

6.2 Orthogonal Sets

A set of vectors is an orthogonal set if the vectors are mutually orthogonal.

$\{\vec{u}_1, \vec{u}_2, \dots, \vec{u}_p\}$ is orthogonal if $\vec{u}_i \cdot \vec{u}_j = 0$ when $i \neq j$

example $\left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \right\} = \{\vec{i}, \vec{j}, \vec{k}\}$

$$\vec{i} \cdot \vec{j} = \vec{i} \cdot \vec{k} = \vec{j} \cdot \vec{k} = 0$$

example $\left\{ \begin{bmatrix} 1 \\ -4 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 4 \end{bmatrix}, \begin{bmatrix} -17 \\ -4 \\ 1 \end{bmatrix} \right\}$ is an orthogonal set

$$[1 \quad -4 \quad 1] \begin{bmatrix} 0 \\ 1 \\ 4 \end{bmatrix} = 0$$

$$[1 \quad -4 \quad 1] \begin{bmatrix} -17 \\ -4 \\ 1 \end{bmatrix} = 0$$

$$[0 \quad 1 \quad 4] \begin{bmatrix} -17 \\ -4 \\ 1 \end{bmatrix} = 0$$

If $S = \{ \vec{u}_1, \dots, \vec{u}_p \}$ is an orthogonal set of nonzero vectors in \mathbb{R}^n , then S is linearly independent and a basis for the subspace spanned by S .

Why? $S = \{ \vec{u}_1, \vec{u}_2, \vec{u}_3 \}$ is an orthogonal set
(so $\vec{u}_1 \cdot \vec{u}_2 = \vec{u}_1 \cdot \vec{u}_3 = \vec{u}_2 \cdot \vec{u}_3 = 0$)

Suppose $\vec{0} = c_1 \vec{u}_1 + c_2 \vec{u}_2 + c_3 \vec{u}_3$ for some c_1, c_2, c_3

$$\vec{0} \cdot \vec{u}_1 = c_1 \vec{u}_1 \cdot \vec{u}_1 + c_2 \vec{u}_2 \cdot \vec{u}_1 + c_3 \vec{u}_3 \cdot \vec{u}_1 \rightarrow c_1 = 0$$

$$\vec{0} \cdot \vec{u}_2 = c_1 \vec{u}_1 \cdot \vec{u}_2 + c_2 \vec{u}_2 \cdot \vec{u}_2 + c_3 \vec{u}_3 \cdot \vec{u}_2 \rightarrow c_2 = 0$$

$$\vec{0} \cdot \vec{u}_3 = c_1 \vec{u}_1 \cdot \vec{u}_3 + c_2 \vec{u}_2 \cdot \vec{u}_3 + c_3 \vec{u}_3 \cdot \vec{u}_3 \rightarrow c_3 = 0$$

So, $c_1 = c_2 = c_3 = 0$ is the only way

$\vec{0} = c_1 \vec{u}_1 + c_2 \vec{u}_2 + c_3 \vec{u}_3 \rightarrow \{ \vec{u}_1, \vec{u}_2, \vec{u}_3 \}$ is linearly indep.

If a basis is orthogonal, then it is an orthogonal basis

→ makes calculating the weights of a linear combo easy.

example

Orthogonal basis : $\left\{ \begin{bmatrix} 2 \\ -3 \end{bmatrix}, \begin{bmatrix} 6 \\ 4 \end{bmatrix} \right\} = \{ \vec{u}_1, \vec{u}_2 \}$

$$\vec{x} = \begin{bmatrix} 9 \\ -7 \end{bmatrix}$$

$$c_1 \begin{bmatrix} 2 \\ -3 \end{bmatrix} + c_2 \begin{bmatrix} 6 \\ 4 \end{bmatrix} = \begin{bmatrix} 9 \\ -7 \end{bmatrix}$$

$$c_1 = ? \quad c_2 = ?$$

"old" way: form augmented matrix, then row reduce.

another way: take advantage of orthogonality

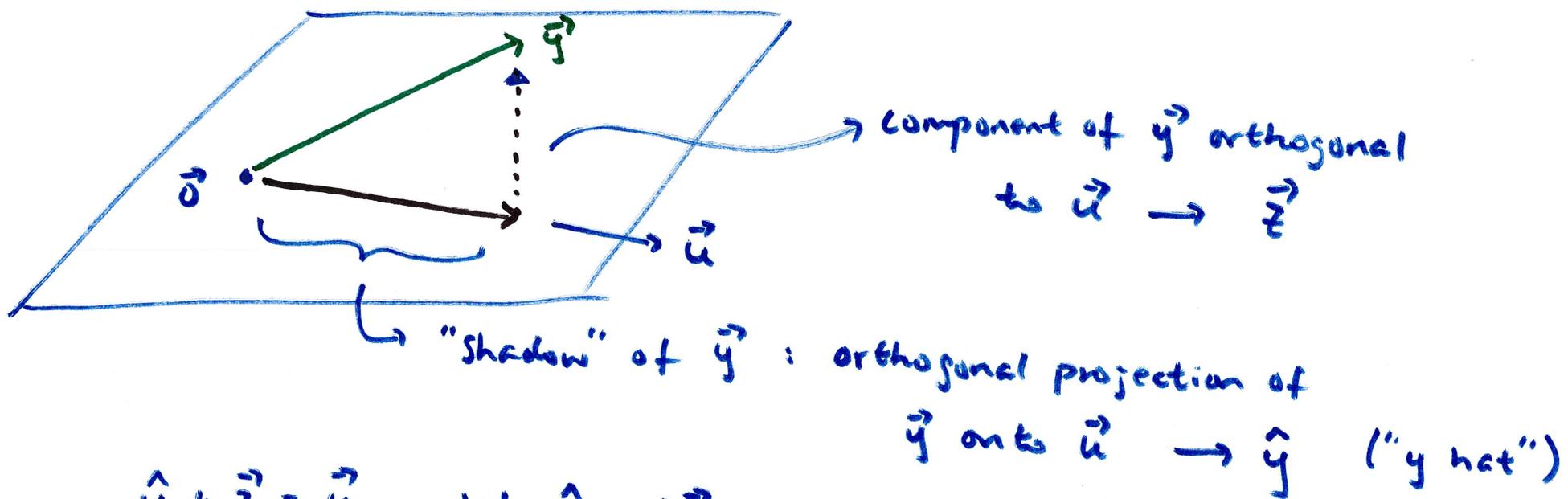
$$\vec{x} = c_1 \vec{u}_1 + c_2 \vec{u}_2$$

$$\vec{x} \cdot \vec{u}_1 = c_1 \vec{u}_1 \cdot \vec{u}_1 + c_2 \cancel{\vec{u}_2 \cdot \vec{u}_1} \rightarrow c_1 = \frac{\vec{x} \cdot \vec{u}_1}{\vec{u}_1 \cdot \vec{u}_1}$$

$$\vec{x} \cdot \vec{u}_2 = c_1 \cancel{\vec{u}_1 \cdot \vec{u}_2} + c_2 \vec{u}_2 \cdot \vec{u}_2 \rightarrow c_2 = \frac{\vec{x} \cdot \vec{u}_2}{\vec{u}_2 \cdot \vec{u}_2}$$

$$C_1 = \frac{[9 \ -7] \begin{bmatrix} 2 \\ -3 \end{bmatrix}}{[2 \ -3] \begin{bmatrix} 2 \\ -3 \end{bmatrix}} = \frac{39}{13} = 3$$

$$C_2 = \frac{[9 \ -7] \begin{bmatrix} 6 \\ 4 \end{bmatrix}}{[6 \ 4] \begin{bmatrix} 6 \\ 4 \end{bmatrix}} = \frac{26}{52} = \frac{1}{2}$$



$$\hat{y} + \vec{z} = \vec{y} \quad \text{let } \hat{y} = \alpha \vec{u}$$

$$\text{then } \vec{z} = \vec{y} - \hat{y} = \vec{y} - \alpha \vec{u}$$

$$\vec{z} \cdot \vec{u} = 0 = (\vec{y} - \alpha \vec{u}) \cdot \vec{u} = \vec{y} \cdot \vec{u} - \alpha \vec{u} \cdot \vec{u}$$

$$\alpha = \frac{\vec{y} \cdot \vec{u}}{\vec{u} \cdot \vec{u}}$$

therefore,

$$\hat{y} = \frac{\vec{y} \cdot \vec{u}}{\vec{u} \cdot \vec{u}} \vec{u}$$

orthogonal
projection of
 \vec{y} onto subspace
spanned by \vec{u}

length of \vec{u} doesn't matter

let $\vec{u} = c\vec{u}$

$$\hat{y} = \frac{\vec{y} \cdot c\vec{u}}{c\vec{u} \cdot c\vec{u}} c\vec{u} = \frac{\cancel{c} \vec{y} \cdot \vec{u}}{\cancel{c} \vec{u} \cdot \vec{u}} \cancel{c} \vec{u}$$

example

$$\vec{y} = \begin{bmatrix} 2 \\ 3 \end{bmatrix} \quad \vec{u} = \begin{bmatrix} 1 \\ -5 \end{bmatrix}$$

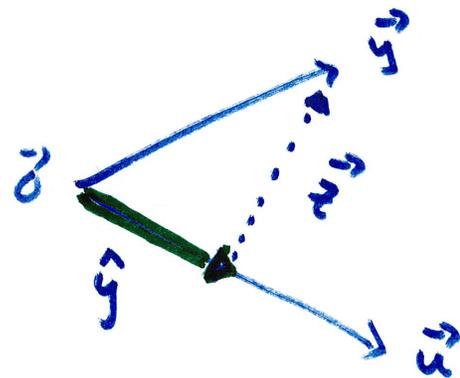
write \vec{y} as $\vec{y} = \hat{y} + \vec{z}$

$$\hat{y} = \frac{\begin{bmatrix} 2 & 3 \end{bmatrix} \begin{bmatrix} 1 \\ -5 \end{bmatrix}}{\begin{bmatrix} 1 & -5 \end{bmatrix} \begin{bmatrix} 1 \\ -5 \end{bmatrix}} \begin{bmatrix} 1 \\ -5 \end{bmatrix} = \frac{-13}{26} \begin{bmatrix} 1 \\ -5 \end{bmatrix} = \begin{bmatrix} -1/2 \\ 5/2 \end{bmatrix}$$

$$\vec{z} = \vec{y} - \hat{y} = \begin{bmatrix} 2 \\ 3 \end{bmatrix} - \begin{bmatrix} -1/2 \\ 5/2 \end{bmatrix}$$

$$= \begin{bmatrix} 5/2 \\ 1/2 \end{bmatrix}$$

$$\vec{y} = \begin{bmatrix} 2 \\ 3 \end{bmatrix} = \begin{bmatrix} -1/2 \\ 5/2 \end{bmatrix} + \begin{bmatrix} 5/2 \\ 1/2 \end{bmatrix}$$



notice $\|\vec{z}\|$ is the shortest distance from $(2, 3)$
to the line through $(0, 0)$ and $(1, -5)$

If $\{\vec{u}_1, \dots, \vec{u}_p\}$ is an orthogonal set and
 $\|\vec{u}_i\| = 1$ for all i , then the set is an
orthonormal set

orthogonal \rightarrow lin. indep.

lin. indep. \rightarrow orthogonal?

No,



lin indep.

but not

orthogonal