

Clarifying the Wronskian

Recall that

$$\omega(y_1, y_2, y_3) = \begin{vmatrix} y_1 & y_2 & y_3 \\ y_1' & y_2' & y_3' \\ y_1'' & y_2'' & y_3'' \end{vmatrix}.$$

By its definition, if y_1, y_2, y_3 are functions of x , then $\omega(y_1, y_2, y_3)$ is also a function of x .

We saw this in an example with 2 funcs.:

$$\begin{aligned} \omega(e^x, e^{3x}) &= \begin{vmatrix} e^x & e^{3x} \\ e^x & 3e^{3x} \end{vmatrix} = 3e^{4x} - e^{4x} \\ &= \underline{2e^{4x}}, \end{aligned}$$

which is certainly a function of x .

Thus, sometimes we might write

$$\omega(e^x, e^{3x})(x)$$

to emphasize this dependence on x .

Similarly, with 3 functions we can write either $\omega(y_1, y_2, y_3)$ or $\omega(y_1, y_2, y_3)(x)$

The following is a good test-style question:

If $f_1 = e^{3x}$, $f_2 = xe^{3x}$, $f_3 = x^2e^{3x}$,
compute $W(f_1, f_2, f_3)(0)$.

For this, we want to evaluate

$W(e^{3x}, xe^{3x}, x^2e^{3x})$ at the input $x=0$,
so we first "setup" the Wronskian.

$$(x^2e^{3x})' = 2xe^{3x} + 3x^2e^{3x} = \underline{(2x+3x^2)e^{3x}}$$

$$\begin{aligned}(x^2e^{3x})'' &= (2+6x)e^{3x} + (6x+9x^2)e^{3x} \\ &= \underline{(2+12x+9x^2)e^{3x}}\end{aligned}$$

$$\begin{aligned}W(e^{3x}, xe^{3x}, x^2e^{3x}) \\ &= \begin{vmatrix} e^{3x} & xe^{3x} & x^2e^{3x} \\ 3e^{3x} & (1+3x)e^{3x} & (2x+3x^2)e^{3x} \\ 9e^{3x} & (6+9x)e^{3x} & (2+12x+9x^2)e^{3x} \end{vmatrix}\end{aligned}$$

Now, it would be quite tedious to expand this entire determinant, but in fact we don't exactly:

Because we only want the determinant at $x=0$, we plug in $x=0$, then compute the determinant.

So

$$\begin{vmatrix} e^{3x} & xe^{3x} & x^2 e^{3x} \\ 3e^{3x} & (1+3x)e^{3x} & (2x+3x^2)e^{3x} \\ 9e^{3x} & (6+9x)e^{3x} & (2+12x+9x^2)e^{3x} \end{vmatrix}$$

becomes

(expand along row 1)

$$\begin{vmatrix} 1 & 0 & 0 \\ 3 & 1 & 0 \\ 9 & 6 & 2 \end{vmatrix} = 1 \cdot \begin{vmatrix} 1 & 0 \\ 6 & 2 \end{vmatrix} + 0 \dots$$

$$= (2 - 0) = \boxed{2}$$

In total,

$$W(e^{3x}, xe^{3x}, x^2 e^{3x})(0) = 2$$

The Wronskian and linear independence

The following theorem contains the core idea/fact about the Wronskian

Thm: Let I be some interval (e.g. $(0, \infty)$, $(-\frac{\pi}{2}, \frac{\pi}{2})$, $(-\infty, \infty)$, etc.) and let y_1, y_2, y_3 be functions of x defined on said interval I .



The Wronskian $\omega(y_1, y_2, y_3)$, a.k.a.

$$\omega(y_1, y_2, y_3)(x) \stackrel{\text{DEF}}{=} \begin{vmatrix} y_1 & y_2 & y_3 \\ y_1' & y_2' & y_3' \\ y_1'' & y_2'' & y_3'' \end{vmatrix} \quad \text{is a}$$

function of x , also defined on I .

Case 1: If this resulting function $\omega(y_1, y_2, y_3)$ is the " 0 -function on I ",* then y_1, y_2, y_3 are linearly dependent.

Case 2: If $\omega(y_1, y_2, y_3)$ (aka. $\omega(y_1, y_2, y_3)(x)$) is not the constant 0 function on I **, then y_1, y_2, y_3 are linearly independent.

* that is, the function with domain I and constant range 0 .

** to not be the constant 0 function on I , all you need is some x -value $x_0 \in I$ for which $\omega(y_1, y_2, y_3)(x_0) \neq 0$

Naturally, the theorem holds similarly if you have

just two funcs. y_1, y_2 , or four y_1, y_2, y_3, y_4 ,
or five, etc. ... provided that you use the
proper size/shape Wronskian. Ex: for four
 y_1, y_2, y_3, y_4 , you use

$$\begin{vmatrix} y_1 & y_2 & y_3 & y_4 \\ y_1' & y_2' & y_3' & y_4' \\ y_1'' & y_2'' & y_3'' & y_4'' \\ y_1''' & y_2''' & y_3''' & y_4''' \end{vmatrix}, \text{ and so on...}$$