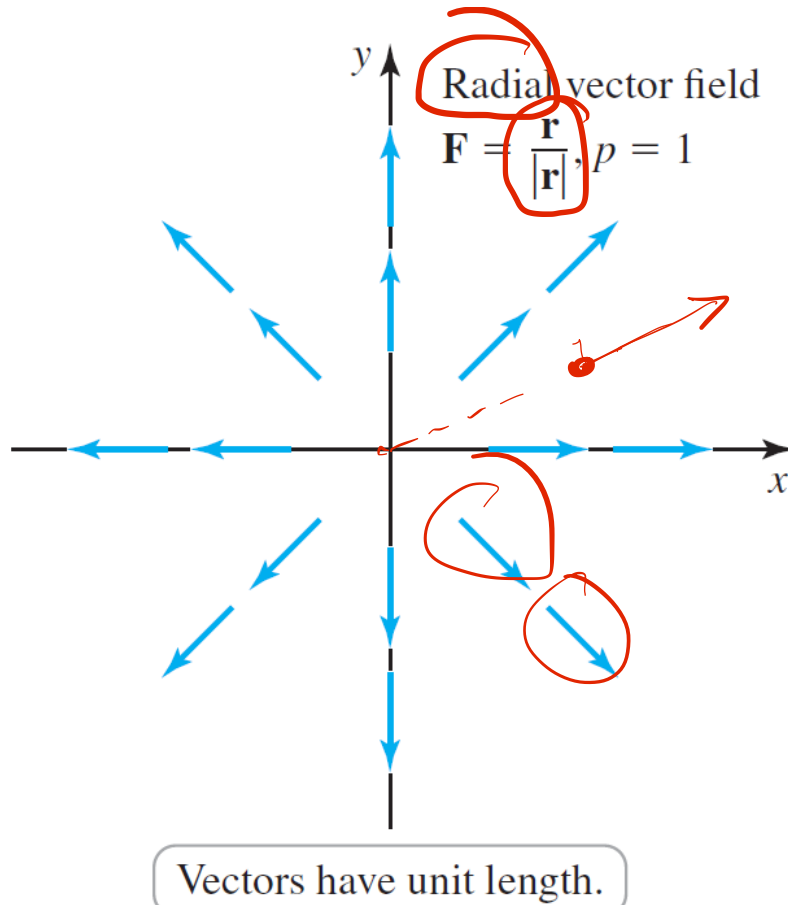


Figure 17.7



Definition Radical Vectors Fields in R^2

Let $\mathbf{r} = \langle x, y \rangle$. A vector field of the form $\mathbf{F} = f(x, y)\mathbf{r}$,

where f is a scalar-valued function, is a **radial vector field**. Of specific interest are the radial vector fields

$$\mathbf{F}(x, y) = \frac{\mathbf{r}}{|\mathbf{r}|^p} = \frac{\langle x, y \rangle}{|\mathbf{r}|^p},$$

where p is a real number. At every point (except the origin), the vectors of this field are directed outward from the origin with a

Magnitude of $|\mathbf{F}| = \frac{1}{|\mathbf{r}|^{p-1}}$.

Example 2 Let C be the circle $x^2 + y^2 = a^2$, where $a > 0$.

(a) Show that at each pt of C , $\vec{F} = \vec{r}/|\vec{r}|$ is orthogonal to the line tangent to C at that pt.

(b) $\vec{G} = \frac{\langle -y, x \rangle}{\sqrt{x^2 + y^2}}$ is parallel

Figure 17.8

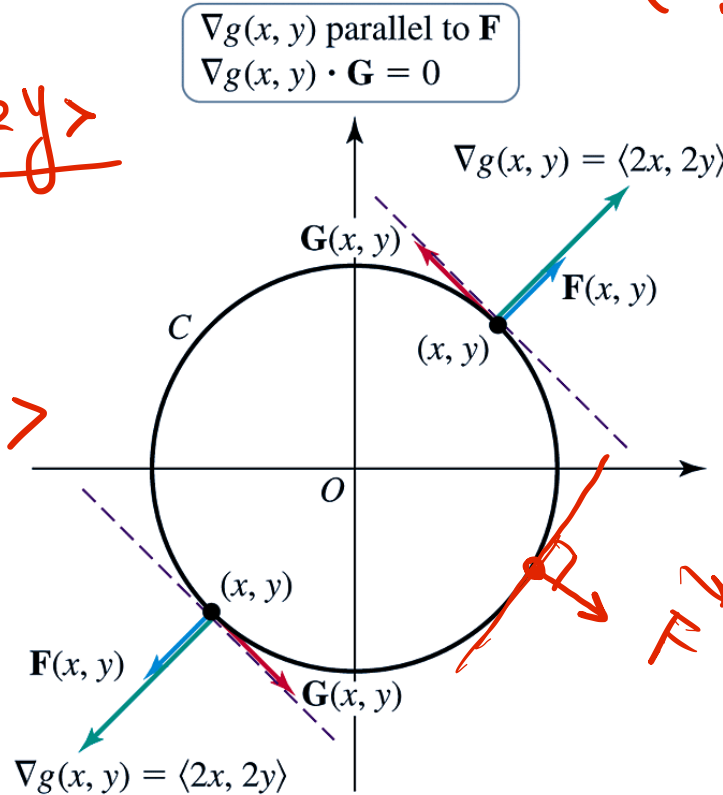
$$C: \phi = x^2 + y^2 = a^2$$

$$\nabla \phi = \langle \phi_x, \phi_y \rangle = \langle 2x, 2y \rangle$$

$$= 2 \langle x, y \rangle$$

$$\vec{F} = \frac{\langle x, y \rangle}{\sqrt{x^2 + y^2}} = \frac{1}{a} \langle x, y \rangle$$

$$= \frac{1}{2a} \nabla \phi$$



$$\text{Radial field } \vec{F} = \frac{\langle x, y \rangle}{\sqrt{x^2 + y^2}}$$

$$\text{Rotation field } \vec{G} = \frac{\langle -y, x \rangle}{\sqrt{x^2 + y^2}}$$

(b) $\nabla \phi \perp \vec{G}$

$$2 \langle x, y \rangle \cdot \frac{\langle -y, x \rangle}{\sqrt{x^2 + y^2}}$$

$$= \frac{2}{a} (-xy + yx) = 0$$

$$\Rightarrow \nabla \phi \perp \vec{G}$$

Definition Vector Fields and Radical Vector Fields in $\mathbb{R}^3$

Let f , g , and h be defined on a region D of $\mathbb{R}^3$. A **vector field** in $\mathbb{R}^3$ is a function $\mathbf{F}$ that assigns to each point in D a vector

$\langle f(x, y, z), g(x, y, z), h(x, y, z) \rangle$. The vector field is written as

$$\mathbf{F}(x, y, z) = \langle f(x, y, z), g(x, y, z), h(x, y, z) \rangle \text{ or } \mathbb{R} \rightarrow \mathbb{R}^3$$

$$\mathbf{F}(x, y, z) = f(x, y, z) \mathbf{i} + g(x, y, z) \mathbf{j} + h(x, y, z) \mathbf{k}.$$

A vector field $\mathbf{F} = \langle f, g, h \rangle$ is continuous or differentiable on a region D of $\mathbb{R}^3$ if f , g and h are continuous or differentiable on D , respectively. Of particular importance are the **radical vector fields**

$$\mathbf{F}(x, y, z) = \frac{\mathbf{r}}{|\mathbf{r}|^p} = \frac{\langle x, y, z \rangle}{|\mathbf{r}|^p},$$

where p is a real number.

Example 3 Sketch and discuss the following VFs: ≥ 0

(a) $\vec{F} = \langle x, y, e^{-z} \rangle$, for $z \geq 0$;

(b) $\vec{F} = \langle 0, 0, 1 - x^2 - y^2 \rangle$, for $x^2 + y^2 \leq 1$
 $= \langle 0, 0, 1 - r^2 \rangle$ $r \leq 1$

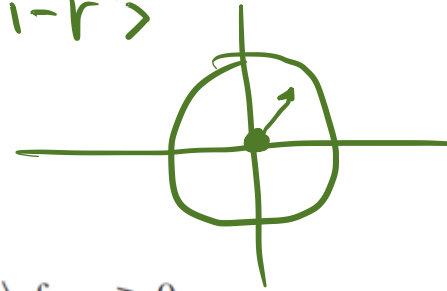


Figure 17.9

$\mathbf{F} = \langle x, y, e^{-z} \rangle$, for $z \geq 0$

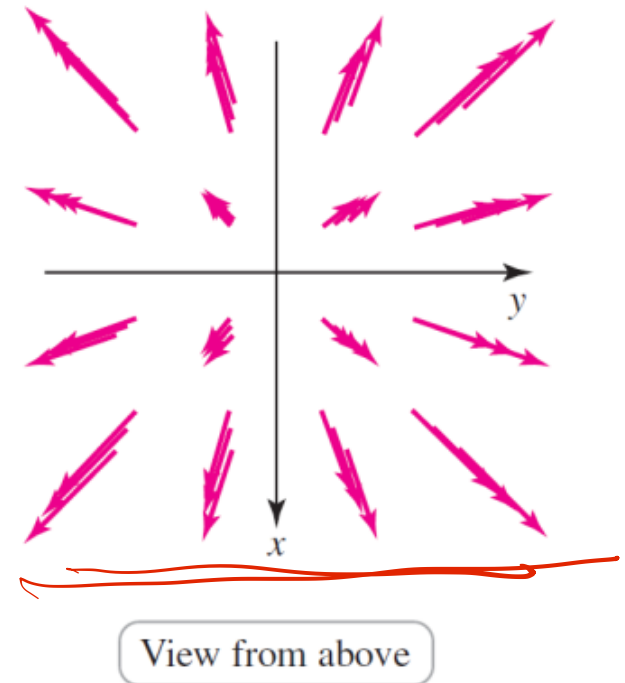
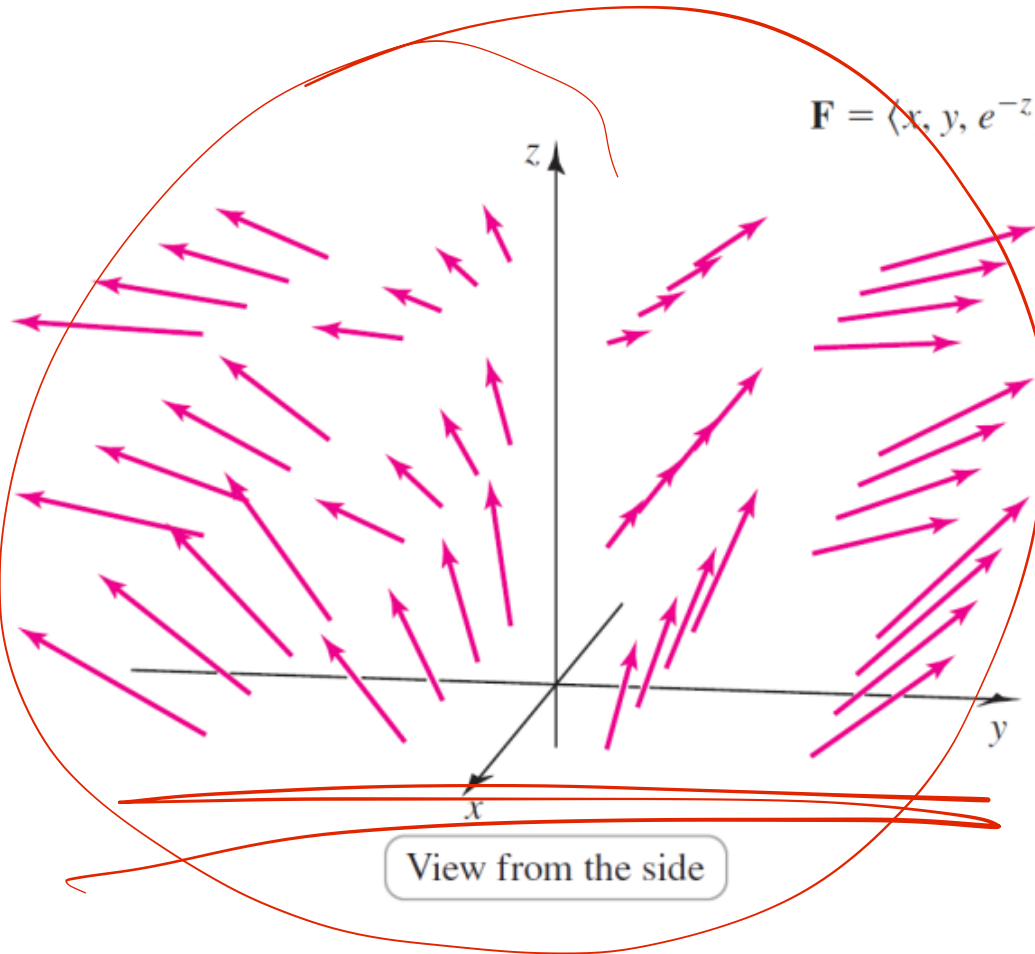
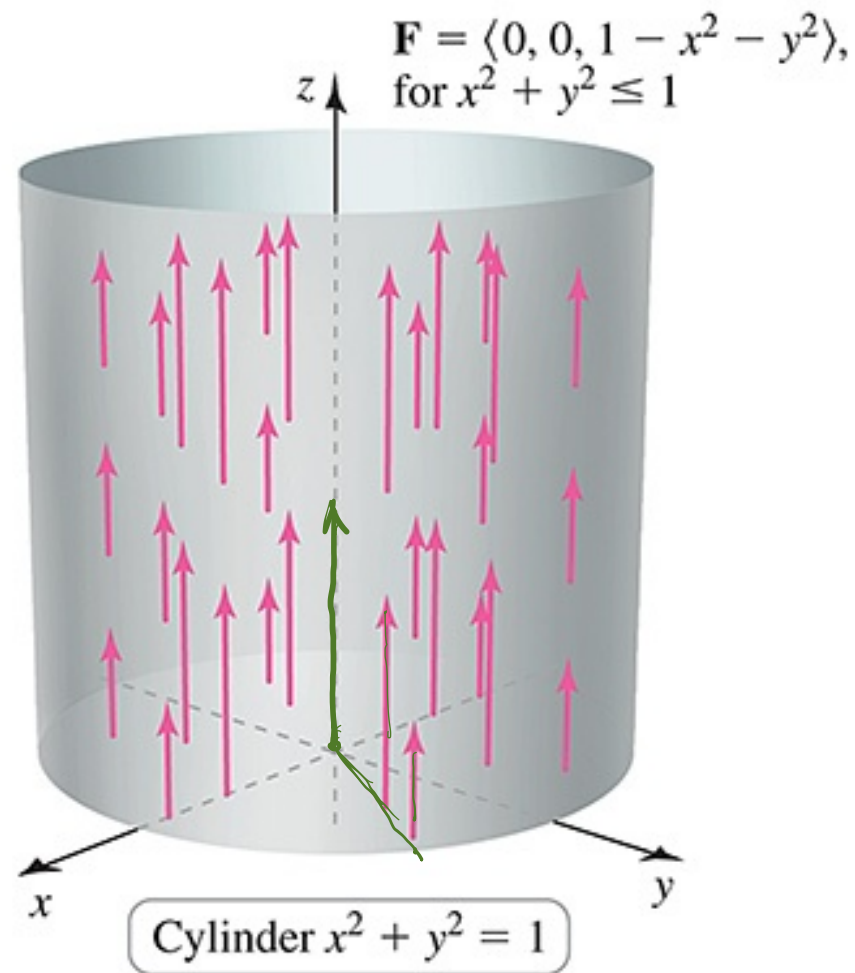


Figure 17.10



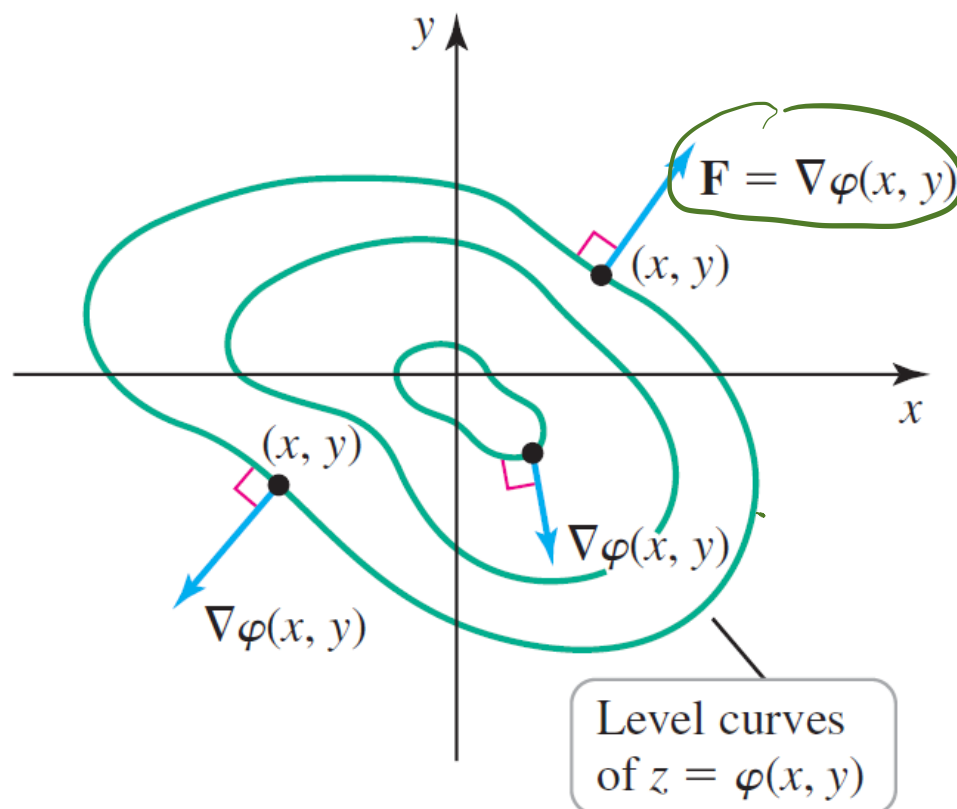
Gradient Fields and Potential Functions

$$\vec{F} = \nabla \varphi(x, y, z) = \langle \varphi_x, \varphi_y, \varphi_z \rangle$$

Figure 17.11

$$\vec{F} = \nabla \varphi$$

The vector field $\mathbf{F} = \nabla \varphi$ is orthogonal to the level curves of φ at (x, y) .



Definition Gradient Fields and Potential Functions

Let φ be differentiable on a region of $\mathbb{R}^2$ or $\mathbb{R}^3$.

The vector field $\underline{\mathbf{F}} = \nabla \underline{\varphi}$ is a **gradient field** and the function φ is a **potential function** for $\mathbf{F}$.

Example 4 (a) Sketch and interpret the gradient field associated with the temperature function $T = 200 - x^2 - y^2$ on $R = \{(x, y) : x^2 + y^2 \leq 25\}$.

(b) $\phi = \tan^{-1}(xy)$

$$\frac{(\tan^{-1} t)'}{1+t^2} = \frac{1}{1+t^2}$$

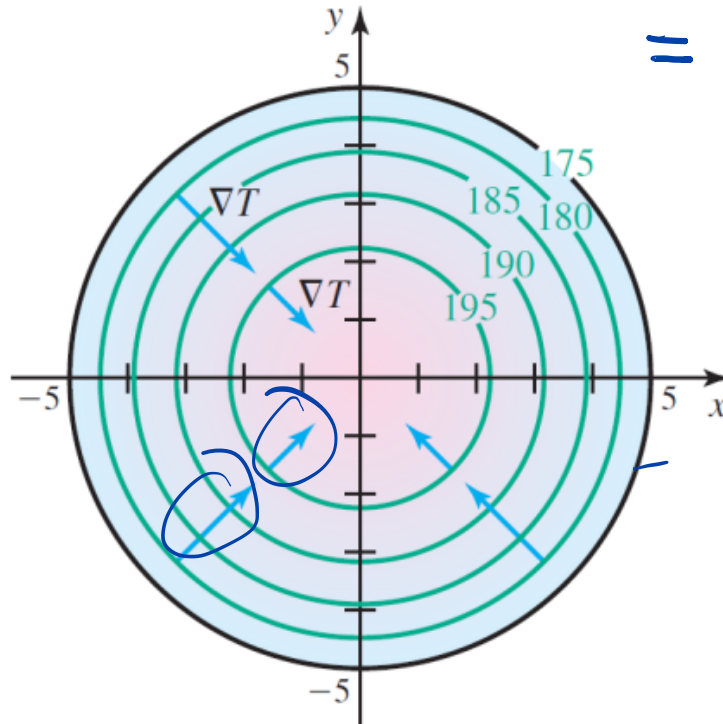
Figure 17.12

(a) $\nabla T = \langle T_x, T_y \rangle = \langle -2x, -2y \rangle = -2 \langle x, y \rangle$

$$T(x, y) = 200 - x^2 - y^2 = c$$

$$\Rightarrow \underline{x^2 + y^2 = 200 - c}$$

Gradient vectors ∇T
(not drawn to scale)
are orthogonal to
the level curves.



Level curves of $T(x, y) = 200 - x^2 - y^2$

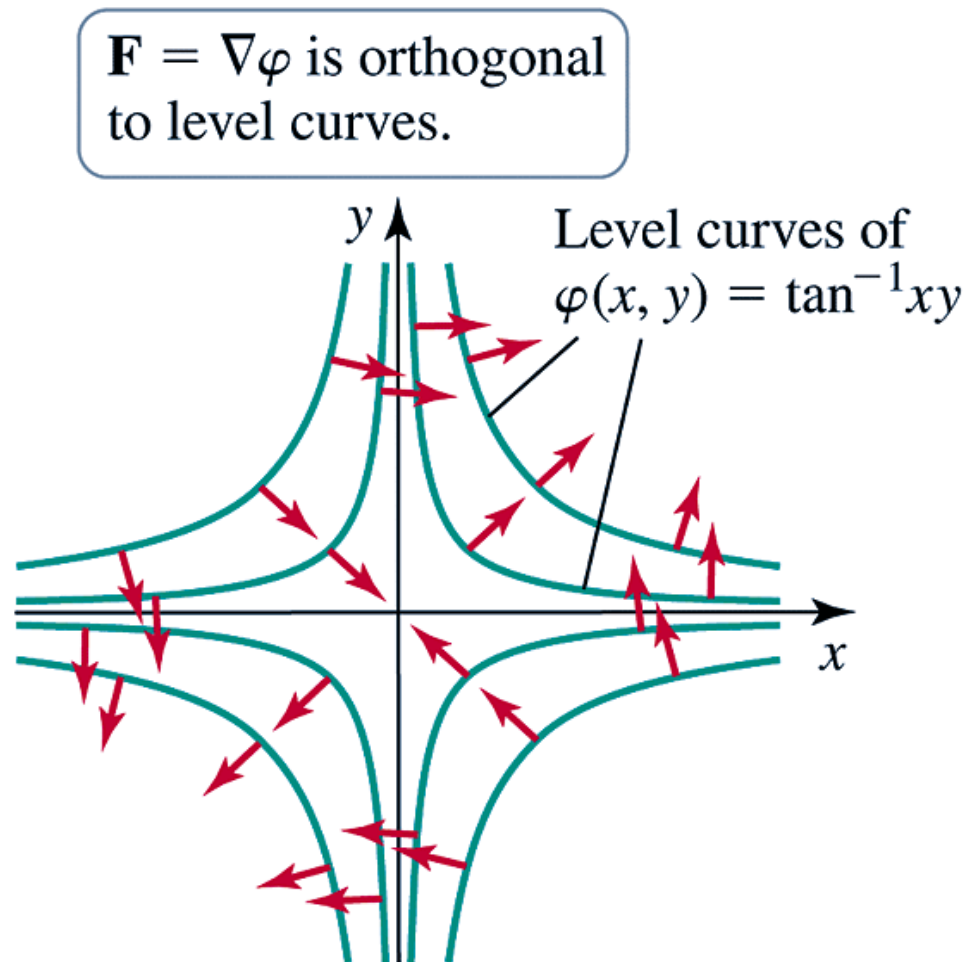
(b) $\nabla \phi = \langle \phi_x, \phi_y \rangle$
 $= \left\langle \frac{1}{1+(xy)^2} y, \frac{x}{1+(xy)^2} \right\rangle$

$$= \frac{1}{1+(xy)^2} \langle y, x \rangle$$

$$\phi = \tan^{-1}(xy) = c$$

$$\underline{xy = \tan c}$$

Figure 17.13



Equipotential Curves and Flow Curves

$$\vec{F}(x,y) = \langle f(x,y), g(x,y) \rangle$$

gradient VF

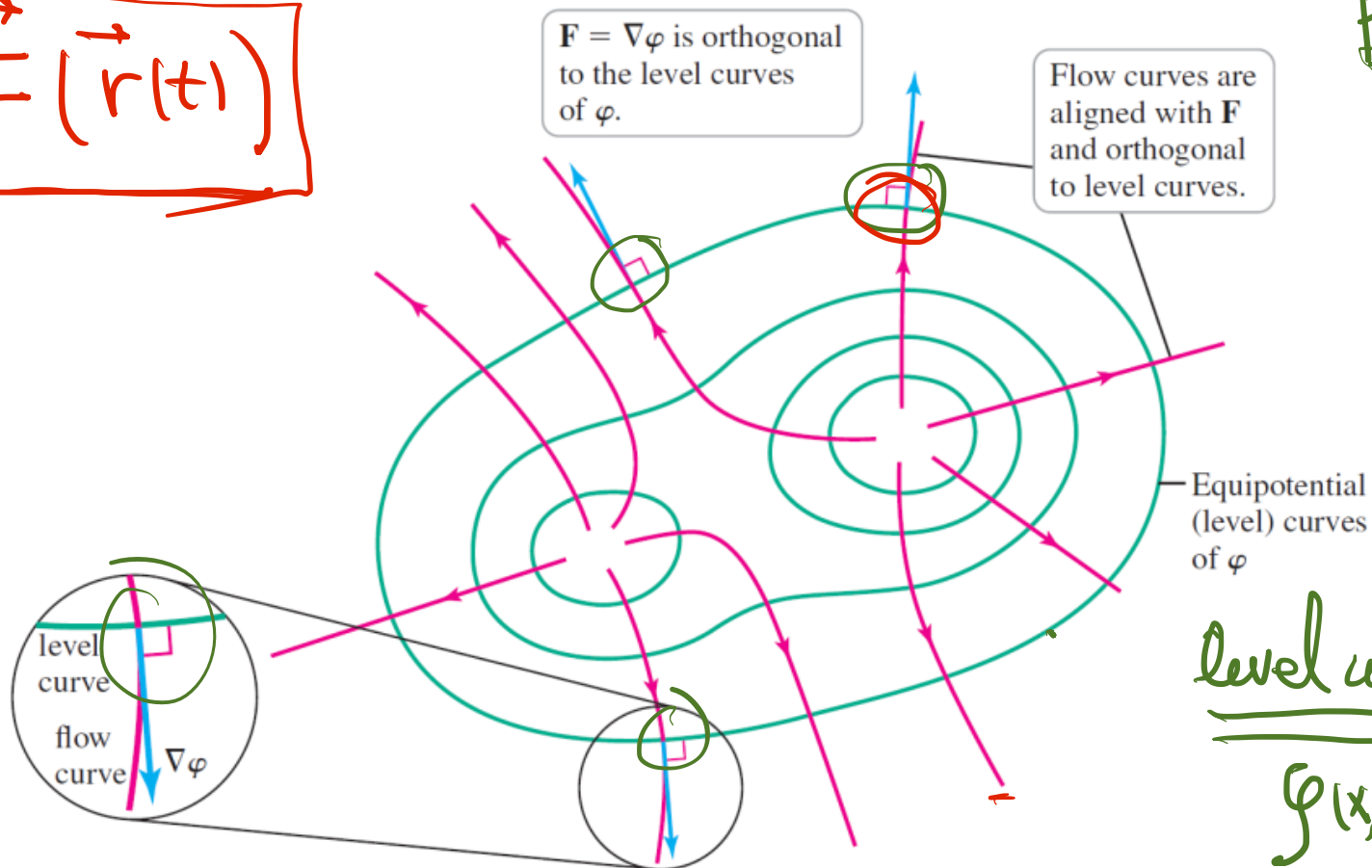
$$\vec{F} = \nabla \varphi$$

scalar-valued
potential

Figure 17.14

$$\vec{r}(t) = \langle x(t), y(t) \rangle$$

$$\vec{r}'(t) = \vec{F}(\vec{r}(t))$$

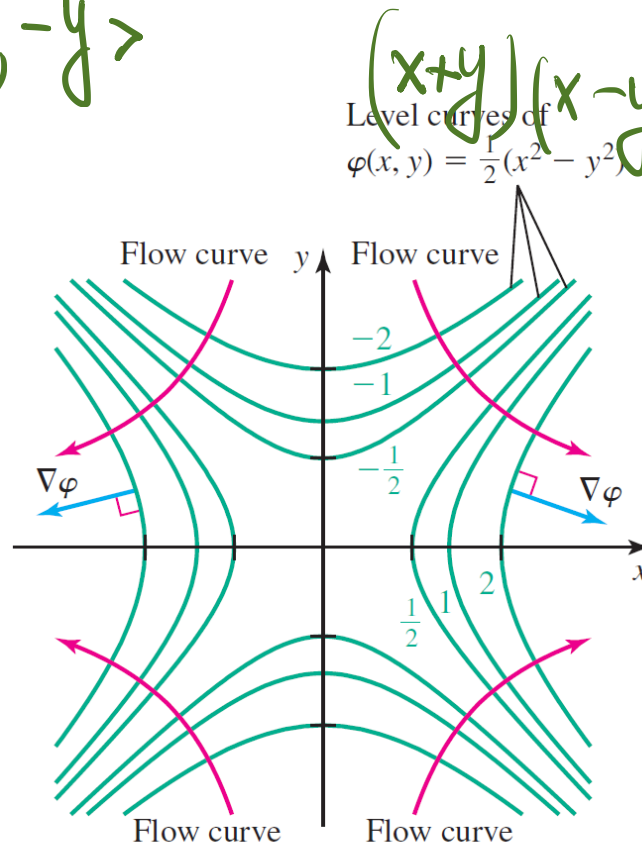


level curve of g
 $g(x,y) = c$

Example 5 The equipotential curves for the potential function $\phi = \frac{1}{2}(x^2 - y^2)$ are shown in green.
 (a) Find the gradient field associated with ϕ and verify that $\vec{F} = \nabla\phi$ is orthogonal to the equipotential curve at $(2,1)$; and (b) at all pts.

Figure 17.15

(a) $\nabla\phi = \langle \phi_x, \phi_y \rangle = \langle x, -y \rangle$



level curves of ϕ
 $\phi = c \quad \frac{1}{2}(x^2 - y^2) = c$
 $(x+y)(x-y) = \boxed{x^2 - y^2 = C}$

$xy = C$

$$\int_C f \, ds$$

$$f(x, y)$$

$$\int_C \vec{F} \cdot d\vec{r} = \int_C (\vec{F} \cdot \vec{T}) \, ds$$

$$\vec{F}(x, y) = \langle f(x, y), g(x, y) \rangle$$

Section 17.2 Line Integrals

Parametrization of a smooth curve C

- graph in $\mathbb{R}^2$ $y = f(x)$, $x \in [a, b]$

$$\begin{aligned} \vec{r}(t) &= \langle x(t), y(t) \rangle \\ &= \langle t, f(t) \rangle \\ t &\in [a, b] \end{aligned}$$

- level curve in $\mathbb{R}^2$

$$\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1$$

$$\begin{aligned} \vec{r}(t) &= \langle a \cos t, b \sin t \rangle \\ 0 &\leq t \leq 2\pi \end{aligned}$$

$$\int_C \underline{f} ds = \lim_{\Delta S_k \rightarrow 0} \sum_k \underline{f(x(t_k^*), y(t_k^*)) (\Delta S_k)}$$

Figure 17.16

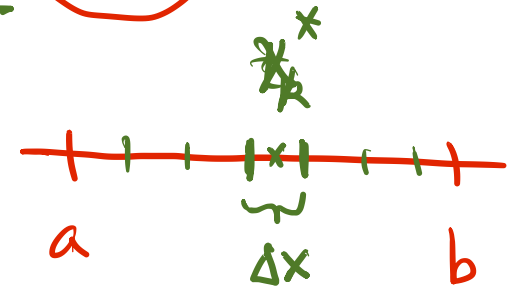
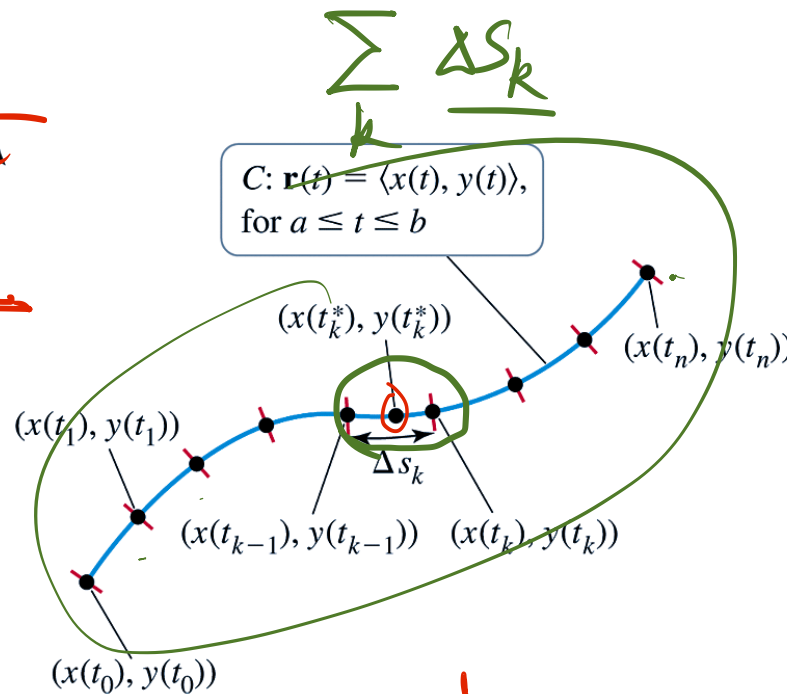
$$\int_C 1 ds = \int_a^b |\vec{r}'(t)| dt$$

$$\vec{r}(t) = ?$$

parametrization

$$\int_C \underline{f} ds = \int_a^b \underline{f(\vec{r}(t))} |\vec{r}'(t)| dt$$

The parameter t resides on the t -axis. As t varies from a to b , the curve C in the xy -plane is generated from $(x(a), y(a))$ to $(x(b), y(b))$.



$$\int_a^b f(x) dx$$

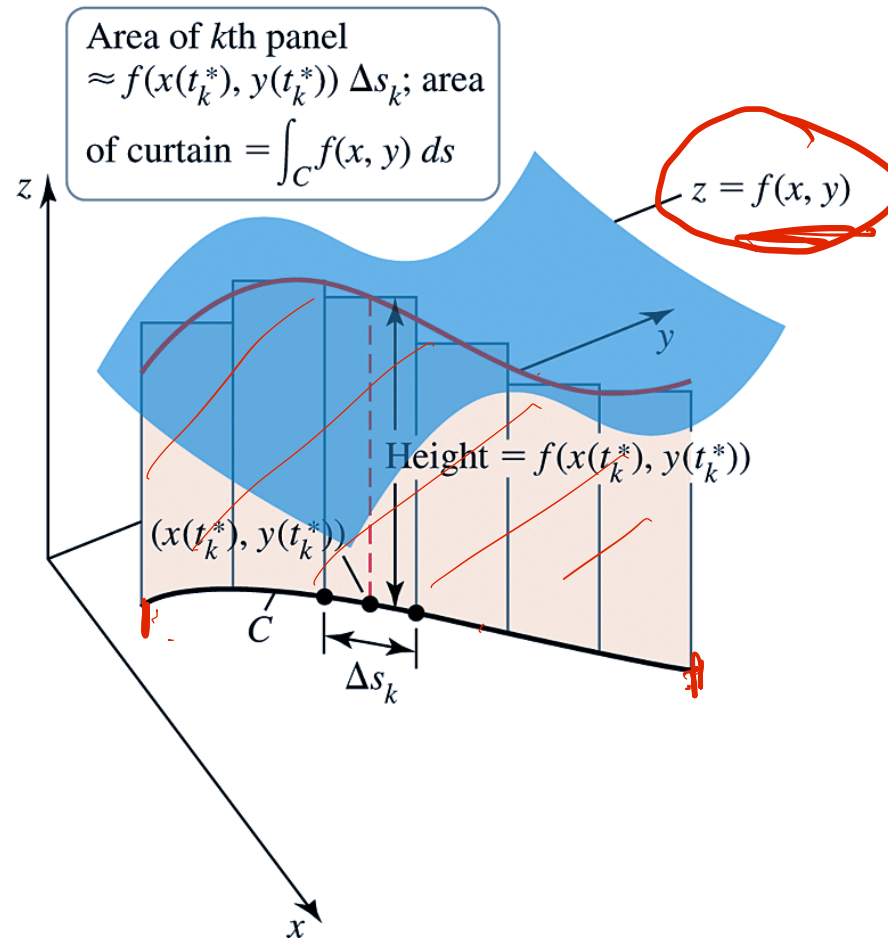
Definition Scalar Line Integral in the Plane

Suppose the scalar-valued function f is defined on a region containing the smooth curve C given by $\mathbf{r}(t) = \langle x(t), y(t) \rangle$, for $a \leq t \leq b$. **The line integral of f over C is**

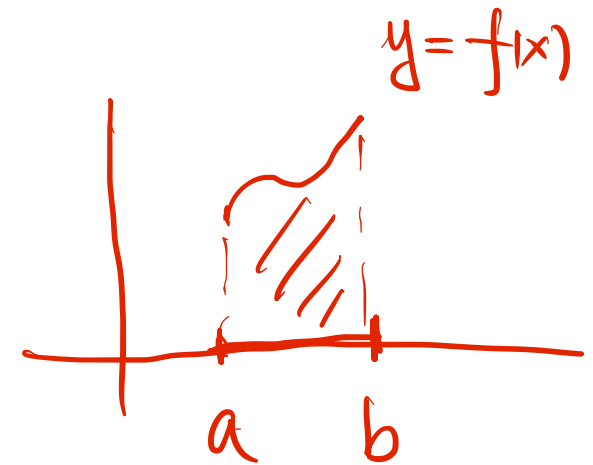
$$\int_C f(x(t), y(t)) ds = \lim_{\Delta \rightarrow 0} \sum_{k=1}^n f(x(t_k^*), y(t_k^*)) \Delta s_k$$

provided this limit exists over all partitions of $[a, b]$. When the limit exists, f is said to be **integrable** on C .

Figure 17.17



$$\int_a^b f(x) dx$$



$$\iint_R f dA = V$$

Theorem 17.1 Evaluating Scalar Line Integrals in $\mathbb{R}^2$

Let f be continuous on a region containing a smooth curve $C: \mathbf{r}(t) = \langle x(t), y(t) \rangle$, for $a \leq t \leq b$. Then

$$\int_C f \, ds = \int_a^b f(x(t), y(t)) |\mathbf{r}'(t)| \, dt$$

$$= \int_a^b f(x(t), y(t)) \sqrt{x'(t)^2 + y'(t)^2} \, dt. = \int_a^b f(\vec{r}(t)) |\vec{r}'(t)| \, dt$$

$$C: \vec{r}(t) = \langle x(t), y(t), z(t) \rangle, a \leq t \leq b$$

$$\int_C f \, ds = \int_a^b f(\vec{r}(t)) |\vec{r}'(t)| \, dt$$

Procedure Evaluating the Line Integral $\int_C f \, ds$

1. Find a parametric description of C in the form

$$\mathbf{r}(t) = \langle x(t), y(t) \rangle, \text{ for } a \leq t \leq b.$$

2. Compute $|\mathbf{r}'(t)| = \sqrt{x'(t)^2 + y'(t)^2}.$

3. Make substitution for x and y in the integrand and evaluate an ordinary integral:

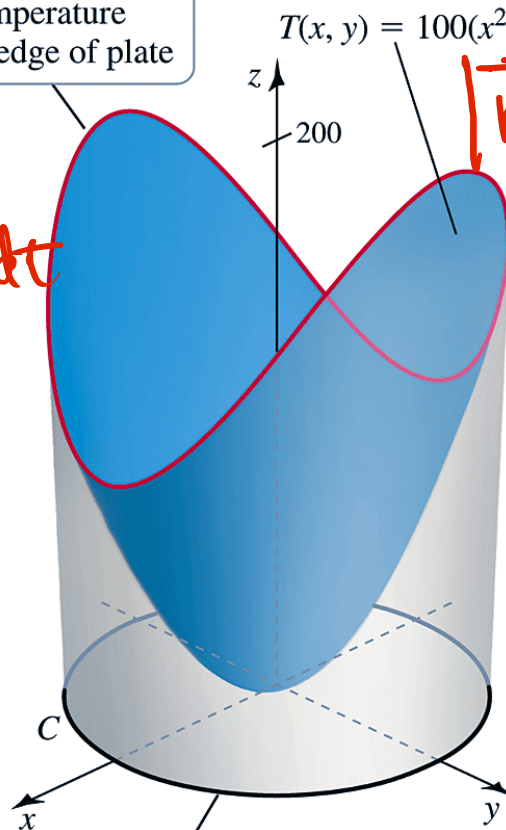
$$\int_C f \, ds = \int_a^b f(x(t), y(t)) |\mathbf{r}'(t)| \, dt.$$

Example 1 The temperature of the circular plate $R = \{(x, y) : x^2 + y^2 \leq 1\}$ is $T(x, y) = 100(x^2 + 2y^2)$. Find the average temperature along the edge of the plate.

Figure 17.18

$$\begin{aligned}\bar{T} &= \frac{\int_C T ds}{\int_C 1 ds} \\ &= \frac{\int_0^{2\pi} 100(x^2 + 2y^2) \cdot 1 dt}{\int_0^{2\pi} 1 \cdot 1 dt} \\ &= \frac{100}{2\pi} \int_0^{2\pi} (x^2 + 2y^2) dt \\ &\quad \parallel \\ &= \frac{50}{\pi} \int_0^{2\pi} (1 + \sin^2 t) dt \\ &\quad \parallel \\ &= \frac{50}{\pi} \int_0^{2\pi} (1 + \frac{1 + \cos 2t}{2}) dt\end{aligned}$$

Temperature on edge of plate



Edge of plate $x^2 + y^2 = 1$
 $\mathbf{r} = \langle x, y \rangle = \langle \cos t, \sin t \rangle$,
 for $0 \leq t \leq 2\pi$

$$\begin{cases} \mathbf{r}(t) = \langle \cos t, \sin t \rangle \\ 0 \leq t \leq 2\pi \end{cases}$$



$$\begin{aligned}|\mathbf{r}'(t)| &= |\langle -\sin t, \cos t \rangle| \\ &= \sqrt{\sin^2 t + \cos^2 t} = 1\end{aligned}$$

$$C: x^2 + y^2 = 1$$

$f(x, y)$ on R

$$\bar{f} = \frac{\iint_R f(x, y) dA}{|R|}$$

$$\bar{f} = \frac{\int_a^b f(x) dx}{(b-a)}$$

$$\cos^2 t = \cos t - \sin t$$

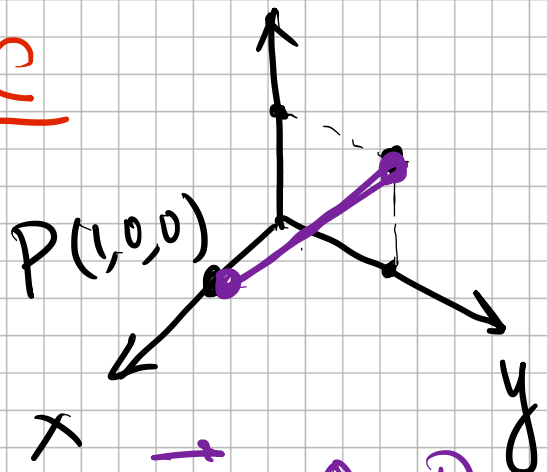
$$1 + \cos^2 t - \sin^2 t = 2 \cos^2 t$$

Example 2 Evaluate $\int_C (xy + 2z) ds = \int_0^1 [(1-t)t + 2t] \sqrt{3} dt$

(a) C is the line segment from $P(1,0,0)$ to $Q(0,1,1)$

(b) C ... $Q(0,1,1)$ to $P(1,0,0)$

C



$$\vec{v} = Q - P$$

$$= \langle 0, 1, 1 \rangle - \langle 1, 0, 0 \rangle$$

$$= \langle -1, 1, 1 \rangle$$

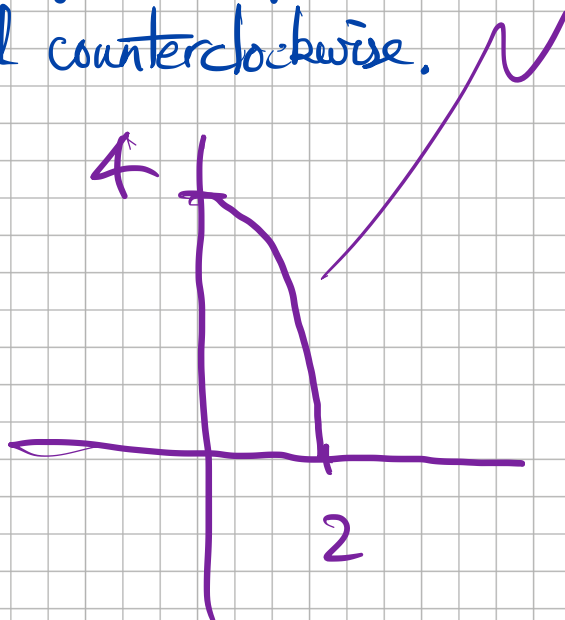
$$\begin{aligned} \vec{r}(t) &= \langle 1, 0, 0 \rangle + t \vec{v} \\ &= \langle 1, 0, 0 \rangle + t \langle -1, 1, 1 \rangle \\ &= \langle 1-t, t, t \rangle \\ 0 &\leq t \leq 1 \end{aligned}$$

$$\begin{aligned} |\vec{r}'(t)| &= |\langle -1, 1, 1 \rangle| \\ &= \sqrt{3} \end{aligned}$$

Example 3 (#29) C is a portion of the ellipse $\frac{x^2}{4} + \frac{y^2}{16} = 1$ in the first quadrant, oriented counterclockwise.

$$\int_C xy \, ds$$

① $\vec{r}(t) = \langle 2\cos t, 4\sin t \rangle$
 $0 \leq t \leq \frac{\pi}{2}$



② $|\vec{r}'(t)| = | \langle -2\sin t, 4\cos t \rangle | = \sqrt{4\sin^2 t + 16\cos^2 t}$
 $= 2\sqrt{\sin^2 t + 4\cos^2 t} = 2\sqrt{1+3\cos^2 t}$

③ $\int_C xy \, ds = \int_0^{\frac{\pi}{2}} 2\cos t \cdot 4\sin t \cdot 2\sqrt{1+3\cos^2 t} \, dt$
 $= 16 \int_0^{\frac{\pi}{2}} \cos t \sin t \sqrt{1+3\cos^2 t} \, dt$

$u = 1+3\cos^2 t$ $16 \int_4^1 -\frac{1}{6} \sqrt{u} \, du$
 $du = 6\cos t \cdot (-\sin t)$

Theorem 17.2 Evaluating Scalar Line Integrals in $\mathbb{R}^3$

Let f be continuous on a region containing a smooth

curve C : $\mathbf{r}(t) = \langle x(t), y(t), z(t) \rangle$, for $a \leq t \leq b$. Then

$$\int_C f \, ds = \int_a^b f(x(t), y(t), z(t)) |\mathbf{r}'(t)| \, dt = \int_a^b f(\vec{r}(t)) |\vec{r}'(t)| \, dt$$
$$= \int_a^b f(x(t), y(t), z(t)) \sqrt{x'(t)^2 + y'(t)^2 + z'(t)^2} \, dt.$$

Line Integral of Vector-valued Function

- $\vec{F}(x,y,z) = \langle f(x,y,z), g(x,y,z), h(x,y,z) \rangle$ vector-valued function
- C is a smooth curve parametrized by $\vec{r}(t) = \langle x(t), y(t), z(t) \rangle$
 $a \leq t \leq b$

$$\begin{aligned} \int_C \vec{F} \cdot d\vec{r} &= \int_C (\vec{F} \cdot \vec{T}) ds \\ &= \int_a^b \vec{F}(\vec{r}(t)) \cdot \frac{\vec{r}'(t)}{|\vec{r}'(t)|} |\vec{r}'(t)| dt \end{aligned}$$

A diagram showing a curve C in 3D space. A point on the curve is marked, and a tangent vector $\vec{T}$ is shown. The derivative vector $\vec{r}'(t)$ is also shown, pointing in the same direction as $\vec{T}$. The relationship $\vec{T} = \frac{\vec{r}'(t)}{|\vec{r}'(t)|}$ is indicated.

unit tangent vector

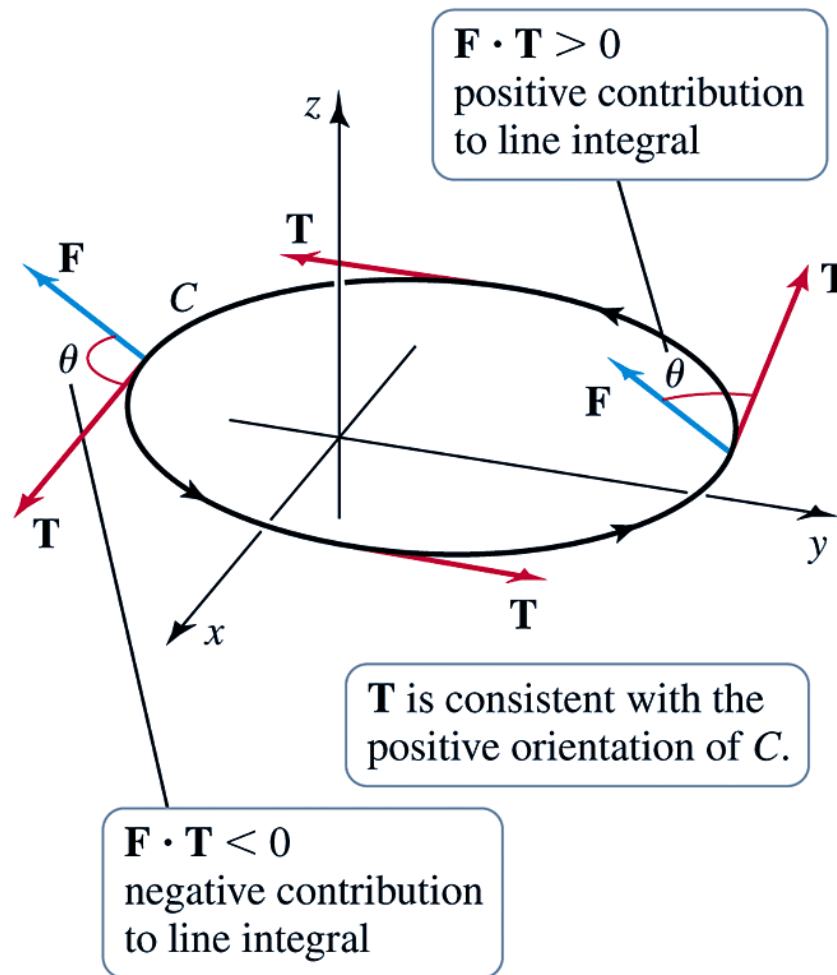
$$= \int_a^b \vec{F}(\vec{r}(t)) \cdot \vec{r}'(t) dt = \int_C \vec{F} \cdot d\vec{r}$$

$$\int_a^b \langle f, g, h \rangle \cdot \langle x', y', z' \rangle dt$$

$$= \int_a^b f x' dt + g y' dt + h z' dt$$

$$\int_C f dx + g dy + h dz$$

Figure 17.19



Definition Line Integral of a Vector Field

Let $\mathbf{F}$ be a vector field that is continuous on a region containing a smooth oriented curve C parameterized by arc length. Let $\mathbf{T}$ be the unit tangent vector at each point of C consistent with the orientation. The line integral of $\mathbf{F}$ over C is

$$\int_C \mathbf{F} \cdot \mathbf{T} \, ds.$$

Different Forms of Line Integrals of Vector Fields

The line integral $\int_C \mathbf{F} \cdot \mathbf{T} \, ds$ may be expressed in the following forms, where $\mathbf{F} = \langle f, g, h \rangle$ and C has a parameterization $\mathbf{r}(t) = \langle x(t), y(t), z(t) \rangle$, for $a \leq t \leq b$:

$$\int_b^a \mathbf{F} \cdot \mathbf{r}'(t) dt = \int_b^a (f(t)x'(t) + g(t)y'(t) + h(t)z'(t)) dt$$

$$= \int_C f \, dx + g \, dy + h \, dz = \int_C \mathbf{F} \cdot d\mathbf{r}.$$

For line integrals in the plane, we let $\mathbf{F} = \langle f, g \rangle$ and assume C is parameterized in the form $\mathbf{r}(t) = \langle x(t), y(t) \rangle$, for $a \leq t \leq b$.

$$\text{Then } \int_a^b \mathbf{F} \cdot \mathbf{r}' \, dt = \int_a^b (f(t)x'(t) + g(t)y'(t)) dt = \int_C f \, dx + g \, dy = \int_C \mathbf{F} \cdot d\mathbf{r}.$$

Example 4 $I = \int_C \vec{F} \cdot d\vec{r}$, $\vec{F} = \langle y-x, x \rangle$.

- (a) The quarter-circle C_1 from $P(0,1)$ to $Q(1,0)$
 (b) $-C_1$ from $Q(1,0)$ to $P(0,1)$
 (c) The path C_2 from $P(0,1)$ to $Q(1,0)$ via two line segments through $O(0,0)$.

Figure 17.20

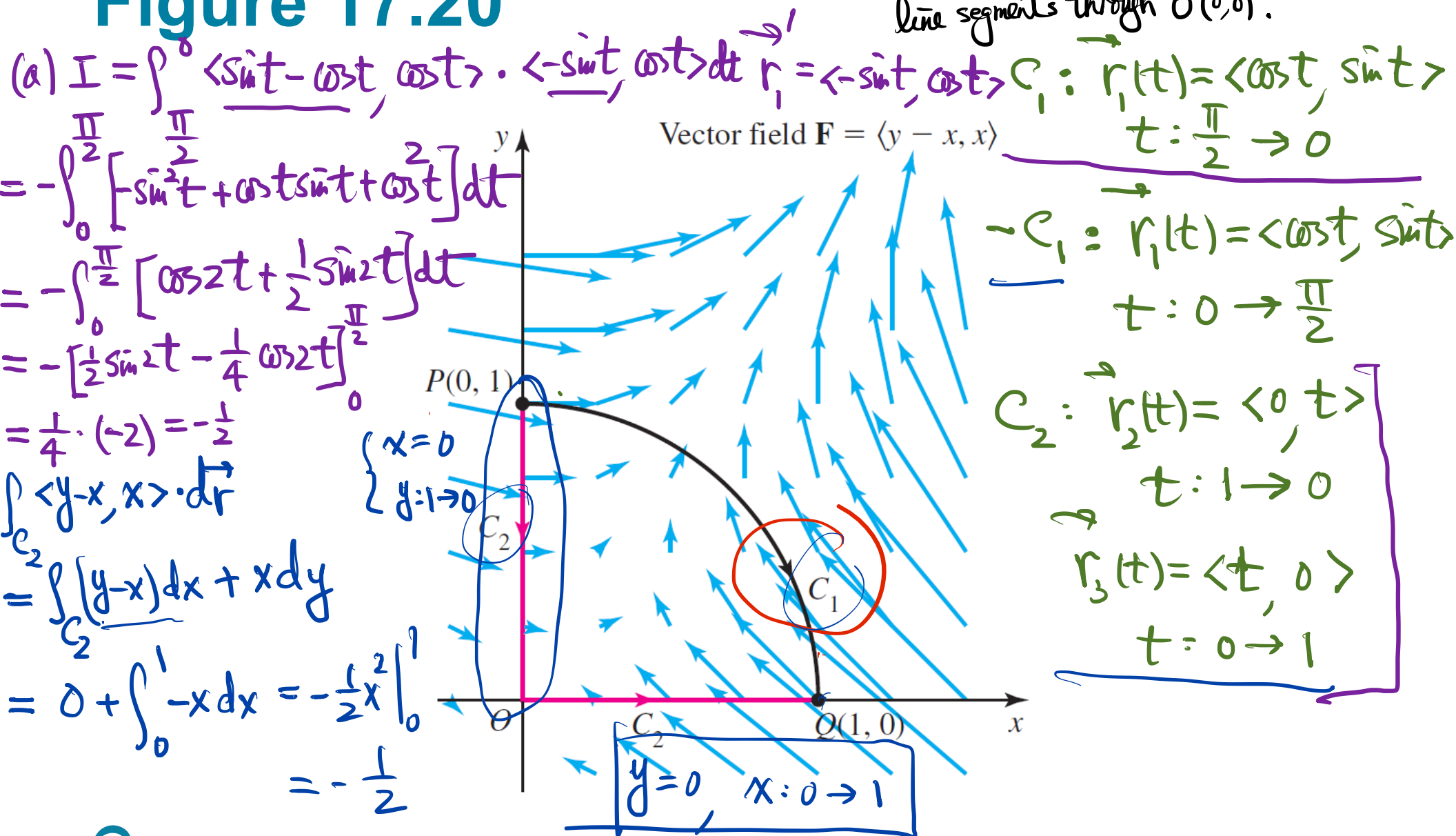
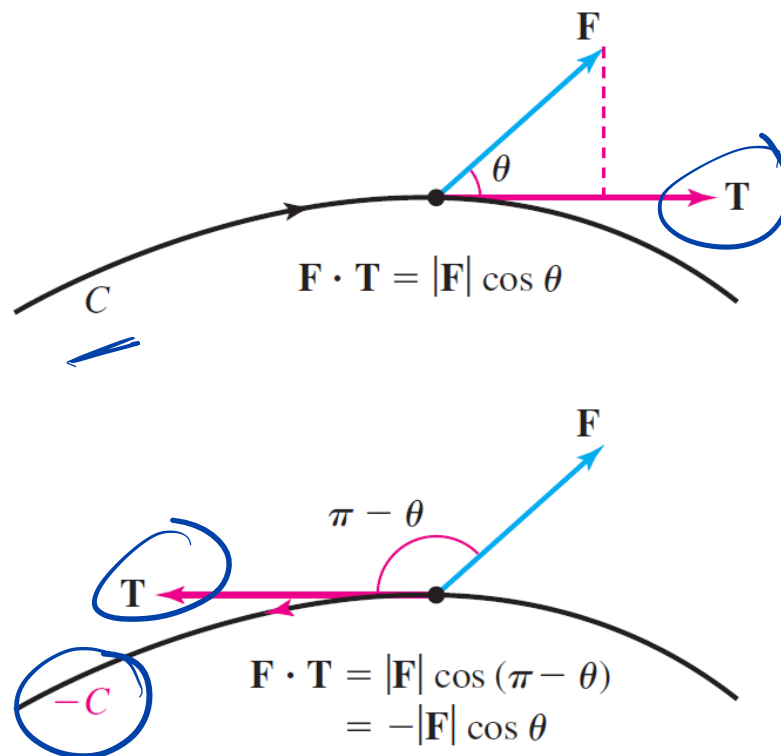


Figure 17.21

$$\int_C \vec{F} \cdot d\vec{r} = - \int_{-C} \vec{F} \cdot d\vec{r}$$



Reversing the orientation of C changes the sign of $\mathbf{F} \cdot \mathbf{T}$ at each point on C .

Figure 17.22 (a & b)

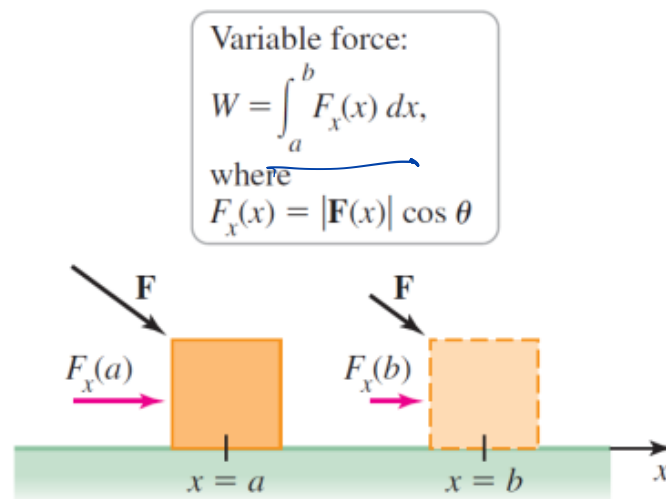
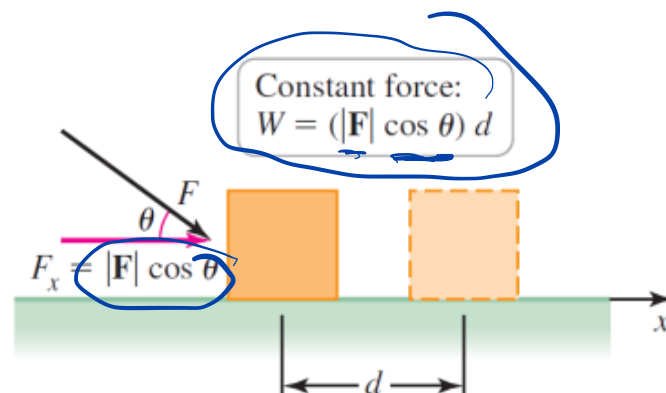
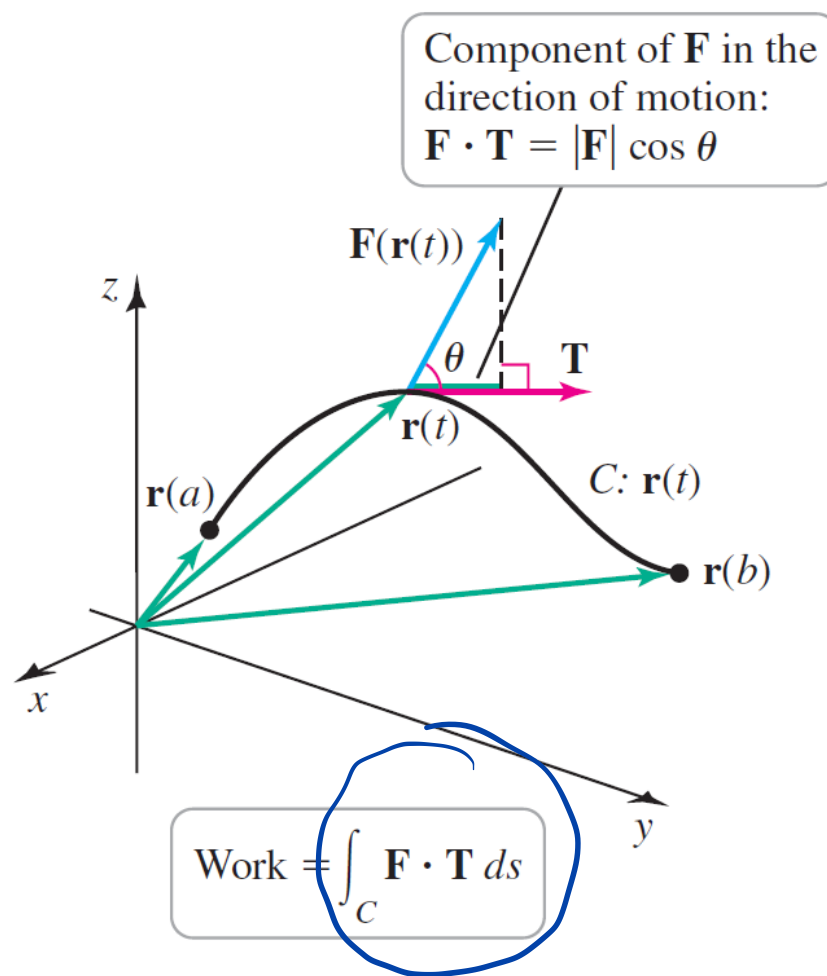


Figure 17.23



Definition Work Done in a Force Field

Let $\mathbf{F}$ be a continuous force field in a region D of $\mathbb{R}^3$.

Let $C : \mathbf{r}(t) = \langle x(t), y(t), z(t) \rangle$, for $a \leq t \leq b$, be a smooth curve in D with a unit tangent vector $\mathbf{T}$ consistent with the orientation. The work done in moving an object along C in the positive direction is

$$W = \int_C \mathbf{F} \cdot \mathbf{T} ds = \int_a^b \mathbf{F} \cdot \mathbf{r}'(t) dt.$$

Define Circulation

Let $\mathbf{F}$ be a continuous vector field on a region D of $\mathbb{R}^3$ and let C be a closed smooth oriented curve in D . The circulation of $\mathbf{F}$ on C is $\int_C \mathbf{F} \cdot \mathbf{T} \, ds$, $= \int_C \mathbf{F} \cdot d\mathbf{r}$ where $\mathbf{T}$ is the unit vector tangent to C consistent with the orientation

Example 6 Let C be the unit circle with counterclockwise orientation. Find the circulation on C of the following vector fields. (a) the radial field $\vec{F} = \langle x, y \rangle$
 (b) the rotation field $\vec{F} = \langle -y, x \rangle$

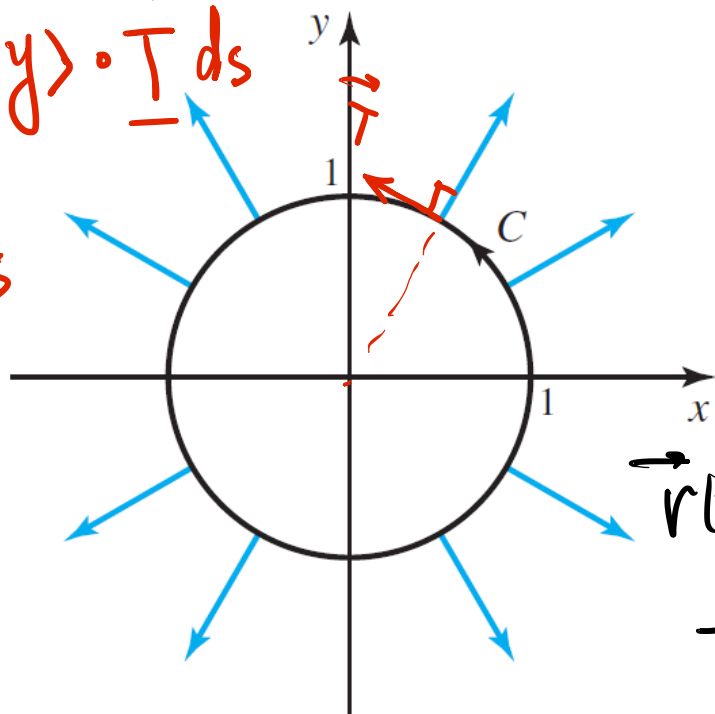
Figure 17.24 (a & b)

(a) $\int_C \langle x, y \rangle \cdot d\vec{r} = 0$

$= \int_C \langle x, y \rangle \cdot \vec{T} ds$

$= \int_C 0 ds$

$= 0$



On the unit circle, $\mathbf{F} = \langle x, y \rangle$ is orthogonal to C and has zero circulation on C .

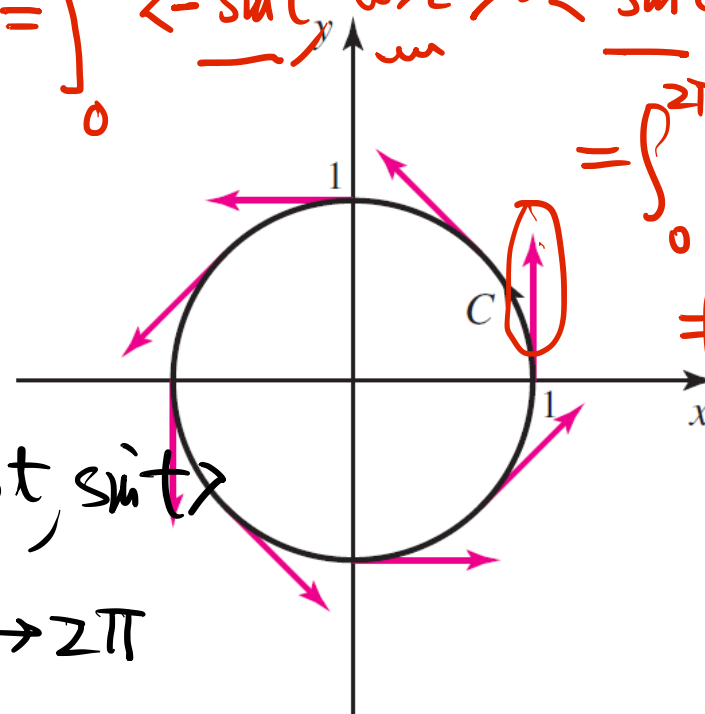
(b) $\int_C \langle -y, x \rangle \cdot d\vec{r} = ?$

$= \int_C \langle -y, x \rangle \cdot \langle x', y' \rangle ds$

$= \int_0^{2\pi} \langle -\sin t, \cos t \rangle \cdot \langle -\sin t, \cos t \rangle dt$

$= \int_0^{2\pi} 1 dt$

$= 2\pi$



$\vec{r}(t) = \langle \cos t, \sin t \rangle$

$t: 0 \rightarrow 2\pi$

On the unit circle, $\mathbf{F} = \langle -y, x \rangle$ is tangent to C and has positive circulation on C .

Example 7 $I = \int_C \vec{F} \cdot d\vec{r}$, where $\vec{F} = \langle z, x, -y \rangle$ and $C: \vec{r}(t) = \langle \cos t, \sin t, \cos t \rangle$, $0 \leq t \leq 2\pi$.

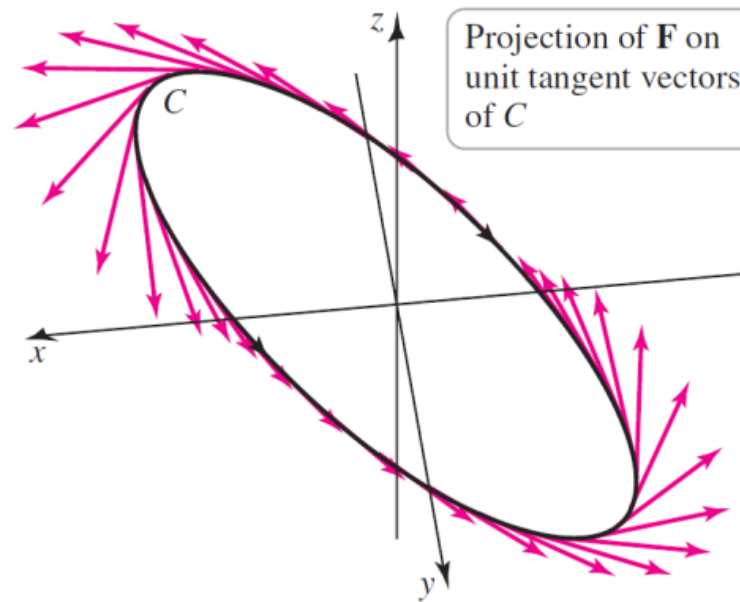
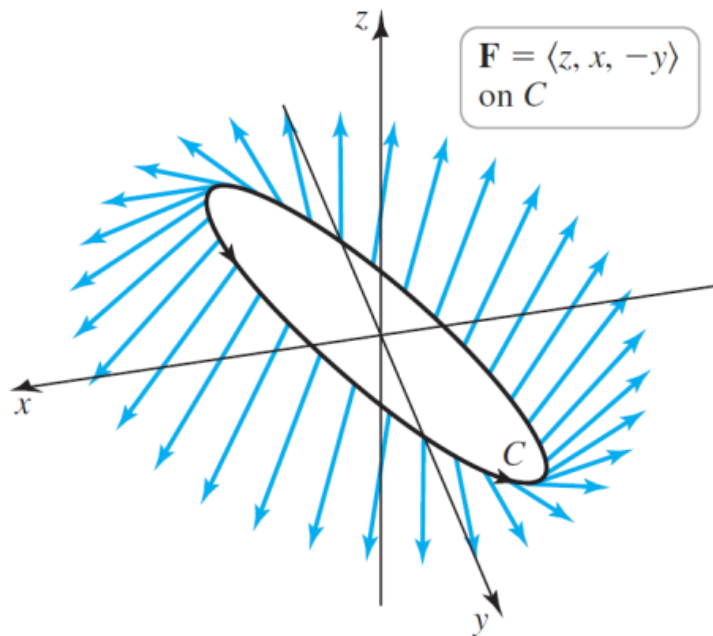
$$= \int_0^{2\pi} \langle \cos t, \cos t - \sin t \rangle \cdot \langle -\sin t, \cos t, -\sin t \rangle dt$$

Figure 17.25 (a & b)

$$= \int_0^{2\pi} [-\cos t \sin t + \cos^2 t + \sin^2 t] dt = \int_0^{2\pi} \left[1 - \frac{1}{2} \sin 2t \right] dt$$

$$= 2\pi + \frac{1}{4} \cos 2t \Big|_0^{2\pi}$$

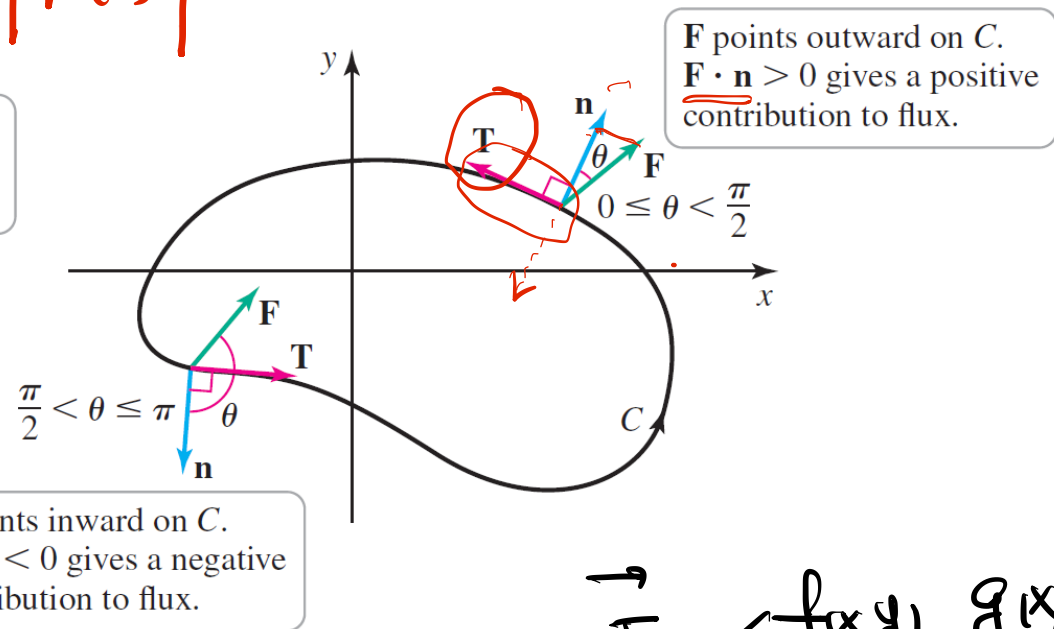
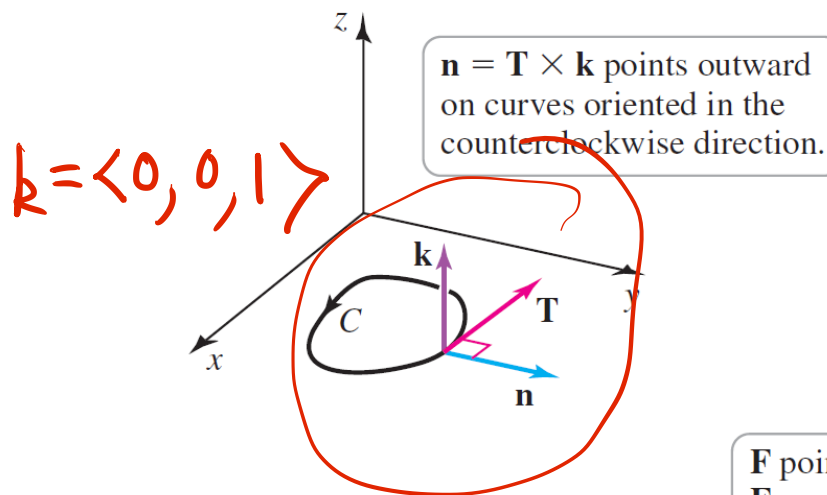
$$= 2\pi$$



$$\int_C (\vec{F} \cdot \vec{n}) ds = \int_a^b \vec{F}(\vec{r}(t)) \cdot \frac{\langle y', x' \rangle}{|\vec{r}'(t)|} |\vec{r}'(t)| dt$$

Figure 17.26 (a & b)

$$\vec{T} = \frac{\langle x', y' \rangle}{|\vec{r}'(t)|} \quad \vec{n} = \frac{\langle y'(t), -x'(t) \rangle}{|\vec{r}'(t)|}$$



$$\vec{F} = \langle f(x, y), g(x, y) \rangle$$

$$\vec{n} = \langle y', -x' \rangle$$

Definition Flux

Let $\mathbf{F} = \langle f, g \rangle$ be a continuous vector field on a region R of $\mathbb{R}^2$.

Let $C: \mathbf{r}(t) = \langle x(t), y(t) \rangle$, for $a \leq t \leq b$, be a smooth oriented curve in R that does not intersect itself. The **flux** of the vector field $\mathbf{F}$ across C is

$$\int_C \mathbf{F} \cdot \mathbf{n} \, dS = \int_a^b (f(t)y'(t) - g(t)x'(t))dt, \quad = \int_a^b \vec{F}(\vec{r}(t)) \cdot \underline{\langle y', -x' \rangle} dt$$

where $\mathbf{n} = \mathbf{T} \times \mathbf{k}$ is the unit normal vector and $\mathbf{T}$ is the unit

tangent vector consistent with the orientation. If C is a closed curve with counterclockwise orientation, $\mathbf{n}$ is the outward normal vector and the flux integral gives the **outward flux** across C .

Example 8 Find the outward flux across the unit circle with counterclockwise orientation for

(a) $\vec{F} = \langle x, y \rangle$

(b) $\vec{F} = \langle -y, x \rangle$

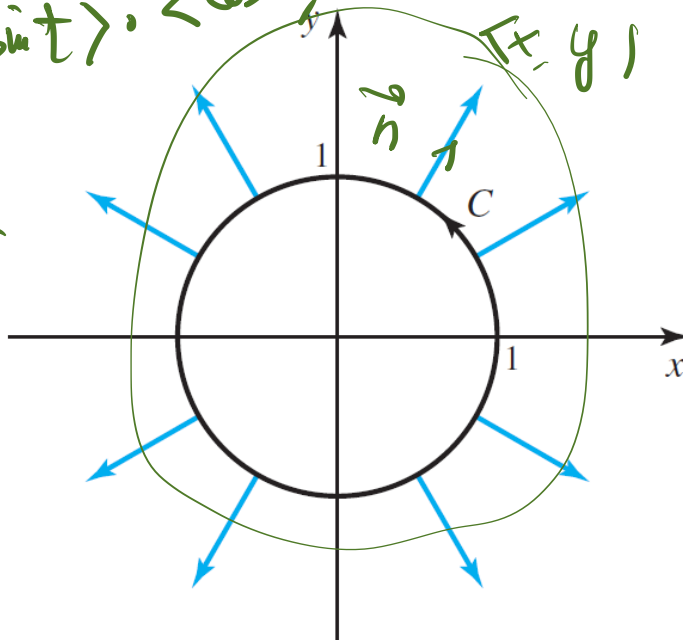
Figure 17.27 (a & b)

(a) $\int_C \langle x, y \rangle \cdot \vec{n} \, ds$

$$= \int_0^{2\pi} \langle \cos t, \sin t \rangle \cdot \langle \cos t, \sin t \rangle \, dt$$

$$= \int_0^{2\pi} 1 \, dt$$

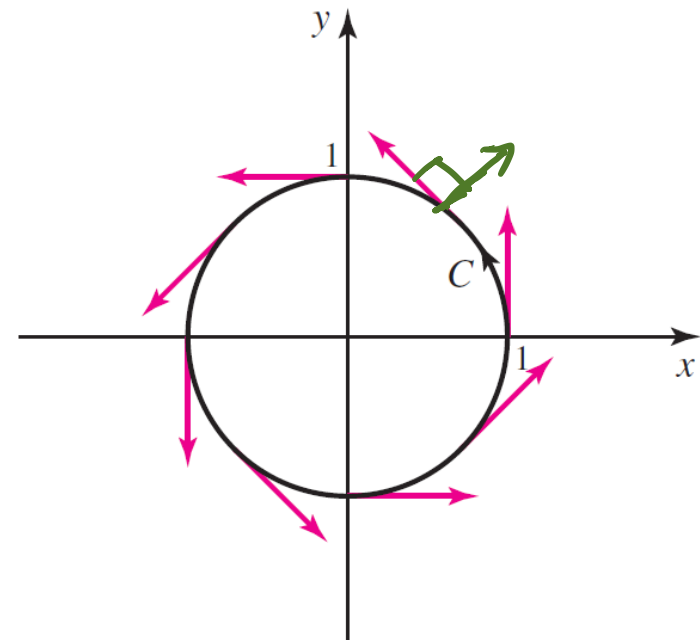
$$= 2\pi$$



On the unit circle, $\mathbf{F} = \langle x, y \rangle$ is orthogonal to C and has positive outward flux on C .

(b) $\int_C \langle -y, x \rangle \cdot \vec{n} \, ds$

$$= \int_C 0 \, ds = 0$$



On the unit circle, $\mathbf{F} = \langle -y, x \rangle$ is tangent to C and has zero outward flux on C .

Section 17.3 Conservative Vector Fields

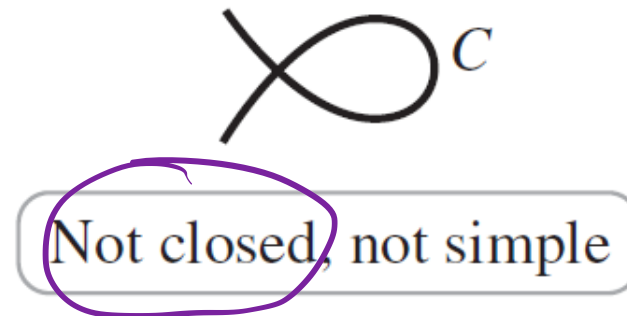
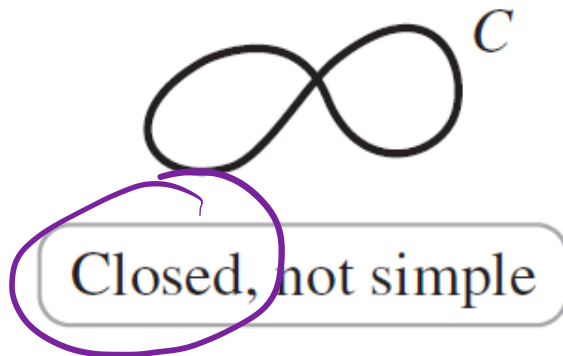
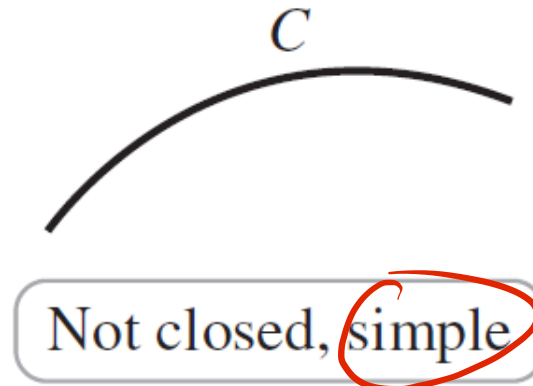
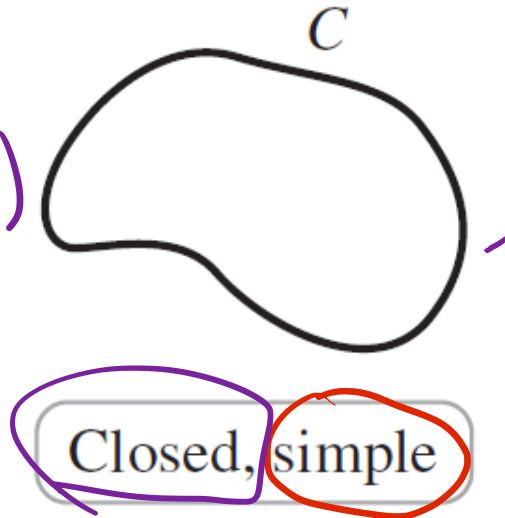
$$\underline{\underline{C}} : \vec{r}(t) = \langle x(t), y(t), z(t) \rangle, a \leq t \leq b$$

Figure 17.28

$$\forall t_1, t_2 \in (a, b) \text{ and } t_1 \neq t_2 \text{ s.t.} \\ \vec{r}(t_1) \neq \vec{r}(t_2)$$

$$\vec{r}(a) = \vec{r}(b)$$

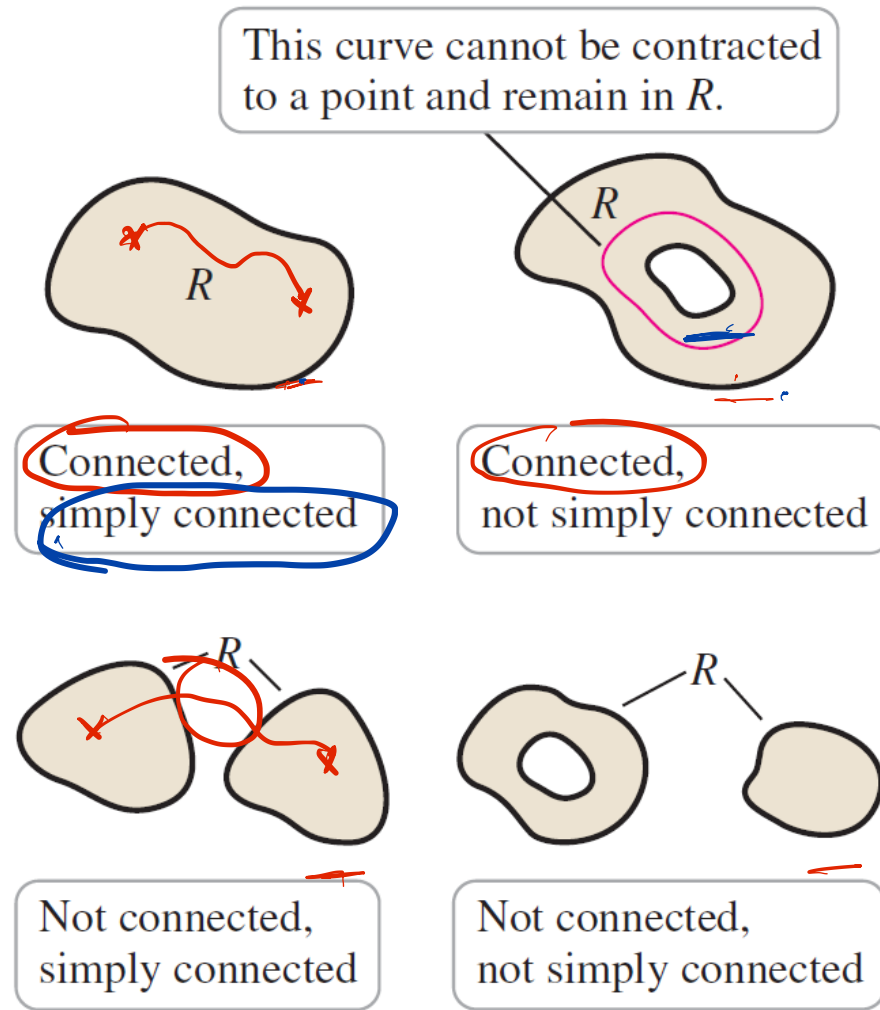
closed



Definition Simple and Closed Curves

Suppose a curve C (in $\mathbb{R}^2$ or $\mathbb{R}^3$) is described parametrically by $\mathbf{r}(t)$, where $a \leq t \leq b$. Then C is a **simple curve** if $\mathbf{r}(t_1) \neq \mathbf{r}(t_2)$ for all t_1 and t_2 , with $a < t_1 < t_2 < b$; that is, C never intersects itself between its endpoints. The curve C is **closed** if $\mathbf{r}(a) = \mathbf{r}(b)$; that is, the initial and terminal points of C are the same (Figure 17.28).

Figure 17.29



Definition Connected and Simply Connected Regions

An open region R in $\mathbb{R}^2$ (or D in $\mathbb{R}^3$)

is **connected** if it is possible to connect any two points of R by a continuous curve lying in R . An open region R is **simply connected** if every closed simple curve in R can be deformed and contracted to a point in R (Figure 17.29).

Definition Conservative Vector Field

A vector field $\mathbf{F}$ is said to be conservative on a region

(in $\mathbb{R}^2$ or $\mathbb{R}^3$) if there exists a scalar function φ such that

$$\boxed{\mathbf{F} = \nabla \varphi} \text{ on that region.}$$

Curl of $\vec{F} = \langle f, g, h \rangle$

$$\vec{F}(x, y) = \langle f(x, y), g(x, y), 0 \rangle$$

$$\vec{F} = \nabla \varphi \iff \nabla \times \vec{F} = \langle 0, 0, 0 \rangle$$

$$\nabla \times \vec{F} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ f & g & h \end{vmatrix}$$

$$= \left\langle \frac{\partial h}{\partial y} - \frac{\partial g}{\partial z}, \frac{\partial f}{\partial z} - \frac{\partial h}{\partial x}, \frac{\partial g}{\partial x} - \frac{\partial f}{\partial y} \right\rangle$$

$$\nabla \times \vec{F}(x, y) = \langle 0, 0, \frac{\partial g}{\partial x} - \frac{\partial f}{\partial y} \rangle$$

Theorem 17.3 Test for Conservative Vector Fields

Let $\mathbf{F} = \langle f, g, h \rangle$ be a vector field defined on a connected and simply connected region D of $\mathbb{R}^3$, where f , g , and h have continuous first partial derivatives on D . Then $\mathbf{F}$ is a conservative vector field D (there is a potential function φ such that $\mathbf{F} = \nabla \varphi$) if and only if

$$\frac{\partial f}{\partial y} = \frac{\partial g}{\partial x}, \quad \frac{\partial f}{\partial z} = \frac{\partial h}{\partial x}, \quad \text{and} \quad \frac{\partial g}{\partial z} = \frac{\partial h}{\partial y}.$$

For vector fields in $\mathbb{R}^2$, we have the single condition $\frac{\partial f}{\partial y} = \frac{\partial g}{\partial x}$.

Procedure Finding Potential Functions in R^3

Suppose $\mathbf{F} = \langle f, g, h \rangle$ is a conservative vector field. To find φ such that $\mathbf{F} = \nabla \varphi$, use the following steps:

1. Integrate $\varphi_x = f$ with respect to x to obtain φ , which includes an arbitrary function $c(y, z)$.
2. Compute φ_y and equate it to g to obtain an expression for $c_y(y, z)$.
3. Integrate $c_y(y, z)$ with respect to y to obtain $c(y, z)$, including an arbitrary function $d(z)$.
4. Compute φ_z and equate it to h to get $d(z)$.

A simple procedure beginning with $\varphi_y = g$ or $\varphi_z = h$ may be easier in some cases.

Example 1 (a) $\vec{F} = \langle e^x \cos y, -e^x \sin y \rangle = \langle f, g \rangle$

(b) $\vec{F} = \langle 2xy - z^2, x^2 + 2z, 2y - 2xz \rangle$

(i) Is $\vec{F}$ a conservative field?

(ii) If so, find a potential function.

(a) $\frac{\partial f}{\partial y} \stackrel{?}{=} \frac{\partial g}{\partial x}$ $\frac{\partial f}{\partial y} = \frac{\partial}{\partial y} (e^x \cos y) = -e^x \sin y$

(ii) $\frac{\partial g}{\partial x} = \frac{\partial}{\partial x} (-e^x \sin y) = -e^x \sin y$

$\vec{F} = \nabla \phi$

(ii) $\phi = ?$

$\nabla \phi = \langle \frac{\partial \phi}{\partial x}, \frac{\partial \phi}{\partial y} \rangle = \langle f, g \rangle = \langle e^x \cos y, -e^x \sin y \rangle$

$\phi(x, y) = ?$ p. differential eq.

$\frac{\partial \phi}{\partial x} = e^x \cos y$

$\phi = \int \frac{\partial \phi}{\partial x} dx = \int e^x \cos y dx = e^x \cos y + C(y)$

$\Rightarrow \phi(x, y) = e^x \cos y + C(y)$ $C(y) = ?$

$\frac{\partial \phi}{\partial y} = -e^x \sin y$

$\phi(x, y) = e^x \cos y + \text{const.}$

$\frac{\partial}{\partial y} [e^x \cos y + C(y)]$

$= -e^x \sin y + C'(y) = -e^x \sin y$

$\Rightarrow C'(y) = 0$

$\Rightarrow C(y) = \text{const.}$

$$\int_a^b f'(x) dx = f(b) - f(a)$$

Theorem 17.4 Fundamentals Theorem for Line Integrals

Let R be a region in $\mathbb{R}^2$ or $\mathbb{R}^3$ and let φ be a differentiable potential function defined on R . If $\mathbf{F} = \nabla \varphi$ (which means that $\mathbf{F}$ is conservative), then

$$\int_C \mathbf{F} \cdot \mathbf{T} ds = \int_C \mathbf{F} \cdot d\mathbf{r} = \varphi(B) - \varphi(A) = \int_C \nabla \varphi \cdot d\mathbf{r}$$

for all points A and B in R and all piecewise-smooth oriented curves C in R from A to B .

Handwritten notes and diagrams:

- Diagram of a curve C from point A to point B . The curve is labeled $C: \mathbf{r}(t) = \langle x(t), y(t), z(t) \rangle$ for $a \leq t \leq b$. Point A is labeled $\mathbf{r}(a) = A$ and point B is labeled $B = \mathbf{r}(b)$.
- Handwritten equation: $\varphi(\mathbf{r}(b)) - \varphi(\mathbf{r}(a)) = \varphi(\mathbf{r}(t)) \Big|_a^b = \int_a^b \frac{d}{dt} \varphi(\mathbf{r}(t)) dt$
- Handwritten equation: $\int_a^b \nabla \varphi(\mathbf{r}(t)) \cdot \mathbf{r}'(t) dt$

$$\vec{F}(x, y) = \langle f(x, y), g(x, y), 0 \rangle, \quad \nabla \times \vec{F} = \langle 0, 0, g_x - f_y \rangle$$

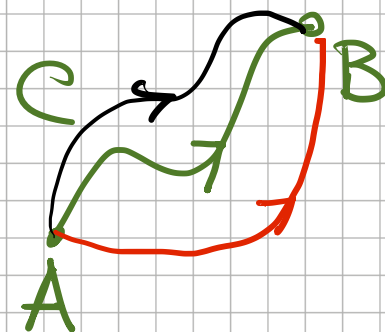
$$\vec{F}(x, y, z) = \langle f(x, y, z), g(x, y, z), h(x, y, z) \rangle$$

$$\vec{F} \text{ is a conservative field} \iff \vec{F} = \nabla \phi$$

$$\nabla \times \vec{F} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \partial_x & \partial_y & \partial_z \\ f & g & h \end{vmatrix} = \langle h_y - g_z, f_z - h_x, g_x - f_y \rangle$$

$$\int_C \vec{F} \cdot d\vec{r} = \phi(B) - \phi(A)$$

$$\nabla \phi = \vec{F}$$



$$\int_a^b F dx = f(b) - f(a)$$

$$f' = F$$

$$\vec{F}(x, y, z) = \langle f(x, y, z), g(x, y, z), h(x, y, z) \rangle$$

The following statements are equivalent

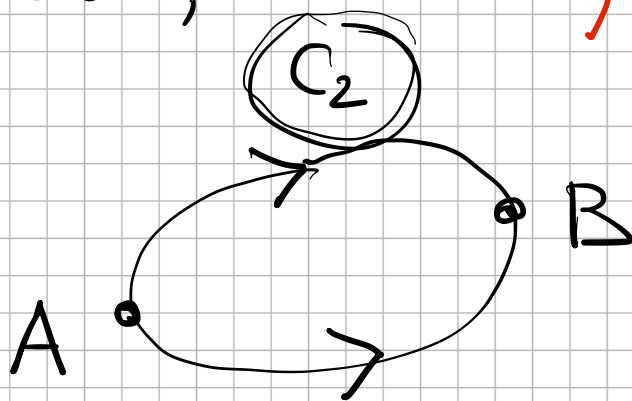
$$(1) \vec{F} \text{ is a conservative field} \Leftrightarrow \vec{F} = \nabla \phi$$

$$(2) \nabla \times \vec{F} = \vec{0}$$

$$(3) \int_C \vec{F} \cdot d\vec{r} \text{ is independent of path}$$

$$(4) \text{ Let } C \text{ be a simple, closed, oriented curve.}$$

$$\int_C \vec{F} \cdot d\vec{r} = \underline{0.}$$



$$\int_{C_1} \vec{F} \cdot d\vec{r} + \int_{-C_2} \vec{F} \cdot d\vec{r}$$

$$\int_{C_1} \vec{F} \cdot d\vec{r} = \int_{C_2} \vec{F} \cdot d\vec{r}$$

$$\int_C \vec{F} \cdot d\vec{r} = \int_{C_1} \vec{F} \cdot d\vec{r} - \int_{C_2} \vec{F} \cdot d\vec{r} = 0$$

Definition Independence of Path

Let $\mathbf{F}$ be a continuous vector field with domain R . If

$$\int_{C_1} \mathbf{F} \cdot d\mathbf{r} = \int_{C_2} \mathbf{F} \cdot d\mathbf{r} \text{ for all piecewise-smooth curves}$$

C_1 and C_2 in R with the same initial and terminal points,
then the line integral is **independent of path**.

Theorem 17.5

Let $\mathbf{F}$ be a continuous vector field on an open connected region R in $\mathbb{R}^2$. If $\int_C \mathbf{F} \cdot d\mathbf{r}$ is independent of path, then $\mathbf{F}$ is conservative; that is, there exists a potential function φ such that $\mathbf{F} = \nabla \varphi$ on R .

Example 3 Consider the potential function $\phi(x,y) = \frac{1}{2}(x^2 - y^2)$ and its gradient field $\vec{F} = \langle x, -y \rangle$.

- Let C_1 be $\vec{r}(t) = \langle \cos t, \sin t \rangle$, $0 \leq t \leq \frac{\pi}{2}$ from $A(1,0)$ to $B(0,1)$
- Let C_2 be $\vec{r}(t) = \langle 1-t, t \rangle$, $0 \leq t \leq 1$, also from A to B .

Evaluate $\int_{C_1} \vec{F} \cdot d\vec{r}$, $\int_{C_2} \vec{F} \cdot d\vec{r}$, $\phi(B) - \phi(A)$.

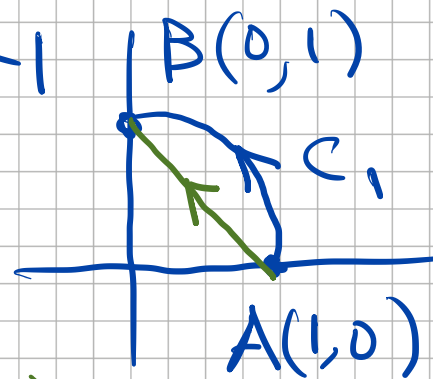
$$\begin{aligned} \int_{C_1} \vec{F} \cdot d\vec{r} &= \int_0^{\frac{\pi}{2}} \langle x, -y \rangle \cdot \vec{r}'(t) dt = \int_0^{\frac{\pi}{2}} \langle \cos t, -\sin t \rangle \cdot \langle -\sin t, \cos t \rangle dt \\ &= - \int_0^{\frac{\pi}{2}} 2 \cos t \sin t dt = - \int_0^{\frac{\pi}{2}} \sin 2t dt = \frac{\cos 2t}{2} \Big|_0^{\frac{\pi}{2}} = -1 \end{aligned}$$

$$\begin{aligned} \int_{C_2} \vec{F} \cdot d\vec{r} &= \int_0^1 \langle x, -y \rangle \cdot \vec{r}'(t) dt = \int_0^1 \langle 1-t, -t \rangle \cdot \langle -1, 1 \rangle dt \\ &= \int_0^1 [-(1-t) - t] dt = - \int_0^1 dt = -1 \end{aligned}$$

$$\phi = ? \begin{cases} \frac{\partial \phi}{\partial x} = x \Rightarrow \phi(x,y) = \frac{1}{2}x^2 + C(y) \\ \frac{\partial \phi}{\partial y} = -y = \frac{\partial}{\partial y} \left(\frac{1}{2}x^2 + C(y) \right) = C'(y) \end{cases}$$

$$\Rightarrow C(y) = -\frac{1}{2}y^2 + D \Rightarrow \phi = \frac{1}{2}x^2 - \frac{1}{2}y^2 + D$$

$$\phi(B) - \phi(A) = \left[-\frac{1}{2} + D \right] - \left[\frac{1}{2} + D \right] = -1$$



Example 4

Let C be a simple curve from $A(-3, -2, -1)$ to $B(1, 2, 3)$.

Evaluate

$$\int_C \langle 2xy - z^2, x^2 + 2z, 2y - 2xz \rangle \cdot d\vec{r}$$

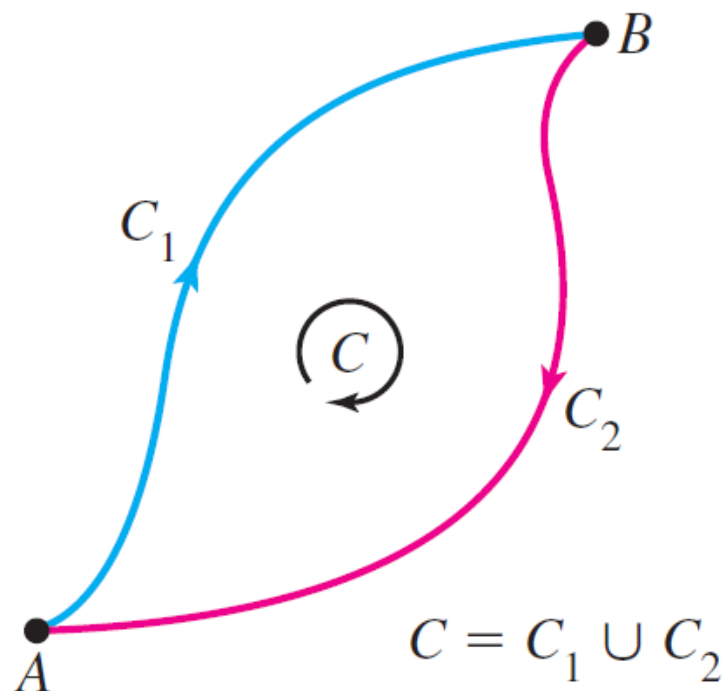
$$\nabla \phi$$

$$\boxed{\phi = ?}$$

$$= \phi(B) - \phi(A)$$

$$= \phi(1, 2, 3) - \phi(-3, -2, -1)$$

Figure 17.30



$$\oint_C \mathbf{F} \cdot d\mathbf{r} = \int_{C_1} \mathbf{F} \cdot d\mathbf{r} + \int_{C_2} \mathbf{F} \cdot d\mathbf{r}$$

Theorem 17.6 Line Integrals on Closed Curves

Let R be an open connected region in $\mathbb{R}^2$ or $\mathbb{R}^3$.

Then $\mathbf{F}$ is a conservative vector field on R if and only if

$\int_C \mathbf{F} \cdot d\mathbf{r} = 0$ on all simple closed piecewise-smooth oriented curves C in R .

Example 5 Without using Theorems 17.4 & 17.6,

evaluate $\int_C \nabla(-\underline{x}y + \underline{x}z + \underline{y}z) \cdot d\vec{r} = 0$

where $C: \vec{r}(t) = \langle \sin t, \underline{\cos t}, \sin t \rangle$, for $0 \leq t \leq 2\pi$.

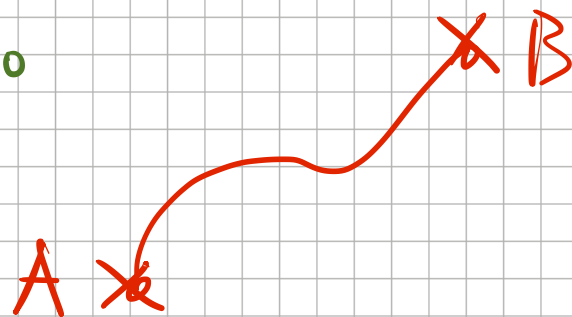
$$= \int_0^{2\pi} \langle -y + z, -x + z, x + y \rangle \cdot \vec{r}'(t) dt$$

$$= \int_0^{2\pi} \langle -\cos t + \sin t, 0, \sin t + \cos t \rangle \cdot \langle \cos t - \sin t, \cos t \rangle dt$$

$$= \int_0^{2\pi} \left[-\cancel{\cos^2 t} + \sin t \cos t \right] + 0 + \left[\sin t \cos t + \cancel{\cos^2 t} \right] dt$$

$$= \int_0^{2\pi} \sin 2t dt = -\frac{\cos 2t}{2} \Big|_0^{2\pi}$$

$$= -\frac{1}{2} [\cos 4\pi - \cos 0] = 0$$



$$\int_C \nabla \phi \cdot d\vec{r} = \phi(B) - \phi(A)$$

Section 17.4 Green's Theorem

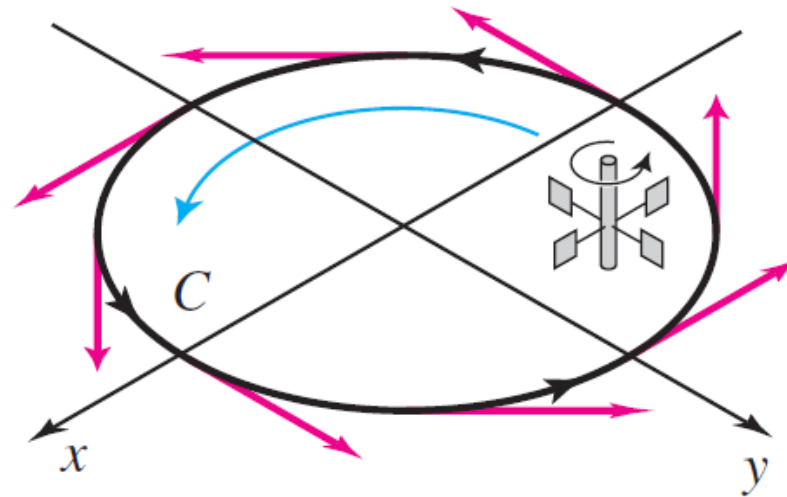
Stokes Theorem

Gauss Divergence Theorem

Circulation Form of Green's Theorem

Figure 17.31

Paddle wheel at one point of vector field.

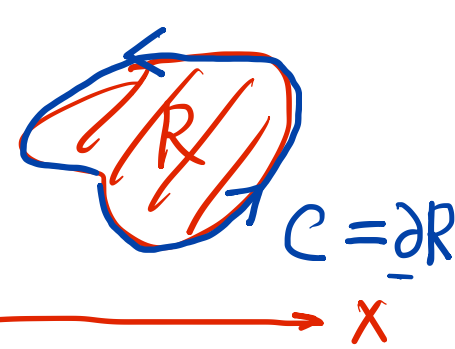


$\mathbf{F} = \langle -y, x \rangle$ has positive (counterclockwise) circulation on C .

$$\nabla \times \vec{F} = g_x - f_y, \quad \vec{F} = \langle f, g \rangle$$

Theorem 17.7 Green's Theorem- Circulation Form

$$\iint_R \nabla \times \vec{F} \, dA = \oint_C \vec{F} \cdot d\vec{r}$$



Let C be a simple closed piecewise-smooth curve, oriented counterclockwise, that encloses a connected and simply connected region R in the plane. Assume $\mathbf{F} = \langle f, g \rangle$, where f and g have continuous first partial derivatives in R . Then

$$\oint_C \mathbf{F} \cdot d\mathbf{r} = \oint_C f \, dx + g \, dy = \iint_R \left(\frac{\partial g}{\partial x} - \frac{\partial f}{\partial y} \right) dA.$$

circulation
circulation

$$\frac{\partial g}{\partial x} - \frac{\partial f}{\partial y} = 1$$

$$\begin{aligned} \vec{F} &= \langle -y, 0 \rangle \\ \nabla \times \vec{F} &= 1 \\ \vec{F} &= \langle 0, x \rangle \\ \nabla \times \vec{F} &= 1 \end{aligned}$$

$\vec{F}$ < conservative, gradient, irrotational

$\vec{F} = \nabla \phi$

Definition Two-Dimensional Curl

The **two-dimensional curl** of the vector field $\mathbf{F} = \langle f, g \rangle$

is $\nabla \times \mathbf{F} = \frac{\partial g}{\partial x} - \frac{\partial f}{\partial y}$. If the curl is zero throughout a region, the

vector field is **irrotational** on that region.

Example 1 Using Green's Thrm to compute $\oint_C \langle -y, x \rangle \cdot d\vec{r}$, where C is the unit circle oriented counterclockwise.



$$\begin{aligned} & \iint_R \left(\frac{\partial g}{\partial x} - \frac{\partial f}{\partial y} \right) dA \\ &= \iint_R [1 - (-1)] dA = 2 \iint_R dA \\ &= 2\pi \end{aligned}$$

Theorem 17.8 Area of a Plane Region by Line Integrals



$$A(R) = \iint_R 1 \, dA$$

$$= \oint_C \langle -y, 0 \rangle \cdot d\mathbf{r}$$

$$= \oint_C \langle 0, x \rangle \cdot d\mathbf{r}$$

Under the conditions of Green's Theorem, the area of a region R enclosed by a curve C is

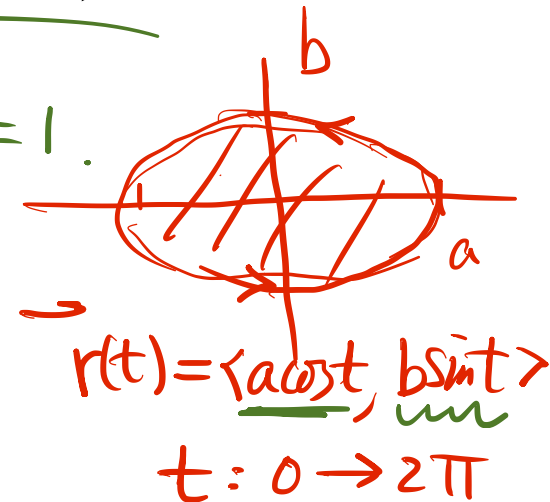
$$\int_C x \, dy = - \int_C y \, dx = \frac{1}{2} \int_C (x \, dy - y \, dx).$$

Example 2 Find the area of the ellipse $\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1$.

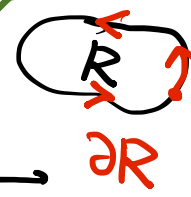
$$A(R) = \int_C x \, dy = \int_0^{2\pi} a \cos t \, d(b \sin t) = ab \int_0^{2\pi} \cos t \, dt$$

$$= \int_C -y \, dx = - \int_0^{2\pi} b \sin t \, d(a \cos t) = +ab \int_0^{2\pi} \sin t \, dt$$

$$= \frac{1}{2} \left[ab \int_0^{2\pi} \cos^2 t \, dt + ab \int_0^{2\pi} \sin^2 t \, dt \right] = \frac{ab}{2} \int_0^{2\pi} 1 \, dt = ab\pi$$



$$\underbrace{\iint_R \nabla \times \vec{F} dA}_{\text{Stokes's Thrm}} = \oint_{\partial R} \vec{F} \cdot d\vec{r} = \oint_{\partial R} f dx + g dy \quad \vec{F} = \langle f, g, h \rangle$$

$$\iint_S \nabla \times \vec{F} \cdot d\vec{S} = \oint_{\partial S} \vec{F} \cdot d\vec{r}$$


Definition Two-Dimensional Divergence

The **two-dimensional divergence** of the vector field

$$\nabla \times \vec{F} = \frac{\partial f}{\partial x} - \frac{\partial g}{\partial y}$$

$\vec{F} = \langle f, g \rangle$ is $\frac{\partial f}{\partial x} + \frac{\partial g}{\partial y}$. If the divergence is zero

throughout a region, the vector field is **source free** on that region.

$$\nabla \cdot \vec{F} = \left\langle \frac{\partial}{\partial x}, \frac{\partial}{\partial y} \right\rangle \cdot \langle f, g \rangle = \frac{\partial f}{\partial x} + \frac{\partial g}{\partial y} \quad \text{scalar-valued function}$$

$$\nabla \cdot \vec{F} = \left\langle \frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z} \right\rangle \cdot \langle f, g, h \rangle = \frac{\partial f}{\partial x} + \frac{\partial g}{\partial y} + \frac{\partial h}{\partial z}$$

$$\nabla \times \vec{F} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ f & g & h \end{vmatrix} = \langle h_y - g_z, f_z - h_x, g_x - f_y \rangle \quad \text{vector-valued}$$

$$\vec{T} = \langle x', y' \rangle / |\vec{r}'| \quad \vec{n} = \langle y', -x' \rangle$$

Theorem 17.9 Green's Theorem—Flux Form

$$\iint_R \nabla \cdot \vec{F} \, dA = \oint_{\partial R} \vec{F} \cdot \vec{n} \, ds = \oint_{\partial R} f \, dy - g \, dx$$

Let C be a simple closed piecewise-smooth curve, oriented counterclockwise, that encloses a connected and simply connected

region R in the plane. Assume $\vec{F} = \langle f, g \rangle$, where f and g have

continuous first partial derivatives in R . Then

$$\oint_C (-g) \, dx + f \, dy$$

$C \parallel$

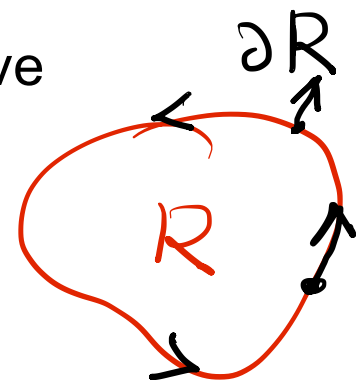
$$\iint_R \left[\frac{\partial}{\partial x} (f) - \frac{\partial}{\partial y} (-g) \right] dA$$

$$= \iint_R \nabla \cdot \vec{F} \, dA$$

$$\oint_C \vec{F} \cdot \vec{n} \, ds = \oint_C f \, dy - g \, dx = \iint_R \left(\frac{\partial f}{\partial x} + \frac{\partial g}{\partial y} \right) dA,$$

Outward flux

Outward flux



$$\int_C \nabla \psi \cdot d\vec{r} = \psi \Big|_A^B$$

Example 3 Use Green's Thrm to compute the outward flux of $\vec{F} = \langle x, y \rangle$ across the unit circle.

Figure 17.34

$$\int_C (\vec{F} \cdot \vec{n}) ds = \int_C x dy - y dx$$

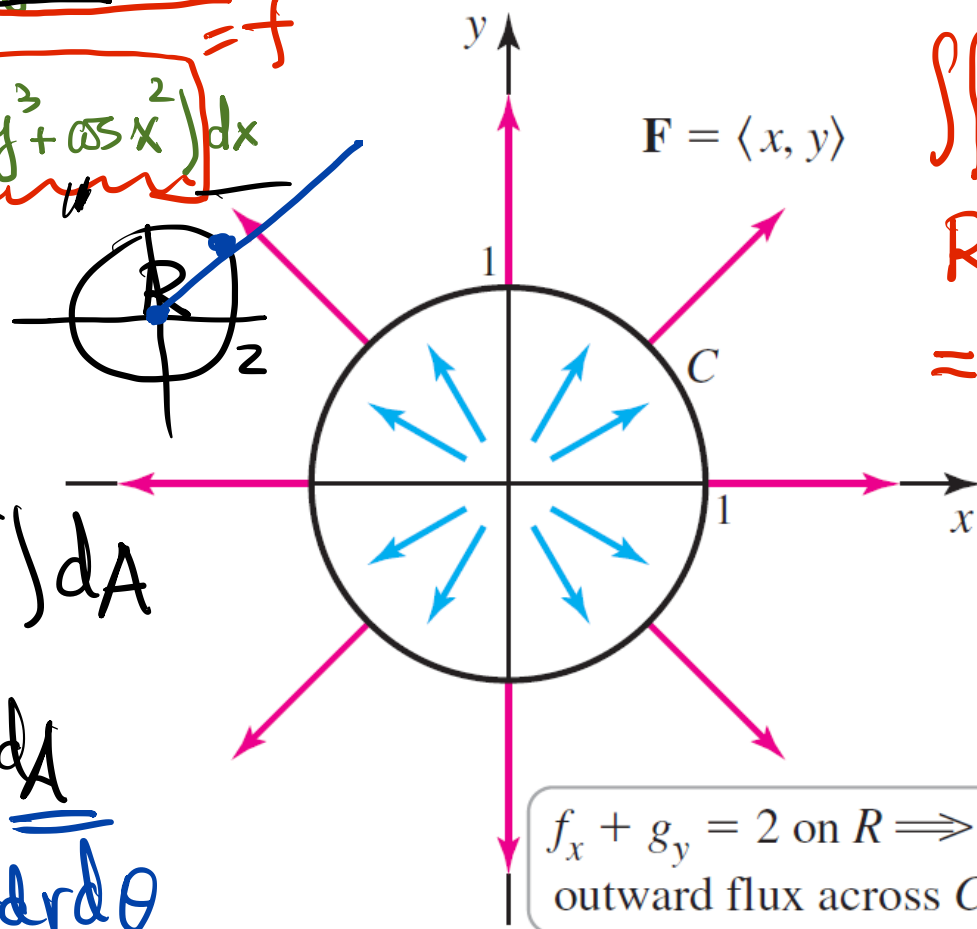
$$\iint_R \nabla \cdot \vec{F} dA$$

$$= \iint_R \left(\frac{\partial x}{\partial x} + \frac{\partial y}{\partial y} \right) dA$$

$$= 2 \iint_R dA$$

$$= 2 \text{ area}(R)$$

$$= 2\pi$$



$f_x + g_y = 2$ on $R \Rightarrow$
outward flux across C .

Example 4 $C: x^2 + y^2 = 4$ oriented
counterclockwise.

$$\oint_C (4x^3 + 5xy^2) dy - (4y^3 + 5x^2y) dx$$

$$= \oint_C f dx + g dy$$

$$= \iint_R \left(\frac{\partial g}{\partial x} - \frac{\partial f}{\partial y} \right) dA$$

$$= \iint_R (12x^2 + 12y^2) dA$$

$$= \int_0^{2\pi} \int_0^2 12r^2 \cdot r dr d\theta$$

Example 5 C is the boundary of $R = \{(x, y) : 1 \leq x^2 + y^2 \leq 9, y \geq 0\}$

Figure 17.35

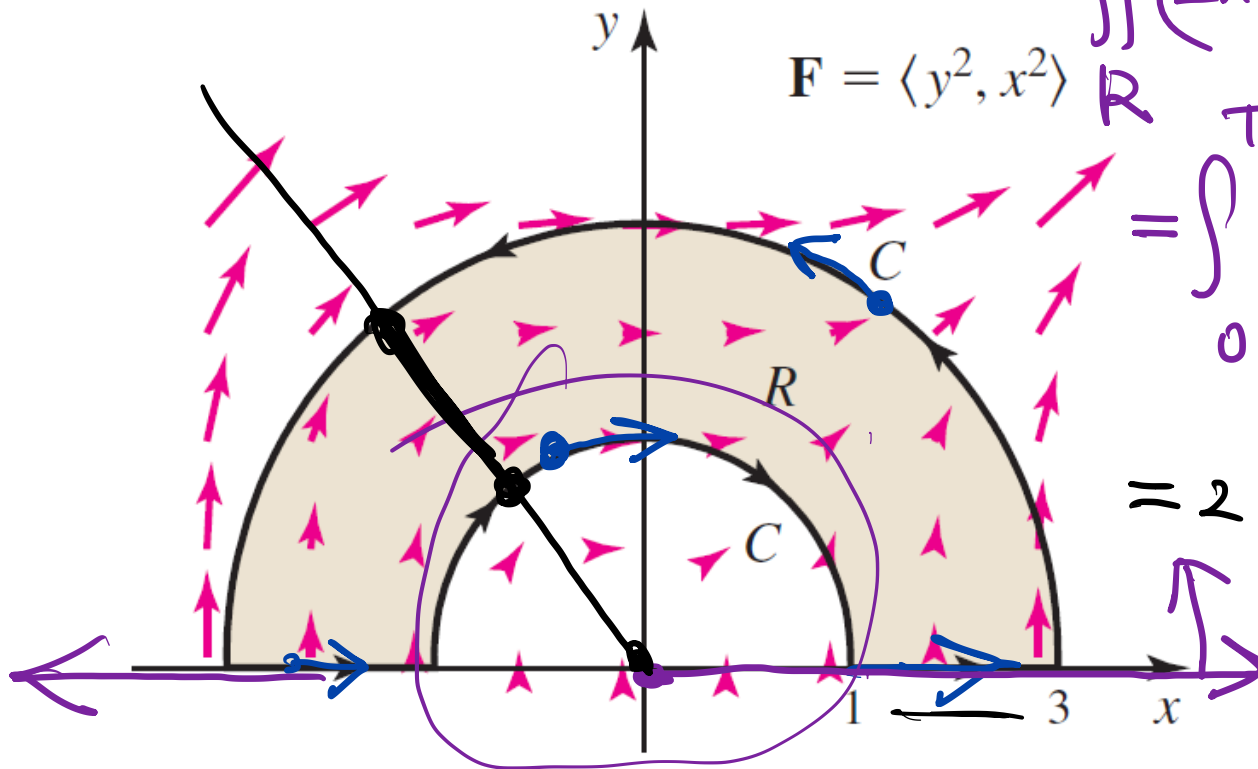
$$\oint_C y^2 dx + x^2 dy = \iint_R \left(\frac{\partial x^2}{\partial x} - \frac{\partial y^2}{\partial y} \right) dA$$

$$= \iint_R (2x - 2y) dA$$

$$\mathbf{F} = \langle y^2, x^2 \rangle$$

$$= \int_0^\pi \int_1^3 2r(\cos\theta - \sin\theta) \cdot r dr d\theta$$

$$= 2 \int_0^\pi (\cos\theta - \sin\theta) d\theta \cdot \int_1^3 r^2 dr$$



Circulation on boundary of R is negative.

Example 6 Find the outward flux of $\vec{F} = \langle xy^2, x^2y \rangle$ across the boundary of $R = \{(x,y) : 1 \leq x^2 + y^2 \leq 4\}$.

Figure 17.36

$$\iint_R \nabla \times \vec{F} dA = \iint_{R_1} + \iint_{R_2} \nabla \times \vec{F} dA = \underbrace{\oint_{\partial R_1} \vec{F} \cdot d\vec{r}} + \underbrace{\oint_{\partial R_2} \vec{F} \cdot d\vec{r}}$$

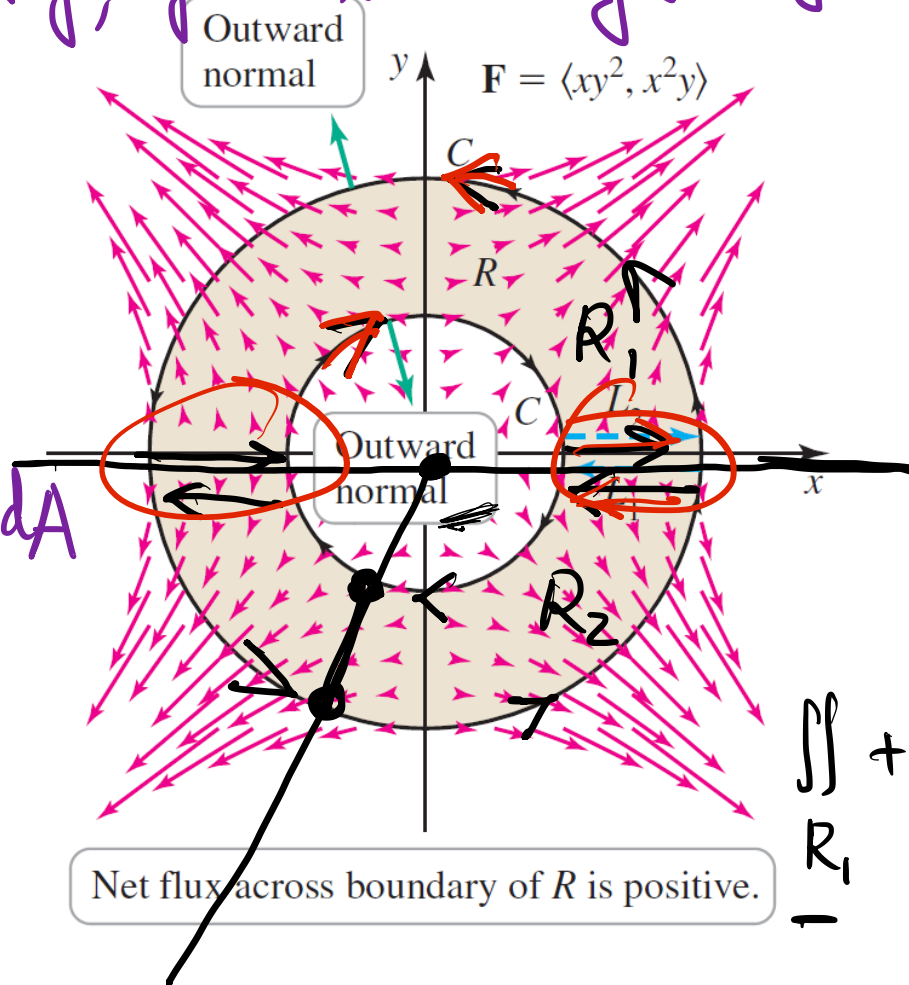
$$\nabla \cdot \langle xy^2, x^2y \rangle = \frac{\partial}{\partial x}(xy^2) + \frac{\partial}{\partial y}(x^2y) = y^2 + x^2$$



$$\oint_{\partial R} (\vec{F} \cdot \vec{n}) ds$$

$$= \iint_R \nabla \cdot \vec{F} dA = \iint_R (x^2 + y^2) dA$$

$$= \int_0^{2\pi} \int_1^2 r^2 \cdot r dr d\theta$$



$$\underbrace{\iint_{R_1}} + \underbrace{\iint_{R_2}} = \iint_R$$

Table 17.1

Conservative Fields $\mathbf{F} = \langle f, g \rangle$	Source-Free Fields $\mathbf{F} = \langle f, g \rangle$
• $\text{curl} = \frac{\partial g}{\partial x} - \frac{\partial f}{\partial y} = 0$ • Potential function φ with $\mathbf{F} = \nabla \varphi \quad \text{or} \quad f = \frac{\partial \varphi}{\partial x}, \quad g = \frac{\partial \varphi}{\partial y}$ • Circulation $= \oint_C \mathbf{F} \cdot d\mathbf{r} = 0$ on all closed curves C. • Path independence $\int_C \mathbf{F} \cdot d\mathbf{r} = \varphi(B) - \varphi(A)$	• divergence $= \frac{\partial f}{\partial x} + \frac{\partial g}{\partial y} = 0$ • Stream function ψ with $f = \frac{\partial \psi}{\partial y}, \quad g = -\frac{\partial \psi}{\partial x}$ • Flux $= \oint_C \mathbf{F} \cdot \mathbf{n} \, ds = 0$ on all closed curves C. • Path independence $\int_C \mathbf{F} \cdot \mathbf{n} \, ds = \psi(B) - \psi(A)$

Table 17.2

Circulation/work integrals: $\oint_C \mathbf{F} \cdot \mathbf{T} \, ds = \int_C \mathbf{F} \cdot d\mathbf{r} = \int_C f \, dx + g \, dy$		
	C closed	C not closed
F conservative ($\mathbf{F} = \nabla \varphi$)	$\oint_C \mathbf{F} \cdot d\mathbf{r} = 0$	$\int_C \mathbf{F} \cdot d\mathbf{r} = \varphi(B) - \varphi(A)$
F not conservative	Green's Theorem $\oint_C \mathbf{F} \cdot d\mathbf{r} = \iint_R (g_x - f_y) \, dA$	Direct evaluation $\int_C \mathbf{F} \cdot d\mathbf{r} = \int_a^b (fx' + gy') \, dt$
Flux integrals: $\oint_C \mathbf{F} \cdot \mathbf{n} \, ds = \int_C f \, dy - g \, dx$		
	C closed	C not closed
F source free ($f = \psi_y, g = -\psi_x$)	$\oint_C \mathbf{F} \cdot \mathbf{n} \, ds = 0$	$\int_C \mathbf{F} \cdot \mathbf{n} \, ds = \psi(B) - \psi(A)$
F not source free	Green's Theorem $\oint_C \mathbf{F} \cdot \mathbf{n} \, ds = \iint_R (f_x + g_y) \, dA$	Direct evaluation $\int_C \mathbf{F} \cdot \mathbf{n} \, ds = \int_a^b (fy' - gx') \, dt$

Section 17.5 Divergence and Curl

$$\vec{F} = \langle f, g, h \rangle \quad \nabla \cdot \vec{F} = \left\langle \frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z} \right\rangle \cdot \langle f, g, h \rangle \\ = f_x + g_y + h_z \quad \text{--- scalar}$$

$$\vec{\nabla} \times \vec{F} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ f & g & h \end{vmatrix} = \langle h_y - g_z, f_z - h_x, g_x - f_y \rangle \quad \text{vector}$$

Definition Divergence of a Vector Field

The **divergence** of a vector field $\mathbf{F} = \langle f, g, h \rangle$ that is differentiable on a region of $\mathbb{R}^3$ is

$$\text{div } \mathbf{F} = \nabla \cdot \mathbf{F} = \frac{\partial f}{\partial x} + \frac{\partial g}{\partial y} + \frac{\partial h}{\partial z}.$$

If $\nabla \cdot \mathbf{F} = 0$, the vector field is **source free**.

rotational VF

Example 1 (a) $\vec{F} = \langle x, y, z \rangle$; (b) $\vec{F} = \langle -y, x-z, y \rangle$; (c) $\vec{F} = \langle -y, x, z \rangle$

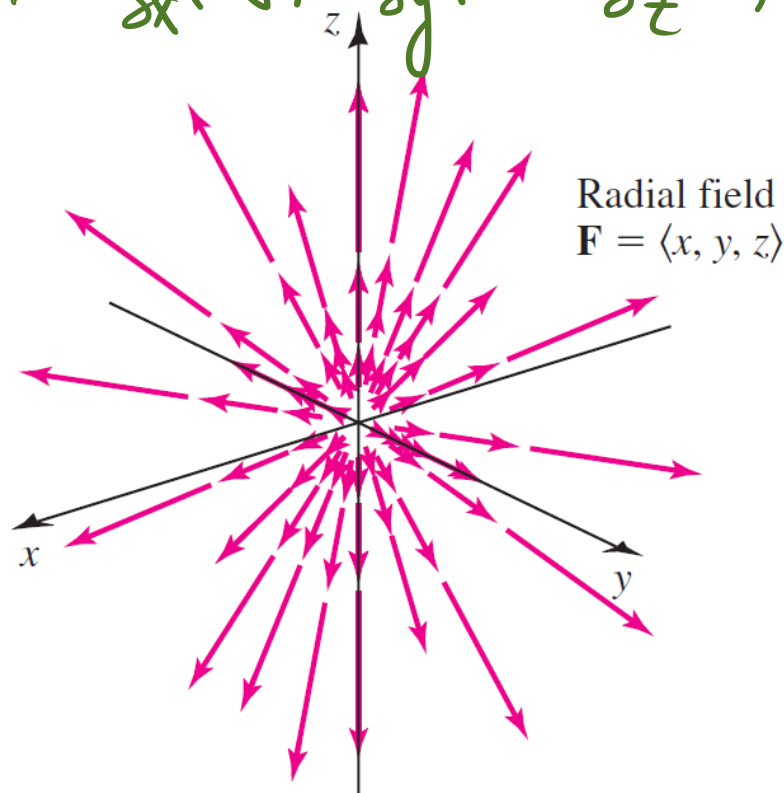
? = $\nabla \cdot \vec{F}$

(a) $\nabla \cdot \vec{F} = \frac{\partial x}{\partial x} + \frac{\partial y}{\partial y} + \frac{\partial z}{\partial z} = 3$

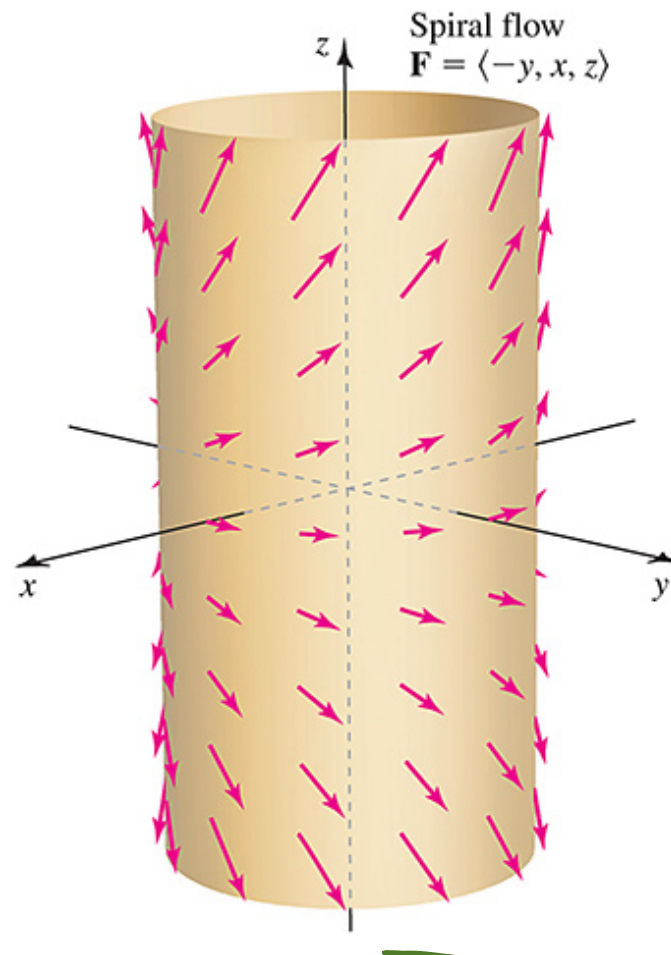
(b) $\nabla \cdot \vec{F} = \frac{\partial}{\partial x}(-y) + \frac{\partial}{\partial y}(x-z) + \frac{\partial}{\partial z}(y) = 0 + 0 + 0 = 0$

Figure 17.38 (a & b)

(c) $\nabla \cdot \vec{F} = \frac{\partial}{\partial x}(-y) + \frac{\partial}{\partial y}(x) + \frac{\partial}{\partial z}(z) = 1$



$\nabla \cdot \mathbf{F} = 3$ at all points $\Rightarrow$
vector field expands outward
at all points.



Theorem 17.10 Divergence of Radial Vector Fields

For a real number p , the divergence of the radial vector field

$$\mathbf{F} = \frac{\mathbf{r}}{|\mathbf{r}|^p} = \frac{\langle x, y, z \rangle}{(x^2 + y^2 + z^2)^{p/2}}$$

is

$$\nabla \cdot \mathbf{F} = \frac{3-p}{|\mathbf{r}|^p}.$$

$p=1$

Example 2 ($p=1$) $\nabla \cdot \vec{F} = ?$

$$\vec{F} = \left\langle \frac{x}{|\vec{r}|}, \frac{y}{|\vec{r}|}, \frac{z}{|\vec{r}|} \right\rangle$$

$$\begin{aligned} \frac{\partial}{\partial x} \left(\frac{x}{|\vec{r}|} \right) &= \frac{1 \cdot |\vec{r}| - x \frac{\partial}{\partial x} |\vec{r}|}{|\vec{r}|^2} \\ &= \frac{|\vec{r}| - x^2 |\vec{r}|^{-1}}{|\vec{r}|^2} = \frac{|\vec{r}|^2 - x^2}{|\vec{r}|^3} = \frac{y^2 + z^2}{|\vec{r}|^3} \end{aligned}$$

$$\vec{r} = \langle x, y, z \rangle, \quad |\vec{r}| = \sqrt{x^2 + y^2 + z^2}$$

$$\frac{\partial}{\partial x} |\vec{r}| = \frac{\partial}{\partial x} \sqrt{x^2 + y^2 + z^2} = \frac{1}{2} (x^2 + y^2 + z^2)^{-\frac{1}{2}} \cdot 2x$$

$$\begin{aligned} &= x |\vec{r}|^{-1} \\ \nabla \cdot \vec{F} &= \frac{y^2 + z^2}{|\vec{r}|^3} + \frac{x^2 + z^2}{|\vec{r}|^3} + \frac{x^2 + y^2}{|\vec{r}|^3} \end{aligned}$$

$$= \frac{2|\vec{r}|^2}{|\vec{r}|^3} = \frac{2}{|\vec{r}|}$$

Example 3 $\vec{F} = \langle x^2, y \rangle$ and C is a circle of radius 2 centered at the origin.

(a) At $Q(1,1)$, is $\nabla \cdot \vec{F}$ positive or negative? Why? (b) Compute $\nabla \cdot \vec{F}(1,1)$.

without computing.

Figure 17.39

(c) Inside C , determine regions that $\nabla \cdot \vec{F}$ is pos. or neg.

$$\nabla \cdot \vec{F}(1,1) = \frac{\partial x^2}{\partial x} + \frac{\partial y}{\partial y} \Big|_{(1,1)} = (2x+1) \Big|_{(1,1)} = 3 > 0$$

$$\vec{F} = \langle f, g, h \rangle$$

$$\nabla \cdot \vec{F} = \frac{\partial f}{\partial x} + \frac{\partial g}{\partial y} + \frac{\partial h}{\partial z}$$

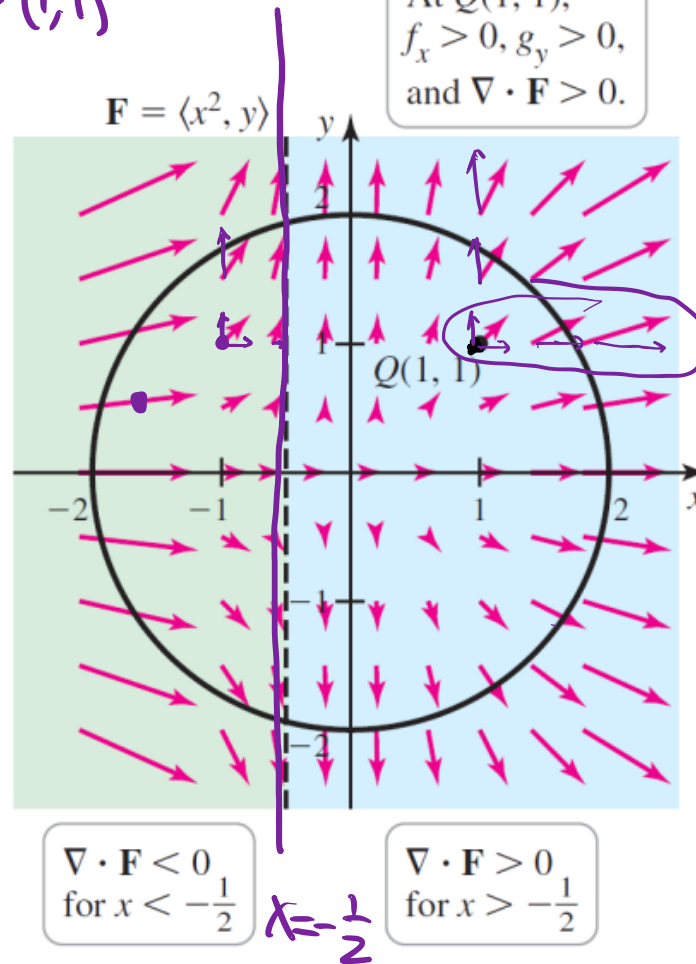
$$\nabla \cdot \langle f, g \rangle = \frac{\partial f}{\partial x} + \frac{\partial g}{\partial y}$$

$$f(x) \uparrow \Rightarrow f'(x) > 0$$

$$(c) \quad 2x + 1 > 0$$

$$x > -\frac{1}{2} \Rightarrow \nabla \cdot \vec{F} > 0$$

$$x < -\frac{1}{2}, \quad \nabla \cdot \vec{F} < 0$$



Definition Curl of a Vector Field

The **curl** of a vector field $\mathbf{F} = \langle f, g, h \rangle$ that is differentiable on a region of $\mathbb{R}^3$ is

$$\nabla \times \mathbf{F} = \text{curl } \mathbf{F}$$

$$= \left(\frac{\partial h}{\partial y} - \frac{\partial g}{\partial z} \right) \mathbf{i} + \left(\frac{\partial f}{\partial z} - \frac{\partial h}{\partial x} \right) \mathbf{j} + \left(\frac{\partial g}{\partial x} - \frac{\partial f}{\partial y} \right) \mathbf{k}.$$

Handwritten purple annotations showing the derivation of the curl formula for the k-component. It starts with $\mathbf{F} = \langle f, g \rangle$ (with h implied). Then it shows $\nabla \times \mathbf{F} = \left(\frac{\partial g}{\partial x} - \frac{\partial f}{\partial y} \right) \mathbf{k}$. A bracket connects this to the $\mathbf{k}$ component of the printed formula above.

If $\nabla \times \mathbf{F} = \mathbf{0}$, the vector field is **irrotational**.

• General Rotation Vector Field

$$? = \nabla \times \vec{F}$$

Figure 17.41

$$\vec{F} = \vec{a} \times \vec{r}, \text{ where } \vec{a} = \langle a_1, a_2, a_3 \rangle, \vec{r} = \langle x, y, z \rangle$$

$$= \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ a_1 & a_2 & a_3 \\ x & y & z \end{vmatrix} = \langle a_2 z - a_3 y, a_3 x - a_1 z, a_1 y - a_2 x \rangle$$

$$\nabla \times \vec{F} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \partial_x & \partial_y & \partial_z \\ a_2 z - a_3 y & a_3 x - a_1 z & a_1 y - a_2 x \end{vmatrix}$$

$$= \langle a_1 + a_1, a_2 + a_2, a_3 + a_3 \rangle$$

$$= 2\langle a_1, a_2, a_3 \rangle$$

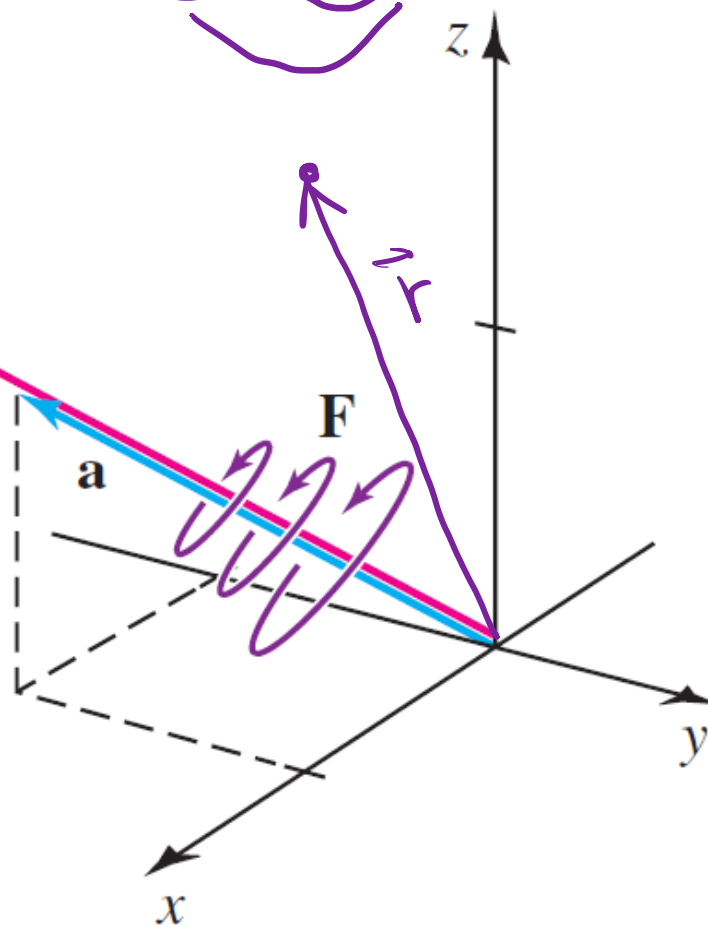
$$= 2\vec{a}$$

General
rotation field

$$\vec{a} = \langle 1, -1, 1 \rangle$$

$$\vec{F} = \vec{a} \times \vec{r}$$

$$\nabla \times \vec{F} = 2\vec{a}$$



General Rotation Vector Field

The **general rotation vector field** is $\mathbf{F} = \mathbf{a} \times \mathbf{r}$, where the nonzero constant vector $\mathbf{a} = \langle a_1, a_2, a_3 \rangle$ is the axis of rotation and $\mathbf{r} = \langle x, y, z \rangle$. For all nonzero choices of $\mathbf{a}$, $|\nabla \times \mathbf{F}| = 2|\mathbf{a}|$ and $\nabla \cdot \mathbf{F} = 0$. If $\mathbf{F}$ is a velocity field, then the constant angular speed of the field is

$$\omega = |\mathbf{a}| = \frac{1}{2} |\nabla \times \mathbf{F}|.$$

Theorem 17.11 Curl of a Conservative Vector Field

Suppose $\mathbf{F}$ is a conservative vector field on an open region D of $\mathbb{R}^3$. Let $\mathbf{F} = \nabla \varphi$, where φ is a potential function with continuous second partial derivatives on D .

Then $\nabla \times \mathbf{F} = \nabla \times \nabla \varphi = \mathbf{0}$: The curl of the gradient is the zero vector and $\mathbf{F}$ is irrotational.

$$\begin{aligned} \vec{0} &= \nabla \times (\nabla \varphi) = \begin{vmatrix} \bar{i} & \bar{j} & \bar{k} \\ \partial_x & \partial_y & \partial_z \\ \partial_x \varphi & \partial_y \varphi & \partial_z \varphi \end{vmatrix} = \langle \underbrace{\varphi_{zy} - \varphi_{yz}}_{=0}, \dots, \dots \rangle \end{aligned}$$

gradient VF
conservative ..
irrotational ..

Theorem 17.12 Divergence of the Curl

Suppose $\mathbf{F} = \langle f, g, h \rangle$ where f , g , and h have

continuous second partial derivatives. Then

$$\nabla \cdot (\nabla \times \mathbf{F}) = 0:$$

The divergence of the curl is zero.

Theorem 17.13 Product Rule for the Divergence

Let u be a scalar-valued function that is differentiable on a region D and let $\mathbf{F}$ be a vector field that is differentiable on D . Then

$$\nabla \cdot (u\mathbf{F}) = \nabla u \cdot \mathbf{F} + u(\nabla \cdot \mathbf{F}).$$

Properties of a Conservative Vector Field

Let $\mathbf{F}$ be a conservative vector field whose components have continuous second partial derivatives on an open connected region D in

o ³. Then $\mathbf{F}$ has the following equivalent properties.

1. There exists a potential function φ such that $\mathbf{F} = \nabla \varphi$ (definition).

2. $\int_C \mathbf{F} \cdot d\mathbf{r} = \varphi(B) - \varphi(A)$ for all points A and B in D and all piecewise-smooth oriented curves C in D from A to B .

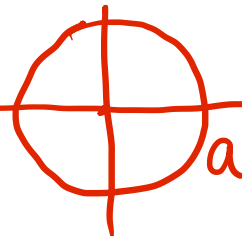
3. $\int_C \mathbf{F} \cdot d\mathbf{r} = 0$ on all simple piecewise-smooth closed oriented curves C in D .

4. $\nabla \times \mathbf{F} = \mathbf{0}$ at all points of D .

$$x^2 + y^2 = a^2$$

$$\begin{cases} x = r \cos \theta \\ y = r \sin \theta \end{cases}$$

$$r(\theta) = a \cos \theta, a \sin \theta$$



$$r = a$$

$$\begin{cases} x = a \cos \theta \\ y = a \sin \theta \end{cases}$$

$$0 \leq \theta \leq 2\pi$$

① graph $y = f(x)$, $a \leq x \leq b$
 ② level curve $f(x, y) = c$
 ③ parametrized curve.

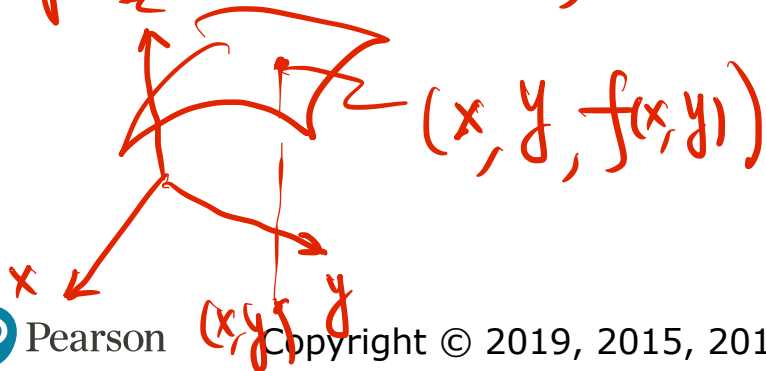
$\vec{r}(x) = \langle x, f(x) \rangle$
 $x \in [a, b]$

$\vec{r}(t) = \langle x(t), y(t) \rangle$
 $a \leq t \leq b$

Section 17.6 Surface Integrals

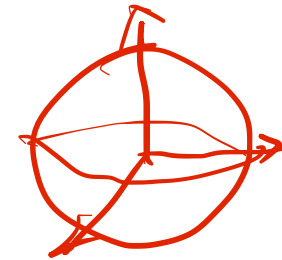
Representation of Surfaces

- graph $z = f(x, y)$, $(x, y) \in \mathbb{R}^2$



- level surfaces

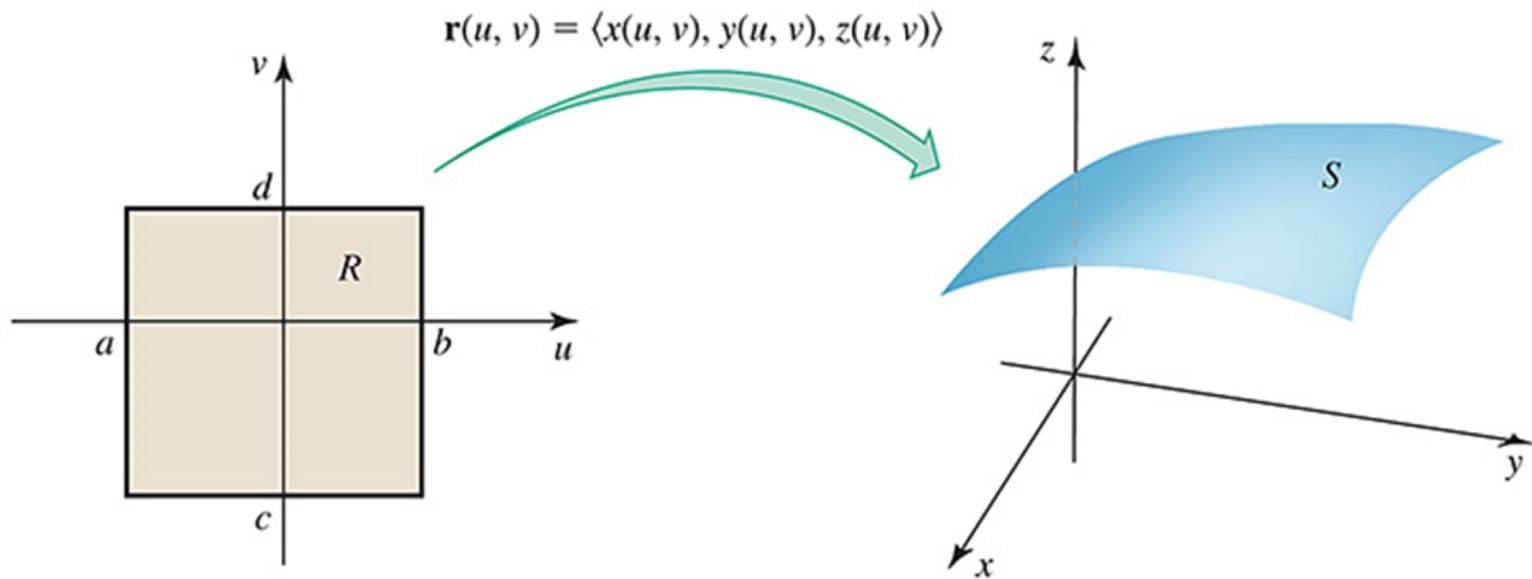
$$f(x, y, z) = c$$



Parametrized Surfaces

$$\vec{r}(u, v) = \langle x(u, v), y(u, v), z(u, v) \rangle$$
$$(u, v) \in R$$

Figure 17.43



A rectangle in the uv -plane is mapped to a surface in xyz -space.

Cylinders

$$x^2 + y^2 = a^2$$

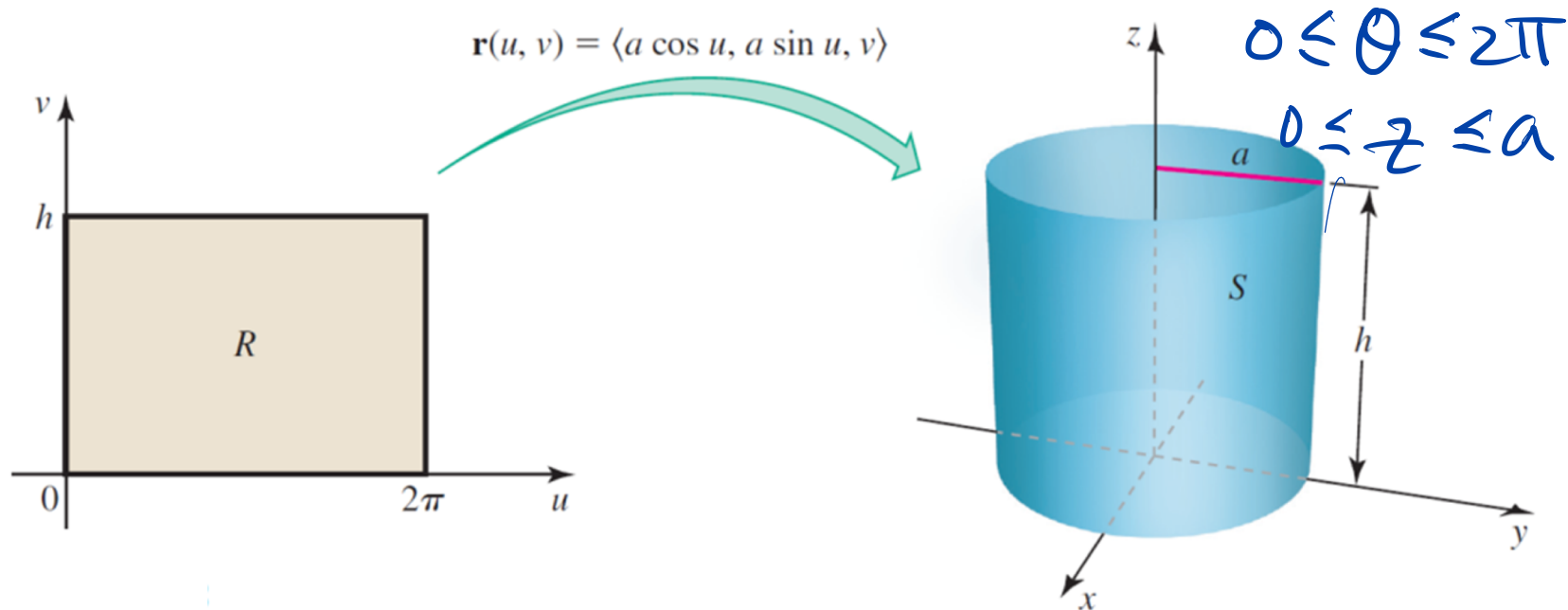
$$\boxed{r=a}$$

Figure 17.44

$$\begin{cases} x = r \cos \theta \\ y = r \sin \theta \\ z = z \end{cases} \quad r=a \Rightarrow$$

$$\begin{cases} x = a \cos \theta \\ y = a \sin \theta \\ z = z \end{cases}$$

$$\vec{r}(\theta, z) = \langle a \cos \theta, a \sin \theta, z \rangle$$



Cones

$$z = \frac{h}{a} \sqrt{x^2 + y^2} \quad \cdot \quad \vec{r}(x, y) = \langle x, y, \frac{h}{a} \sqrt{x^2 + y^2} \rangle, (x, y) \in \underline{\underline{\mathbb{R}}}$$

Figure 17.45

$$\varphi = \arctan \frac{a}{h}$$

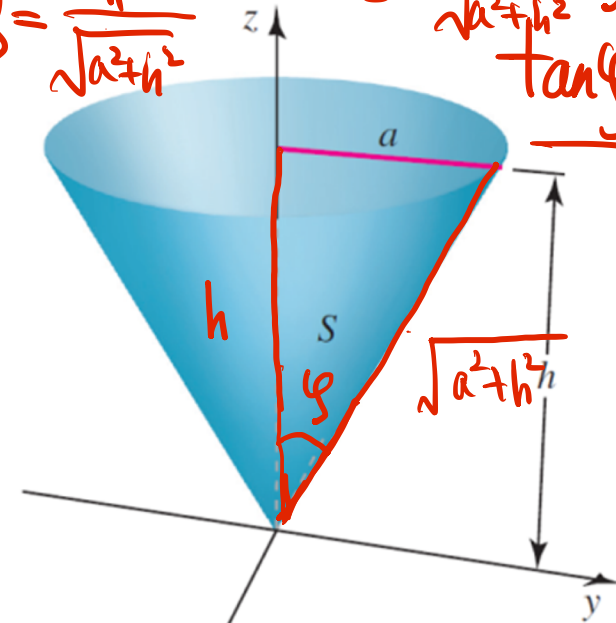
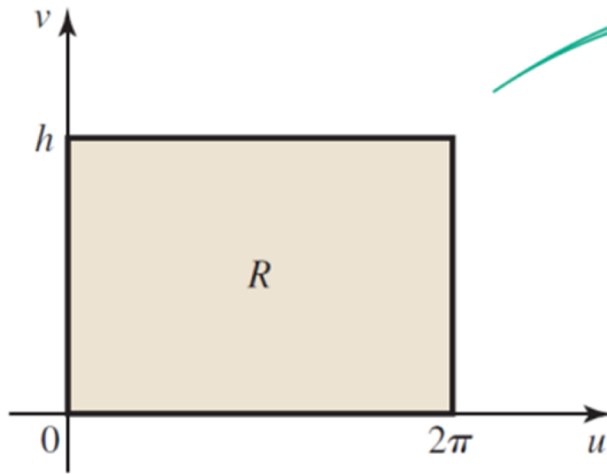
$$\rho \cos \varphi = \frac{h}{a} \rho \sin \varphi$$

$$\begin{cases} x = \rho \sin \varphi \cos \theta \\ y = \rho \sin \varphi \sin \theta \\ z = \rho \cos \varphi \end{cases}$$

$$\begin{aligned} \varphi &= \arctan \frac{a}{h} \\ \sin \varphi &= \frac{a}{\sqrt{a^2 + h^2}} \\ \cos \varphi &= \frac{h}{\sqrt{a^2 + h^2}} \end{aligned}$$

$$\begin{cases} x = \frac{a}{\sqrt{a^2 + h^2}} \rho \cos \theta \\ y = \frac{a}{\sqrt{a^2 + h^2}} \rho \sin \theta \\ z = \frac{h}{\sqrt{a^2 + h^2}} \rho \end{cases} \quad \tan \varphi = \frac{a}{h}$$

$$\vec{r}(u, v) = \left\langle \frac{av}{h} \cos u, \frac{av}{h} \sin u, v \right\rangle$$



$$\vec{r}(\rho, \theta) = \frac{1}{\sqrt{a^2 + h^2}} \langle a \rho \cos \theta, a \rho \sin \theta, h \rho \rangle$$

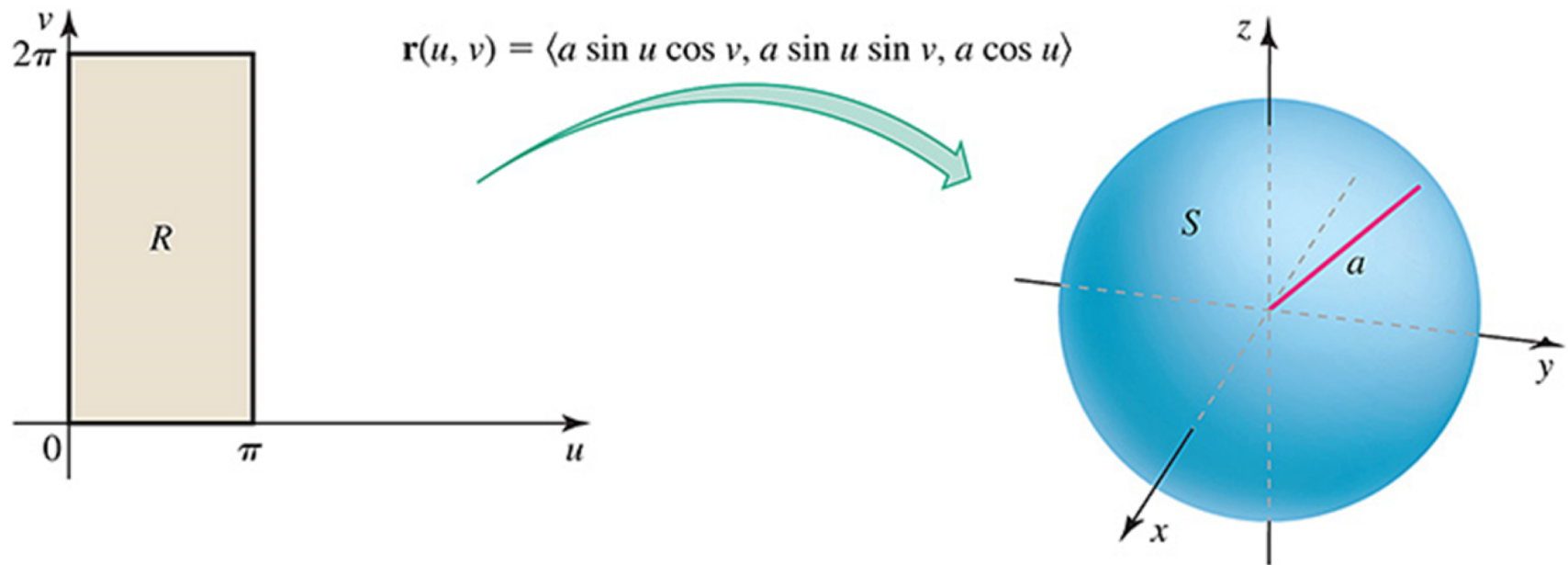
$$0 \leq \theta \leq 2\pi, \quad 0 \leq \rho \leq \sqrt{a^2 + h^2}$$

Spheres $x^2 + y^2 + z^2 = a^2 \iff \rho = a$

$$\vec{r}(\varphi, \theta) = \langle a \sin \varphi \cos \theta, a \sin \varphi \sin \theta, a \cos \varphi \rangle$$

$$0 \leq \varphi \leq \pi, \quad 0 \leq \theta \leq 2\pi$$

Figure 17.46



Example 1 Find parametric descriptions for the following surfaces.

(a) the plane $3x - 2y + z = 2$

(b) the paraboloid $z = x^2 + y^2$, for $0 \leq z \leq 9$

(a) $z = 2 - 3x + 2y$

$\vec{r}(x, y) = \langle x, y, 2 - 3x + 2y \rangle, (x, y) \in \underline{R}$

(b) $\vec{r}(x, y) = \langle x, y, x^2 + y^2 \rangle, R: \underline{0 \leq x^2 + y^2 \leq 9}$

$\vec{r}(r, \theta) = \langle r \cos \theta, r \sin \theta, r^2 \rangle, \begin{matrix} 0 \leq r \leq 3 \\ 0 \leq \theta \leq 2\pi \end{matrix}$

Surface Integrals of Scalar-Valued Functions

$$\iint_S f dS = \iint_R f(\vec{r}(u,v)) \underbrace{|\vec{r}_u \times \vec{r}_v|}_{dS} du dv$$

$$S: \vec{r}(u,v) = \langle x(u,v), y(u,v), z(u,v) \rangle$$

$$(u,v) \in R$$

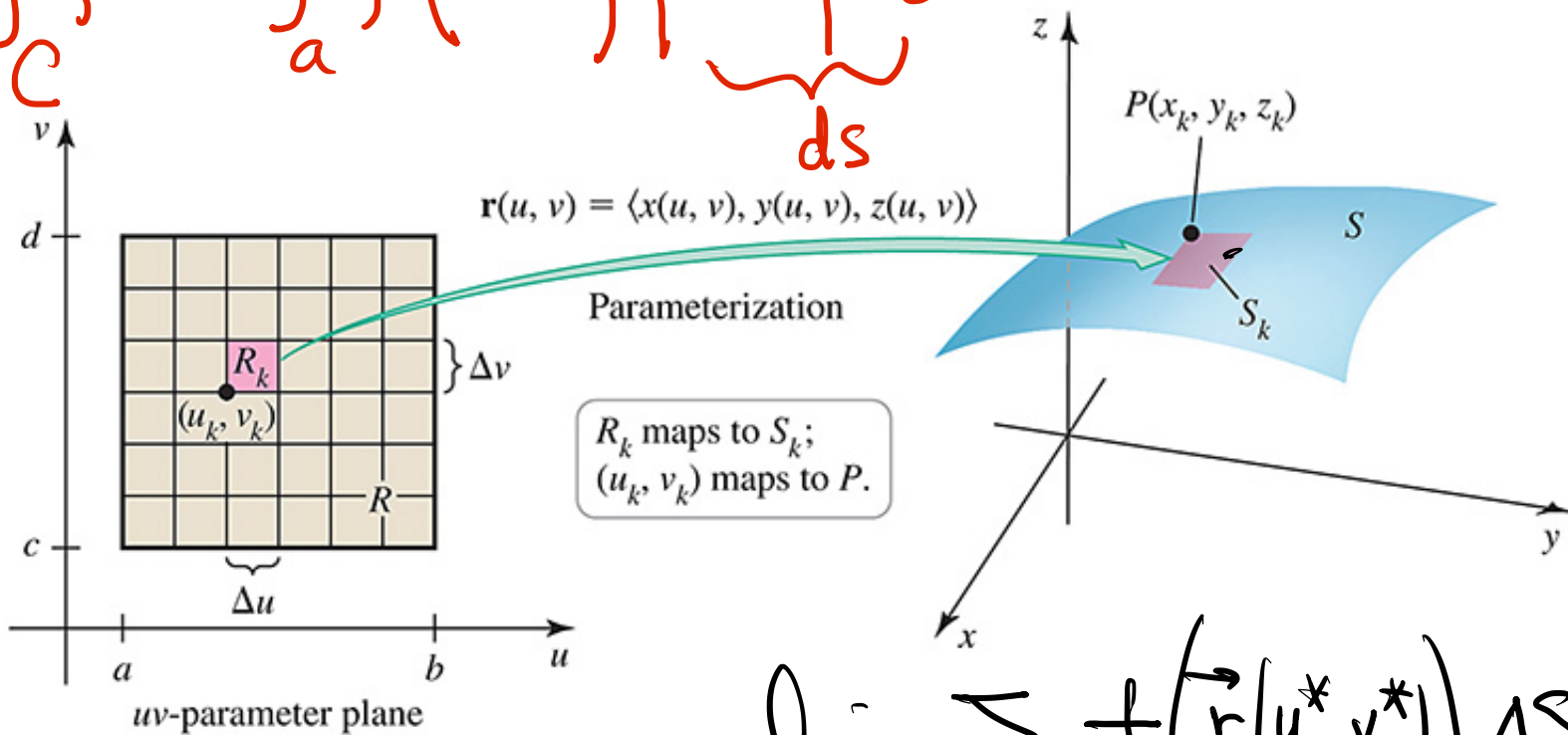
$$C: \vec{r}(t) = \langle x(t), y(t), z(t) \rangle$$

$$t \in [a, b]$$

Figure 17.47

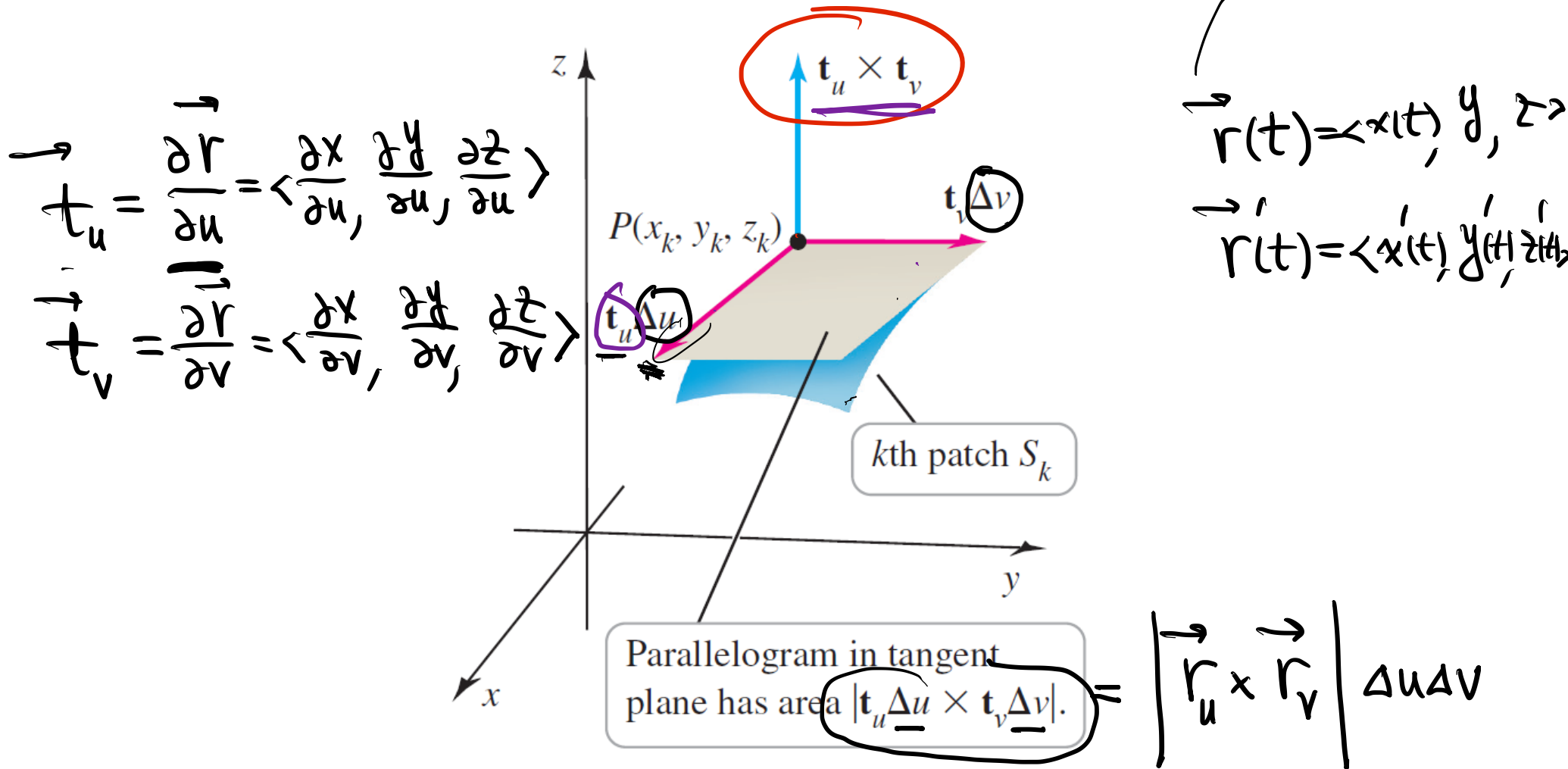
$$\iint_R f dA$$

$$\int_C f ds = \int_a^b f(\vec{r}(t)) \underbrace{|\vec{r}'(t)|}_{ds} dt$$



$$\lim_{\Delta S_k \rightarrow 0} \sum_k f(\vec{r}(u_k^*, v_k^*)) \underbrace{\Delta S_k}_{\substack{|\vec{r}_u \times \vec{r}_v| \Delta u \Delta v}}$$

Figure 17.48



Definition Surface Integral of Scalar-Valued Functions on Parameterized Surfaces

Let f be a continuous scalar-valued function on a smooth surface S given parametrically by $\mathbf{r}(u, v) = \langle x(u, v), y(u, v), z(u, v) \rangle$, where u and v vary over $R = \{(u, v) : a \leq u \leq b, c \leq v \leq d\}$. Assume also that the tangent vectors $\mathbf{t}_u = \frac{\partial \mathbf{r}}{\partial u} = \left\langle \frac{\partial x}{\partial u}, \frac{\partial y}{\partial u}, \frac{\partial z}{\partial u} \right\rangle$ and $\mathbf{t}_v = \frac{\partial \mathbf{r}}{\partial v} = \left\langle \frac{\partial x}{\partial v}, \frac{\partial y}{\partial v}, \frac{\partial z}{\partial v} \right\rangle$ are continuous on R and the normal vector $\mathbf{t}_u \times \mathbf{t}_v$ is nonzero on R . Then the **surface integral** of f over S is

$$\iint_S f(x, y, z) dS = \iint_R f(x(u, v), y(u, v), z(u, v)) |\mathbf{t}_u \times \mathbf{t}_v| dA.$$

If $f(x, y, z) = 1$, this integral equals the surface area of S .

Example 2 Find the surface area.

(a) A cylinder with radius $a > 0$ and height h (excluding the circular ends)

Figure 17.49

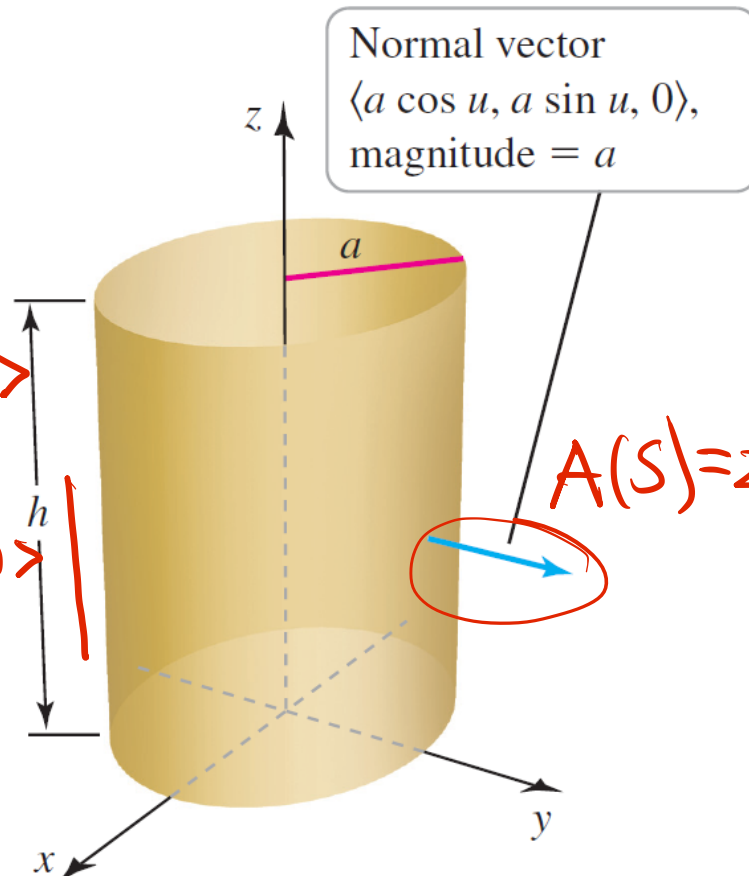
$$A(S) = \iint_S 1 \, dS = \iint_R a \, du \, dv = \int_0^{2\pi} du \int_0^h a \, dv = a \cdot 2\pi \cdot h$$

$$\vec{t}_u = \langle -a \sin u, a \cos u, 0 \rangle$$

$$\vec{t}_v = \langle 0, 0, 1 \rangle$$

$$\vec{t}_u \times \vec{t}_v = \langle a \cos u, a \sin u, 0 \rangle$$

$$|\vec{t}_u \times \vec{t}_v| = a |\langle \cos u, \sin u, 0 \rangle| = a$$



$$A(S) = 2\pi r h +$$

$$\text{Cylinder: } \mathbf{r}(u, v) = \langle a \cos u, a \sin u, v \rangle, \\ 0 \leq u \leq 2\pi \text{ and } 0 \leq v \leq h$$

$$u = \theta, \quad v = z$$

(b) a sphere of radius a . $A(S) = 4\pi a^2$

$$A(S) = \int_S 1 dS = \int_0^\pi \int_0^{2\pi} 1 \cdot a^2 \sin u \, dv \, du$$

$$= a^2 \cdot 2\pi \int_0^\pi \sin u \, du$$

Figure 17.50

Sphere: $u = \varphi, v = \theta$

$$= 2\pi a^2 \cdot [-\cos u]_0^\pi = 4\pi a^2$$

$\mathbf{r}(u, v) = \langle a \sin u \cos v, a \sin u \sin v, a \cos u \rangle,$

$0 \leq u \leq \pi$ and $0 \leq v \leq 2\pi$: R

$$\vec{t}_u = \langle a \cos u \cos v, a \cos u \sin v, -a \sin u \rangle$$

$$\vec{t}_v = \langle -a \sin u \sin v, a \sin u \cos v, 0 \rangle$$

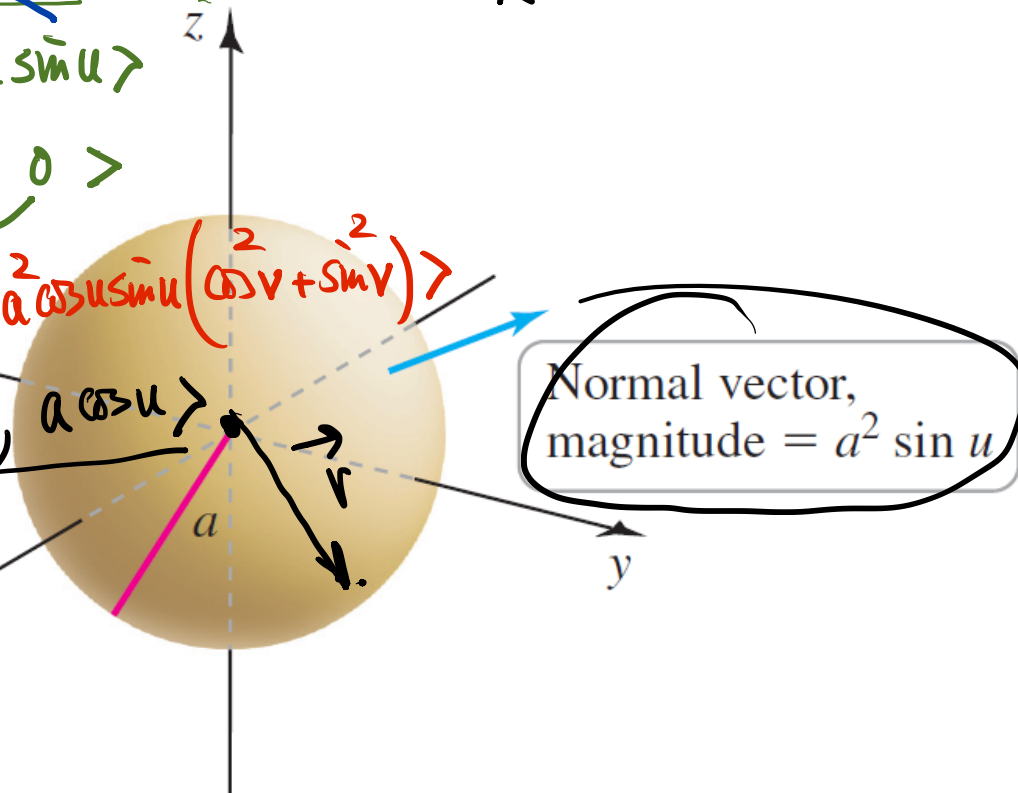
$$\vec{t}_u \times \vec{t}_v = \langle a^2 \sin u \cos v, a^2 \sin u \sin v, a^2 \cos u \sin u (\cos^2 v + \sin^2 v) \rangle$$

$$= a \sin u \langle a \sin u \cos v, a \sin u \sin v, a \cos u \rangle$$

$$= a \sin u \vec{r}(u, v)$$

$$|\vec{t}_u \times \vec{t}_v| = a \sin u |\vec{r}(u, v)|$$

$$= a^2 \sin u$$



Example 3 Find the surface area of the cylinder $\{(r, \theta): r=4, 0 \leq \theta \leq 2\pi\}$ between the planes $\underline{z=0}$ and $\underline{z=16-2x}$ (excluding the top and bottom surfaces).

Figure 17.51

$$\vec{r}_u \times \vec{r}_v = \langle 4 \cos u, 4 \sin u, 0 \rangle$$

$$|\vec{r}_u \times \vec{r}_v| = 4$$

$$= 16 - 2 \cdot 4 \cos u$$

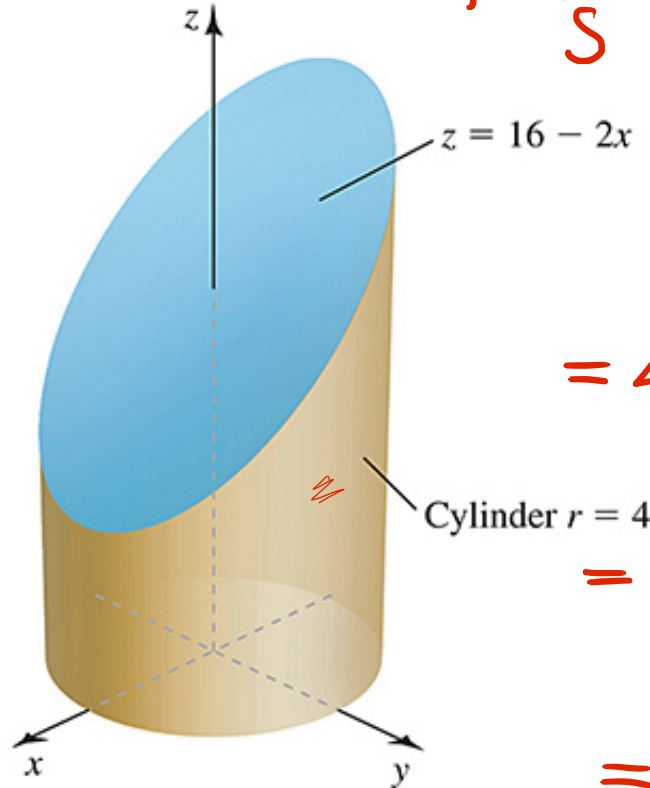
$$A(S) = \iint_S 1 dS = \iint 4 du dv$$

$$= \int_0^{2\pi} \int_0^{16-8\cos u} 4 dv du$$

$$= 4 \int_0^{2\pi} (16 - 8 \cos u) du$$

$$= 4 \left[16u - 8 \sin u \right]_0^{2\pi}$$

$$= 4 \cdot 16 \cdot 2\pi$$



Sliced cylinder is generated by
 $\mathbf{r}(u, v) = \langle 4 \cos u, 4 \sin u, v \rangle$, where
 $0 \leq u \leq 2\pi, 0 \leq v \leq 16 - 8 \cos u$.

$$u = \theta, \quad v = z$$

Surface Integrals on Graph

$$S: z = g(x, y), (x, y) \in R$$

Figure 17.52

$$\vec{r}(x, y) = \langle x, y, g(x, y) \rangle, (x, y) \in R$$

$$\vec{t}_x = \frac{\partial \vec{r}}{\partial x} = \langle 1, 0, g_x \rangle$$

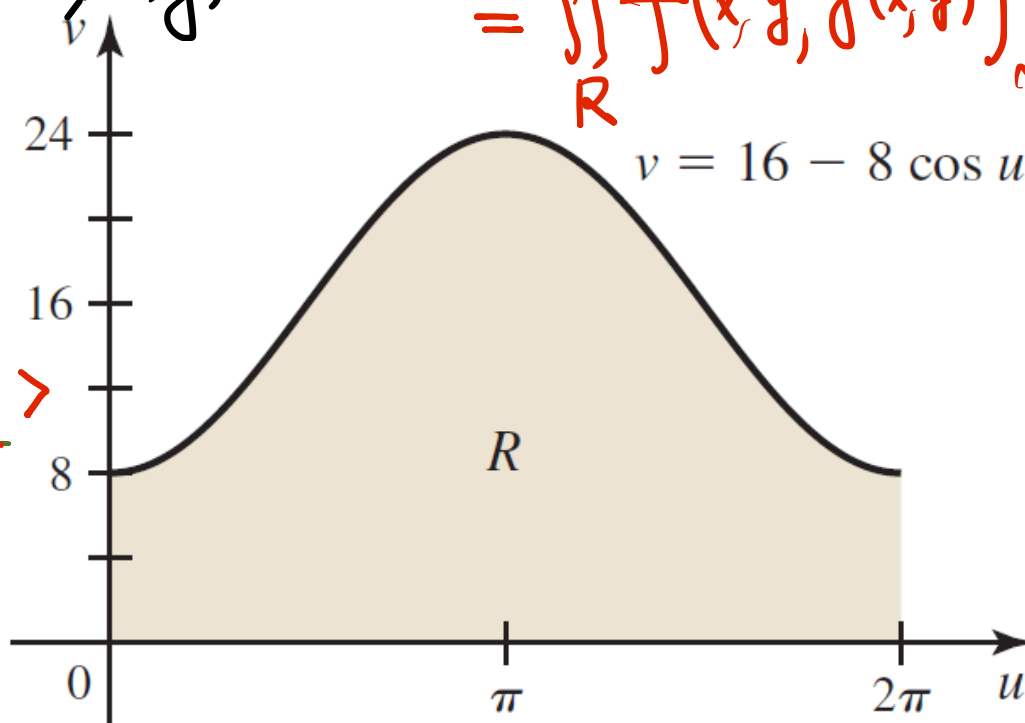
$$\vec{t}_y = \frac{\partial \vec{r}}{\partial y} = \langle 0, 1, g_y \rangle$$

$$\vec{t}_x \times \vec{t}_y = \langle -g_x, -g_y, 1 \rangle$$

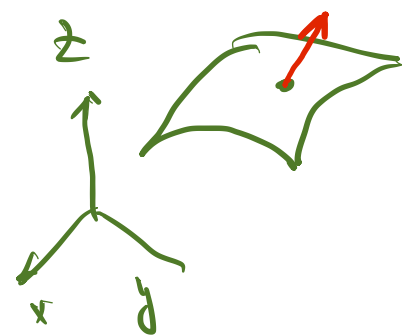
$$\iint_S f dS = \iint_R f(x, y, g(x, y)) |\vec{t}_x \times \vec{t}_y| dx dy$$

$$= \iint_R f(x, y, g(x, y)) \sqrt{1 + g_x^2 + g_y^2} dx dy$$

$$\sqrt{1 + z_x^2 + z_y^2}$$



Region of integration in the uv -plane is
 $R = \{(u, v): 0 \leq u \leq 2\pi, 0 \leq v \leq 16 - 8 \cos u\}.$



Theorem 17.14 Evaluation of Surface Integrals of Scalar-Valued Functions on Explicitly Defined Surfaces

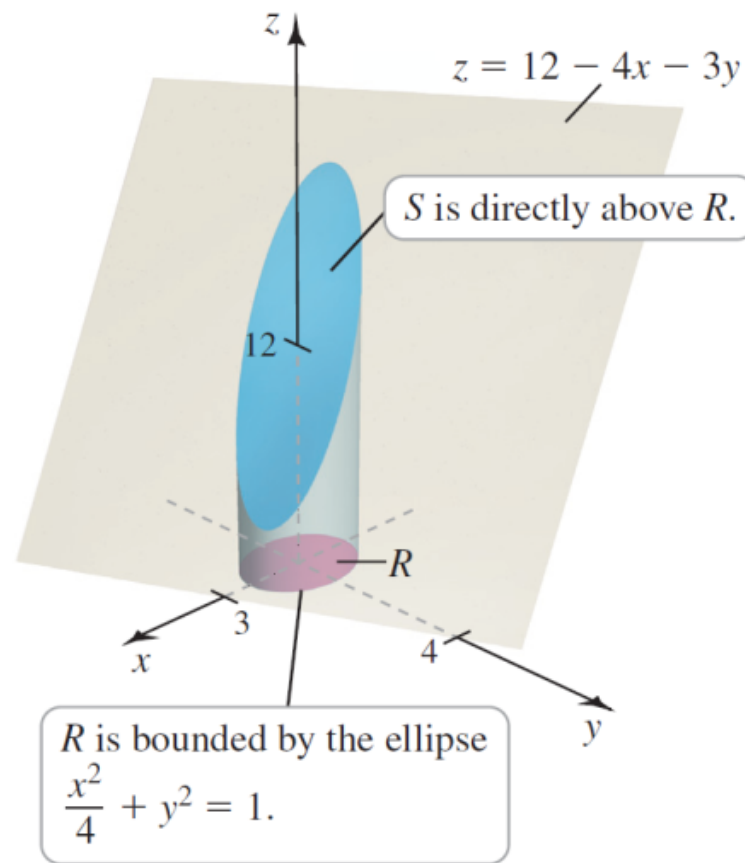
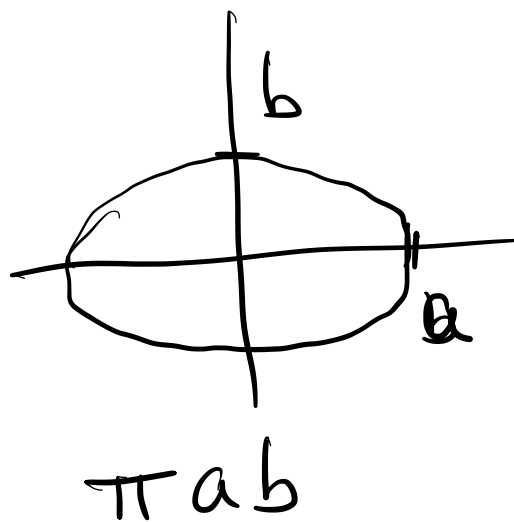
Let f be a continuous function on a smooth surface S given by $z = g(x, y)$, for (x, y) in a region R . The surface integral of f over S is

$$\iint_S f(x, y, z) \, dS = \iint_R f(x, y, g(x, y)) \underbrace{\sqrt{z_x^2 + z_y^2 + 1}}_{dS} \, dA.$$

If $f(x, y, z) = 1$, the surface integral equal the area of the surface.

Example 5 Find the area of the surface S that lies in the plane $z = 12 - 4x - 3y$ directly above the region R bounded by the ellipse $\frac{x^2}{4} + y^2 = 1$.

Figure 17.53 $A(S) = \iint_S 1 dS = \iint_R \sqrt{1 + z_x^2 + z_y^2} dx dy$



R is bounded by the ellipse $\frac{x^2}{4} + y^2 = 1$.

Area of $S = \sqrt{26} \cdot \text{area of } R$.

$$\begin{aligned}
 &= \iint_R \sqrt{1 + (-4)^2 + (-3)^2} dx dy \\
 &= \sqrt{26} \iint_R dx dy \\
 &= \sqrt{26} A(R) \\
 &= \sqrt{26} \pi \cdot 2 \cdot 1
 \end{aligned}$$

Example 6 A thin conical sheet is described by the surface $z = (x^2 + y^2)^{1/2}$, for $0 \leq z \leq 4$. The density is $\rho(x, y, z) = 8 - z$ g/cm³. What is the mass of the cone?

Figure 17.54

$$m = \iint_S (8 - z) dS = \iint_R (8 - (x^2 + y^2)^{1/2}) \sqrt{1 + z_x^2 + z_y^2} dx dy$$

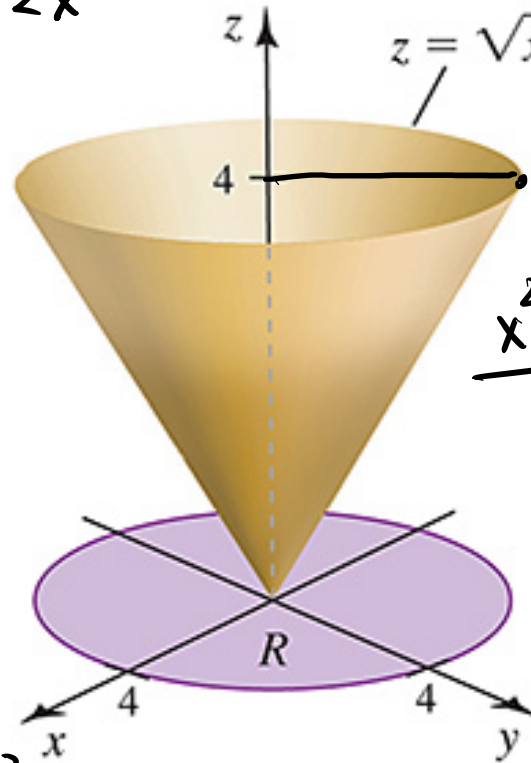
$$\frac{\partial z}{\partial x} = \frac{\partial}{\partial x} (x^2 + y^2)^{1/2} = \frac{1}{2} (x^2 + y^2)^{-1/2} \cdot 2x$$

$$= \frac{x}{\sqrt{x^2 + y^2}}$$

$$\left(\frac{\partial z}{\partial x}\right)^2 = \frac{x^2}{x^2 + y^2}$$

$$\left(\frac{\partial z}{\partial y}\right)^2 = \frac{y^2}{x^2 + y^2}$$

$$1 + z_x^2 + z_y^2 = 1 + \frac{x^2 + y^2}{x^2 + y^2} = 2$$



Density function of sheet is $\rho = 8 - z$.

$$= \sqrt{2} \iint_R (8 - (x^2 + y^2)^{1/2}) dx dy$$

$$= \sqrt{2} \int_0^{2\pi} \int_0^4 (8 - r) r dr d\theta$$

$$= \sqrt{2} \cdot 2\pi \int_0^4 (8r - r^2) dr$$

$$= 2\sqrt{2} \pi \left[4r^2 - \frac{1}{3} r^3 \right]_0^4$$

Table 17.3

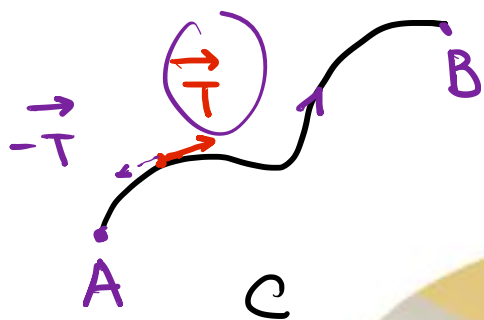
Explicit Description $z=g(x, y)$			Parametric Description	
Surface	Equation	Normal Vector; magnitude $\pm \langle -z_x, -z_y, 1 \rangle; \langle -z_x, -z_y, 1 \rangle $	Equation	Normal Vector; magnitude $t_u \times t_v; t_u \times t_v $
Cylinder	$x^2 + y^2 = a^2,$ $0 \leq z \leq h$	$\langle x, y, 0 \rangle; a$	$\mathbf{r} = \langle a \cos u, a \sin u, v \rangle,$ $0 \leq u \leq 2\pi, 0 \leq v \leq h$ $u=0, v=z$	$\langle a \cos u, a \sin u, 0 \rangle; a$ $u=0, v$
Cone	$z^2 = x^2 + y^2,$ $0 \leq z \leq h$	$\langle x/z, y/z, -1 \rangle; \sqrt{2}$	$\mathbf{r} = \langle v \cos u, v \sin u, v \rangle,$ $0 \leq u \leq 2\pi, 0 \leq v \leq h$	$\langle v \cos u, v \sin u, -v \rangle; \sqrt{2}v$
Sphere	$x^2 + y^2 + z^2 = a^2$ $z = \sqrt{a^2 - x^2 - y^2}$	$\vec{r}(x, y) = \langle x, y, \sqrt{a^2 - x^2 - y^2} \rangle$ $\langle x/z, y/z, 1 \rangle \cdot a/z$ $\vec{t}_x \times \vec{t}_y = \langle -z_x, -z_y, 1 \rangle$	$\mathbf{r} = \langle a \sin u \cos v, a \sin u \sin v, a \cos u \rangle,$ $0 \leq u \leq \pi, 0 \leq v \leq 2\pi$	$\langle a^2 \sin^2 u \cos v, a^2 \sin^2 u \sin v, a^2 \sin u \cos u \rangle; a^2 \sin u$ $\vec{t}_u \times \vec{t}_v$
Paraboloid	$z = x^2 + y^2,$ $0 \leq z \leq h$	$\langle 2x, 2y, -1 \rangle; \sqrt{1 + 4(x^2 + y^2)}$	$\mathbf{r} = \langle v \cos u, v \sin u, v^2 \rangle,$ $0 \leq u \leq 2\pi, 0 \leq v \leq \sqrt{h}$	$\langle 2v^2 \cos u, 2v^2 \sin u, -v \rangle; v\sqrt{1 + 4v^2}$

$$C: \vec{r}(t) = \langle x(t), y(t), z(t) \rangle \text{ for } a \leq t \leq b$$

$$\int_C f ds = \int_a^b f(\vec{r}(t)) \underbrace{|\vec{r}'(t)|}_{ds} dt$$

Figure 17.55

$$\int_C \vec{F} \cdot d\vec{r} = \int_C (\vec{F} \cdot \vec{T}) ds$$



$$\vec{F} = \langle f, g, h \rangle$$

$$\iint_S \vec{F} \cdot d\vec{S} = \iint_S (\vec{F} \cdot \vec{n}) dS$$

$$S: \vec{r}(u, v) = \langle x(u, v), y(u, v), z(u, v) \rangle, (u, v) \in R$$

$$\iint_S f dS = \iint_R f(\vec{r}(u, v)) \underbrace{|\vec{t}_u \times \vec{t}_v|}_{dS} du dv$$

$$S: z = g(x, y), (x, y) \in R$$

$$\iint_R f(x, y, g(x, y)) \sqrt{1 + (z_x)^2 + (z_y)^2} dx dy$$

$$\vec{t}_x \times \vec{t}_y = \langle -z_x, -z_y, 1 \rangle$$

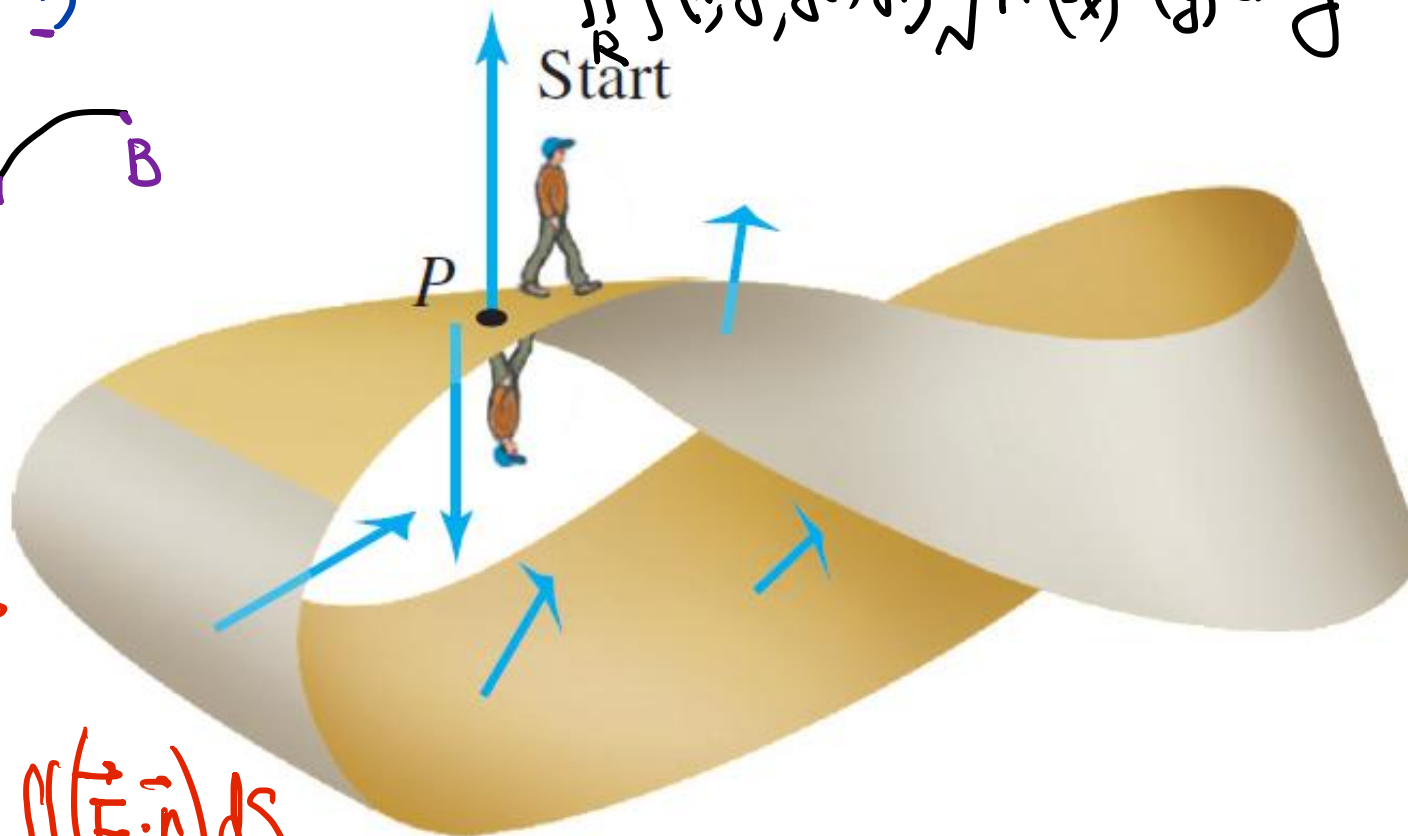
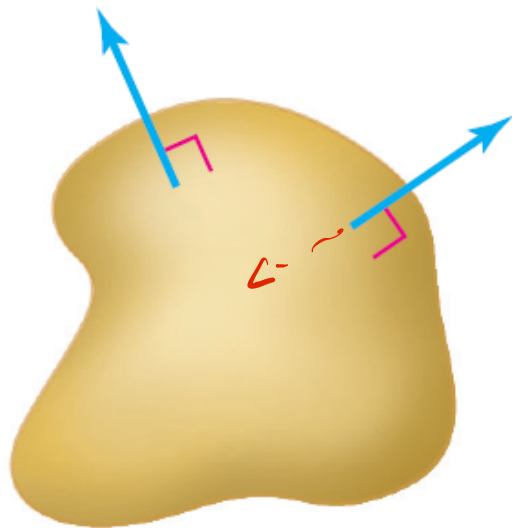
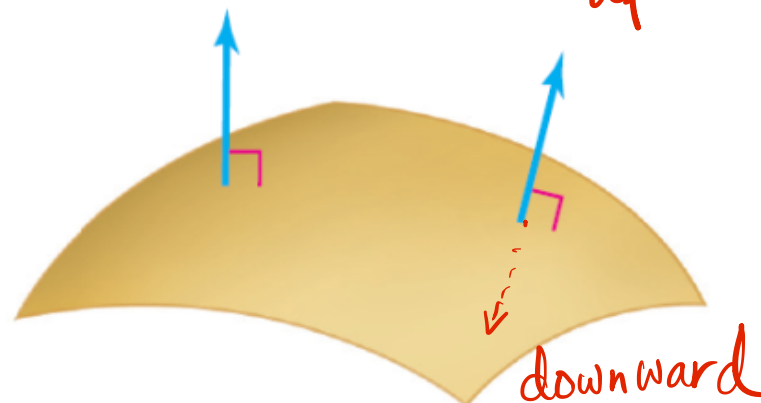
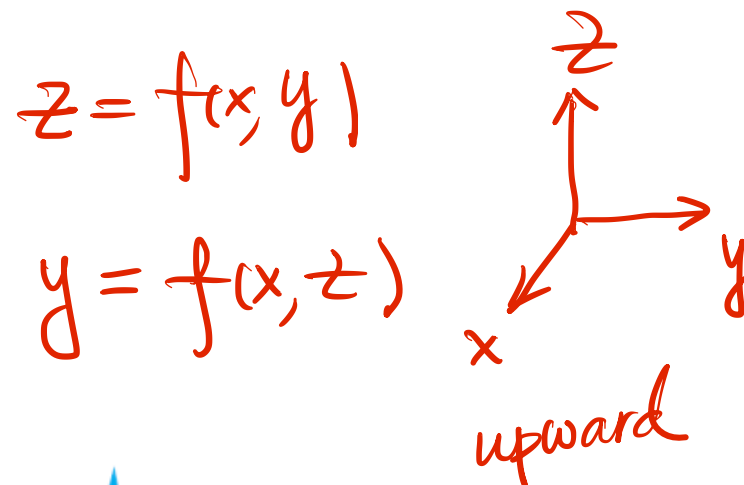


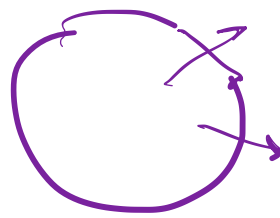
Figure 17.56



Surfaces that enclose a region are oriented so normal vectors point in the outward direction.



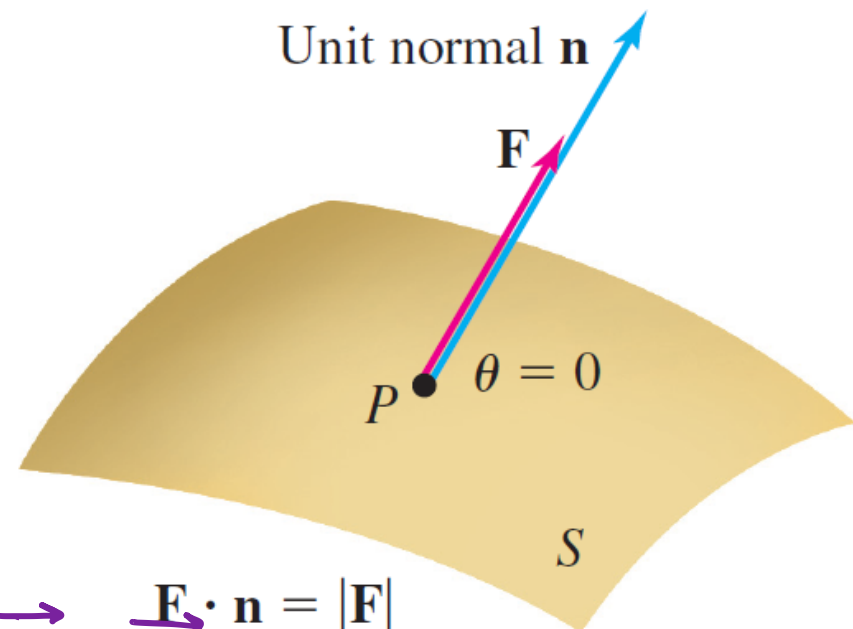
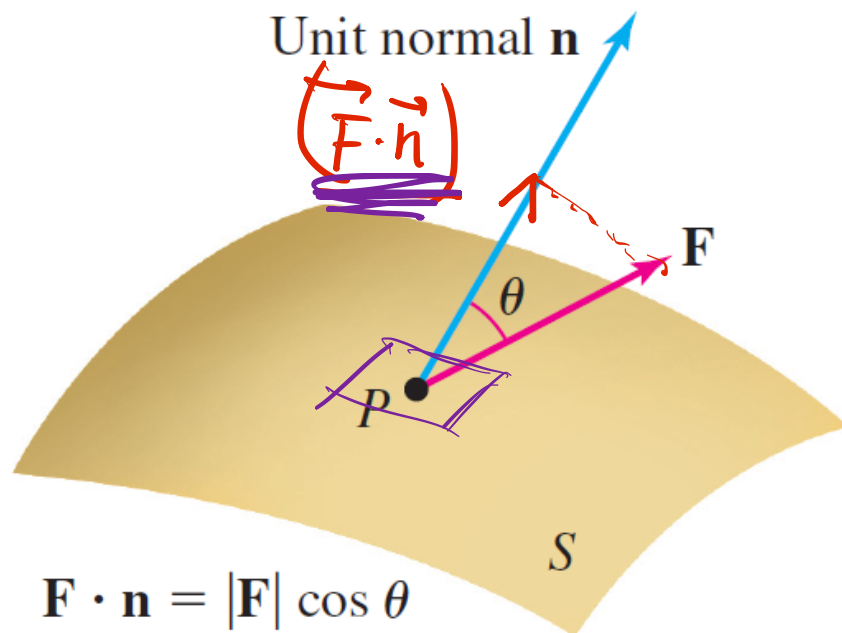
For other surfaces, the orientation of the surface must be specified.



$$\int_C (\vec{F} \cdot \vec{T}) ds \text{ in } \mathbb{R}^d \text{ } \underline{d=2,3}$$

$$\int_C (\vec{F} \cdot \vec{n}) ds$$

Figure 17.57 (a & b)

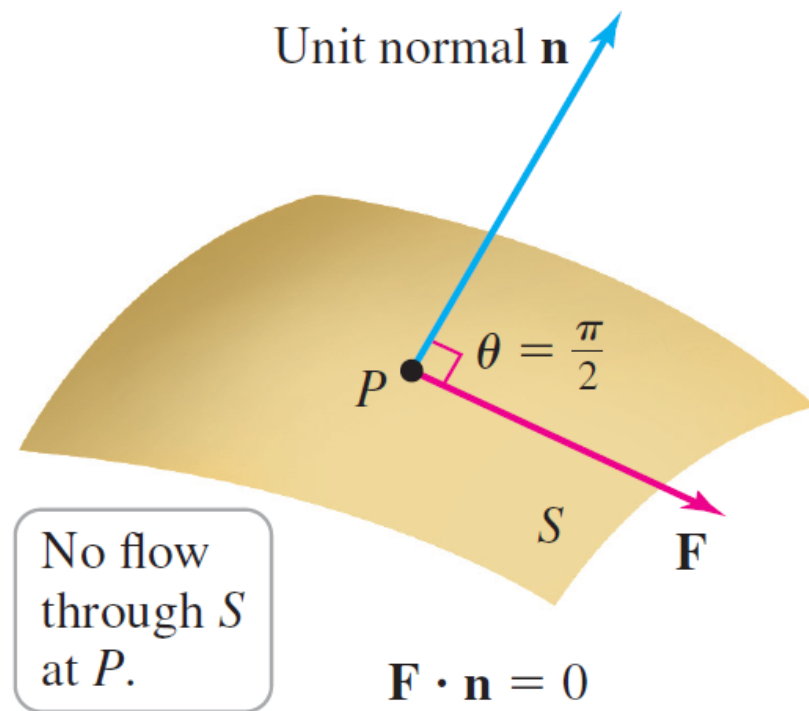
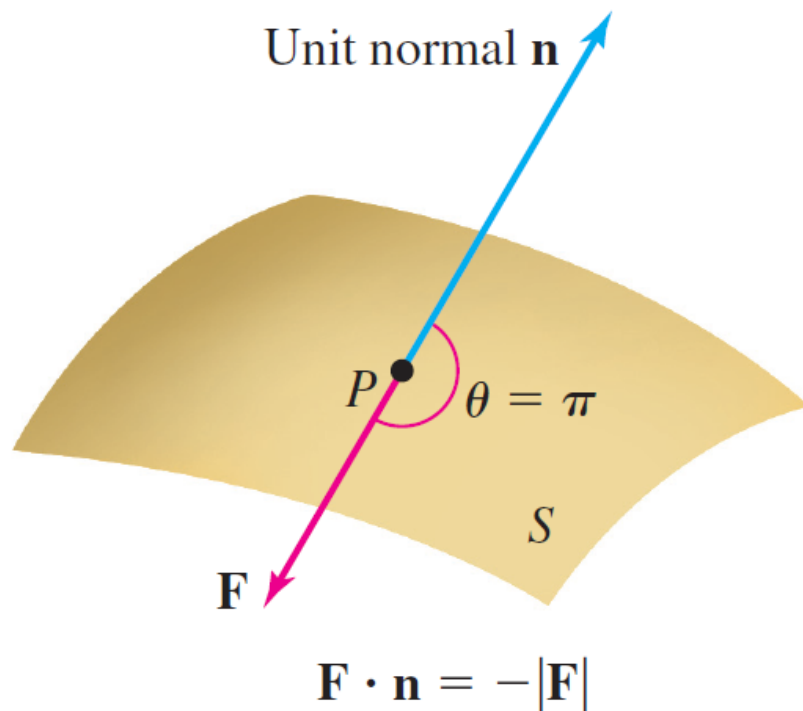


$$\iint_S (\vec{F} \cdot \vec{n}) dS = \iint_R \vec{F}(\vec{r}(u,v)) \cdot \frac{\vec{t}_u \times \vec{t}_v}{|\vec{t}_u \times \vec{t}_v|} du dv$$

~~$|\vec{t}_u \times \vec{t}_v|$~~

$$= \iint_R \vec{F}(\vec{r}(u,v)) \cdot (\vec{t}_u \times \vec{t}_v) du dv$$

Figure 17.57 (c & d)



Definition Surface Integral of a Vector Field

Suppose $\mathbf{F} = \langle f, g, h \rangle$ is a continuous vector field on a region of $\mathbb{R}^3$ containing a smooth oriented surface S . If S is defined parametrically as

$S: \mathbf{r}(u, v) = \langle x(u, v), y(u, v), z(u, v) \rangle$, for (u, v) in a region R , then

$$\iint_S \mathbf{F} \cdot \mathbf{n} \, dS = \iint_R \mathbf{F} \cdot (\mathbf{t}_u \times \mathbf{t}_v) \, dA,$$

where $\mathbf{t}_u = \frac{\partial \mathbf{r}}{\partial u} = \left\langle \frac{\partial x}{\partial u}, \frac{\partial y}{\partial u}, \frac{\partial z}{\partial u} \right\rangle$ and $\mathbf{t}_v = \frac{\partial \mathbf{r}}{\partial v} = \left\langle \frac{\partial x}{\partial v}, \frac{\partial y}{\partial v}, \frac{\partial z}{\partial v} \right\rangle$ are continuous on R ,

the normal vector $\mathbf{t}_u \times \mathbf{t}_v$ is nonzero on R , and the direction of the normal

vector is consistent with the orientation of S . If S is defined in the form

$S: z = s(x, y)$, for (x, y) in a region R , then $\langle f, g, h \rangle \cdot \langle -z_x, -z_y, 1 \rangle \, dA$

$$\iint_S \mathbf{F} \cdot \mathbf{n} \, dS = \iint_R (-fz_x - gz_y + h) \, dA.$$

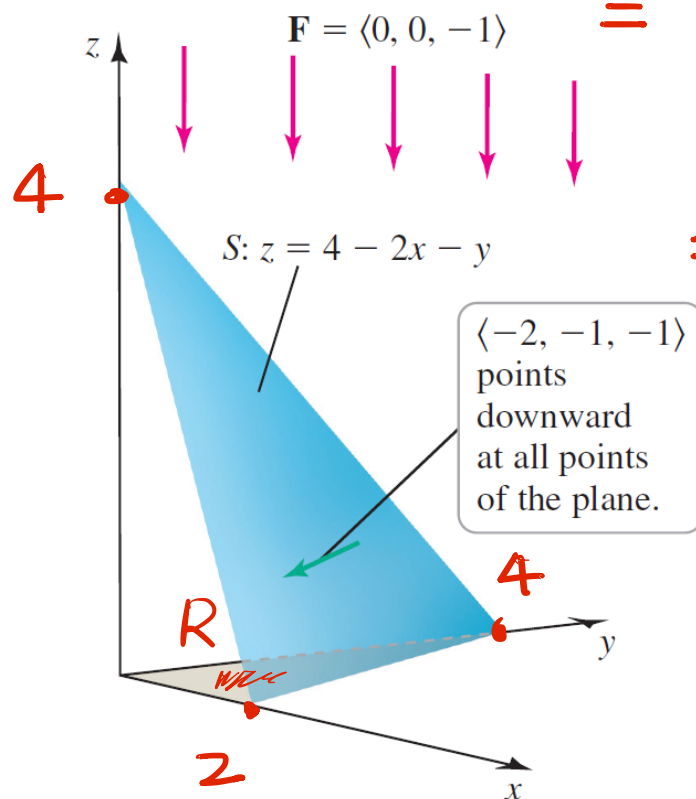
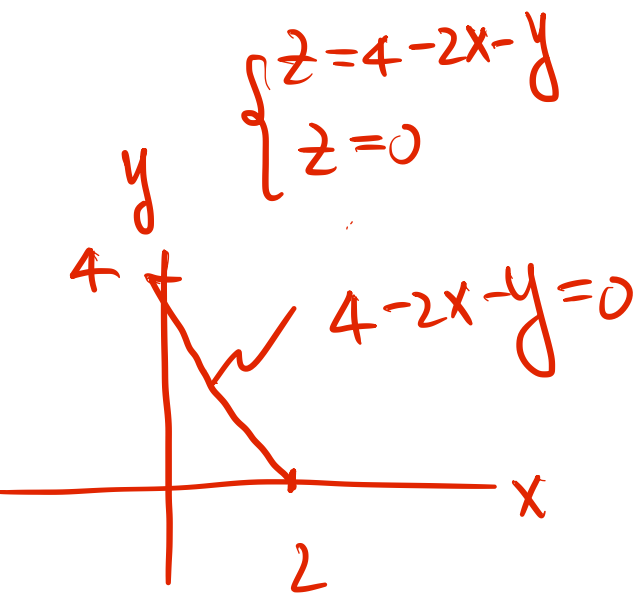
$\vec{r}(x, y) = \langle x, y, s(x, y) \rangle$
 $\vec{r}_x \times \vec{r}_y = \langle -s_x, -s_y, 1 \rangle$ upward



Example 7 $\vec{F} = \langle 0, 0, -1 \rangle$, $S: z = 4 - 2x - y$ in the 1st octant.
Find the flux in the downward direction across the surface S .

Figure 17.58

$$\begin{aligned} \iint_S \vec{F} \cdot \vec{n} \, dS &= - \iint_R (0 + 0 + (-1)) \, dx \, dy \\ &= \iint_R 1 \, dx \, dy = \text{area}(R) \\ &= \frac{1}{2} \cdot 2 \cdot 4 = 4 \end{aligned}$$



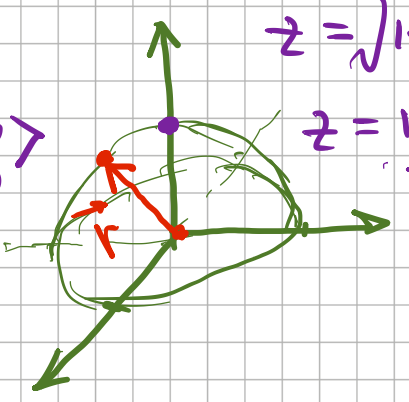
$\langle -2, -1, -1 \rangle$
points
downward
at all points
of the plane.

$$\iint_S \vec{F} \cdot \vec{n} \, dS = \text{area of } R = 4$$

Example 7 $\vec{F} = \langle x, y, z \rangle$. Is the upward flux of $\vec{F}$ greater across the hemisphere $x^2 + y^2 + z^2 = 1$, for $z \geq 0$, or across the paraboloid $z = 1 - x^2 - y^2$, for $z \geq 0$?

(a) $\iint_{S_1} (\vec{F} \cdot \vec{n}) dS$ $\vec{r}(\varphi, \theta) = \langle x, y, z \rangle$
 $= \langle \sin \varphi \cos \theta, \sin \varphi \sin \theta, \cos \varphi \rangle$
 $0 \leq \varphi \leq \frac{\pi}{2}$
 $0 \leq \theta \leq 2\pi$

$z = \sqrt{1 - x^2 - y^2}$
 $z = 1 - x^2 - y^2$



$= \iint_R \langle x, y, z \rangle \cdot \langle x, y, z \rangle \sin \varphi dA$
 $= \iint_R (x^2 + y^2 + z^2) \sin \varphi dA$
 $\vec{r}_\varphi \times \vec{r}_\theta = \sin \varphi \vec{r} = \sin \varphi \langle x, y, z \rangle$
 $= \iint_R \sin \varphi dA = \int_0^{\frac{\pi}{2}} d\varphi \int_0^{2\pi} d\theta \sin \varphi = 2\pi \int_0^{\frac{\pi}{2}} \sin \varphi d\varphi = 2\pi \left[-\cos \varphi \right]_0^{\frac{\pi}{2}} = 2\pi$

(b) $\iint_{S_2} \vec{F} \cdot \vec{n} dS = \iint_R \langle x, y, z \rangle \cdot \langle -z_x, -z_y, 1 \rangle dx dy$
 $= \iint_R \langle x, y, 1 - x^2 - y^2 \rangle \cdot \langle 2x, 2y, 1 \rangle dx dy$
 $= \iint_R (2x^2 + 2y^2 + 1 - x^2 - y^2) dx dy = \iint_R (1 + x^2 + y^2) dx dy$
 $= \int_0^{2\pi} \int_0^1 (1 + r^2) r dr d\theta$
 $= 2\pi \left[\frac{1}{2} r^2 + \frac{1}{4} r^4 \right]_0^1 = 2\pi \left[\frac{1}{2} + \frac{1}{4} \right] = 2\pi \cdot \frac{3}{4} < 2\pi$

$R: x^2 + y^2 \leq 1$

Example 8 (#53) S is the cylinder $x^2 + z^2 = a^2$, $|y| \leq 2$, outward

$$\iint_S \frac{\langle x, 0, z \rangle}{\sqrt{x^2 + z^2}} \cdot \vec{n} \, dS$$
$$= \iint_R \frac{\langle x, 0, z \rangle}{\sqrt{x^2 + z^2}} \cdot \langle x, 0, z \rangle \frac{dA}{\| \frac{d\vec{r}}{dy} \|}$$

$$= \iint_R \frac{x^2 + z^2}{\sqrt{x^2 + z^2}} dA$$

$$= \iint_R \sqrt{x^2 + z^2} dA = a \iint_R dA$$

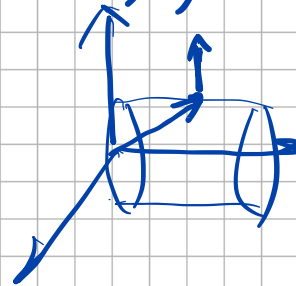
$$= a \cdot 2\pi \cdot 4$$

$$\vec{r}(\theta, y) = \langle a \cos \theta, y, a \sin \theta \rangle$$
$$= \langle x, y, z \rangle$$

$$R: \begin{cases} 0 \leq \theta \leq 2\pi \\ -2 \leq y \leq 2 \end{cases}$$

$$2\pi \cdot 4$$

$$\vec{r}_\theta \times \vec{r}_y = \langle a \cos \theta, 0, a \sin \theta \rangle$$
$$= \langle x, 0, z \rangle$$



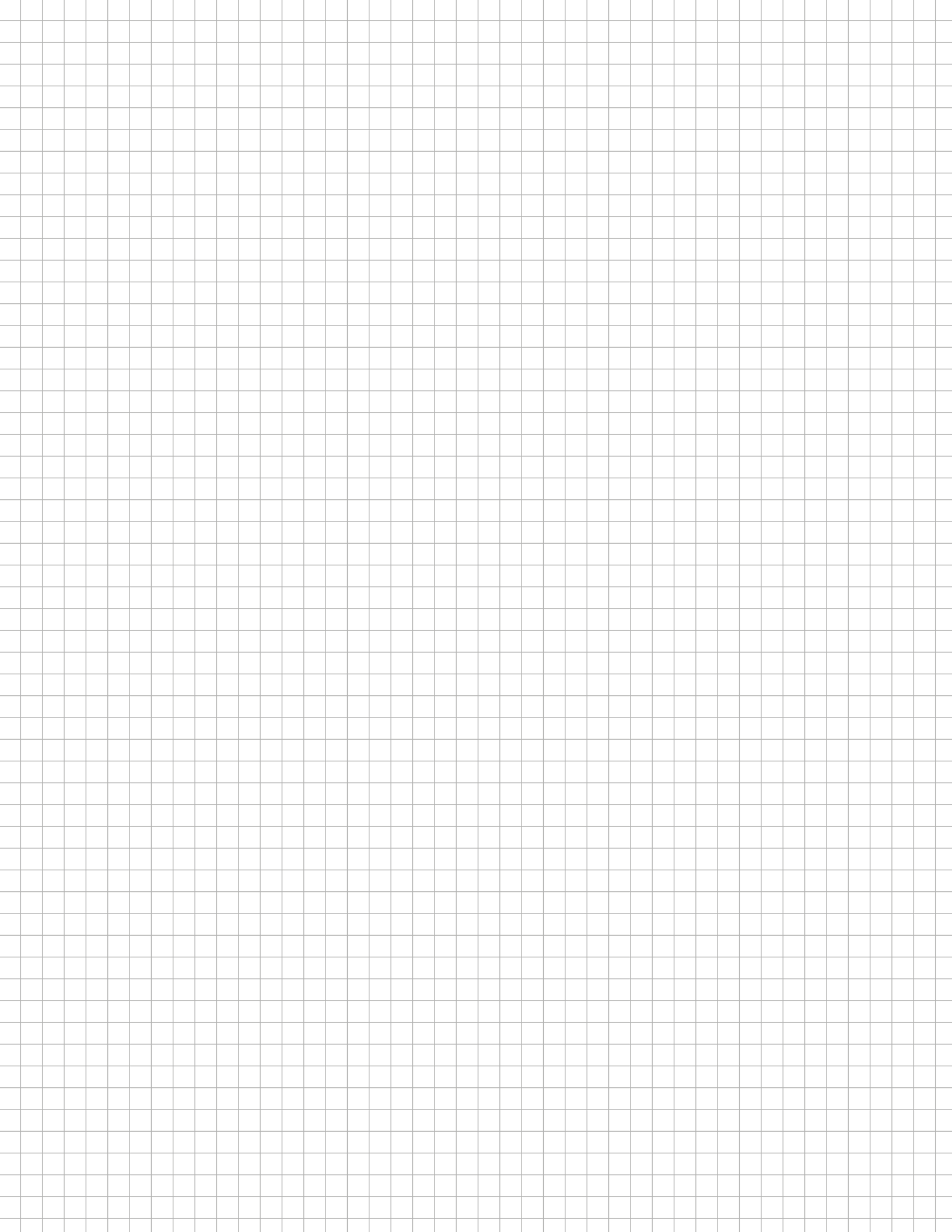
#65 $\vec{F} = \frac{\langle x, y, z \rangle}{(x^2 + y^2 + z^2)^{p/2}} = \frac{\vec{r}}{|\vec{r}|^p}$

S consist of the spheres A and B centered at the origin with radii $0 < a < b$, resp.

The total outward flux across S consists of the flux out of S across the outer sphere B minus the flux into S across the inner sphere A .

(a) Find the total flux across S with $p=0$.

(b) Show that for $p=3$, the flux across S is independent of a and b .



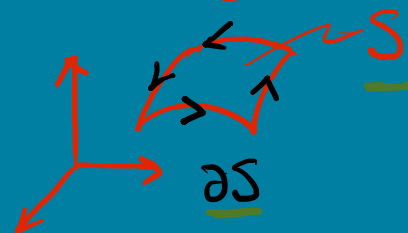
$$\underline{\vec{F}(x,y)} = \langle f(x,y), g(x,y) \rangle$$

$$\underline{\nabla \times \vec{F}} = \langle 0, 0, g_x - f_y \rangle$$



$$\underline{\vec{F}(x,y,z)} = \langle f(x,y,z), g(x,y,z), h(x,y,z) \rangle$$

$$\underline{\nabla \times \vec{F}} = \langle h_y - g_z, f_z - h_x, g_x - f_y \rangle$$



Section 17.7 Stokes' Theorem

Green's Theorem

$$\iint_{\underline{R}} \underline{\nabla \times \vec{F}} \cdot \vec{k} \, dA = \int_{\partial R} \underline{\vec{F}} \cdot d\vec{r}$$



$$\iint_{\underline{S}} \underline{\nabla \times \vec{F}} \cdot \vec{n} \, dS = \oint_{\partial S} \underline{\vec{F}} \cdot d\vec{r}$$

$$\int_{\underline{C}} \underline{\nabla \phi} \cdot d\vec{r} = \underline{\phi(B)} - \underline{\phi(A)}$$

Figure 17.59

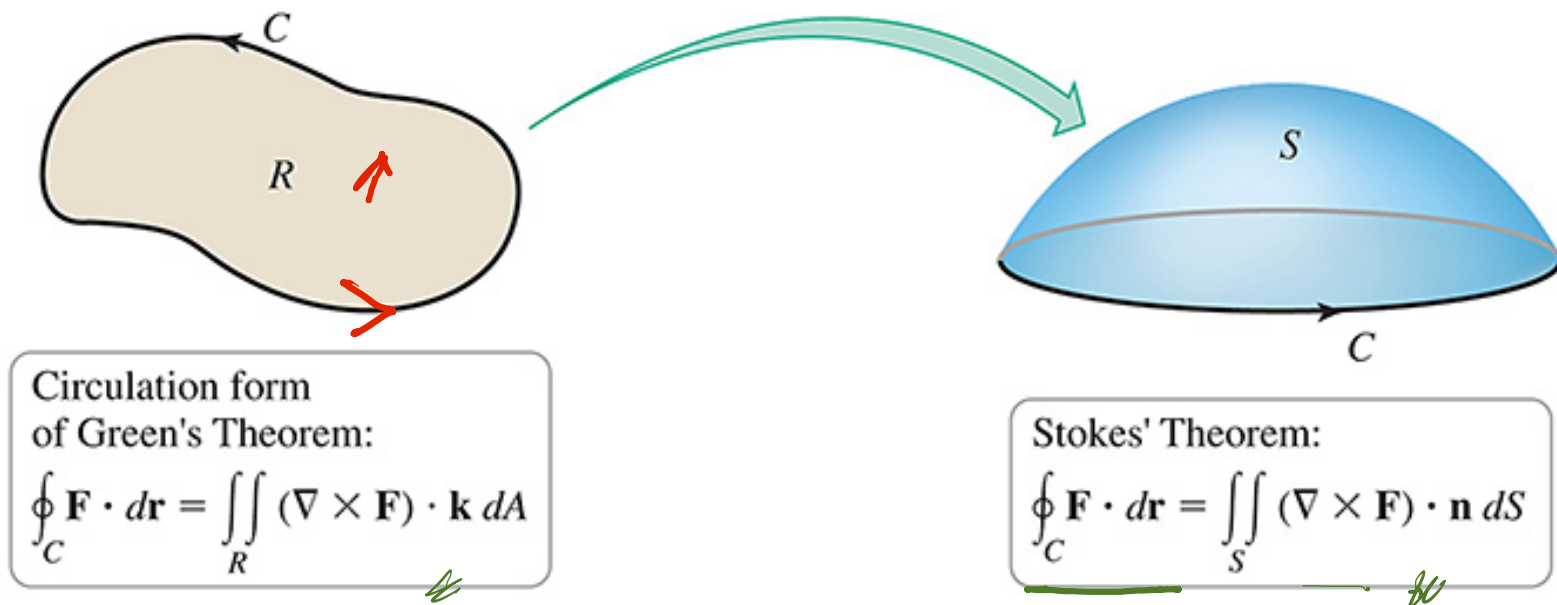
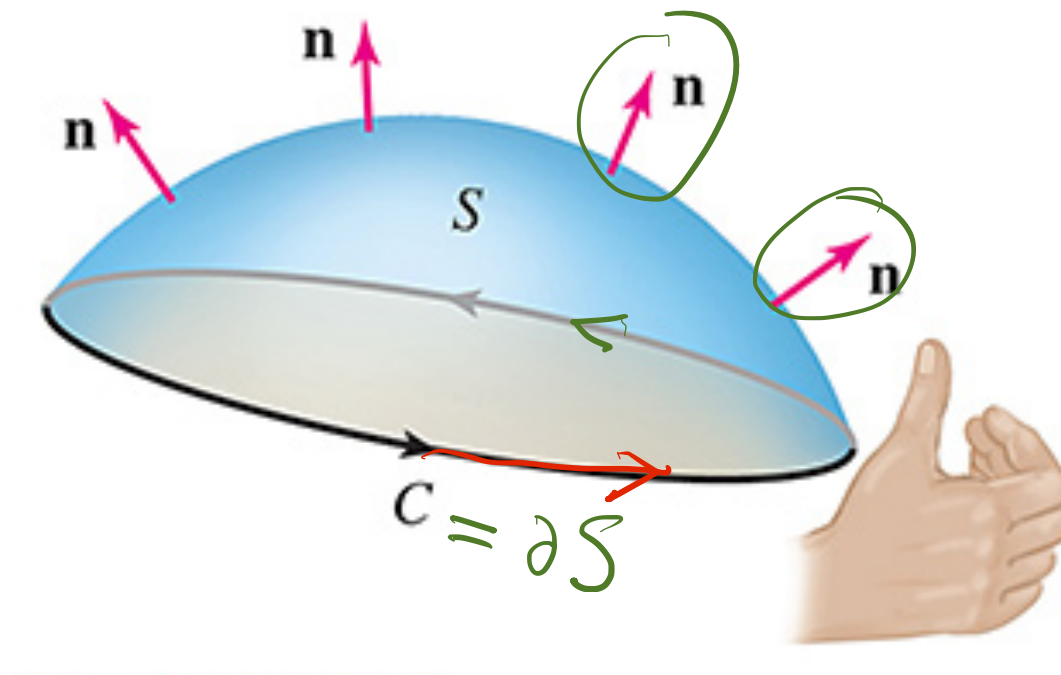


Figure 17.60



Theorem 17.15 Stokes' Theorem

Let S be an oriented surface in $\mathbb{R}^3$ with a piecewise-smooth closed boundary C whose orientation is consistent with that of S . Assume $\mathbf{F} = \langle f, g, h \rangle$ is a vector field whose components have continuous first partial derivatives on S . Then

$$\int_C \mathbf{F} \cdot d\mathbf{r} = \iint_S (\nabla \times \mathbf{F}) \cdot \mathbf{n} \, dS,$$

$$= \iint_R \left(\mathbf{F} \cdot \vec{t}_u \times \vec{t}_v \right) du dv$$

$S: \vec{r}(u, v)$

where $\mathbf{n}$ is the unit vector normal to S determined by the orientation of S .

Example 1 $\vec{F} = \langle z - y, x, -x \rangle$, $S: x^2 + y^2 + z^2 = 4$ for $z \geq 0$

Confirm the Stokes Theorem.

Figure 17.61

LHS = $\iint_R \nabla \times \vec{F} \cdot \left\langle \frac{x}{z}, \frac{y}{z}, 1 \right\rangle dx dy$

$= \iint_R 2 \langle 0, 1, 1 \rangle \cdot \left\langle \frac{x}{z}, \frac{y}{z}, 1 \right\rangle dx dy$

$= 2 \iint_R \left(\frac{y}{\sqrt{4 - x^2 - y^2}} + 1 \right) dx dy$

$= 2 \int_0^2 \int_0^{2\pi} \left(\frac{r \sin \theta}{\sqrt{4 - r^2}} + 1 \right) d\theta r dr$

$= 2 \int_0^2 r \left[\frac{r}{\sqrt{4 - r^2}} (-\cos \theta) \right]_0^{2\pi} + 2\pi \Big| dr$

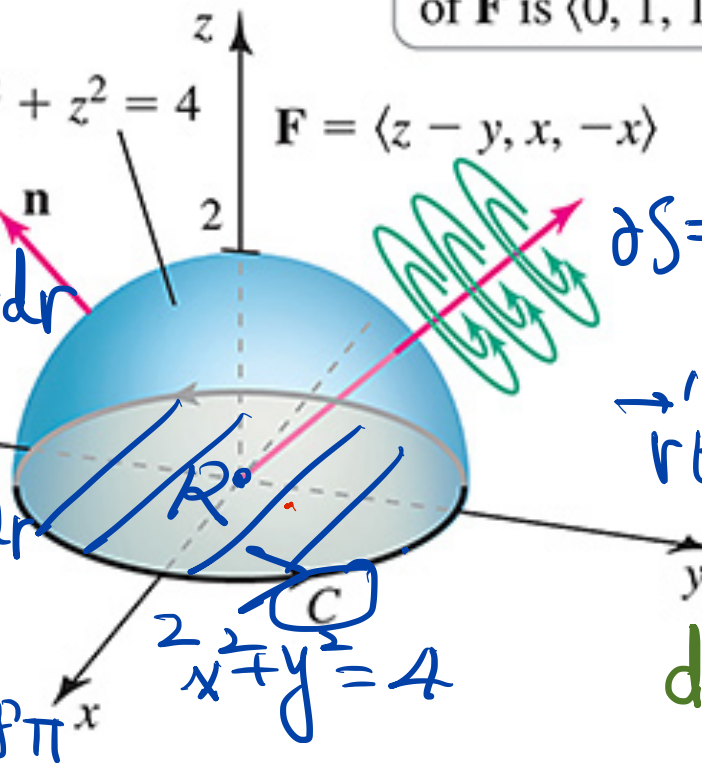
$= 2 \int_0^2 2\pi r dr = 2\pi r^2 \Big|_0^2 = 8\pi$

$\iint_S \nabla \times \vec{F} \cdot \vec{n} dS = \oint_{\partial S} \vec{F} \cdot d\vec{r} = \int_0^{2\pi} \langle -2 \sin t, 2 \cos t, -2 \cos t \rangle \cdot \langle -2 \sin t, 2 \cos t, 0 \rangle dt$

$\vec{F} = \langle 0, 1, 1 \rangle \times \langle x, y, z \rangle$

$\nabla \times \vec{F} = 2\vec{a}$

Axis of rotation of $\vec{F}$ is $\langle 0, 1, 1 \rangle$.



$\partial S = C: \vec{r}(t) = \langle 2 \cos t, 2 \sin t, 0 \rangle$
 $0 \leq t \leq 2\pi$

$\vec{r}'(t) = \langle -2 \sin t, 2 \cos t, 0 \rangle$

$dA = dx dy = r dr d\theta$

Example 2 $\vec{F} = \langle z, -z, x^2 - y^2 \rangle$, C : three segments

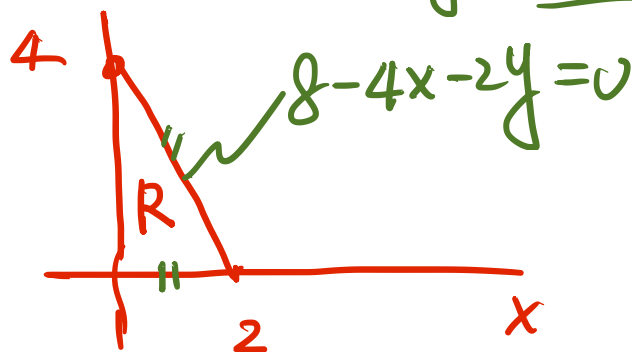
$$\oint_C \vec{F} \cdot d\vec{r} = \iint_S \nabla \times \vec{F} \cdot \vec{n} \, dS = \iint_R \nabla \times \vec{F} \cdot (\vec{t}_x \times \vec{t}_y) \, dx \, dy$$

Figure 17.62

$$S: \vec{r}(x, y) = \langle x, y, 8 - 4x - 2y \rangle$$

$$(x, y) \in R$$

$$\vec{t}_x \times \vec{t}_y = \langle -z_x, -z_y, 1 \rangle$$

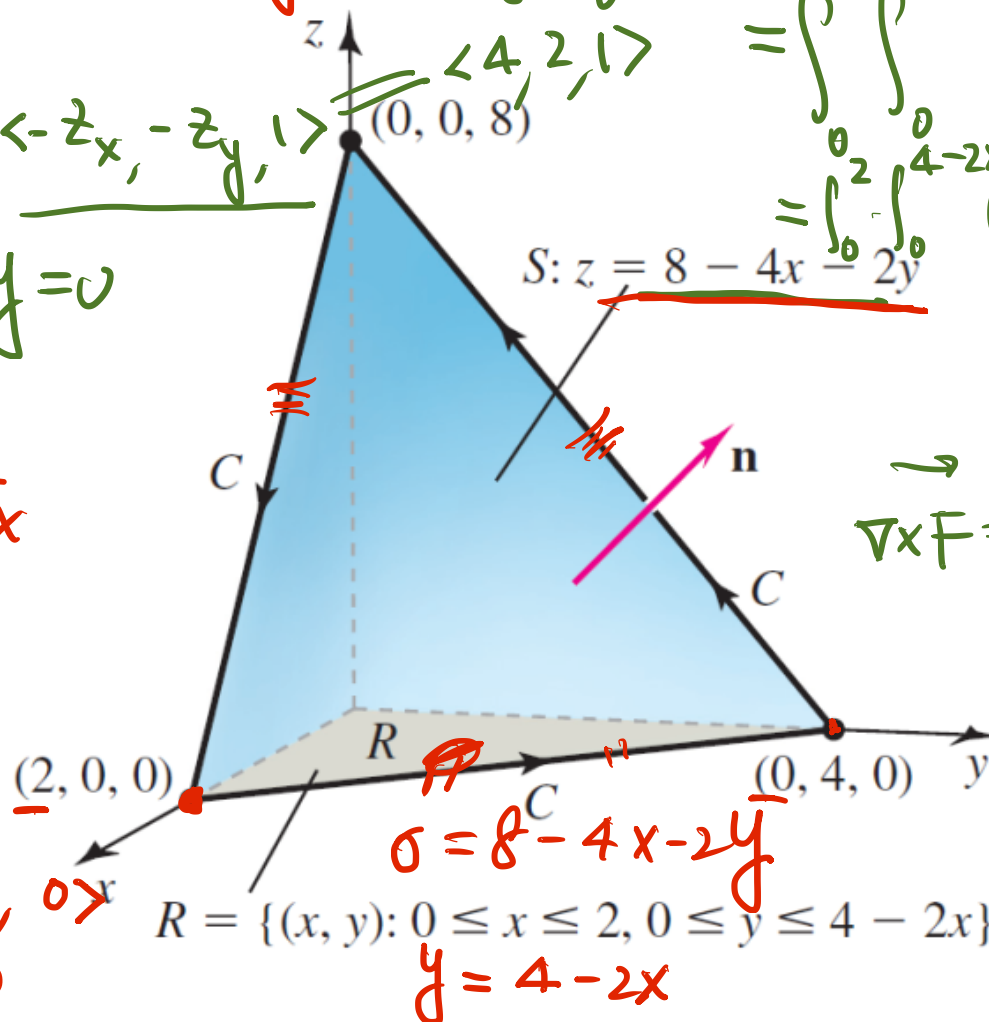


$$R: 0 \leq x \leq 2$$

$$0 \leq y \leq 4 - 2x$$

$$C_1: \vec{r}(x) = \langle x, 4 - 2x, 0 \rangle$$

$$x: 2 \rightarrow 0$$



$$\sigma = 8 - 4x - 2y$$

$$R = \{(x, y): 0 \leq x \leq 2, 0 \leq y \leq 4 - 2x\}$$

$$y = 4 - 2x$$

$$= \int_0^2 \int_0^{4-2x} \langle 1-2y, 1-2x, 0 \rangle \cdot \langle 4, 2, 1 \rangle \, dx \, dy$$

$$= \int_0^2 \int_0^{4-2x} [4(1-2y) + 2(1-2x)] \, dy \, dx$$

$$\nabla \times \vec{F} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \partial_x & \partial_y & \partial_z \\ z & -z & x^2 - y^2 \end{vmatrix} = \langle -2y+1, 1-2x, 0 \rangle$$

Example 3 $\vec{F} = \langle -y, x, z \rangle$, evaluate $\iint \nabla \times \vec{F} \cdot \vec{n} \, dS$, $\vec{n}$ — upward
 (a) S is the part of the paraboloid $z = 4 - x^2 - 3y^2$ that lies within the paraboloid $z = 3x^2 + y^2$

Figure 17.63

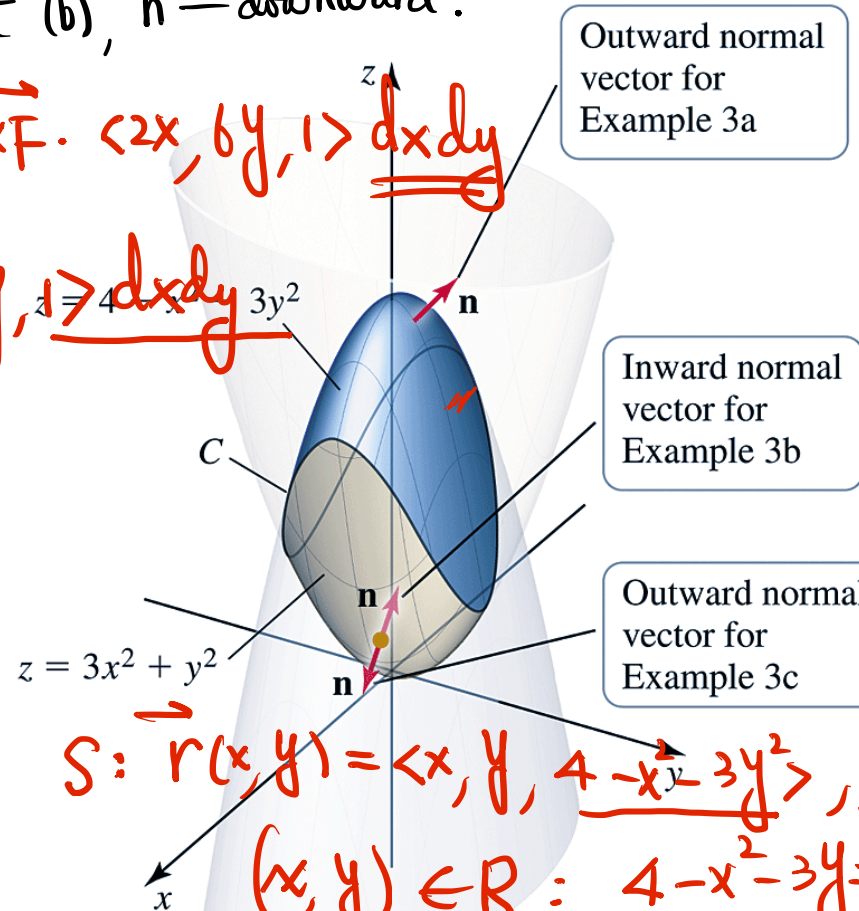
(b) S is the part of $z = 3x^2 + y^2$ that lies $z = 4 - x^2 - 3y^2$, $\vec{n}$ — upward

(c) S is the surface in part (b), $\vec{n}$ — downward.

$$\begin{aligned} \text{(a)} \quad \iint_S \nabla \times \vec{F} \cdot \vec{n} \, dS &= \iint_R \nabla \times \vec{F} \cdot \langle 2x, 6y, 1 \rangle \, dx \, dy \\ &= \iint_R \langle 0, 0, 2 \rangle \cdot \langle 2x, 6y, 1 \rangle \, dx \, dy \\ &= 2 \iint_R dx \, dy = 2\pi \end{aligned}$$

$$\nabla \times \vec{F} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \partial_x & \partial_y & \partial_z \\ -y & x & z \end{vmatrix}$$

$$= \langle 0, 0, 1+1 \rangle = \langle 0, 0, 2 \rangle \quad R: x^2 + y^2 \leq 1 \Rightarrow x^2 + y^2 = 1$$



$$S: \vec{r}(x, y) = \langle x, y, 4 - x^2 - 3y^2 \rangle$$

$$(x, y) \in R: 4 - x^2 - 3y^2 = z = 3x^2 + y^2 \Rightarrow x^2 + y^2 = 1$$

$$\iint_{S_1} \nabla \times \vec{F} \cdot \vec{n} \, dS$$

$$= \oint_{\partial S_1} \vec{F} \cdot d\vec{r}$$

$$\oint_{\partial S_2} \vec{F} \cdot d\vec{r}$$

$$\iint_{S_2} \nabla \times \vec{F} \cdot \vec{n} \, dS$$

$$\vec{t}_x \times \vec{t}_y = \langle -z_x, -z_y, 1 \rangle$$

Interpreting the Curl

average
circulation

$$\frac{1}{A(S)} \oint_{\partial S} \vec{F} \cdot d\vec{r}$$

Example

$$\vec{F} = \vec{a} \times \vec{r} \Rightarrow \nabla \times \vec{F} = 2\vec{a}$$

$$\vec{r} = \langle x, y, z \rangle$$

$$\vec{a} = \langle 0, 0, 1 \rangle$$

$$\vec{F} = \langle -y, x, 0 \rangle$$

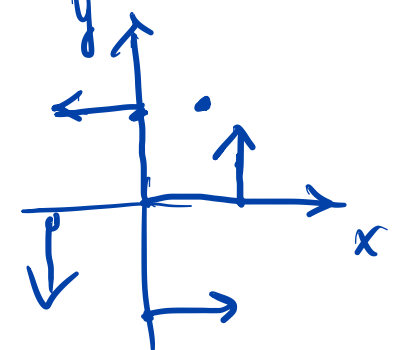


Figure 17.64

$$\frac{1}{A(S)} \oint_{\partial S} \vec{F} \cdot d\vec{r} = \frac{1}{A(S)} \iint_S (\nabla \times \vec{F} \cdot \vec{n}) dS$$

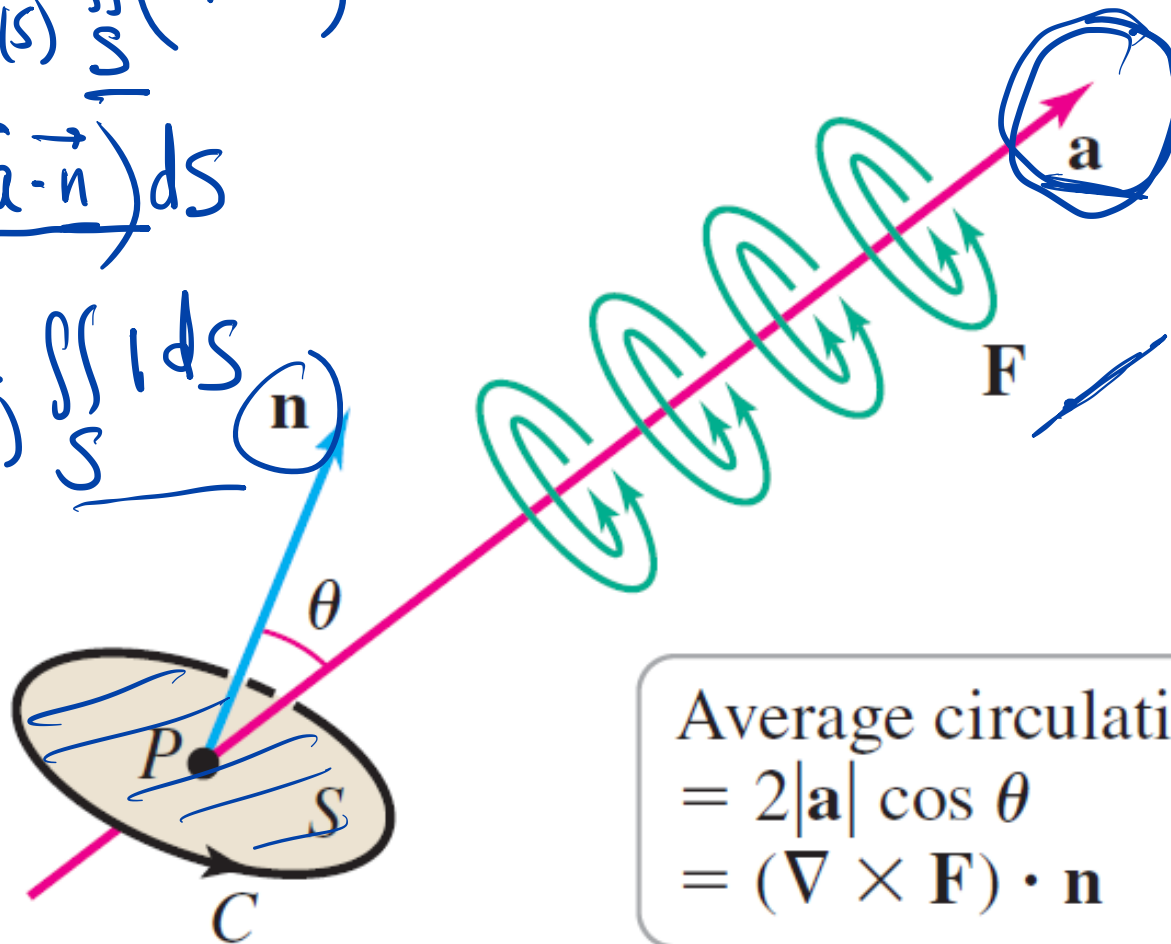
$$= \frac{1}{A(S)} \iint_S (2\vec{a} \cdot \vec{n}) dS$$

$$= 2\vec{a} \cdot \vec{n} \frac{1}{A(S)} \iint_S 1 dS$$

$$= 2\vec{a} \cdot \vec{n}$$

$$= \nabla \times \vec{F} \cdot \vec{n}$$

$$= |\nabla \times \vec{F}| \cos \theta$$



Average circulation

$$= 2|\vec{a}| \cos \theta$$

$$= (\nabla \times \vec{F}) \cdot \vec{n}$$

Example 4 velocity field $\vec{v} = \langle 0, 1 - x^2, 0 \rangle$, for $|x| \leq 1$ and $|z| \leq 1$

- (a) A paddle wheel is placed at $P(\frac{1}{2}, 0, 0)$, in which of the coordinate directions should the axis of the wheel point in order for the wheel to spin? In which direction does it spin? At $Q(-\frac{1}{2}, 0, 0)$?

Figure 17.65 (a & b)

- (b) Compute and graph $\nabla \times \vec{v} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 0 & 1 - x^2 & 0 \end{vmatrix} = \langle 0, 0, -2x \rangle$

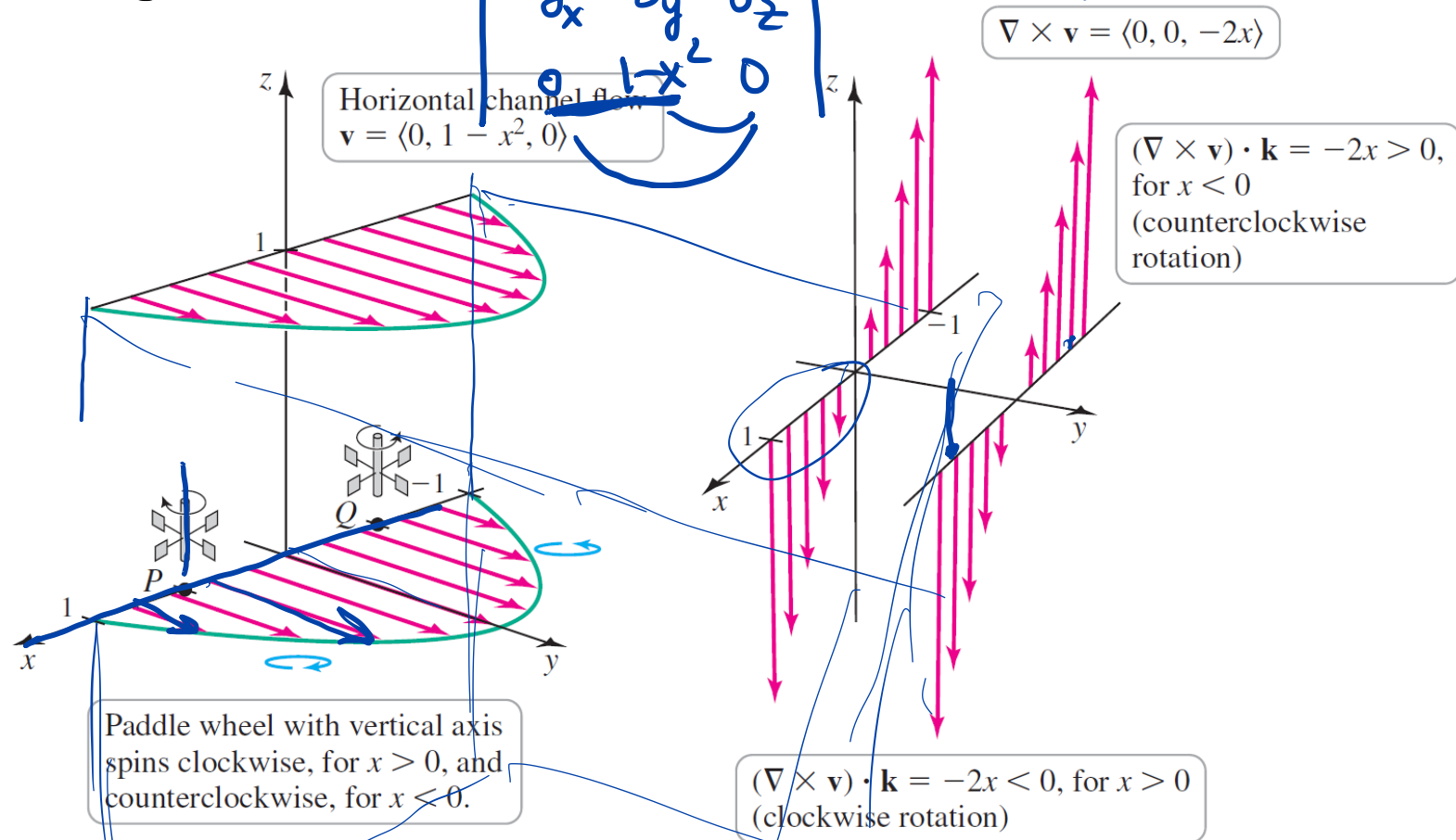
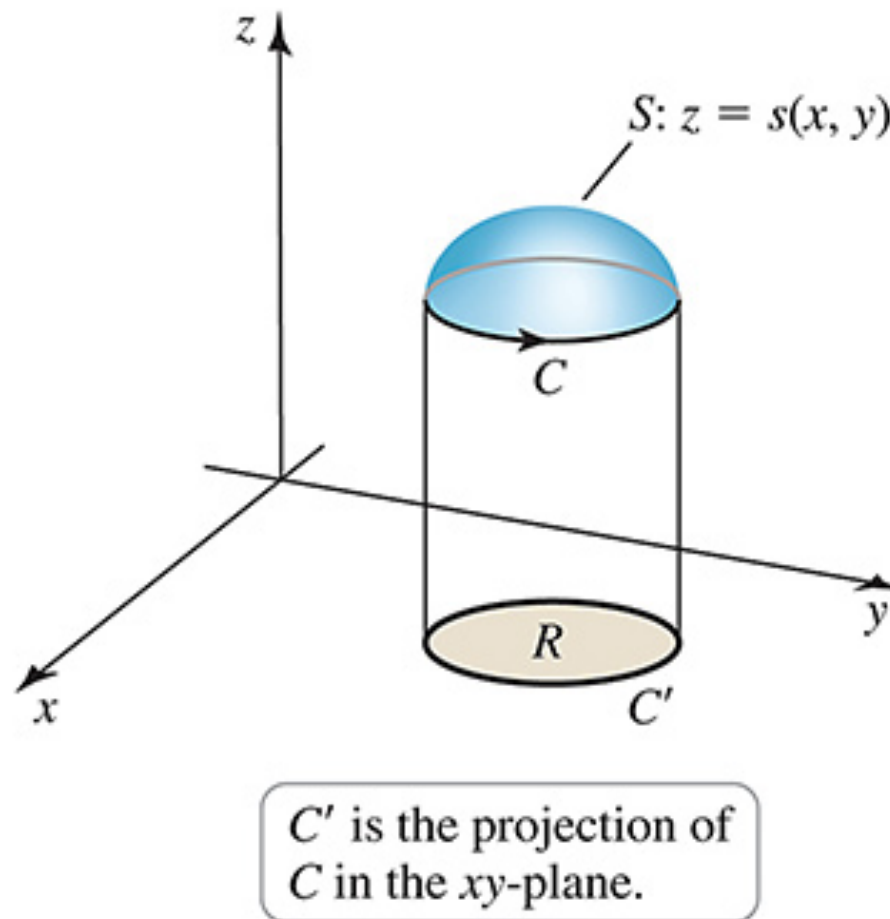


Figure 17.66

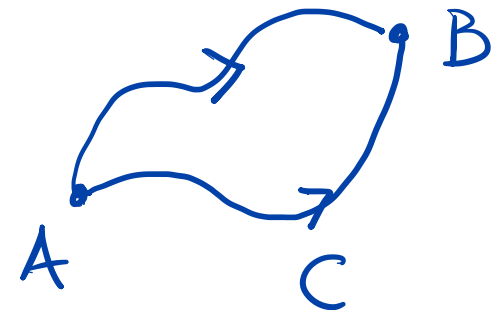


$$\oint_S \nabla \times \vec{F} \cdot \vec{n} \, dS = \int_{\partial S} \vec{F} \cdot d\vec{r}$$

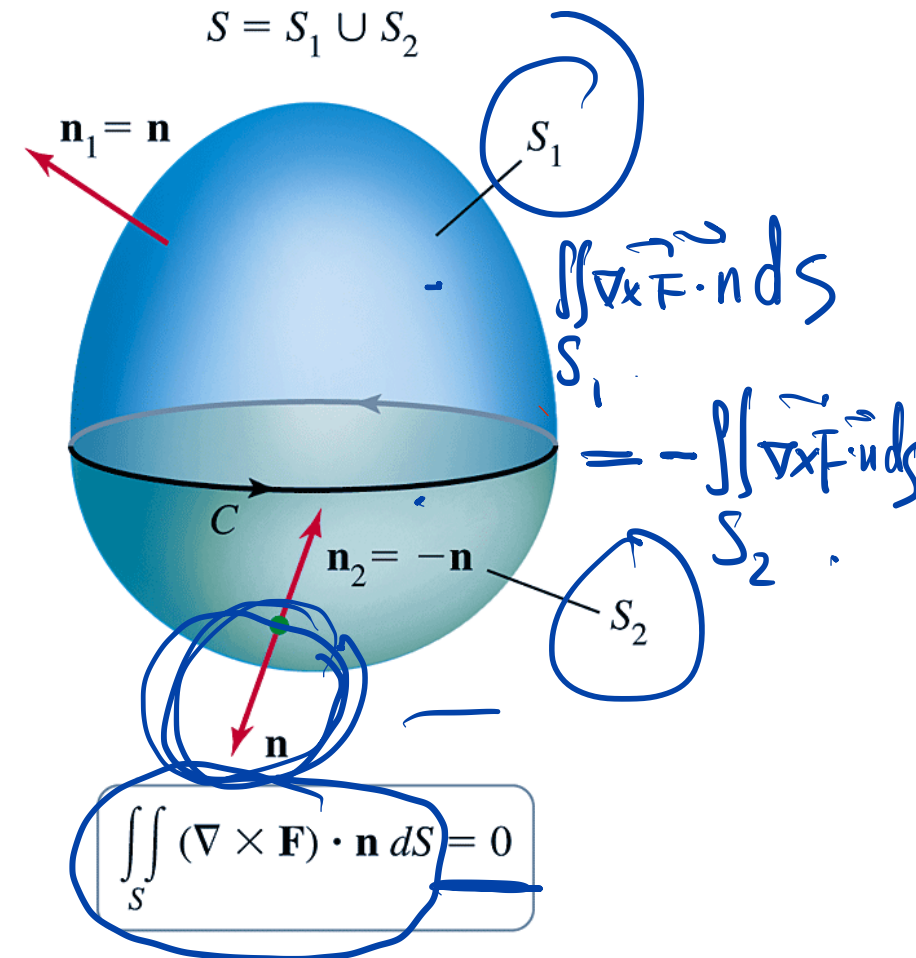
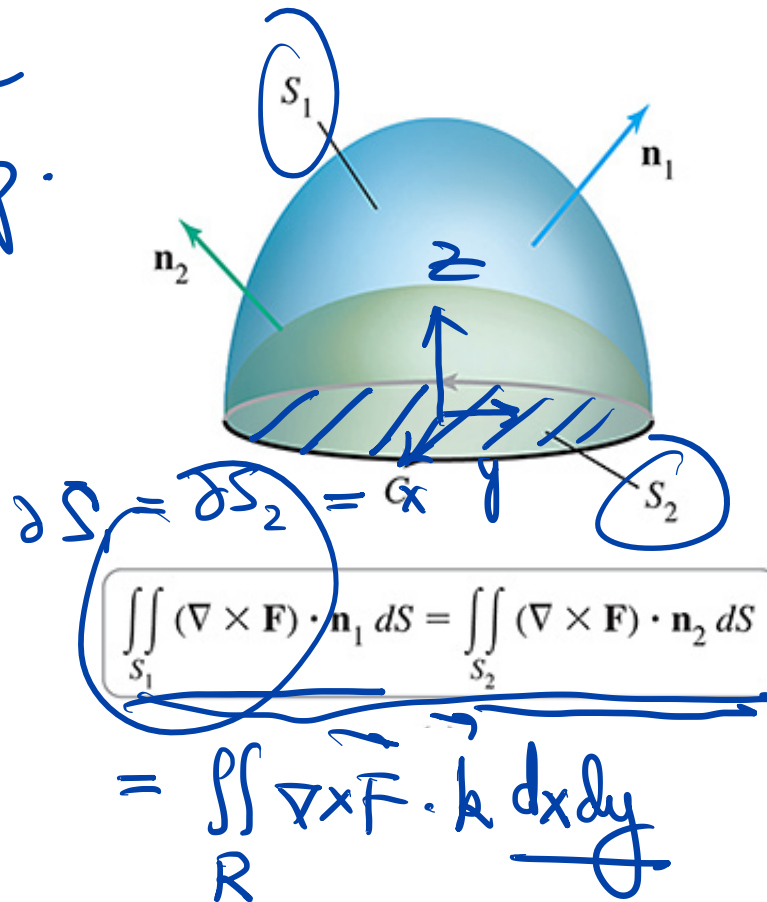
Figure 17.67 (a & b)

$$\int_C \nabla \phi \cdot d\vec{r}$$

path indep.



surface
indep.



Theorem 17.16 $\text{Curl } \mathbf{F} = \mathbf{0}$ Implies $\mathbf{F}$ Is Conservative

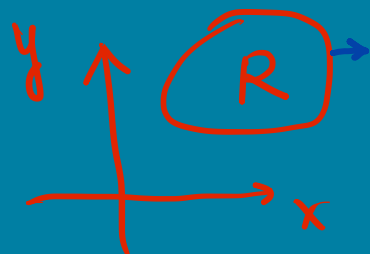
Suppose $\nabla \times \mathbf{F} = \mathbf{0}$ throughout an open simply connected region D of $\mathbb{R}^3$. Then $\int_C \mathbf{F} \cdot d\mathbf{r} = 0$ on all closed simple smooth curves C in D , and $\mathbf{F}$ is conservative vector field on D .

$$\int_C \vec{F} \cdot d\vec{r} = \iint_S \nabla \times \vec{F} \cdot \vec{n} dS = 0$$

$\partial S = C$

$$\vec{F} = \langle f(x, y), g(x, y) \rangle$$

$$\vec{\nabla} \cdot \vec{F} = \frac{\partial f}{\partial x} + \frac{\partial g}{\partial y} \quad \underline{\underline{\text{scalar}}}$$



$$\vec{F} = \langle f(x, y, z), g(x, y, z), h(x, y, z) \rangle$$

$$\vec{\nabla} \cdot \vec{F} = \frac{\partial f}{\partial x} + \frac{\partial g}{\partial y} + \frac{\partial h}{\partial z}$$

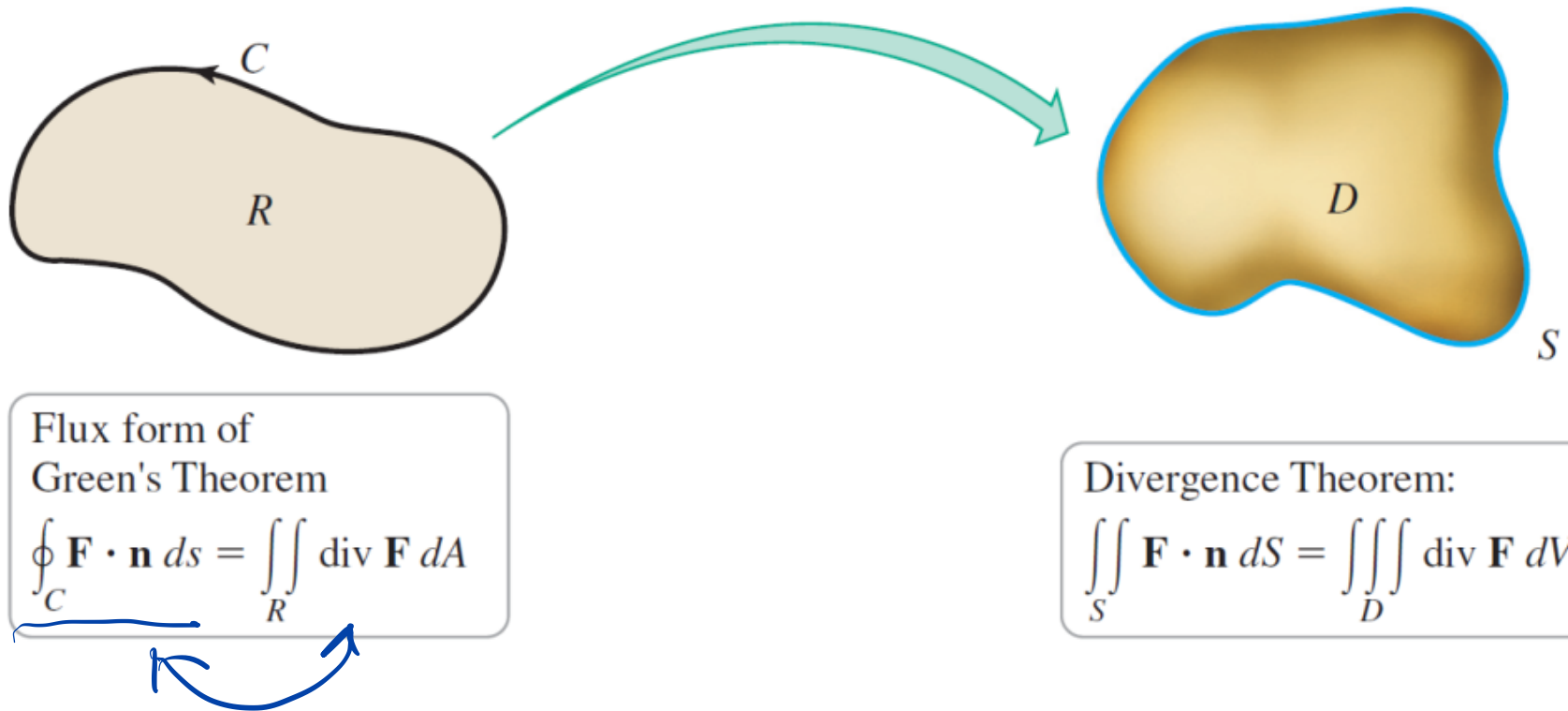


Section 17.8 Divergence Theorem

$$\iint_{\underline{R}} \underline{\vec{\nabla} \cdot \vec{F}} \, dA = \int_{\partial R} (\vec{F} \cdot \underline{\vec{n}}) \, ds$$

$$\iiint_{\underline{D}} \underline{\vec{\nabla} \cdot \vec{F}} \, dV = \iint_{\partial D} (\vec{F} \cdot \underline{\vec{n}}) \, dS$$

Figure 17.68



Theorem 17.17 Divergence Theorem

Let $\mathbf{F}$ be a vector field whose components have continuous first partial derivatives in a connected and simply connected region D in $\mathbb{R}^3$ enclosed by an oriented surface S . Then

$$\iint_S \mathbf{F} \cdot \mathbf{n} \, dS = \iiint_D \nabla \cdot \mathbf{F} \, dV,$$

where $\mathbf{n}$ is the outward unit normal vector on S .

Example 1 $S: x^2 + y^2 + z^2 = a^2$, $\vec{n}$ is the outward unit normal vector to S

$$\vec{F} = \langle x, y, z \rangle, \nabla \cdot \vec{F} = 1 + 1 + 1 = 3 \quad D: x^2 + y^2 + z^2 \leq a^2$$

$$\iiint_D \nabla \cdot \vec{F} dV = \iiint_D 3 dV = 3 \text{Vol}(D) = 3 \cdot \frac{4}{3} \pi a^3 = \underline{\underline{4\pi a^3}}$$

$$\vec{r}(\varphi, \theta) = \langle a \sin \varphi \cos \theta, a \sin \varphi \sin \theta, a \cos \varphi \rangle$$

$$\vec{r}_\varphi = \langle x, y, z \rangle$$

$$\iint_R \langle x, y, z \rangle \cdot a \sin \varphi \langle x, y, z \rangle d\varphi d\theta$$

$$\iint_S \vec{F} \cdot \vec{n} dS = \int_0^{2\pi} \int_0^\pi a \sin \varphi (x^2 + y^2 + z^2) d\varphi d\theta$$

$$R: 0 \leq \varphi \leq \pi, 0 \leq \theta \leq 2\pi$$

$$\vec{r}_\varphi \times \vec{r}_\theta = a \sin \varphi \vec{r}(\varphi, \theta)$$

$$= a \sin \varphi \langle x, y, z \rangle$$

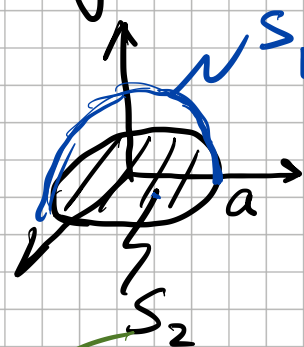
outward

Example 2

$$\vec{F} = \vec{a} \times \vec{r} = \langle 1, 0, 1 \rangle \times \langle x, y, z \rangle = \langle -y, x-z, y \rangle$$

S is the hemisphere $x^2 + y^2 + z^2 = a^2$, for $z \geq 0$, together with its base in the xy -plane. Find the net outward flux across S .

$$\iint_{\underbrace{S}} \vec{F} \cdot \vec{n} dS = \iint_{\underbrace{S_1}} \vec{F} \cdot \vec{n} dS + \iint_{\underbrace{S_2}} \vec{F} \cdot \vec{n} dS$$



$$\iint_D \nabla \cdot \vec{F} dV = 0$$

$$\iint_{S_1} \vec{F} \cdot \vec{n} dS = - \iint_{S_2} \vec{F} \cdot \vec{n} dS$$

$$= - \iint_R \langle -y, x, y \rangle \cdot \langle 0, 0, -1 \rangle dx dy$$

$$= \iint_R y dx dy$$

$$\nabla \cdot \vec{F} = \nabla \cdot \langle -y, x-z, y \rangle = 0 + 0 + 0 = 0$$

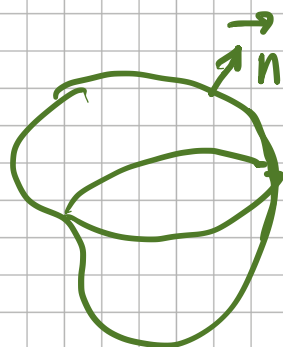
$$S = S_1 \cup S_2$$

$$\vec{r}(x, y) = \langle x, y, 0 \rangle$$

$$(x, y) \in R$$

$$\vec{r}_x \times \vec{r}_y = \langle 0, 0, 1 \rangle$$

$$\iiint_D \vec{\nabla} \cdot \vec{F} dV = \iint_{\partial D} \vec{F} \cdot \vec{n} dS$$



Example 3 $\vec{F} = xyz\langle 1, 1, 1 \rangle$. $S = \partial D$, $D = [0, 1] \times [0, 1] \times [0, 1]$ point outward

Find the net outward flux.

Figure 17.69

$$\begin{aligned}\nabla \cdot \vec{F} &= \frac{\partial}{\partial x}(xyz) + \frac{\partial}{\partial y}(xyz) + \frac{\partial}{\partial z}(xyz) \\ &= yz + xz + xy\end{aligned}$$

$$\iint_S \vec{F} \cdot \vec{n} dS = \iiint_D \nabla \cdot \vec{F} dV$$

$$= \int_0^1 \int_0^1 \int_0^1 (yz + xz + xy) dx dy dz$$

$$\vec{F} = xyz\langle 1, 1, 1 \rangle$$

$$= 3 \int_0^1 \int_0^1 yz dx dy dz$$

$$= 3 \cdot 1 \cdot \left[\frac{1}{2} y^2 \right]_0^1 \cdot \left[\frac{1}{2} z^2 \right]_0^1$$

$$= 3 \cdot \frac{1}{2} \cdot \frac{1}{2} = \frac{3}{4}$$

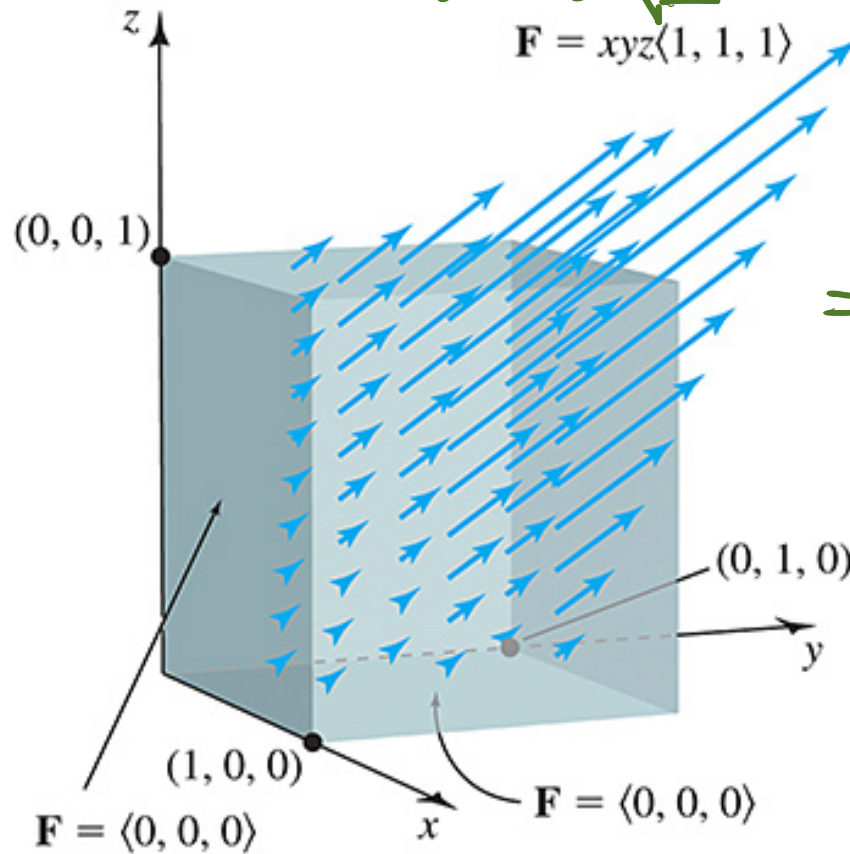
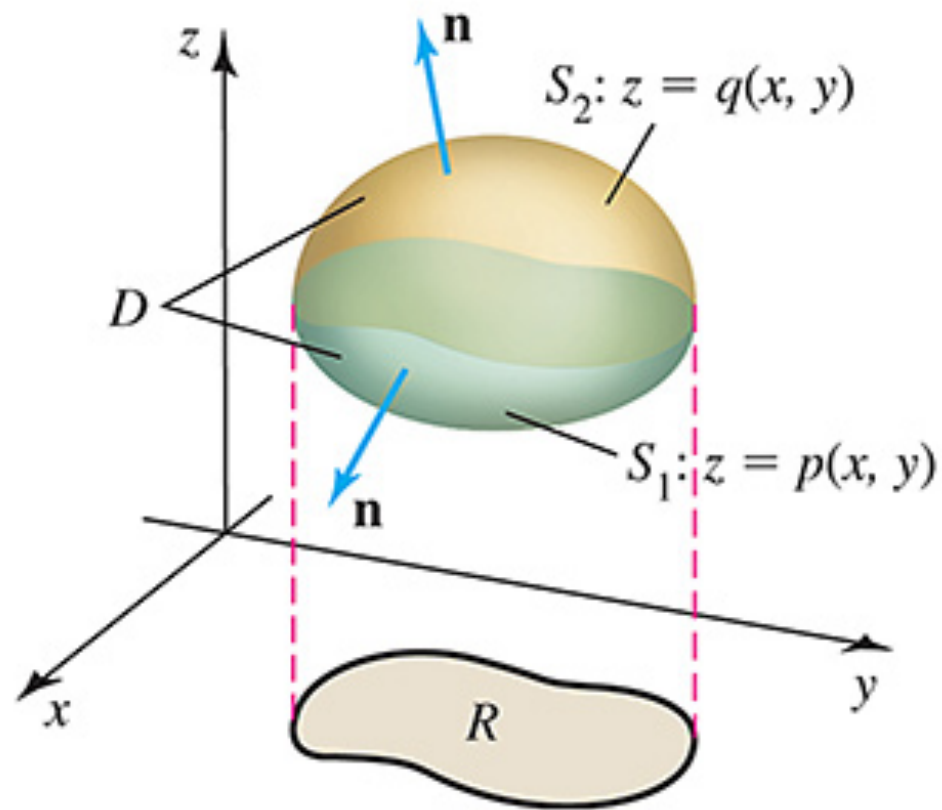


Figure 17.71



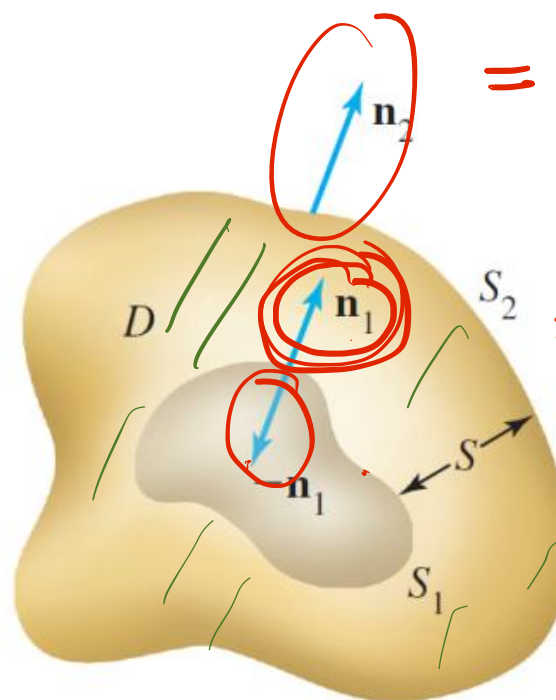
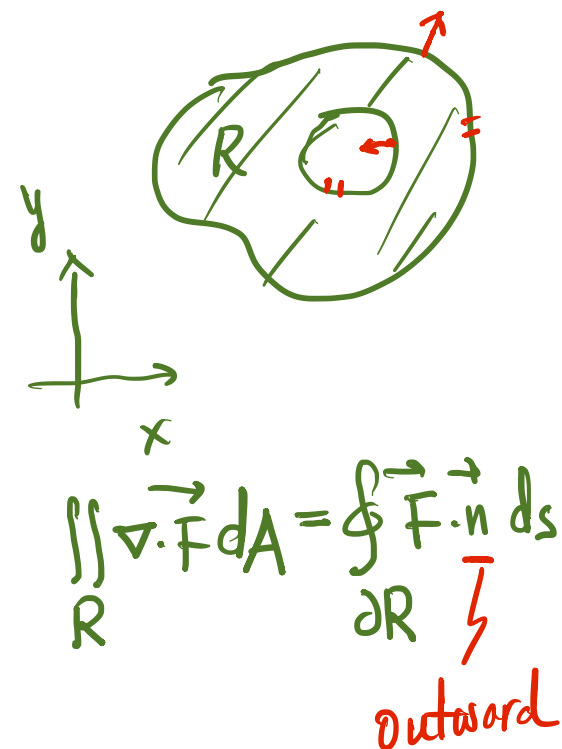
Divergence Theorem for Hollow Regions

Figure 17.72

$$\iiint_D \nabla \cdot \vec{F} dV = \iint_{\partial D} \vec{F} \cdot \vec{n} dS$$

$$= \iint_{S_2} \vec{F} \cdot \vec{n}_2 dS + \iint_{S_1} \vec{F} \cdot (-\vec{n}_1) dS$$

$$= \iint_{S_2} \vec{F} \cdot \vec{n}_2 dS - \iint_{S_1} \vec{F} \cdot \vec{n}_1 dS$$



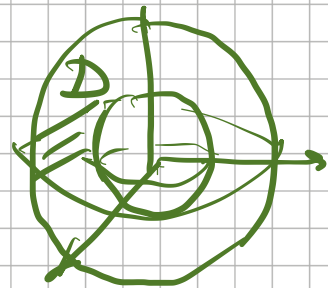
$\vec{n}_1$ is the outward normal to S_1 and points into D . The outward normal to S on S_1 is $-\vec{n}_1$.

Theorem 17.18 Divergence Theorem for Hollow Regions

Suppose the vector field $\mathbf{F}$ satisfies the conditions of the Divergence Theorem on a region D bounded by two oriented surfaces S_1 and S_2 , where S_1 lies within S_2 . Let S be the entire boundary of D ($S = S_1 \cup S_2$) and let $\mathbf{n}_1$ and $\mathbf{n}_2$ be the outward unit normal vectors for S_1 and S_2 , respectively. Then

$$\iiint_D \nabla \cdot \mathbf{F} \, dV = \iint_S \mathbf{F} \cdot \mathbf{n} \, dS = \iint_{S_2} \mathbf{F} \cdot \mathbf{n}_2 \, dS - \iint_{S_1} \mathbf{F} \cdot \mathbf{n}_1 \, dS.$$

Example 4 $\vec{F} = \frac{\vec{r}}{|\vec{r}|^3} = \frac{\langle x, y, z \rangle}{(x^2 + y^2 + z^2)^{3/2}}$



(a) $D = \{(x, y, z) : \underline{a^2 \leq x^2 + y^2 + z^2 \leq b^2}\}$

$\iint_{\partial D} \vec{F} \cdot \vec{n} dS = \iiint_D \nabla \cdot \vec{F} dV = 0$

$\frac{\partial}{\partial x} [x(x^2 + y^2 + z^2)^{-3/2}] = (x^2 + y^2 + z^2)^{-3/2} + x \cdot (-\frac{3}{2}) \cdot (x^2 + y^2 + z^2)^{-5/2} \cdot 2x$
 $= (x^2 + y^2 + z^2)^{-3/2} [x^2 + y^2 + z^2 - 3x^2]$

$\nabla \cdot \vec{F} = (x^2 + y^2 + z^2)^{-5/2} [(y^2 + z^2 - 2x^2) + (x^2 + z^2 - 2y^2) + (x^2 + y^2 - 2z^2)]$

$\nabla \cdot \vec{F} = 0$

(b) Find the outward flux of $\vec{F}$ across any sphere that encloses the origin.

$\iint_S \vec{F} \cdot \vec{n} dS \neq \iiint_B \nabla \cdot \vec{F} dV$

$\vec{r}(\varphi, \theta) = a \langle \sin \varphi \cos \theta, \sin \varphi \sin \theta, \cos \varphi \rangle$
 $R: 0 \leq \varphi \leq \pi, 0 \leq \theta \leq 2\pi$

$\vec{r}_\varphi \times \vec{r}_\theta = a \sin \varphi \vec{r}(\varphi, \theta)$

$\iint_S \frac{\langle x, y, z \rangle}{a^3} \cdot a \sin \varphi \langle x, y, z \rangle d\varphi d\theta = \int_0^\pi \int_0^{2\pi} \sin \varphi d\varphi d\theta$

$= 2\pi \cdot [-\cos \varphi]_0^\pi = 4\pi$

Gauss' Law

$$\vec{E}(x, y, z) = \frac{Q}{4\pi\epsilon_0} \frac{\vec{r}}{|\vec{r}|^3}$$

the electric field due to a point charge Q located at the origin

$$\vec{r} = \langle x, y, z \rangle$$

ϵ_0 is the permittivity of free space

S is any close surface

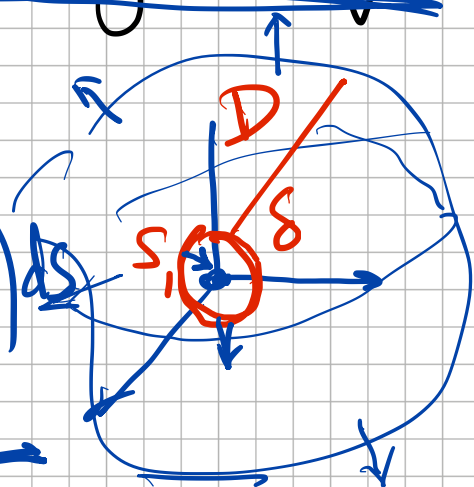
$$\oint_S \vec{E} \cdot \vec{n} dS = \begin{cases} \frac{Q}{\epsilon_0}, & (0,0,0) \text{ inside } S \\ 0, & \text{otherwise} \end{cases}$$

$$\oint \nabla \cdot \vec{F} dV = 0$$

$\Downarrow$

$\parallel$

$$\oint_S \vec{F} \cdot \vec{n} dS = \oint_S \vec{F} \cdot \vec{n} dS + \oint_{S_1} \vec{F} \cdot (-\vec{n}) dS$$



$$\Rightarrow \oint_S \vec{F} \cdot \vec{n} dS = \oint_{S_1} \vec{F} \cdot \vec{n} dS$$

$$= \frac{Q}{4\pi\epsilon_0} \cdot 4\pi$$

$$= \frac{Q}{\epsilon_0}$$

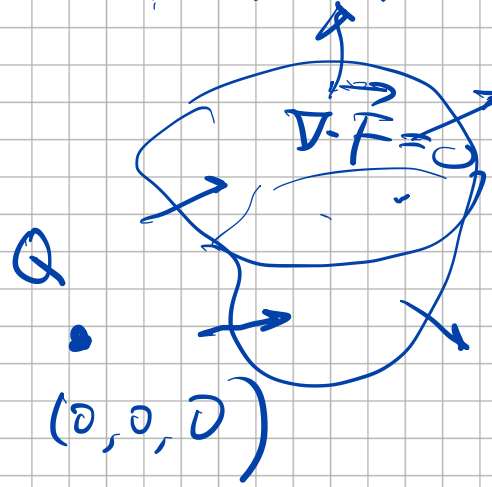
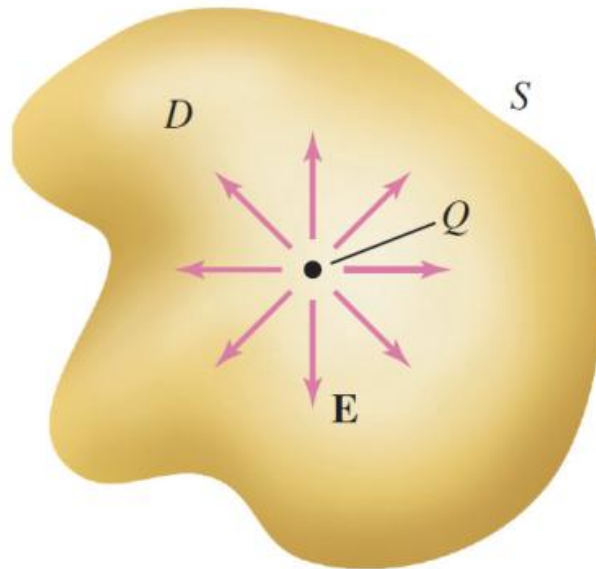
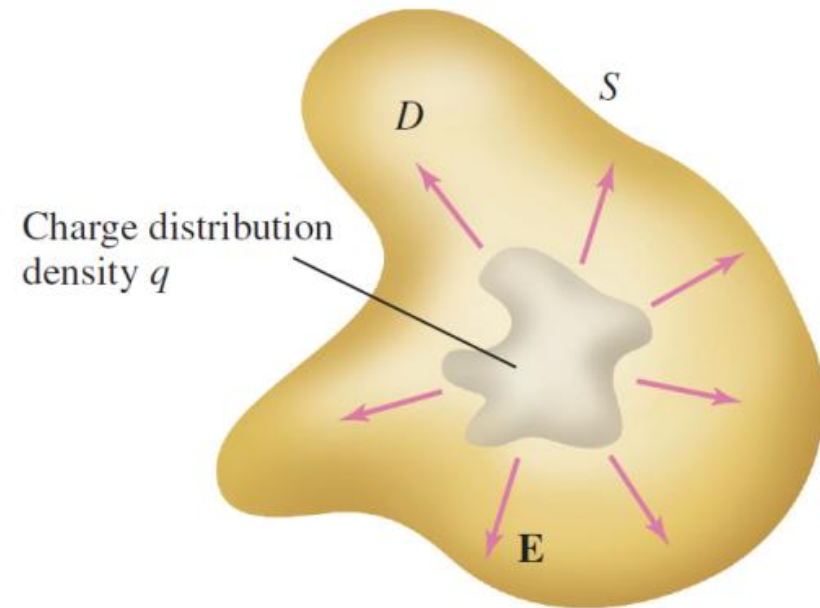


Figure 17.73 (a & b)



Gauss' Law:
Flux of electric field across S
due to point charge Q

$$= \iint_S \mathbf{E} \cdot \mathbf{n} \, dS = \frac{Q}{\epsilon_0}$$



Gauss' Law:
Flux of electric field across S
due to charge distribution q

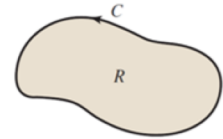
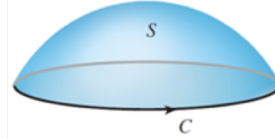
$$= \iint_S \mathbf{E} \cdot \mathbf{n} \, dS = \frac{1}{\epsilon_0} \iiint_D q \, dV$$

Table 17.4

$$f'(x)$$

$$\nabla f(x,y,z) = \left(\frac{\partial f}{\partial x}, \frac{\partial f}{\partial y}, \frac{\partial f}{\partial z} \right)$$

$$\vec{\nabla} \cdot \vec{F} = \frac{\partial f}{\partial x} + \frac{\partial g}{\partial y} + \frac{\partial h}{\partial z}$$

Fundamental Theorem of Calculus	$\int_a^b f'(x) dx = f(b) - f(a)$	
Fundamental Theorem of Line Integral	$\int_C \nabla f \cdot d\mathbf{r} = f(B) - f(A)$	
Green's Theorem (circulation form)	$\iint_R (g_x - f_y) dA = \oint_C f dx + g dy$	
Stokes' Theorem	$\iint_S (\nabla \times \mathbf{F}) \cdot \mathbf{n} dS = \oint_C \mathbf{F} \cdot d\mathbf{r}$	
Divergence Theorem	$\iiint_D \nabla \cdot \mathbf{F} dV = \iint_S \mathbf{F} \cdot \mathbf{n} dS$	