

7.1 + 7.2 Systems of First Order Linear Eqs

Solve multiple DE's simultaneously

$$x_1'(t) = 2x_1(t) + 5x_2(t) \quad x_1(t) = ?$$

$$x_2'(t) = -x_1(t) + x_2(t) \quad x_2(t) = ?$$

these equations are coupled because $x_1(t)$ and $x_2(t)$ depend on each other

these are also homogeneous because there are no other functions of t or constants on right side

nonhomogeneous:

$$x_1'(t) = 2x_1(t) + 5x_2(t) + \underline{\cos(t)}$$

$$x_2'(t) = -x_1(t) + x_2(t) - \underline{5}$$

An n th-order DE can be expressed as system of n first-order DEs

Example $y'' + \frac{1}{2}y' + 2y = \sin(t)$

2nd order \rightarrow sys of 2 first order eqs.

let $x_1(t) = y$

$$x_2(t) = y'$$

write DEs for these

$$x_1'(t) = y' = x_2(t)$$

$$x_2'(t) = y'' = -\frac{1}{2}y' - 2y + \sin(t)$$

$$= -\frac{1}{2}x_2(t) - 2x_1(t) + \sin(t)$$

Equivalent system:

$$x_1'(t) = x_2(t)$$

$$x_2'(t) = -2x_1(t) - \frac{1}{2}x_2(t) + \sin(t)$$

Example

$$y^{(4)} - y = 0$$

4th-order \rightarrow sys. of 4 first-order

$$x_1(t) = y$$

$$x_2(t) = y'$$

$$x_3(t) = y''$$

$$x_4(t) = y'''$$

$$x_1' = x_2$$

$$x_2' = x_3$$

$$x_3' = x_4$$

$$x_4' = x_1$$

Reverse is a little more complicated

example $x_1' = -2x_1 + x_2 \quad - \textcircled{1}$

$$x_2' = x_1 - 2x_2 \quad - \textcircled{2}$$

turn into a 2nd-order eq.

from $\textcircled{1}$, solve for x_2 (appears only once)

$$x_2 = x_1' + 2x_1 \quad \text{sub into } \textcircled{2}$$

$$x_1'' + 2x_1' = x_1 - 2(x_1' + 2x_1) \quad \text{no } x_2 \text{ here}$$

$$x_1'' + 2x_1' = x_1 - 2x_1' - 4x_1$$

$$x_1'' + 4x_1' + 3x_1 = 0 \quad \rightarrow \text{equivalent 2nd-order eq. in } x_1$$

(can do the same for x_2)

$$\text{solve } x_1'' + 4x_1' + 3x_1 = 0$$

$$(r + 3)(r + 1) = 0 \quad r = -1, r = -3$$

$$x_1(t) = c_1 e^{-t} + c_2 e^{-3t}$$

$$x_2 = x_1' + 2x_1 \quad (\text{from earlier step})$$

$$= -c_1 e^{-t} - 3c_2 e^{-3t} + 2c_1 e^{-t} + 2c_2 e^{-3t}$$

$$x_2 = c_1 e^{-t} - c_2 e^{-3t}$$

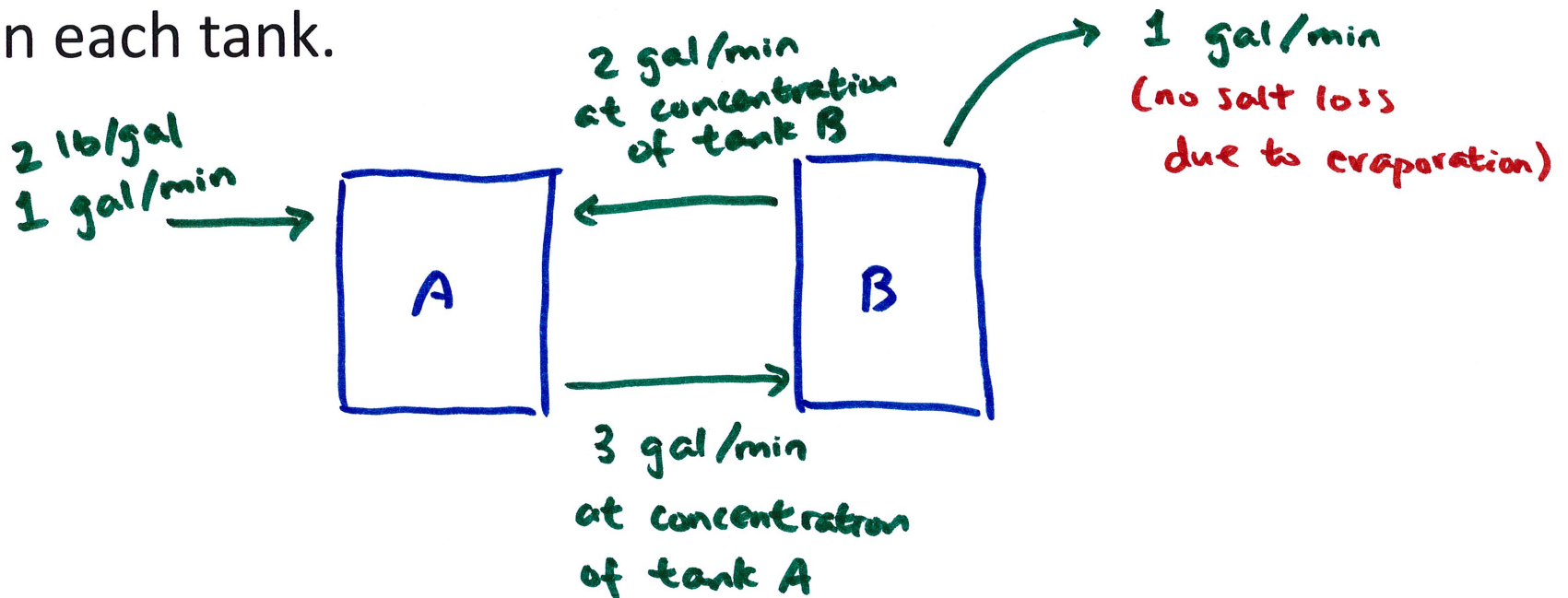
this process can be used (in principle) to solve any system.

but can be cumbersome

usually use techniques based on linear algebra.

another example before linear algebra review.

- There are two 100-gallon tanks both initially full of pure water. Water containing salt at a concentration of 2 lb/gal flows into tank A from an outside source at 1 gal/min. The well-mixed water flows from tank A to tank B at 3 gal/min. Water evaporates from tank B at 1 gal/min and is also piped back to tank A at 2 gal/min. Write a system describing the rate of change of the amount of salt in each tank.



$Q_1(t)$: salt (in lb) in A

$Q_2(t)$: " " " B

$$Q_1' = (\text{rate in}) - (\text{rate out})$$

$$= (2 \text{ lb/gal})(1 \text{ gal/min}) + (2 \text{ gal/min})\left(\frac{Q_2}{100}\right) - (3 \text{ gal/min})\left(\frac{Q_1}{100}\right)$$

$$Q_2' = (3 \text{ gal/min})\left(\frac{Q_1}{100}\right) - (2 \text{ gal/min})\left(\frac{Q_2}{100}\right)$$

$$Q_1' = 2 - \frac{3}{100}Q_1 + \frac{1}{50}Q_2$$

$$Q_2' = \frac{3}{100}Q_1 - \frac{1}{50}Q_2$$

initial conditions: $Q_1(0) = 0$

$$Q_2(0) = 0$$

Review of Matrices

$$A = \begin{bmatrix} 1 & 4 \\ -2 & 3 \end{bmatrix}$$

book notation: $\begin{pmatrix} 1 & 4 \\ -2 & 3 \end{pmatrix}$

$$B = \begin{bmatrix} 3 & -1 \\ 6 & -2 \end{bmatrix}$$

$$C = \begin{bmatrix} 3 \\ -1 \end{bmatrix}$$

can add/subtract matrices of the same size

$A \pm B$ are meaningful but $B \pm C$ are not

$$A + B = \begin{bmatrix} 4 & 3 \\ 4 & 1 \end{bmatrix}$$

multiplication: inner dimensions must match

$$\begin{bmatrix} 1 & 4 \\ -2 & 3 \end{bmatrix} \begin{bmatrix} 3 & -1 \\ 6 & -2 \end{bmatrix} = \begin{bmatrix} 27 & -9 \\ 12 & -4 \end{bmatrix}$$

2×2 2×2
R C

$$\begin{bmatrix} 3 \\ -1 \end{bmatrix} \begin{bmatrix} 1 & 4 \\ -2 & 3 \end{bmatrix} \text{ is meaningless}$$

2×1 2×2
not the same

but $\begin{bmatrix} 1 & 4 \\ -2 & 3 \end{bmatrix} \begin{bmatrix} 3 \\ -1 \end{bmatrix}$ is ok.

inverse of matrices

$$A^{-1}A = I \text{ (identity)}$$

$$AA^{-1} = I$$

but recall $AB \neq BA$ in general
for arbitrary A, B

$$A = \begin{bmatrix} 1 & 4 \\ -2 & 3 \end{bmatrix}$$

$$A = \left[\begin{array}{cc|cc} 1 & 4 & 1 & 0 \\ -2 & 3 & 0 & 1 \end{array} \right]$$

do row ops to make
left $\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$, right is A^{-1}

$$\left[\begin{array}{cc|cc} 1 & 4 & 1 & 0 \\ 0 & 11 & 2 & 1 \end{array} \right]$$

$$\left[\begin{array}{cc|cc} 1 & 0 & 3/11 & -4/11 \\ 0 & 1 & 2/11 & 1/11 \end{array} \right]$$

$$\text{so } A^{-1} = \begin{bmatrix} 3/11 & -4/11 \\ 2/11 & 1/11 \end{bmatrix}$$