

16.6 Integrals for Mass Calculations

mass of things in 2D: $\iint_R \rho(x,y) dA$ ← density

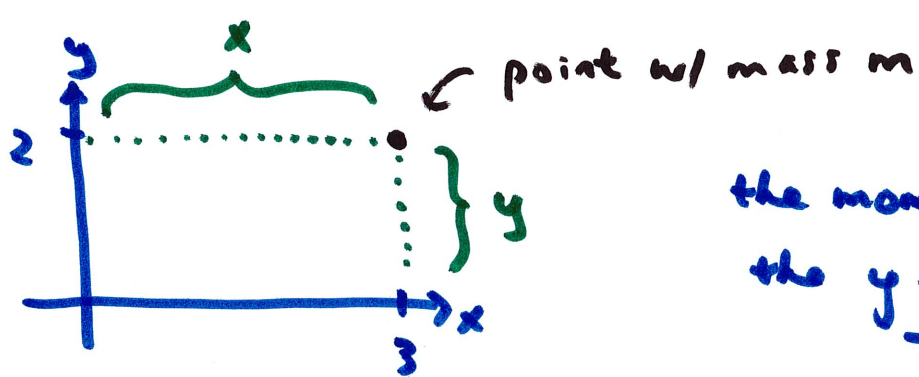
3D: $\iiint_D \rho(x,y,z) dV$

we want to calculate the center of mass of objects

first we need to know how to calculate the moment

(specifically the mass moment)
rotational equivalent of
momentum

mass moment = mass · distance from rotational axis



the moment of the point mass about
the y-axis is

$$M_y = \text{mass} \cdot \underbrace{\text{distance from axis of rotation}}_x$$

$$M_y = m x$$

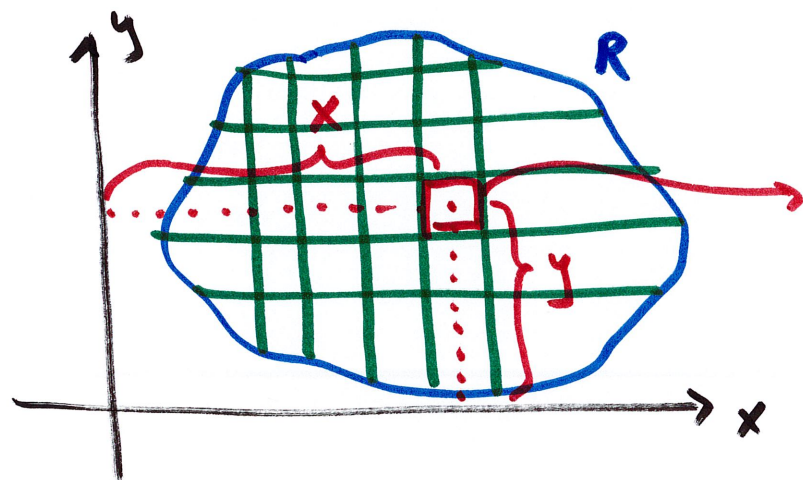
likewise, the moment about x-axis is $M_x = m y$

for example, if $m = 4$

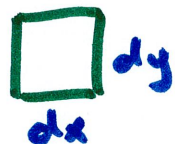
then for this point mass, $M_y = 4 \cdot 3 = 12$

$$M_x = 4 \cdot 2 = 8$$

we will use the point mass idea to find the moments of a region



clap into little pieces



this piece has mass

$$m = \rho(x, y) dx dy$$

$$m = \rho(x, y) dA$$

the small piece is at distance x from y -axis

$$\text{so } M_y = \rho(x, y) \cdot x dA$$

$$\text{and } M_x = \rho(x, y) \cdot y dA$$

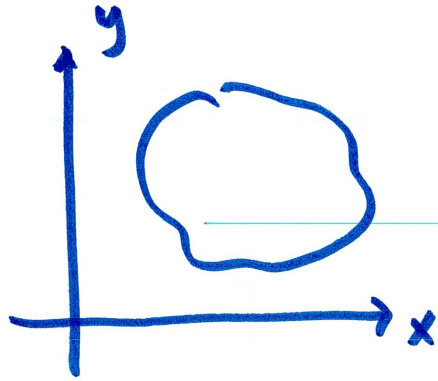
to find moments of entire region (little pieces have varying x, y, ρ)
we accumulate by integration

$$M_y = \iint_R x \rho dA$$

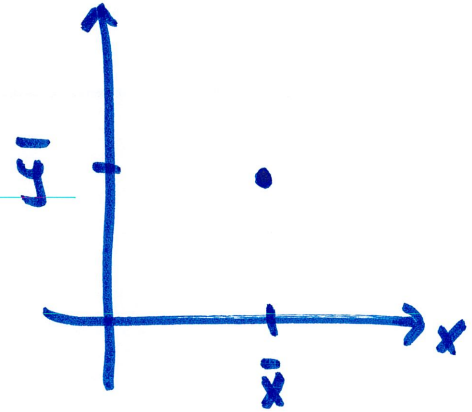
$$M_x = \iint_R y \rho dA$$

One definition of center of mass: the location (\bar{x}, \bar{y}) where a point with same mass as region would be if it were to have the same moments.

"x bar" ← → "y bar"



collapse into one point



has $M_x = \iint_R y \rho dA$

$$M_y = \iint_R x \rho dA$$

$$\text{mass} = \iint_R \rho dA$$

want same M_x, M_y

$$M_x = m \bar{y}$$

$$M_y = m \bar{x}$$

Equate the moments, solve for \bar{x} , \bar{y}

$$M_x = \iint_R y \rho dA = m \bar{y}$$

$$M_y = \iint_R x \rho dA = m \bar{x}$$

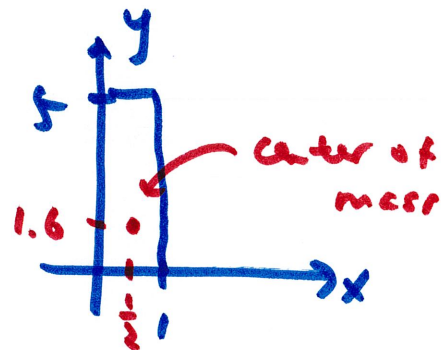
we get

~~$\bar{x} = \frac{1}{m} \iint_R x \rho dA$~~
 ~~$\bar{y} = \frac{1}{m} \iint_R y \rho dA$~~
where ~~$m = \iint_R \rho dA$~~

$\bar{x} = \frac{1}{m} \iint_R x \rho dA$
 $\bar{y} = \frac{1}{m} \iint_R y \rho dA$
 $m = \iint_R \rho dA$

example $R = \{(x, y) : 0 \leq x \leq 1, 0 \leq y \leq 5\}$

$$\rho(x, y) = 2e^{-\frac{1}{2}y}$$

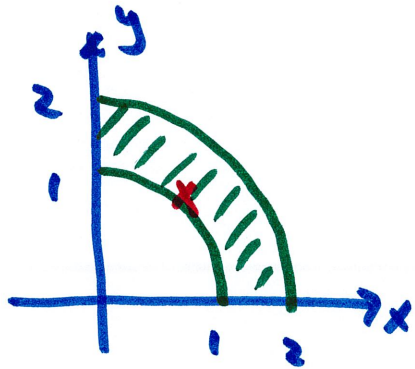


first, mass: $m = \iint_R \rho(x, y) dA = \int_0^1 \int_0^5 2e^{-\frac{1}{2}y} dy dx = \dots = \cancel{4(1-e^{-5/2})}$
 $= 4(1-e^{-5/2})$

$$\bar{x} = \frac{1}{m} \iint_R x \rho dA = \frac{1}{4(1-e^{-5/2})} \int_0^1 \int_0^5 x \cdot 2e^{-\frac{1}{2}y} dy dx = \dots = \boxed{\frac{1}{2}}$$

$$\begin{aligned} \bar{y} &= \frac{1}{m} \iint_R y \rho dA = \frac{1}{4(1-e^{-5/2})} \int_0^1 \int_0^5 y \cdot 2e^{-\frac{1}{2}y} dy dx \\ &= \dots = \frac{-14e^{-5/2} + 4}{2(1-e^{-5/2})} \approx \boxed{1.6} \end{aligned}$$

example R : circles of radii 1 and 2 centered at origin in 1st quadrant with density $\rho(x,y) = \sqrt{x^2+y^2}$



circles, so go to polar

$$1 \leq r \leq 2$$

$$0 \leq \theta \leq \pi/2$$

in polar $\sqrt{x^2+y^2} = \sqrt{r^2} = r$

$$\text{mass: } m = \iint_R \rho \, dA = \int_0^{\pi/2} \int_1^2 r \cdot \overbrace{r \, dr \, d\theta}^{dA} = \dots = \frac{7\pi}{6}$$

$$\bar{x} = \frac{1}{m} \iint_R x \rho \, dA = \frac{1}{7\pi/6} \int_0^{\pi/2} \int_1^2 \underbrace{r \cos \theta}_{x=r \cos \theta} \cdot \underbrace{r}_{\rho} \cdot \underbrace{r \, dr \, d\theta}_{dA} = \frac{45}{14\pi} \approx 1.023$$

$$\bar{y} = \frac{1}{m} \iint_R y \rho \, dA = \frac{1}{7\pi/6} \int_0^{\pi/2} \int_1^2 \underbrace{r \sin \theta}_y \cdot \underbrace{r}_{\rho} \cdot \underbrace{r \, dr \, d\theta}_{dA} = \frac{45}{14\pi} \approx 1.023$$

2D to 3D: change dA to dV , $\rho(x,y) = \rho(x,y,z)$
double integral \rightarrow triple

$$m = \iiint_D \rho(x,y,z) dV$$

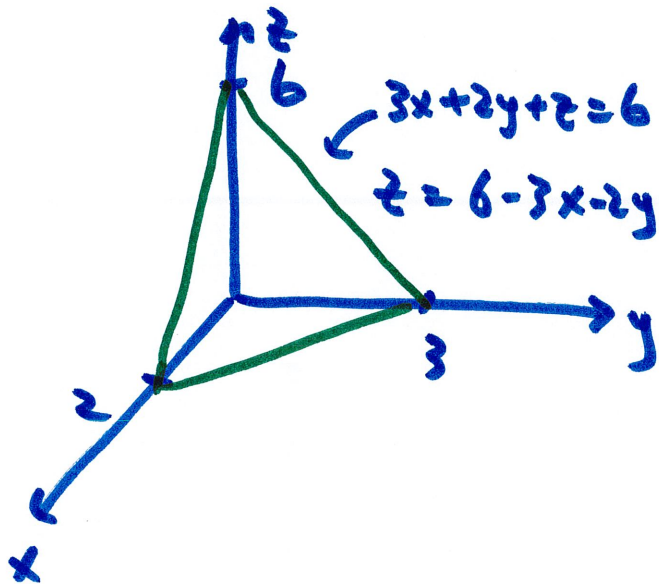
$$\bar{x} = \frac{1}{m} \iiint_D x \rho(x,y,z) dV$$

$$\bar{y} = \frac{1}{m} \iiint_D y \rho(x,y,z) dV$$

$$\bar{z} = \frac{1}{m} \iiint_D z \rho(x,y,z) dV$$

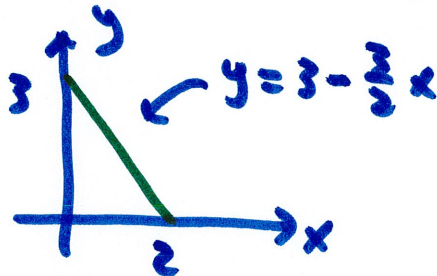
example Find center of mass of solid bounded by $3x+2y+z=6$ and the coordinate planes.

$$\rho(x,y,z) = 1+x$$



describe the volume D

pick a plane to be the "floor" here, let's use xy -plane



$$\begin{aligned} 0 \leq x \leq 2 \\ 0 \leq y \leq 3 - \frac{3}{2}x \end{aligned}$$

z : from xy -plane ($z=0$) to the plane ($z=6-3x-2y$)

$$0 \leq z \leq 6 - 3x - 2y$$

$$\text{mass: } m = \iiint_D \rho \, dV = \int_0^2 \int_0^{3-\frac{3}{2}x} \int_0^{6-3x-2y} \underbrace{(1+x)}_P \underbrace{dz \, dy \, dx}_{dV} = \dots = 9$$

$$\bar{x} = \frac{1}{m} \iiint_D x \rho \, dV = \frac{1}{9} \int_0^2 \int_0^{3-\frac{3}{2}x} \int_0^{6-3x-2y} x \cdot (1+x) \, dz \, dy \, dx = \dots = \frac{3}{5}$$

Similarly, $\bar{y} = \dots = 7/10$, $\bar{z} = \dots = 7/5$

a related quantity, called moment of inertia (or angular mass)

is the rotational equivalent of mass, high \rightarrow hard to rotate

$$I_{\text{axis}} = \iint_R \rho(x,y) d^2 dA \quad (2D)$$

not
moment of
inertia about
an axis

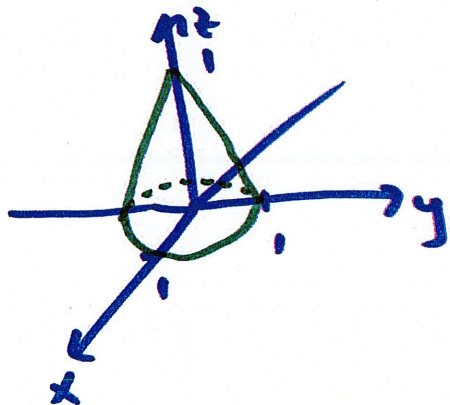
d is distance to that axis
("x" in $M_y = \iint_R x dA$)

$$I_{\text{axis}} = \iiint_D \rho(x,y,z) d^3 dV \quad (3D)$$

example Find the moment of inertia of the solid bounded above by

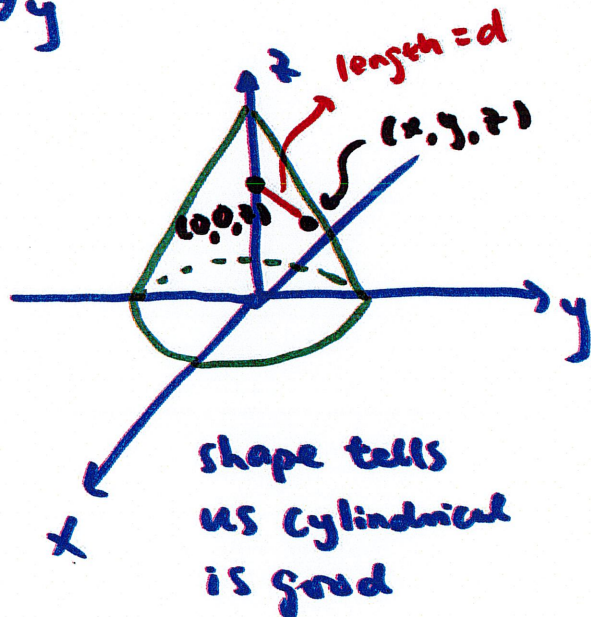
$z = 1 - \sqrt{x^2 + y^2}$ and below by $z = 0$ about the z -axis

$$\rho(x, y, z) = z$$



we want $I_z = \iiint_D \rho(x, y, z) d^2 dv$

d : distance of any point in the shape from z -axis

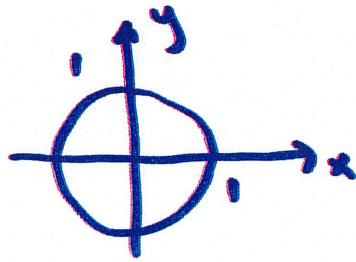


d is distance from (x, y, z) to $(0, 0, z)$

so, $d = \sqrt{x^2 + y^2}$

$$d = \sqrt{(x-0)^2 + (y-0)^2 + (z-z)^2} \\ = \sqrt{x^2 + y^2}$$

use xy -plane as "floor"



$$0 \leq r \leq 1$$
$$0 \leq \theta \leq 2\pi$$

cylindrical is good, so

$$0 \leq z \leq 1-r$$

$$I_z = \iiint_D \rho(x,y,z) d^3v$$

$$= \int_0^{2\pi} \int_0^1 \int_0^{1-r} \underbrace{z (r)^2 r dz dr d\theta}_{dV} = \dots = \boxed{\frac{\pi}{60}}$$

$$\rho \quad d = \sqrt{x^2 + y^2} = r$$