

7.1 + 7.2 Systems of First Order Linear Egs

solve more than one equation at a time

$$\begin{cases} X_1'(t) = 2X_1(t) + 5X_2(t) \\ X_2'(t) = -X_1(t) + X_2(t) \end{cases} \Rightarrow \begin{matrix} X_1(t) = ? \\ X_2(t) = ? \end{matrix}$$

(this is a coupled system — they depend on each other)

the system above is homogeneous because there are no other functions of t or other constants on the right side

this system is nonhomogeneous

$$\begin{cases} X_1'(t) = 2X_1(t) + 5X_2(t) + \cos(t) \\ X_2'(t) = -X_1(t) + X_2(t) + 5 \end{cases}$$

an n th-order differential equation can be written as a system of n first-order eqs.

example $y'' + \frac{1}{2}y' + 2y = \sin t$

this is a 2nd-order eq.

→ equivalent to sys of two 1st-order eqs.

let $x_1 = y$ $x_2 = y'$

write first-order eqs for these

$$\begin{cases} x_1' = x_2 \\ x_2' = -2x_1 - \frac{1}{2}x_2 + \sin t \end{cases}$$

$$y'' = -\frac{1}{2}y' - 2y + \sin t$$

\uparrow \uparrow \uparrow
 x_2' x_2 x_1

example (Project 1) $u'' + ku + \epsilon u^3 = 0$

in Matlab, we represented it as a system in
function file

let $x_1 = u$

$$x_2 = u'$$

$$\begin{cases} x_1' = x_2 \\ x_2' = -kx_1 - \epsilon (x_1)^3 \end{cases} \quad \text{nonlinear sys.}$$

example

$$y^{(4)} - y = 0$$

4th-order \rightarrow 4 first-order eqs.

let $x_1 = y$

$$x_2 = y'$$

$$x_3 = y''$$

$$x_4 = y'''$$

\Rightarrow lower order deriv. (0^{th} order)
step up in deriv.

until the $(n-1)^{\text{th}}$ deriv.

$$x_1' = x_2$$

$$x_2' = x_3$$

$$x_3' = x_4$$

$$x_4' = x_1$$

$$x_4' = (y''')' = y^{(4)}$$

from DE, $y^{(4)} = y$

\uparrow
 x_1

\rightarrow DE

turn sys back to nth-order DE, then solve.

example

$$X_1' = -2X_1 + X_2 \quad \text{--- (1)}$$

$$X_2' = X_1 - 2X_2 \quad \text{--- (2)}$$

what is the equivalent 2nd-order DE?

solve either for one variable

from (1)

$$X_2 = X_1' + 2X_1$$

solve for the one that
appears least often

$$X_2' = X_1'' + 2X_1'$$

sub these into (2)

$$X_1'' + 2X_1' = X_1 - 2(X_1' + 2X_1) \quad \text{no } X_2 \text{ any more}$$

$$X_1'' + 4X_1' + 3X_1 = 0$$

$$X_1(t) = C_1 e^{-t} + C_2 e^{-3t}$$

to find X_2 , use (1)

$$x_2 = x_1' + 2x_1$$

$$= -c_1 e^{-t} - 3c_2 e^{-3t} + 2(c_1 e^{-t} + c_2 e^{-3t})$$

$$x_2 = c_1 e^{-t} - c_2 e^{-3t}$$

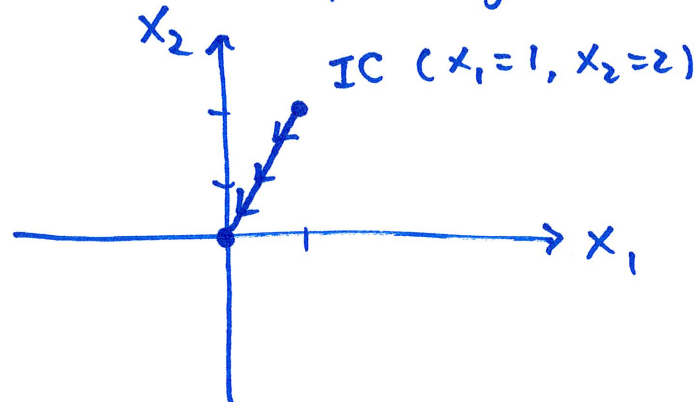
$$x_1 = c_1 e^{-t} + c_2 e^{-3t}$$

IC's: $x_1(0) = 1, x_2(0) = 2$

then $x_1 = \frac{3}{2}e^{-t} - \frac{1}{2}e^{-3t}$

$$x_2 = \frac{3}{2}e^{-t} + \frac{1}{2}e^{-3t}$$

if we graph x_1 vs x_2 , we get a phase plot.



solving systems by transforming into higher-order eqs is not hard but can be cumbersome.

→ borrow concepts from linear algebra to speed things up.

Review of Matrices

$$A = \begin{bmatrix} 1 & 4 \\ -2 & 3 \end{bmatrix}$$

$$B = \begin{bmatrix} 3 & -1 \\ 6 & 2 \end{bmatrix}$$

$$\begin{pmatrix} 1 & 4 \\ -2 & 3 \end{pmatrix} \text{ book notation}$$

$$C = \begin{bmatrix} 3 \\ -1 \end{bmatrix}$$

we can add/subtract matrices if they are of the same
size

$$A + B = \begin{bmatrix} 4 & 3 \\ 4 & 5 \end{bmatrix}$$

$$A - B = \begin{bmatrix} -2 & 5 \\ -8 & 1 \end{bmatrix}$$

$$3A = \begin{bmatrix} 3 & 12 \\ -6 & 9 \end{bmatrix}$$

$$2A + 3B = \begin{bmatrix} 11 & 5 \\ 14 & 12 \end{bmatrix}$$

multiply matrices ~~if~~ is only possible if inner dimensions match

$$A = \begin{bmatrix} 1 & 4 \\ -2 & 3 \end{bmatrix}$$

2×2
 \nearrow rows \nwarrow columns

$$B = \begin{bmatrix} 3 & -1 \\ 6 & 2 \end{bmatrix}$$

2×2

$$C = \begin{bmatrix} 3 \\ -1 \end{bmatrix}$$

2×1

$A \ C$
 $2 \times 2 \quad 2 \times 1$
 must match

$C \ A \rightarrow$ is meaningless
 $2 \times 1 \quad 2 \times 2$ (operation is
 don't match NOT allowed)

$$AC = \begin{bmatrix} 1 & 4 \\ -2 & 3 \end{bmatrix} \begin{bmatrix} 3 \\ -1 \end{bmatrix} = \begin{bmatrix} 1 \cdot 3 + 4 \cdot (-1) \\ -2 \cdot 3 + 3 \cdot (-1) \end{bmatrix} = \begin{bmatrix} -1 \\ -9 \end{bmatrix}$$

$2 \times 2 \quad 2 \times 1$
 size of AC

$$AB = \begin{bmatrix} 1 & 4 \\ -2 & 3 \end{bmatrix} \begin{bmatrix} 3 & -1 \\ 6 & 2 \end{bmatrix} = \begin{bmatrix} 27 & 7 \\ 12 & 8 \end{bmatrix}$$

$2 \times 2 \quad 2 \times 2 \quad 2 \times 2$

$AB = BA ?$ NO. In general $AB \neq BA$.

we can express systems of DEs as matrix eqs.

example

$$x_1' = -2x_1 + x_2$$

$$x_2' = x_1 - 2x_2$$

$$\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}' = \begin{bmatrix} -2 & 1 \\ 1 & -2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} -2x_1 + x_2 \\ x_1 - 2x_2 \end{bmatrix}$$

$$\text{let } \vec{x} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \quad A = \begin{bmatrix} -2 & 1 \\ 1 & -2 \end{bmatrix}$$

$$\vec{x}' = A \vec{x}$$

example

$$y^{(4)} - y = 0$$

write as matrix eq.

$$x_1 = y$$

$$x_1' = x_2$$

$$x_2 = y'$$

$$x_2' = x_3$$

$$x_3 = y''$$

$$x_3' = x_4$$

$$x_4 = y'''$$

$$x_4' = x_1$$

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix}' = \begin{bmatrix} 0x_1 + x_2 + 0x_3 + 0x_4 \\ 0x_1 + 0x_2 + x_3 + 0x_4 \\ 0x_1 + 0x_2 + 0x_3 + x_4 \\ x_1 + 0x_2 + 0x_3 + 0x_4 \end{bmatrix}$$

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix}' = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix}$$