

Exam 1

Average : 74

A: 86

B: 73

C: 60

D: 50

4.5 The Dimension of a Vector Space

4.4: a vector space V with basis B containing n vectors is isomorphic to \mathbb{R}^n

example: the standard basis of \mathbb{P}_3 is $B = \{1, t, t^2, t^3\}$
a typical element in \mathbb{P}_3 is $\vec{p}(t) = a_0 + a_1 t + a_2 t^2 + a_3 t^3$
it behaves and acts like a vector in \mathbb{R}^4 $\vec{p} = \begin{bmatrix} a_0 \\ a_1 \\ a_2 \\ a_3 \end{bmatrix}$

$$\vec{p}(t) = a_0 + a_1 t + a_2 t^2 + a_3 t^3$$

$$\vec{q}(t) = b_0 + b_1 t + b_2 t^2 + b_3 t^3$$

$$\vec{p} + \vec{q} = (a_0 + b_0) + (a_1 + b_1)t + (a_2 + b_2)t^2 + (a_3 + b_3)t^3$$

same as $\vec{p} = \begin{bmatrix} a_0 \\ a_1 \\ a_2 \\ a_3 \end{bmatrix}$ $\vec{q} = \begin{bmatrix} b_0 \\ b_1 \\ b_2 \\ b_3 \end{bmatrix}$

$$\vec{p} + \vec{q} = \begin{bmatrix} a_0 + b_0 \\ a_1 + b_1 \\ a_2 + b_2 \\ a_3 + b_3 \end{bmatrix}$$

same for
scalar multiplication

If a vector space V has a basis $B = \{b_1^{\rightarrow}, \dots, b_n^{\rightarrow}\}$,
then any set in V containing more than n vectors
must be linearly dependent.

why? each b_i^{\rightarrow} is $n \times 1$

if we have m vectors, where $m > n$, then the
matrix $A = [b_1^{\rightarrow}, \dots, b_m^{\rightarrow}]$ has n rows and m
columns, and A ~~can have~~ has n pivots
but there are m columns, so there are free variables
in $A\vec{x} = \vec{0} \rightarrow$ dependent set.

The number of basis vectors is called the dimension of the vector space. Vector spaces can be finite-dimensional or infinite-dimensional.

example: all continuous functions.

we already know about $\dim \text{Col } A$ and $\dim \text{Nul } A$

of
basic variables

of free variables

example: How many dimensions does a subspace of all \mathbb{P}_{10} whose 5th and 7th coefficients are the same have?

10. Because \mathbb{P}_{10} has 11 coefficients, but we can only freely choose 10 of them.

example The first 3 Chebyshev polynomials are
 $1, t, 2t^2 - 1$. Can $\hat{\mathbb{R}}^3$ form a basis for \mathbb{P}_2 ?
these

\mathbb{P}_2 is 3-dimensional, ~~and~~ $a_0 + a_1 t + a_2 t^2$.

The standard basis: $\{1, t, t^2\}$

$\{1, t, 2t^2 - 1\}$ has 3 vectors, and we know from earlier results if these vectors are linearly ~~and~~ independent, then they must form a basis.

→ rewrite as vectors using $\{1, t, t^2\}$ as "coordinates" in $\hat{\mathbb{R}}^3$

$$\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \quad \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \quad \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

$$\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \quad \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \quad \begin{bmatrix} -1 \\ 0 \\ 2 \end{bmatrix}$$

$$\begin{bmatrix} \boxed{1} & 0 & -1 \\ 0 & \boxed{1} & 0 \\ 0 & 0 & \boxed{2} \end{bmatrix}$$

3 pivots, 3 vectors, so linearly independent

so $\{1, t, 2t^2 - 1\}$ must be a basis for \mathbb{P}_2

Spanning Set Theorem allows us to make basis by

throwing out linearly dependent ones: e.g. $\left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \end{bmatrix} \right\}$

is NOT basis for \mathbb{R}^2

but $\left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right\}$

is.

Like wise, we can add linearly independent vectors to make basis for a subspace

$$\left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix} \right\}$$

add $\begin{bmatrix} 0 \\ 1 \end{bmatrix}$ (indep from existing ones)

$$\left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right\} \text{ is basis for } \mathbb{R}^2$$