

Meeting 2.1: Other 3-manifold encodings

I. Heegaard splittings and diagrams

II. Knots and links: stick presentations and diagrams

III. Bridge position, braid groups, and trace closures

Skipping for now: surgery presentations of 3-manifolds

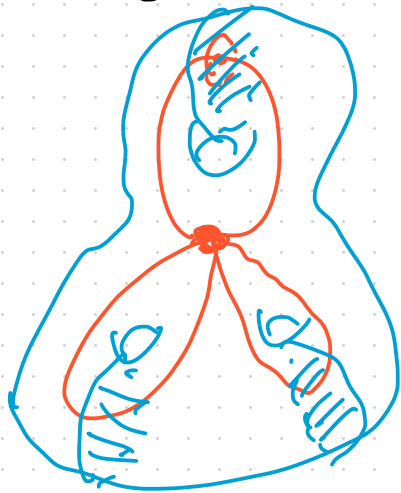
Next time: structure of 3-manifolds

Announcements: - office half hour on Wednesdays, 3:30-4:00.
w/ option to go extra half hour

- Class will end today at 3pm.

I. Heegaard splittings and diagrams

A handlebody of genus g is a 3-manifold homeomorphic to a regular neighborhood of a wedge of g circles in \mathbb{R}^3 .



$$\bigcup_{p \in \text{Wedge}} \overline{B_\varepsilon(p)} \quad (\varepsilon \text{ small enough})$$

Let M be a (closed, orientable) 3-manifold.

A Heegaard surface (or Heegaard splitting) is an embedded surface $S \subseteq M$ of

some genus g such that "cutting M along S " results in two handlebodies.

"Cut M along S " means " $M - \overset{\circ}{N}(S)$."

Lemma Every (closed, orientable) 3-manifold has a Heegaard surface. More precisely, if \mathcal{T} is a triangulation of a 3-manifold with t tetrahedra, then \mathcal{T} has Heegaard surface of genus $= \# \mathcal{T}^1 - \# \text{Max Tree}(\mathcal{T}^1)$.

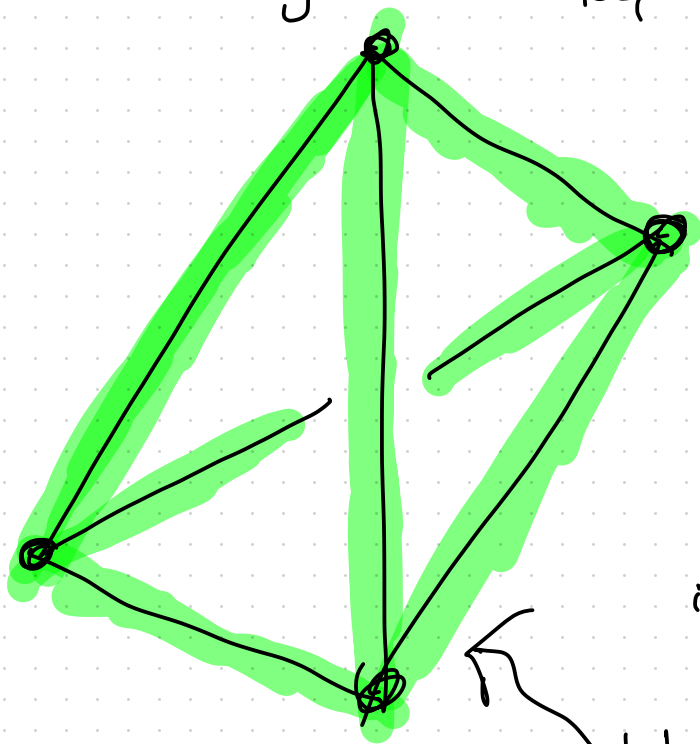


$\mathcal{T}^1 = \text{one skeleton}$

Remark: the genus will typically be way bigger than necessary. We define $\text{genus}(M^3)$ to be the minimum genus of all Heegaard splittings of M . $\text{genus}(M^3)$ is an invariant.

Proof by picture

For Heegaard surface,



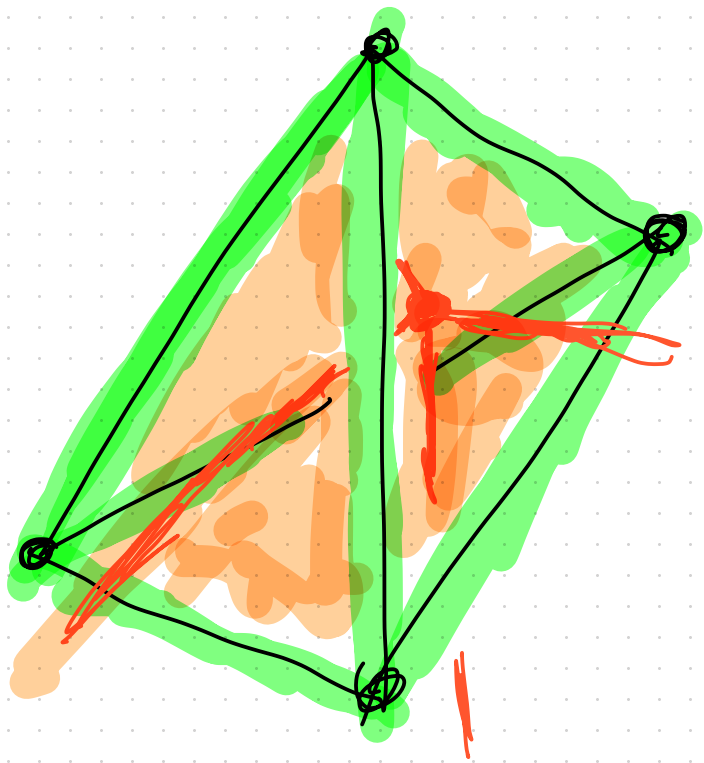
let $S = \partial N(\gamma_1)$. We need to check that each piece of $\gamma - S$ is a handlebody of genus $\# \gamma_1 - \# \text{Max Tree}(\gamma_1)$.

We can contract any maximal tree in H_0 to get a homeomorphic manifold. By construction the 3-manifold is a wedge of $\# \gamma_1 - \# \text{Max Tree}(\gamma_1)$ many circles.

$$H_0 = N(\gamma_1)$$

Note that $H_1 = \mathcal{Y} - H_0$ has boundary S .

To see that it is a 3-manifold homeomorphic to a regular neighborhood of a graph, look at dual one skeleton of \mathcal{Y} . □



We want to recover a 3-manifold from a surface (which will be the Heegaard splitting) + finite amount of extra data

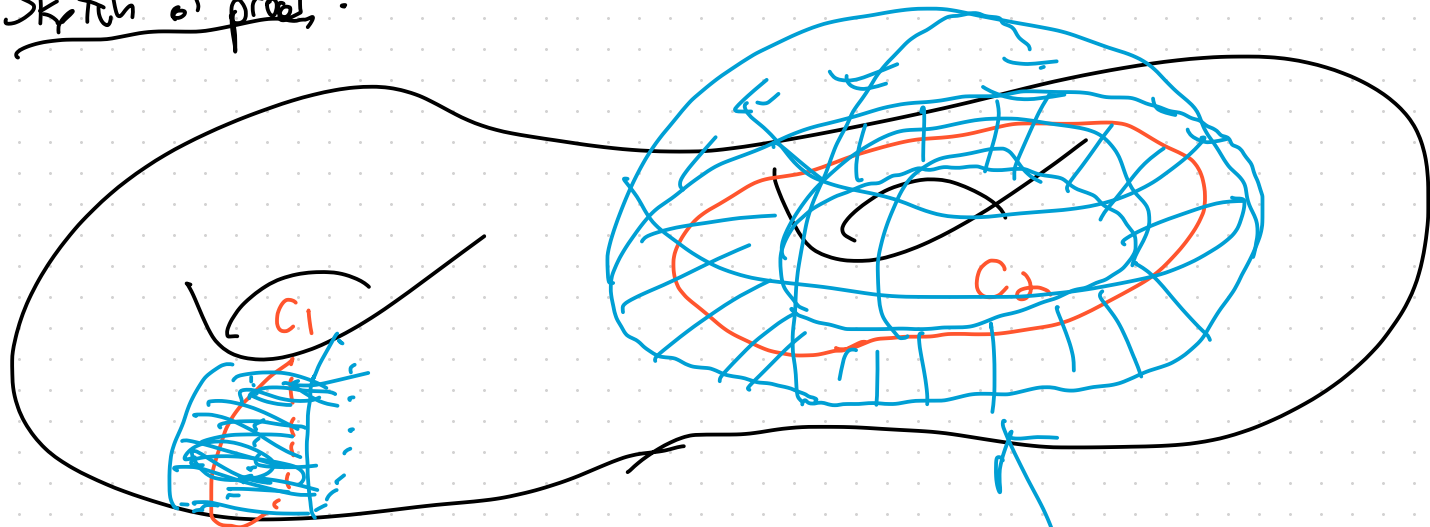
Def'n Call a collection of ^{simple closed} curves c_1, c_2, \dots, c_g on a genus g surface S a complete disk system if:

- i) c_i 's pairwise disjoint
- ii) $S - \bigcup_{i=1}^g c_i$ is connected.

Theorem Let S be a genus g surface with a complete disk system c_1, \dots, c_g . Then, up to ^(orientation-preserving) homeomorphism rel S , there is a unique handlebody H with $\partial H = S$ such that each c_i bounds an embedded disk.

Sketch of proof:

$S \times [-1, 0]$



glue: $D^2 \times [-1, 1]$
so $D^2 \times \{0\}$
is identified w/ c_1

Similarly over base

$$N = \bigcup_{i=1}^g N(c_i)$$

$$D = \bigcup_{i=1}^g D^2 \times \{-1, +1\}$$

Then $D \cup (S \sim N)$ is a 2-sphere.

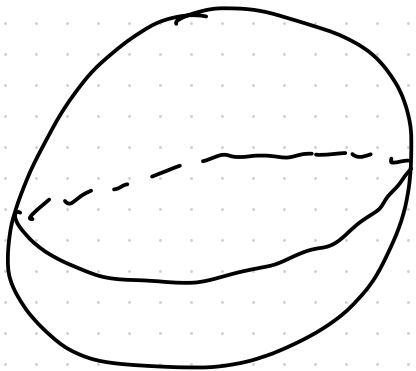
Up to orientation preserving isobpy, there is exactly one way to glue a 3-ball to $D \cup (S \sim N)$.

□

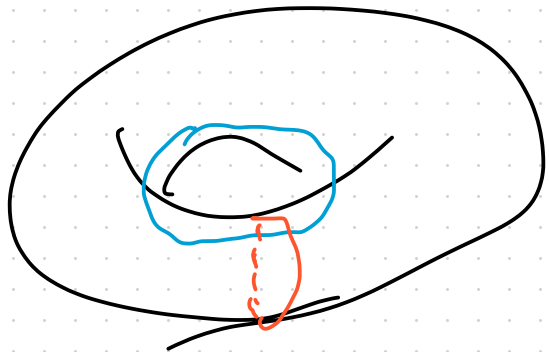
Corollary Every closed orientable 3-manifold can be presented as a Heegaard diagram, which consists of a surface S of some genus g , together w/ two complete disk systems on S .

In fact, S can be triangulated, and each curve in the disk systems is a normal curve.

Example 1



S^3



S^3