

IQC Note for April 16

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1 Pauli Group G_1

To reduce Pauli stabilizer codes to classical representation, we are interested in the commutation of Pauli operators. Here we use $[g, h] = ghg^{-1}h^{-1}$ to denote the commutator in group-theoretic sense. So, the commutator of Pauli operators are,

$$\begin{aligned}[X, Y] &= XYX^{-1}Y^{-1} = XYXY = -I \\ [X, Z] &= [Y, Z] = -I\end{aligned}$$

Using this notion of commutator, Pauli group G_1 of one qubit $G_1 = \{\pm I, \pm iI, \pm X, \pm iX, \pm Y, \pm iY, \pm Z, \pm iZ\}$ can be decomposed into two subgroups:

- The *center* (i.e. the subset of elements that commute with every other element) of G_1 , $C(G_1) = \{\pm I, \pm iI\}$. This subgroup is isomorphic to $\mathbb{Z}/4\mathbb{Z}$.
- The quotient group $G_1/\{\pm 1, \pm i\}$. This subgroup is isomorphic to $\mathbb{Z}/2\mathbb{Z} \oplus \mathbb{Z}/2\mathbb{Z}$.

In the following sections, we use \mathbb{F}_2 to denote $\mathbb{Z}/2\mathbb{Z}$ for convenience.

2 Reduce Pauli Group G_n to Symplectic Vector Space

We already have a good idea about G_1 . Now we will use *symplectic vector space* to investigate G_n . First, let's define a notation that encode a sequence of Pauli operators as a vector of \mathbb{F}_2 ,

$$\begin{aligned}X(\vec{x}) &= \prod_{i=1}^n X_i^{\vec{x}(i)} \quad \text{for any } \vec{x} \in \mathbb{F}_2^n \\ Z(\vec{z}) &= \prod_{i=1}^n Z_i^{\vec{z}(i)} \quad \text{for any } \vec{z} \in \mathbb{F}_2^n\end{aligned}$$

For example, $X(1, 0, 1) = X \otimes I \otimes X$. Using this notation, G_n can be written as,

$$G_n = \{\eta X(\vec{x})Z(\vec{z}) \mid \vec{x}, \vec{z} \in \mathbb{F}_2^n, \eta \in \{\pm 1, \pm i\}\}$$

Here are some simple observations of $X(\vec{x})$ and $Z(\vec{z})$.

$$\begin{aligned}X(\vec{x})^{-1} &= X(\vec{x}) & Z(\vec{z})^{-1} &= Z(\vec{z}) \\ X(\vec{x}_1)X(\vec{x}_2) &= X(\vec{x}_1 + \vec{x}_2) & Z(\vec{z}_1)Z(\vec{z}_2) &= Z(\vec{z}_1 + \vec{z}_2) \\ Z(\vec{z})X(\vec{x}) &= \left(\prod_{i=1}^n Z_i^{\vec{z}(i)}\right) \left(\prod_{i=1}^n X_i^{\vec{x}(i)}\right) \\ &= Z^{\vec{z}(1)} X^{\vec{x}(1)} \otimes \dots \otimes Z^{\vec{z}(n)} X^{\vec{x}(n)} \\ &= (-1)^{\vec{z}(1)\vec{x}(1)} X^{\vec{x}(1)} Z^{\vec{z}(1)} \otimes \dots \otimes (-1)^{\vec{z}(n)\vec{x}(n)} X^{\vec{x}(n)} Z^{\vec{z}(n)} \\ &= (-1)^{\vec{z} \cdot \vec{x}} X^{\vec{x}(1)} Z^{\vec{z}(1)} \otimes \dots \otimes X^{\vec{x}(n)} Z^{\vec{z}(n)} \\ &= (-1)^{\vec{z} \cdot \vec{x}} X(\vec{x})Z(\vec{z})\end{aligned} \tag{1}$$

Then we define symplectic product as a operator on symplectic vector space $\mathbb{F}_2^n \oplus \mathbb{F}_2^n$.

Definition 1 (Symplectic Product on $\mathbb{F}_2^n \oplus \mathbb{F}_2^n$). *Symplectic product* is an operator ω takes two $\mathbb{F}_2^n \oplus \mathbb{F}_2^n$ and returns a single \mathbb{F}_2 , which

$$\begin{aligned}\omega : (\mathbb{F}_2^n \oplus \mathbb{F}_2^n) \times (\mathbb{F}_2^n \oplus \mathbb{F}_2^n) &\mapsto \mathbb{F}_2 \\ ((\vec{x}_1, \vec{z}_1), (\vec{x}_2, \vec{z}_2)) &\mapsto \vec{x}_1 \cdot \vec{z}_2 + \vec{x}_2 \cdot \vec{z}_1\end{aligned}$$

Now we are ready to introduce a homomorphism from Pauli group G_n to symplectic vector space $\mathbb{F}_2^n \oplus \mathbb{F}_2^n$.

Lemma 1 (Homomorphism from Pauli Group to $\mathbb{F}_2^n \oplus \mathbb{F}_2^n$). There exists a surjective group homomorphism π , that maps elements in Pauli group G_n to $\mathbb{F}_2^n \oplus \mathbb{F}_2^n$

$$\begin{aligned} \pi : \quad G_n &\mapsto \mathbb{F}_2^n \oplus \mathbb{F}_2^n \\ \eta X(\vec{x})Z(\vec{z}) &\mapsto (\vec{x}, \vec{z}) \end{aligned}$$

Proof. Once we multiply two elements in G_n , we have,

$$\begin{aligned} &\eta_1 X(\vec{x}_1)Z(\vec{z}_1)\eta_2 X(\vec{x}_2)Z(\vec{z}_2) \\ &= \eta_1 \eta_2 X(\vec{x}_1)Z(\vec{z}_1)X(\vec{x}_2)Z(\vec{z}_2) \\ &= \eta_1 \eta_2 (-1)^{\vec{z}_1 \cdot \vec{x}_2} X(\vec{x}_1)X(\vec{x}_2)Z(\vec{z}_1)Z(\vec{z}_2) \\ &= \eta_1 \eta_2 (-1)^{\vec{z}_1 \cdot \vec{x}_2} X(\vec{x}_1 + \vec{x}_2)Z(\vec{z}_1 + \vec{z}_2) \end{aligned}$$

Thus, $\pi(\eta_1 X(\vec{x}_1)Z(\vec{z}_1) \eta_2 X(\vec{x}_2)Z(\vec{z}_2)) = \pi(\eta_1 X(\vec{x}_1)Z(\vec{z}_1)) + \pi(\eta_2 X(\vec{x}_2)Z(\vec{z}_2))$. \square

Lemma 2. $\eta_1 X(\vec{x}_1)Z(\vec{z}_1)$ and $\eta_2 X(\vec{x}_2)Z(\vec{z}_2)$ commute iff $\omega((\vec{x}_1, \vec{z}_1), (\vec{x}_2, \vec{z}_2)) = 0$.

Proof. Using (1) to exchange X and Z ,

$$\begin{aligned} &\eta_1 X(\vec{x}_1)Z(\vec{z}_1)\eta_2 X(\vec{x}_2)Z(\vec{z}_2) \\ &= \eta_1 \eta_2 X(\vec{x}_1)Z(\vec{z}_1)X(\vec{x}_2)Z(\vec{z}_2) \\ &= \eta_1 \eta_2 (-1)^{\vec{z}_1 \cdot \vec{x}_2} X(\vec{x}_1)X(\vec{x}_2)Z(\vec{z}_1)Z(\vec{z}_2) \\ &= \eta_1 \eta_2 (-1)^{\vec{z}_1 \cdot \vec{x}_2} X(\vec{x}_2)X(\vec{x}_1)Z(\vec{z}_2)Z(\vec{z}_1) \\ &= \eta_1 \eta_2 (-1)^{\vec{z}_1 \cdot \vec{x}_2} (-1)^{\vec{x}_1 \cdot \vec{z}_2} X(\vec{x}_2)Z(\vec{z}_2)X(\vec{x}_1)Z(\vec{z}_1) \\ &= (-1)^{\omega((\vec{x}_1, \vec{z}_1), (\vec{x}_2, \vec{z}_2))} \eta_2 X(\vec{x}_2)Z(\vec{z}_2)\eta_1 X(\vec{x}_1)Z(\vec{z}_1) \end{aligned}$$

Thus

$$[\eta_1 X(\vec{x}_1)Z(\vec{z}_1), \eta_2 X(\vec{x}_2)Z(\vec{z}_2)] = (-1)^{\omega((\vec{x}_1, \vec{z}_1), (\vec{x}_2, \vec{z}_2))} I$$

Then $\eta_1 X(\vec{x}_1)Z(\vec{z}_1)$ and $\eta_2 X(\vec{x}_2)Z(\vec{z}_2)$ commute if and only if $\omega((\vec{x}_1, \vec{z}_1), (\vec{x}_2, \vec{z}_2)) = 0$. \square

3 Subspaces generated by Pauli Stabilizer

Now we discuss subspaces generated by a set of Pauli stabilizer: $S \subseteq G_n$.

Lemma 3. If $\langle S \rangle$ generates a nonabelian group, then $-I \in \langle S \rangle$.

Proof. On one hand, if $\langle S \rangle$ is nonabelian, exists $g, h \in \langle S \rangle$ such that, $[g, h] \neq I$. On the other hand, as we know from Lemma 2, $[g, h] = \pm I$. Thus we get $[g, h] = -I$. And because $[g, h] \in \langle S \rangle$, we know $-I \in \langle S \rangle$. \square

Lemma 4. If $\langle S \rangle$ generates an abelian group and $-I \notin \langle S \rangle$, then for any $g \in \langle S \rangle$, $g^2 = I$, and in particular, $\eta(g) = \pm 1$ where $g = \eta(g)X(\vec{x}_g)Z(\vec{z}_g)$.

Proof. If $\langle S \rangle$ is abelian, then, $g^2 = \eta(g)^2 X(2\vec{x}_g)Z(2\vec{z}_g) = \eta(g)^2$. And because $-I \notin \langle S \rangle$, $g^2 \neq -I$, which means $\eta(g) \neq \pm i$. Then $\eta(g) = \pm 1$. \square

Before discussing C_S , the vector space stabilized by S , we have to define notation of *symplectic complement* for symplectic vector space.

Definition 2 (Symplectic Complement). Let $W \subseteq \mathbb{F}_2^n \oplus \mathbb{F}_2^n$, the *symplectic complement* of W is defined by,

$$W^\perp = \left\{ (\vec{x}, \vec{z}) \in \mathbb{F}_2^n \oplus \mathbb{F}_2^n \mid \omega((\vec{x}, \vec{z}), (\vec{w}_1, \vec{w}_2)) = 0, \text{ for any } (\vec{w}_1, \vec{w}_2) \in W \right\}$$

We also say W is isotropic iff $W \subseteq W^\perp$.

Example 1. Let $W = \{(\vec{x}, 0) \mid \vec{x} \in \mathbb{F}_2\} \subseteq \mathbb{F}_2^n \oplus \mathbb{F}_2^n$. It's easy to show that $W = W^\perp$.

- $W \subseteq W^\perp$: Obviously, $\omega((\vec{x}_1, 0), (\vec{x}_2, 0)) = 0$.
- $W^\perp \subseteq W$: If for any $w \in \mathbb{F}_2$, $\omega((\vec{w}, 0), (\vec{x}, \vec{z})) = 0$, then $\vec{z} = 0$.

Lemma 5. If $\langle S \rangle$ is abelian, then $\pi(\langle S \rangle)$ is an isotropic subspace. And $\pi : \langle S \rangle \mapsto \mathbb{F}_2^n \oplus \mathbb{F}_2^n$ is injective iff $-I \notin \langle S \rangle$.

Lemma 5 means we can always map any abelian subspace of G_n that not containing $-I$ to an isotropic subspace of $\mathbb{F}_2^n \oplus \mathbb{F}_2^n$. This map is also bijection but it will be hard to prove that.

Definition 3 (Symplectomorphism). An isomorphism $\alpha : \mathbb{F}_2^n \oplus \mathbb{F}_2^n \mapsto \mathbb{F}_2^n \oplus \mathbb{F}_2^n$ is a *symplectomorphism*, if for any $(\vec{x}_1, \vec{z}_1), (\vec{x}_2, \vec{z}_2) \in \mathbb{F}_2^n \oplus \mathbb{F}_2^n$,

$$\omega(\alpha(\vec{x}_1, \vec{z}_1), \alpha(\vec{x}_2, \vec{z}_2)) = \omega((\vec{x}_1, \vec{z}_1), (\vec{x}_2, \vec{z}_2))$$

Definition 4 (Clifford Unitary). Any unitary $U : (\mathbb{C}^2)^{\otimes n} \mapsto (\mathbb{C}^2)^{\otimes n}$ is called *Clifford*, if for any $g \in G_n$,

$$UgU^* \in G_n$$

Here we list some key facts about isotropic subspace and symplectomorphism.

1. Isotropic subspace of $\mathbb{F}_2^n \oplus \mathbb{F}_2^n$ have dimension at most n .
2. Any two isotropic subspace of the same dimension are equal up to symplectomorphism.
3. Any symplectomorphism can be implemented by a Clifford operator U , i.e. $\pi(UgU^*) = \alpha(\pi(g))$.

Proposition 1. $C_S = \{\vec{0}\} \Leftrightarrow -I \in \langle S \rangle$.

Proof. (\Leftarrow) This direction we have proved last time.

(\Rightarrow) For any clifford U we have $U(-I)U^* = -I$ and $UC_S = C_{USU^*}$. So in particular, it suffice to find a clifford U for which we can show $-I \notin \langle USU^* \rangle$.

By Fact 3, it suffices to find a symplectomorphism α , such that $\alpha(\pi(\langle S \rangle)) = \pi(\langle S' \rangle)$ where $-I \notin \langle S' \rangle$.

By Fact 1 and 2, we know that $\dim \pi(\langle S \rangle) = k \leq n$.

And by Fact 2, we can use symplectomorphism α that maps $\pi(\langle S \rangle)$ to the following isotropic subspaces.

$$\{(x_1, x_2, \dots, x_k, \underbrace{0, \dots, 0}_{n-k}, \underbrace{0, \dots, 0}_n) \mid x_1, x_2, \dots, x_k \in \mathbb{F}_2\} \subseteq \mathbb{F}_2^n \oplus \mathbb{F}_2^n$$

This is exactly $\pi(\langle S' \rangle)$ where,

$$S' = \{X(x_1, x_2, \dots, x_k, 0, \dots, 0) \mid x_1, x_2, \dots, x_k \in \mathbb{F}_2\} \subseteq G_n$$

which means $-I \notin \langle S' \rangle$. □

With a little more work we can prove,

Proposition 2. There exists a bijection: $\{\text{subgroups } \langle S \rangle \in G_n \text{ that are abelian and don't contain } -1\} \longleftrightarrow \{\text{isotropic subgroup of } \mathbb{F}_2^n \oplus \mathbb{F}_2^n\}$

Theorem 1. There exists a bijection: $\{\text{Pauli stabilizer codes}\} \longleftrightarrow \{\text{isotropic subgroup of } \mathbb{F}_2^n \oplus \mathbb{F}_2^n\}$