

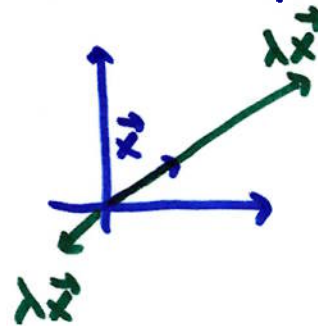
Review of Linear Algebra (continued)

eigenvalues and eigenvectors

matrix A ($n \times n$) has eigenvalues (λ) and eigenvectors ($\vec{x}$)

such that $A\vec{x} = \lambda\vec{x}$

eigenvectors preserve their directions



λ scales the length
but retains direction

for example, $A = \begin{bmatrix} 5 & 0 \\ 2 & 1 \end{bmatrix}$

one eigenvector is $\begin{bmatrix} 2 \\ 1 \end{bmatrix}$

$$\begin{bmatrix} 5 & 0 \\ 2 & 1 \end{bmatrix} \begin{bmatrix} 2 \\ 1 \end{bmatrix} = \begin{bmatrix} 10 \\ 5 \end{bmatrix} = 5 \begin{bmatrix} 2 \\ 1 \end{bmatrix}$$

A $\vec{x}$

lengthened by factor of 5
(eigenvalue)

to find the eigenvalues and eigenvectors, we work with

$$A\vec{x} = \lambda\vec{x}$$

$$A\vec{x} - \lambda\vec{x} = \vec{0}$$

$$(A - \lambda I)\vec{x} = \vec{0}$$

homogeneous system: $\vec{x} = \vec{0}$ is a solution
but we don't want that

must have infinitely-many solutions to have non trivial solutions

→ $\boxed{\det(A - \lambda I) = 0}$ solve for λ : n of these for an
 $n \times n$ matrix A

then solve for $\boxed{(A - \lambda I)\vec{x} = \vec{0}}$ using those λ 's
for $\vec{x}$

$$A = \begin{bmatrix} 7 & 4 \\ -3 & -1 \end{bmatrix}$$

$$\det(A - \lambda I) = \begin{vmatrix} 7-\lambda & 4 \\ -3 & -1-\lambda \end{vmatrix} = 0$$

$$(7-\lambda)(-1-\lambda) + 12 = 0$$

$$\lambda^2 - 6\lambda + 5 = 0 \quad \text{characteristic equation}$$

$$(\lambda - 5)(\lambda - 1) = 0$$

$$\boxed{\lambda = 1, \quad \lambda = 5}$$

find the corresponding eigenvectors

$$\lambda = 1 : (A - \lambda I)\vec{x} = \vec{0}$$

$$\left[\begin{array}{cc|c} 6 & 4 & 0 \\ -3 & -2 & 0 \end{array} \right] \rightarrow \dots \rightarrow \left[\begin{array}{cc|c} -3 & -2 & 0 \\ 0 & 0 & 0 \end{array} \right]$$

$$\vec{x} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

2nd row of $(A - \lambda I)\vec{x} = \vec{0} \rightarrow x_2$ is free
 $x_2 = r$

1st row : $-3x_1 - 2x_2 = 0$

$$x_1 = -\frac{2}{3}x_2 = -\frac{2}{3}r$$

$$\vec{x} = \begin{bmatrix} -\frac{2}{3}r \\ r \end{bmatrix}$$

choose any nonzero r

$$r = -3$$

$$\boxed{\vec{x} = \begin{bmatrix} 2 \\ -3 \end{bmatrix}, \lambda = 1}$$

following same steps for $\lambda = 5$

we get

$$\boxed{\vec{x} = \begin{bmatrix} -2 \\ 1 \end{bmatrix}, \lambda = 5}$$

$$A = \begin{bmatrix} 4 & 0 & 1 \\ -2 & 1 & 0 \\ -2 & 0 & 1 \end{bmatrix}$$

$$\det(A - \lambda I) = 0 \quad \begin{vmatrix} 4-\lambda & 0 & 1 \\ -2 & 1-\lambda & 0 \\ -2 & 0 & 1-\lambda \end{vmatrix} = 0$$

cofactor expansion
(here, along col 2)

$$(1-\lambda) \begin{vmatrix} 4-\lambda & 1 \\ -2 & 1-\lambda \end{vmatrix} = 0$$

$$(1-\lambda) [(4-\lambda)(1-\lambda) + 2] = 0$$

$$(1-\lambda)(\lambda^2 - 5\lambda + 6) = 0$$

$$(1-\lambda)(\lambda - 2)(\lambda - 3) = 0$$

$$\boxed{\lambda = 1, 2, 3}$$

$$\lambda = 1: (A - \lambda I) \vec{x} = \vec{0}$$

$$\left[\begin{array}{ccc|c} 3 & 0 & 1 & 0 \\ -2 & 0 & 0 & 0 \\ -2 & 0 & 0 & 0 \end{array} \right] \rightarrow \left[\begin{array}{ccc|c} 3 & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

$$\rightarrow \left[\begin{array}{ccc|c} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

$$x_2 = \text{free} = r$$

$$x_1 = 0$$

$$x_3 = 0$$

$$\vec{x} = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \quad \lambda = 1$$

following the same process, we get the other eigenvectors

$$\vec{x} = \begin{bmatrix} -1 \\ 2 \\ 2 \end{bmatrix} \quad \lambda = 2$$

$$\vec{x} = \begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix} \quad \lambda = 3$$

Eigenvectors are
linearly independent
from one another
(good basis vectors)

7.4 Basic Theory of Sys. of 1st-order Linear Eqs.

$$x_1' = p_{11}(t)x_1 + p_{12}(t)x_2 + \dots + p_{1n}(t)x_n + g_1(t)$$

$$x_2' = p_{21}(t)x_1 + p_{22}(t)x_2 + \dots + p_{2n}(t)x_n + g_2(t)$$

$\vdots$

$$x_n' = p_{n1}(t)x_1 + p_{n2}(t)x_2 + \dots + p_{nn}(t)x_n + g_n(t)$$

in matrix form

$$\vec{x}' = P(t) \vec{x} + \vec{g}(t) \quad \begin{bmatrix} g_1 \\ g_2 \\ \vdots \\ g_n \end{bmatrix}$$
$$\begin{bmatrix} x_1' \\ x_2' \\ \vdots \\ x_n' \end{bmatrix} = \begin{bmatrix} p_{11} & p_{12} & \dots & p_{1n} \\ & \ddots & & \\ p_{n1} & & & p_{nn} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}$$

if $\vec{g} = \vec{0}$, $\vec{x}' = P(t) \vec{x}$ is a homogeneous system

it has solutions $\vec{x}^{(1)} = \begin{bmatrix} x_{11} \\ x_{21} \\ \vdots \\ x_{n1} \end{bmatrix}$, $\vec{x}^{(2)} = \begin{bmatrix} x_{12} \\ x_{22} \\ \vdots \\ x_{n2} \end{bmatrix}$, ..., $\vec{x}^{(k)} = \begin{bmatrix} x_{1k} \\ \vdots \\ x_{nk} \end{bmatrix}$

k of these k = n

these solutions form a fundamental set of solutions

the general solution is a linear combination of the vectors in that set

$$\vec{x} = c_1 \vec{x}^{(1)} + c_2 \vec{x}^{(2)} + \dots + c_n \vec{x}^{(n)}$$

the Wronskian of the solutions is

$$W[\vec{x}^{(1)}, \vec{x}^{(2)}, \dots, \vec{x}^{(n)}] = \begin{vmatrix} \vec{x}^{(1)} & \vec{x}^{(2)} & \dots & \vec{x}^{(n)} \end{vmatrix}$$

fundamental solutions
as columns

$W(t_0) \neq 0 \rightarrow$ solutions are linearly independent at that $t = t_0$

if we have initial conditions $x_1(t_0) = x_{10}$, $x_2(t_0) = x_{20}$, ...

then there is one and only one way to form

$$\vec{x} = c_1 \vec{x}^{(1)} + c_2 \vec{x}^{(2)} + \dots + c_n \vec{x}^{(n)}$$

Abel's Theorem: if $\vec{x}^{(1)}, \vec{x}^{(2)}, \dots, \vec{x}^{(n)}$ are solutions on some interval of t , then on that interval the Wronskian is either always zero or never zero

→ only need to check ONE t on an interval to ensure nonzero W throughout that interval

true ~~has~~ related to the fact that $W' + PW = 0$

solution is $W = ce^{\int p(t) dt}$

$$\vec{x}' = \begin{bmatrix} 1 & 1 \\ 4 & -2 \end{bmatrix} \vec{x} \text{ has solutions } \left. \begin{array}{l} \vec{x}^{(1)} = \begin{bmatrix} 1 \\ -4 \end{bmatrix} e^{-3t} \\ \vec{x}^{(2)} = \begin{bmatrix} 1 \\ 1 \end{bmatrix} e^{2t} \end{array} \right\} \text{ satisfy } \vec{x}' = \begin{bmatrix} 1 & 1 \\ 4 & -2 \end{bmatrix} \vec{x}$$

$$W = \begin{vmatrix} e^{-3t} & e^{2t} \\ -4e^{-3t} & e^{2t} \end{vmatrix} = 5e^{-t} \neq 0 \text{ for any } t$$