

$$10. \quad y'' - 2y' + y = \frac{e^t}{1+t^2}$$

$$y_1 = e^t \quad y_2 = te^t$$

$$y = u_1 e^t + u_2 te^t$$

$$u_1' y_1 + u_2' y_2 = 0$$

$$u_1' y_1' + u_2' y_2' = g(t)$$

$$u_1' e^t + u_2' te^t = 0$$

$$u_1' e^t + u_2' (te^t + e^t) = \frac{e^t}{1+t^2}$$

$$u_2' e^t = \frac{e^t}{1+t^2}$$

$$u_2' = \frac{1}{1+t^2} \quad u_2 = \tan^{-1}(t) + C_2$$

$$u_1' = -u_2' t$$

$$= -\frac{t}{1+t^2}$$

$$u_1 = -\frac{1}{2} \ln |1+t^2| + C_1$$

$$J. \quad t^2 y'' - 4ty' + 4y = -2t^2 \quad y_1 = t \quad y_2 = t^4$$

$$y(1) = 2 \quad y'(1) = 0$$

$$y = u_1 y_1 + u_2 y_2$$

$$u_1' y_1 + u_2' y_2 = 0$$

$$u_1' y_1' + u_2' y_2' = g(t)$$

$$u_1' t + u_2' t^4 = 0$$

$$u_1' + 4u_2' t^3 = -2$$

$$u_1' t + 4u_2' t^4 = -2t$$

$$3u_2' t^4 = -2t$$

$$u_2' = -\frac{2}{3} t^{-3}$$

$$u_2 = +\frac{1}{3} t^{-2} + C_2$$

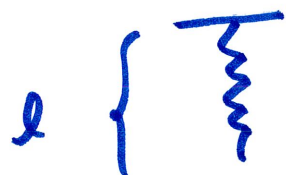
$$u_1' = -u_2' t^3$$

$$= -\left(-\frac{2}{3} t^{-3}\right) t^3 = \frac{2}{3}$$

$$u_1 = \frac{2}{3} t + C_1$$

3.7 Mechanical Vibrations

Spring with natural length of l , spring constant K



attach object mass m

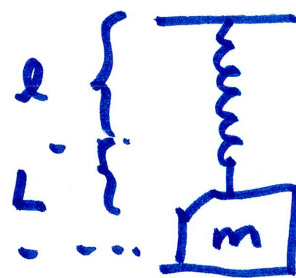
at equilibrium ($u=0$)

force due to spring $F_s = -KL$

and is equal to weight: mg

$$\text{so } mg - KL = 0$$

$$\left. \begin{array}{l} \text{if } u > 0, \quad F_s < 0 \\ u < 0, \quad F_s > 0 \end{array} \right\} F_s = -K(L+u)$$



↓ down
positive

now attach a damper that exerts a force proportional to speed in the opposite direction of velocity. (like drag)

$$F_d = -\gamma u'$$

↑ damping constant

Newton's 2nd Law: $F = ma$

$$mu'' = \underbrace{-k(L+u)}_{\text{spring}} + \underbrace{mg}_{\text{gravity}} - \underbrace{\gamma u'}_{\text{damper}}$$

$$= -KL - ku + mg - \gamma u' \quad mg - Lk = 0$$

$$mu'' + \gamma u' + ku = 0$$

Equation of Motion

$m, \gamma, k > 0$
constants

Linear, constant coeff, homogeneous

roots of char. eq.

$$mr^2 + \gamma r + k = 0$$

$$r = \frac{-\gamma \pm \sqrt{\gamma^2 - 4km}}{2m}$$

$$= -\frac{1}{2} \frac{\gamma}{m} \pm \frac{\sqrt{\gamma^2 - 4km}}{2m}$$

if $\gamma = 0$ (undamped free vibration)

$$r = \pm \frac{\sqrt{-4km}}{2m} = \pm i \sqrt{\frac{k}{m}}$$

$$u = C_1 \cos \sqrt{\frac{k}{m}} t + C_2 \sin \sqrt{\frac{k}{m}} t$$

$\sqrt{\frac{k}{m}}$: circular frequency (ω_0)

$\frac{2\pi}{\sqrt{\frac{k}{m}}}$: period (T)

if $\gamma^2 > 4km$ (overdamped \rightarrow no oscillation because roots are real) and distinct

$$u = c_1 e^{r_1 t} + c_2 e^{r_2 t}$$

need $\lim_{t \rightarrow \infty} u = 0$ from physical intuition

$$\gamma, m, k > 0 \quad \text{so} \quad \gamma^2 > \gamma^2 - 4km$$

$$r = -\frac{1}{2} \frac{\gamma}{m} \pm \frac{\sqrt{\gamma^2 - 4km}}{2m} \rightarrow \text{less than } \gamma$$

if $\gamma^2 = 4km$ (critically damped \rightarrow no oscillation) repeated roots

$$u = c_1 e^{rt} + c_2 t e^{rt} \quad r = -\frac{\gamma}{2m} < 0$$

crit. damped \rightarrow return to $u=0$ in shortest possible time

if $\gamma^2 < 4km$ (underdamped)
has oscillations

$$u = e^{-\gamma/2m t} \left(C_1 \cos \frac{\sqrt{\gamma^2 - 4km}}{2m} t + C_2 \sin \frac{\sqrt{\gamma^2 - 4km}}{2m} t \right)$$

example

mass weighing 2 lb stretches spring
6 in. no damping.

$$m u'' + \cancel{\gamma} u' + k u = 0$$

K: Hooke's Law

$$F = K x$$

↙ deviation
from natural

↙ 6 in

$$2 \text{ lb} = K \cdot \left(\frac{1}{2} \text{ ft} \right)$$

$$K = 4 \text{ lb/ft}$$

$$m: 2 \text{ lb} = m (32 \text{ ft/s}^2)$$

$$m = \frac{1}{16} \underbrace{\text{lb} \cdot \text{s}^2 / \text{ft}}_{\text{slug}}$$

$$\text{eg: } mu'' + ku = 0$$

$$\frac{1}{16} u'' + 4u = 0$$

$$u'' + 64u = 0$$

$$u = C_1 \cos 8t + C_2 \sin 8t$$

$$\text{IC: } \underbrace{u(0) = 3 \text{ in}}_{\text{pull down 3 in from equilibrium}}$$

pull down
3 in from
equilibrium

$$\underbrace{u'(0) = 3 \text{ in/s}}_{\text{downward initial velocity}}$$

downward initial
velocity

$$\vdots$$
$$C_1 = \frac{1}{4} \quad C_2 = \frac{1}{32}$$

$$u = \left(\frac{1}{4}\right) \cos 8t + \left(\frac{1}{32}\right) \sin 8t$$

freq. phase angle

rewrite as $u = R \cos(\omega_0 t - \delta)$

↑ amplitude

$$u = \underbrace{R \cos \delta}_{\text{amplitude}} \cos \omega_0 t + \underbrace{R \sin \delta}_{\text{phase angle}} \sin \omega_0 t$$

$$R \cos \delta = \frac{1}{4}$$

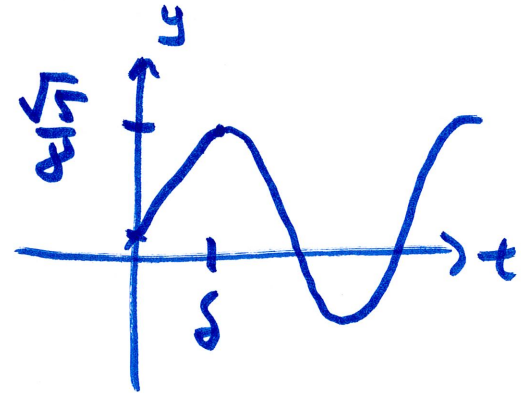
$$R \sin \delta = \frac{1}{32}$$

$$\tan \delta = \frac{1}{8}$$

$$\delta = \tan^{-1}\left(\frac{1}{8}\right)$$

$$R^2 = \left(\frac{1}{4}\right)^2 + \left(\frac{1}{32}\right)^2 = \frac{\sqrt{5}}{8}$$

$$u = \frac{\sqrt{5}}{8} \cos\left(8t - \underbrace{\tan^{-1}\left(\frac{1}{8}\right)}_{\delta}\right)$$



example $4u'' + 4u' + 37u = 0 \quad u(0)=1, u'(0)=0$

$$u'' + u' + 9.25u = 0$$

$$r = -\frac{1}{2} \pm 3i$$

underdamped

⋮

$$u(t) = e^{-\frac{1}{2}t} \left(\cos 3t + \frac{1}{6} \sin 3t \right)$$

$$R \cos(\omega t - \delta)$$

see last example

$$= e^{-\frac{1}{2}t} \frac{\sqrt{37}}{6} \left(\cos(3t) - \tan^{-1}\left(\frac{1}{6}\right) \right)$$

↳ damped frequency

"quasi-frequency"

quasi-period: $\frac{2\pi}{3}$ &

$$= \boxed{\frac{\sqrt{37}}{6} e^{-\frac{1}{2}t}} \left(\cos 3t - \tan^{-1}\left(\frac{1}{6}\right) \right)$$

