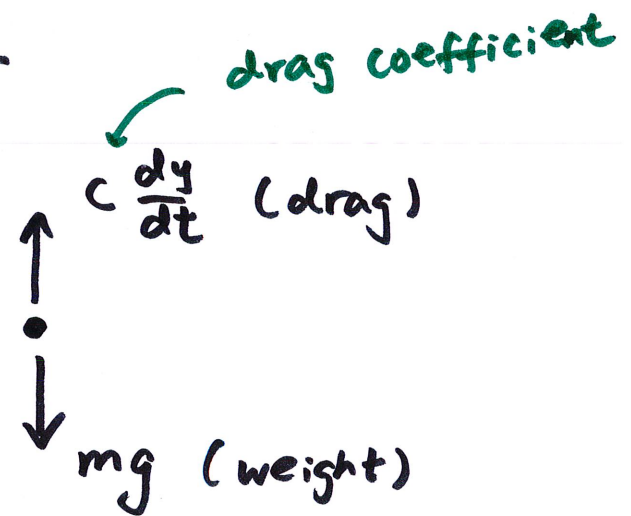


## 1.2 Solutions of Some DEs

object in free fall

$v(t) \rightarrow$  velocity ( $\frac{dy}{dt}$ )



$$\text{DE: } m \frac{dv}{dt} = mg - cv$$

$$\text{let } m = 10 \text{ kg} \quad c = 2 \text{ kg/s}$$

$$10 \frac{dv}{dt} = 98 - 2v$$

$$\frac{dv}{dt} = 9.8 - 0.2v \quad \Rightarrow \quad v(t) = ?$$

$$\text{assume: } v(0) = 0$$

$$\frac{dv}{dt} = 0.2(49 - v) = -0.2(v - 49)$$

$$\frac{1}{v-49} \frac{dv}{dt} = -0.2$$

recall from calculus,  $\frac{d}{dt} \ln |v(t) - 49| = \frac{1}{v(t) - 49} \frac{dv}{dt}$

$$\frac{d}{dt} \ln |v - 49| = -0.2$$

integrate with respect  
to  $t$

$$\ln |v - 49| = -0.2t + A \quad \leftarrow \text{constant}$$

$$e^{\ln |v - 49|} = e^{-0.2t + A}$$

$$v - 49 = e^{-0.2t} \underbrace{e^A}_{\text{also constant} = C} = C e^{-0.2t}$$

$$v = 49 + C e^{-0.2t}$$

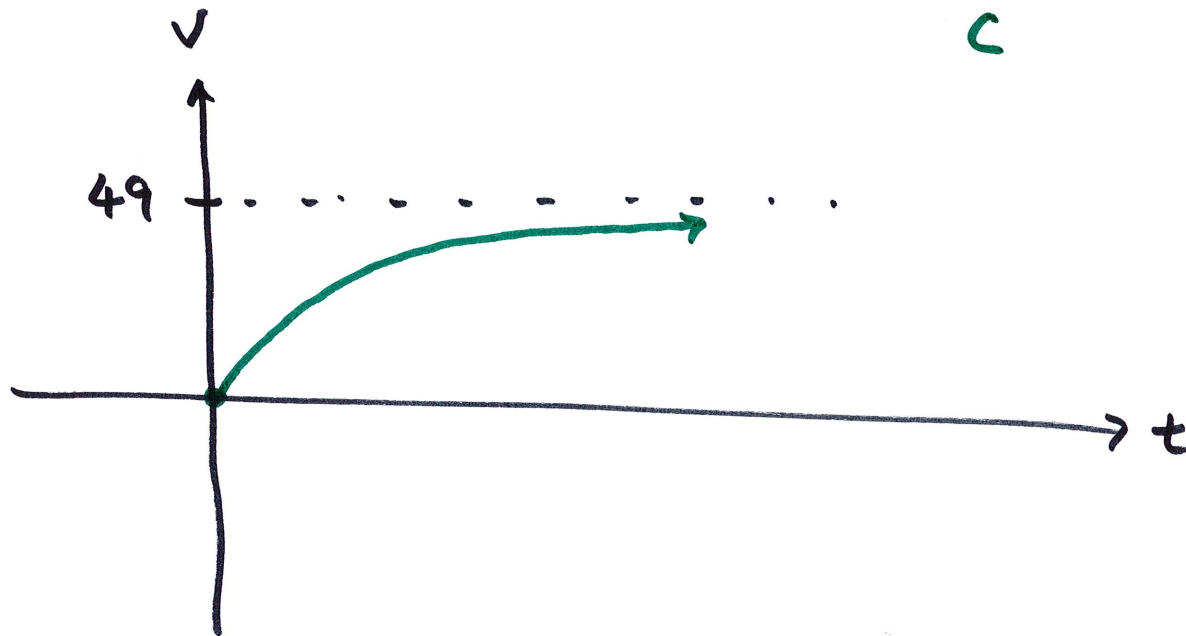
find  $C$ :  $v(0) = 0$

$$0 = 49 + C \quad \text{so} \quad C = -49$$

so  $V(t) = 49 - 49e^{-0.2t}$

note: as  $t \rightarrow \infty$   $V \rightarrow 49$  (because  $\lim_{t \rightarrow \infty} e^{-t} = 0$ )

↓  
terminal velocity  
(weight balances drag)  
 $= \frac{mg}{c}$

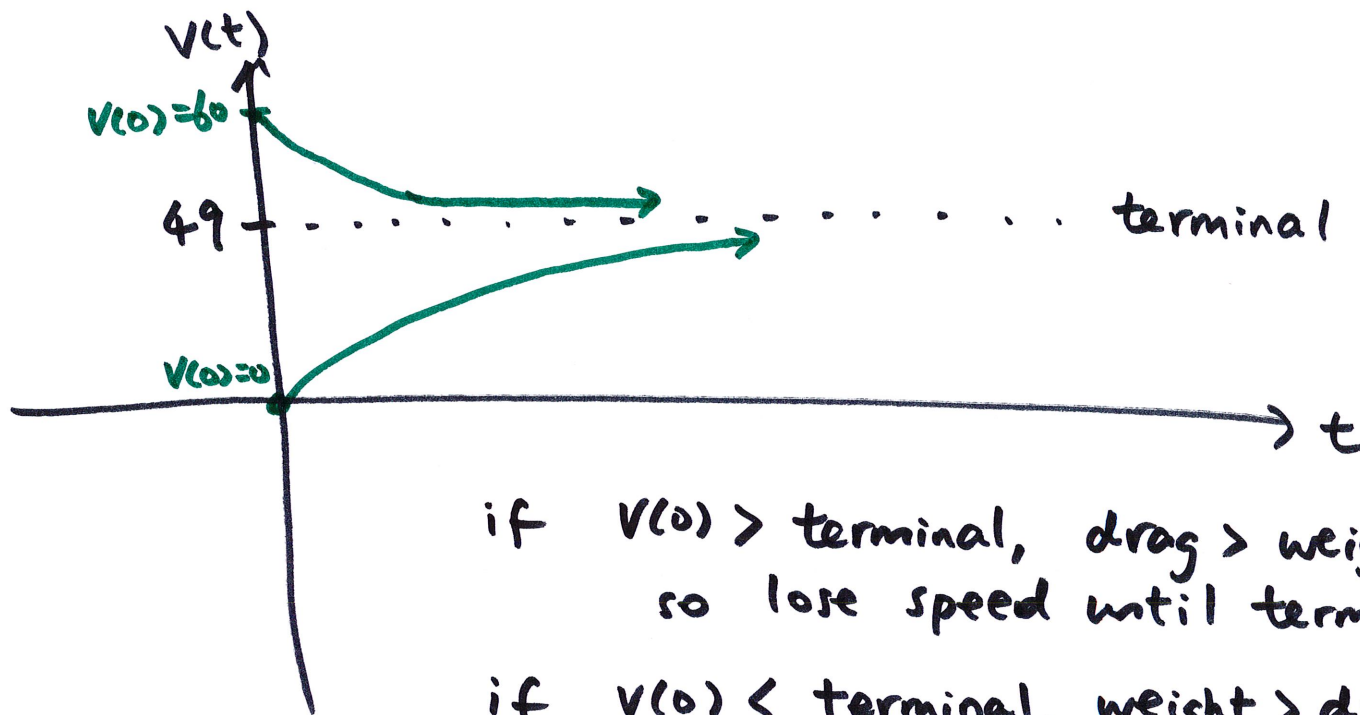


now, assume  $V(0) = V_0$

$$V(t) = 49 + C e^{-0.2t} \quad V(0) = V_0$$

$$V_0 = 49 + C \quad \text{so} \quad C = V_0 - 49$$

$$V(t) = 49 + (V_0 - 49) e^{-0.2t}$$



if  $V(0) > \text{terminal}$ , drag  $>$  weight initially,  
so lose speed until terminal

if  $V(0) < \text{terminal}$ , weight  $>$  drag initially,  
so gain speed until terminal

if  $V(0) = \text{terminal}$ , then drag = weight  
stays at terminal

we can use the same steps to solve all

equations of the form  $\frac{dy}{dt} = ay + b$

$a, b$  constants

### 1.3 Classifications of DEs

ordinary DE (ODE) : eqs with ordinary derivatives  
(no partial derivs)

partial DE (PDE) : eqs with at least one partial  
deriv.

$$\alpha^2 \frac{\partial^2 u}{\partial x^2} = \frac{\partial u}{\partial t} \quad (\text{heat equation})$$

order of DE : order is the order of the highest  
derivative in eq.

$$y'' + y' + y = 0 \quad \text{ODE of 2nd order}$$

$$\alpha^2 u_{xx} = u_t \quad \text{PDE of 1st order}$$

## linear vs nonlinear:

a DE is linear if it is a linear function  
of all its derivs of dependent variable

→ not multiplied together  
not raised to any power other than 1  
not part of transcendental functions  
(e.g. exponential  $e^y$   
sine, cosine, etc)

examples:

$y'' + y' + y = 0$	linear	"easy" to solve
$y'' + \underline{(y')^2} + y = 0$	nonlinear	"hard to solve"
$y'' + y'y + \sin(y) = 0$	nonlinear	

$$y'' + y = 0$$

linear, 2nd order ODE

$$ty'' + y = 0$$

" " "

↑  
independent variable

$$t^2 y'' + t y' = \sin(t)$$

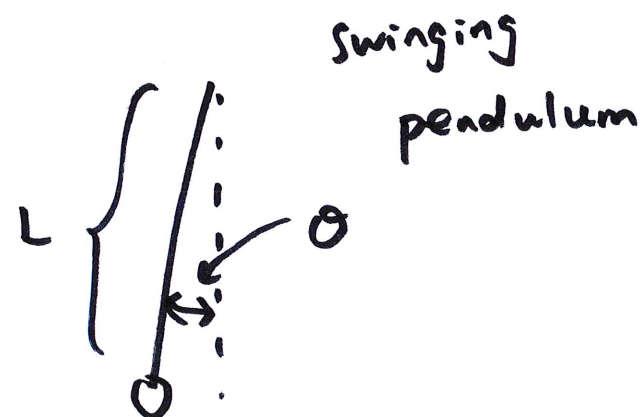
linear 2nd order ODE

transcendental  
~~at~~ but w/  
indep. var.

$$\frac{d^2 \theta}{dt^2} + \frac{g}{L} \sin(\theta) = 0$$

$\theta$ : dependent variable

nonlinear





Solution: any function that satisfies the DE

example:  $\frac{dy}{dt} = y$  function = its own deriv.

$$y = e^t \quad y' = e^t$$

$$\rightarrow \boxed{y = Ce^t}$$

solution of DE

many DEs will have  $y = e^{rt}$  as a solution  
 $r = \text{constant}$

example:  $y'' + 2y' - 3y = 0$

for what values of  $r$  is  $y = e^{rt}$   
a solution?

plus  $y = e^{rt}$  into  $y'' + 2y' - 3y = 0$

$$y' = r e^{rt}$$

$$y'' = r^2 e^{rt}$$

$$r^2 e^{rt} + 2r e^{rt} - 3e^{rt} = 0$$

$$e^{rt} (r^2 + 2r - 3) = 0$$

$$\text{since } e^{rt} \neq 0, \quad r^2 + 2r - 3 = 0$$

$$(r + 3)(r - 1) = 0$$

$$r = -3, \text{ or } r = 1$$

$y'' + 2y' - 3y = 0$  has  $e^{-3t}$  and  $e^t$  as solutions