

### 3.3 Complex Roots of the Char. Eq.

$$\underbrace{y'' + y = 0}_{r^2 + 1 = 0} \quad r^2 + 1 = 0 \quad r = i, -i \quad i^2 = -1 \quad i = \sqrt{-1}$$

$y$  such that it is the negative of its 2nd derivative

$$\rightarrow y = \cos(t), \quad y = \sin(t)$$

Solution:  $y = e^{rt}$      $y_1 = e^{it}$      $y_2 = e^{-it}$

$\cos(t), \sin(t)$  somehow?

how does this work?

$$e^t = 1 + t + \frac{t^2}{2!} + \frac{t^3}{3!} + \frac{t^4}{4!} + \dots + \frac{t^n}{n!} + \dots$$

$$e^{(it)} = 1 + it - \frac{t^2}{2!} - \frac{it^3}{3!} + \frac{t^4}{4!} + \frac{it^5}{5!} + \frac{-t^6}{6!} + \dots$$

$$= \left(1 - \frac{t^2}{2!} + \frac{t^4}{4!} - \frac{t^6}{6!} + \dots\right) + i \left(t - \frac{t^3}{3!} + \frac{t^5}{5!} + \dots\right)$$

   $e^{it} = \cos(t) + i \sin(t)$

Euler's Formula

$$y'' + y = 0 \quad r = \pm i$$

$$y_1 = e^{it} = \underline{\cos(t)} + i\underline{\sin(t)}$$

$$\begin{aligned}y_2 = e^{-it} &= e^{i(c-t)} = \cos(-t) + i \sin(-t) \\&= \underline{\cos(t)} - i\underline{\sin(t)}\end{aligned}$$

general solution:  $y = c_1 y_1 + c_2 y_2$  is real for real-valued

$$\underbrace{c_1, c_2}_{y(t_0) = y_0, y'(t_0) = y'_0}$$

expression contains  $i$

usually, we don't want  $i$  in our real-valued solutions

notice the real part and imaginary part ( $\cos(t)$ ,  $\sin(t)$ )  
are themselves solutions to  $y'' + y = 0$

so, it's equally valid to say  $y_1 = \cos(t)$ ,  $y_2 = \sin(t)$

→ use the real and imaginary parts of either solution  
as the fundamental solutions

example  $y'' + 2y' + 2y = 0$

$$r^2 + 2r + 2 = 0$$

$$r = \frac{-2 \pm \sqrt{2^2 - 4(1)(2)}}{2(1)} = \frac{-2 \pm \sqrt{-4}}{2} = \frac{-2 \pm 2i}{2} = -1 \pm i$$

form one solution using  $e^{rt}$ , extract real and imag. parts  
as fundamental solutions

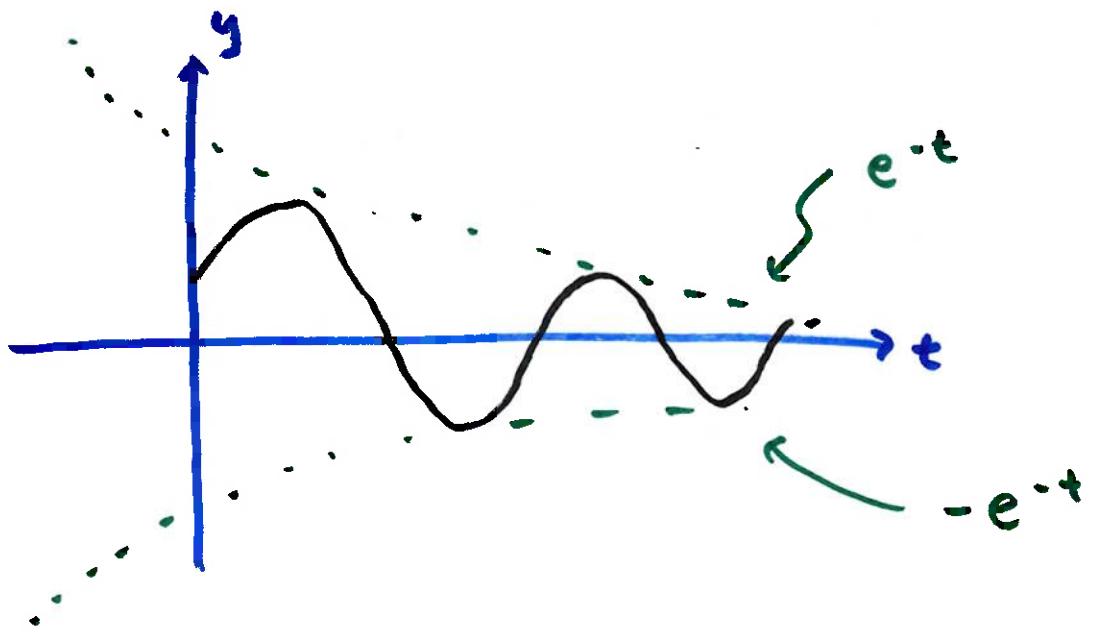
$$\begin{aligned} e^{(-1+i)t} &= e^{-t} e^{it} = e^{-t} (\cos(t) + i \sin(t)) \\ &= \boxed{e^{-t} \cos(t)} + i \boxed{e^{-t} \sin(t)} \end{aligned}$$

so, fundamental solutions are  $y_1 = e^{-t} \cos(t)$

$$y_2 = e^{-t} \sin(t)$$

general solution

$$y = c_1 e^{-t} \cos(t) + c_2 e^{-t} \sin(t)$$



### 3.4 Repeated Roots, Reduction of Order

$$y'' - 2y' + y = 0$$

$$r^2 - 2r + 1 = 0 \quad (r-1)(r-1) = 0 \quad r = 1, 1$$

$$y_1 = e^{rt} = e^t$$

$$y_2 = e^{r_2 t} = e^t ?$$

$$W[y_1, y_2] = \begin{vmatrix} e^t & e^t \\ e^t & e^t \end{vmatrix} = 0$$

cannot  
find  $C_1, C_2$   
to meet the  
initial condition  
to find a  
unique solution

$y_2$  must NOT be the same as  $y_1$ .

$$y_2 = ?$$

Reduction of Order (due to D'Alembert)

$$y_2 = v(t) y_1$$

to find  $v(t)$ , sub  $y_2 = v(t)y_1$  into the diff. eq.

$$y'' - 2y' + y = 0$$

$$y_1 = e^t$$

$$y_2 = ve^t$$

$$y_2' = ve^t + v'e^t$$

$$\begin{aligned}y_2'' &= ve^t + v'e^t + v'e^t + v''e^t \\&= ve^t + 2v'e^t + v''e^t\end{aligned}$$

$$\cancel{ve^t} + \cancel{2v'e^t} + \cancel{v''e^t} - 2\cancel{ve^t} - 2\cancel{v'e^t} + \cancel{ye^t} = 0$$

$$v'' = 0$$

$v = at + b$  we can use ANY  $a, b$  ( $a \neq 0$ ) as  $v$  for  $y_2 = vg_1$ ,

let's use  $v = t$

$$\text{then } y_1 = e^t$$

$$y_2 = te^t$$

$$w[y_1, y_2] = \begin{vmatrix} e^t & te^t \\ e^t & te^t + e^t \end{vmatrix}$$

$$= te^{2t} + e^{2t} - te^{2t} = e^{2t} \neq 0 \text{ (good!)}$$

if the differential eq. has constant coefficient

$y_2 = t y_1$  is ALWAYS a valid 2nd solution.

but Reduction of Order can be used to find missing solution even for non-constant coefficients

$$t^2 y'' + t y' - 9y = 0 \quad (\text{this is an example of Euler's equation})$$

has one solution  $y_1 = t^3$  (somehow we found this)

$$y_2 = ?$$

$$y_2 = v y_1 = vt^3$$

$$y_2' = 3vt^2 + v't^3$$

$$y_2'' = 6vt + 6v't^2 + v''t^3$$

$$t^2(6vt + 6v't^2 + v''t^3) + t(3vt^2 + v't^3) - 9(vt^3) = 0$$

:

$$t^5 v'' + 7v't^4 = 0$$

$$v'' = -\gamma v' t^{-1} \quad v'' = \frac{d(v')}{dt}$$

$$\frac{d(v')}{dt} = -\frac{\gamma v'}{t} \quad \text{separable in } v' \text{ and } t$$

$$\text{solve for } v' \dots \quad v' = C t^{-\gamma}$$

$$\text{then } v = -\frac{C}{\gamma} t^{-\gamma} + d \quad \text{choose } C = -6, d = 0$$

$$v = t^{-6}$$

$$\text{so } y_2 = v y_1 = t^{-6} \cdot t^3 = t^{-3}$$