

$$(a+bi) \pm (c+di) = (a+c) \pm (b+d)i$$

$$(a+bi)(c+di) = ac + adi + cbi + bdi^2 \quad \nearrow -1$$

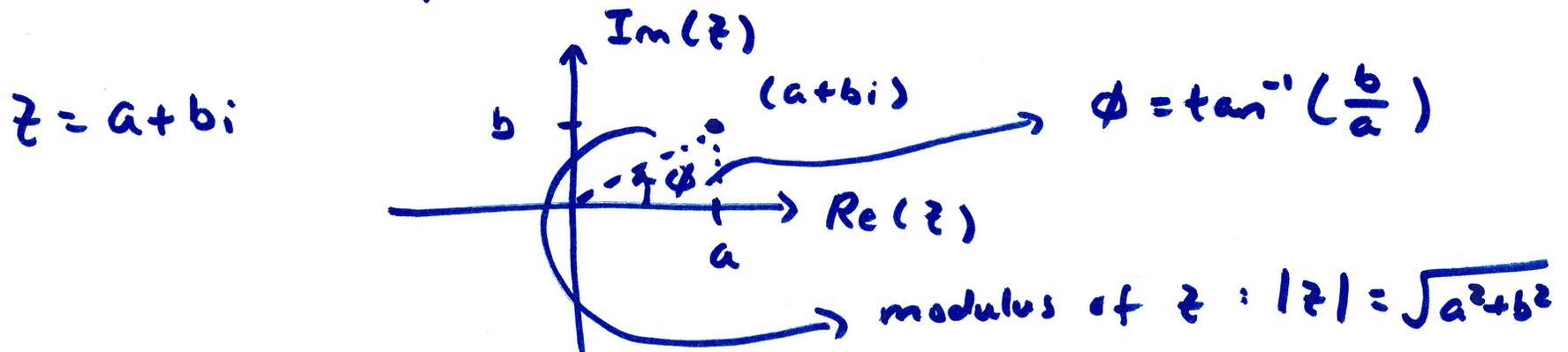
$$= (ac - bd) + (ad + cb)i$$

division is not like polynomials

$$\frac{1+2i}{3+4i} = \frac{1+2i}{3+4i} \cdot \frac{3-4i}{3-4i} = \frac{(1+2i)(3-4i)}{(3+4i)(3-4i)}$$

$$= \frac{3-4i+6i-8i^2}{9-12i+12i-16i^2} = \frac{11+2i}{25} = \frac{11}{25} + \frac{2}{25}i$$

$a+bi$ can be interpreted like a vector in \mathbb{R}^2



polar form : $z = a + bi = r e^{i\phi}$ where r, ϕ defined
as on last page
 $= r (\cos \phi + i \sin \phi)$

de Moivre's Theorem : $z = r (\cos \phi + i \sin \phi)$

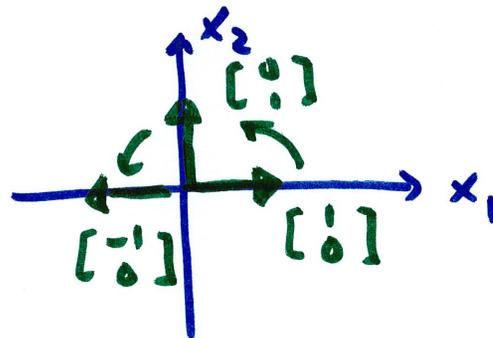
then $z^k = r^k (\cos k\phi + i \sin k\phi)$

5.5 Complex Eigenvalues

$$A = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$$

what does this do to \vec{x} ?

$$A \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$



$$A \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \begin{bmatrix} -1 \\ 0 \end{bmatrix}$$

this is a quarter circle turn counterclockwise

$$A \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} -y \\ x \end{bmatrix} \quad \text{no vector can preserve heading}$$

$$A\vec{x} = \lambda\vec{x} \quad \lambda = ?$$

find λ 's: $|A - \lambda I| = 0$ $A = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$

$$\begin{vmatrix} -\lambda & -1 \\ 1 & -\lambda \end{vmatrix} = \lambda^2 + 1 = 0 \rightarrow \lambda = \pm i$$

find eigenvectors

$$\lambda = i \quad (A - \lambda I)\vec{x} = \vec{0} \quad \begin{bmatrix} -i & -1 & 0 \\ 1 & -i & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & -i & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

x_2 free $x_1 = ix_2$ choose $x_2 = 1$

$$\vec{v} = \begin{bmatrix} i \\ 1 \end{bmatrix}$$

$$\lambda = -i \quad (A - \lambda I)\vec{x} = \vec{0}$$

$$\begin{bmatrix} i & -1 & 0 \\ 1 & i & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & i & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

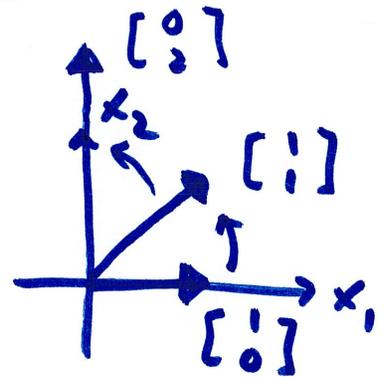
x_2 free $x_1 = -ix_2$ choose $x_2 = 1$

$$\vec{v} = \begin{bmatrix} -i \\ 1 \end{bmatrix}$$

note λ 's and \vec{v} 's are complex conjugate pairs.

Complex λ 's are associated with rotation, but there can be scaling, too.

$$A = \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix} \quad A \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$
$$A \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 2 \end{bmatrix}$$



45° ccw turn with a lengthening by a factor of $\sqrt{2}$

eigenvalues tell us this

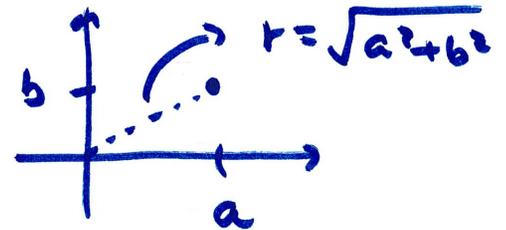
$$\begin{vmatrix} 1-\lambda & -1 \\ 1 & 1-\lambda \end{vmatrix} = 0 \quad (1-\lambda)^2 + 1 = 0 \quad 1-\lambda = i \quad \text{or} \quad 1-\lambda = -i$$
$$\lambda = 1-i \quad \text{or} \quad \lambda = 1+i$$

$\lambda = a + bi$ then the scaling factor is $\sqrt{a^2 + b^2}$

$\phi = \tan^{-1}\left(\frac{b}{a}\right)$ is the turning angle

rotation matrix : $\begin{bmatrix} a & -b \\ b & a \end{bmatrix}$ a, b real, not both zero

$$\begin{bmatrix} a & -b \\ b & a \end{bmatrix} = r \begin{bmatrix} a/r & -b/r \\ b/r & a/r \end{bmatrix}$$



$$= \begin{bmatrix} r & 0 \\ 0 & r \end{bmatrix} \begin{bmatrix} \cos \phi & -\sin \phi \\ \sin \phi & \cos \phi \end{bmatrix}$$

↳ scaling factor

$\phi = \tan^{-1}\left(\frac{b}{a}\right)$
turning angle

example

$$A = \begin{bmatrix} 1 & -2 \\ 1 & 3 \end{bmatrix}$$

$$\lambda = 2 + i$$

$$\vec{v} = \begin{bmatrix} -1 + i \\ 1 \end{bmatrix}$$

$$\lambda = 2 - i$$

$$\vec{v} = \begin{bmatrix} -1 - i \\ 1 \end{bmatrix}$$

$$\lambda = a \pm bi$$

here, $a=2$, $b=1$

$$r = \sqrt{a^2 + b^2} = \sqrt{5}$$

$$\text{define } C = \begin{bmatrix} a & -b \\ b & a \end{bmatrix} = \begin{bmatrix} 2 & -1 \\ 1 & 2 \end{bmatrix}$$

this is
hidden inside A

we can decompose A much like how we diagonalize matrices

$$A = P C P^{-1}$$

↳ not diagonal, but a rotation matrix

eigenvectors: $\begin{bmatrix} -1+i \\ 1 \end{bmatrix}, \begin{bmatrix} -1-i \\ 1 \end{bmatrix}$ separate real and imag parts

$$\vec{v} = \begin{bmatrix} -1 \\ 1 \end{bmatrix} \pm i \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

↓ use as columns of P

$$P = \begin{bmatrix} -1 & 1 \\ 1 & 0 \end{bmatrix} \quad P^{-1} = \begin{bmatrix} 0 & 1 \\ 1 & 1 \end{bmatrix} \quad C = \begin{bmatrix} 2 & -1 \\ 1 & 2 \end{bmatrix}$$

$$A = \begin{bmatrix} 1 & -2 \\ 1 & 3 \end{bmatrix} = P C P^{-1} = \begin{bmatrix} -1 & 1 \\ 1 & 0 \end{bmatrix} \underbrace{\begin{bmatrix} 2 & -1 \\ 1 & 2 \end{bmatrix}}_{\text{scaling + rotation}} \begin{bmatrix} 0 & 1 \\ 1 & 1 \end{bmatrix}$$

$$A\vec{x} = P \underbrace{C P^{-1}}_{\text{change of coordinates/variables}} \vec{x}$$

$$\underbrace{\hspace{10em}}_{\text{scale, rotate}}$$

$$\underbrace{\hspace{10em}}_{\text{undo change of variables/coordinates}}$$

λ , if complex, must come in pairs.

$$A = \begin{bmatrix} 4 & 0 & 0 \\ 0 & 1 & -1 \\ 0 & 5 & -3 \end{bmatrix}$$

pairs of complex λ 's

$$\lambda = -1+i, -1-i, 4$$

$$\vec{v} = \underbrace{\begin{bmatrix} 0 \\ 2/5 + 1/5i \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 2/5 - 1/5i \\ 1 \end{bmatrix}}_{\text{pairs}}, \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$