

Ex: $\underline{\underline{A}} = \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix}$ $\underline{\underline{C}} = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}$

$\underline{\underline{A}} \underline{\underline{C}} = \text{X NOT Defined}$
 $(2 \times 3) (2 \times 2)$
 X

$\underline{\underline{C}} \underline{\underline{A}} = \begin{bmatrix} \quad \quad \quad \end{bmatrix} (2 \times 3)$ this is defined
 $(2 \times 2) (2 \times 3)$
 (3×3)

Roll: $\underline{\underline{A}} = \begin{bmatrix} 1 & 4 & 7 \\ 2 & 5 & 8 \\ 3 & 6 & 9 \end{bmatrix}$ $\underline{\underline{B}} = \begin{bmatrix} 1 & 1 & 1 \\ 2 & 2 & 2 \end{bmatrix}$
 (3×3) (2×3)

Which of the following matrix mult. is valid?

$\text{X (a) } \underline{\underline{A}} \underline{\underline{B}} (3 \times 3)(2 \times 3)$ (c) neither

(b) $\underline{\underline{B}} \underline{\underline{A}} (2 \times 3)(3 \times 3)$ (d) both X

III. Determinant :

If $\underline{\underline{A}}$ is a 2×2 matrix then its determinant

$\det(\underline{\underline{A}}) = |\underline{\underline{A}}| = \begin{vmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{vmatrix} = a_{11}a_{22} - a_{12}a_{21}$

Ex: $\det \begin{bmatrix} 1 & 2 \\ 4 & 3 \end{bmatrix} = 1 \cdot 3 - 2 \cdot 4 = 3 - 8 = -5$

For determinant of bigger square matrices, we use Expansion by Minors

If $\underline{\underline{A}}$ is an $n \times n$ matrix

... $(n-1) \times (n-1)$ matrix obtained by

If $\underline{A}$ is an $n \times n$ matrix

Let $\underline{A}_{ij}$ be the $(n-1) \times (n-1)$ matrix obtained by deleting the i th row and j th column

$$\det(\underline{A}) = \sum_{j=1}^n (-1)^{i+j} a_{ij} \det(\underline{A}_{ij})$$

Ex: $\underline{A} = \begin{bmatrix} 3 & 1 & -2 \\ 4 & 2 & 1 \\ -2 & 3 & 5 \end{bmatrix}$

let $i=1$

$$\det(\underline{A}) = (-1)^{1+1} a_{11} \det(\underline{A}_{11}) + (-1)^{1+2} a_{12} \det(\underline{A}_{12}) + (-1)^{1+3} a_{13} \det(\underline{A}_{13})$$

$$= (-1)^2 (3) \det \begin{bmatrix} 2 & 1 \\ 3 & 5 \end{bmatrix} + (-1)^3 (1) \det \begin{bmatrix} 4 & 1 \\ -2 & 5 \end{bmatrix}$$

$$+ (-1)^4 (-2) \det \begin{bmatrix} 4 & 2 \\ -2 & 3 \end{bmatrix}$$

$$= 3(2 \cdot 5 - 1 \cdot 3) + (-1)(4 \cdot 5 - 1(-2)) + (-2)(4 \cdot 3 - 2(-2))$$

$$\boxed{\det(\underline{A}) = -33}$$

IV, Matrix-Valued Functions :

Def: A matrix-valued function is a matrix in which each element is a function of t

Ex: $\underline{x}(t) = \begin{bmatrix} t \\ 3t^2 \end{bmatrix}$ $\underline{A}(t) = \begin{bmatrix} \sin(t) & 7 \\ 0 & 8t^2 + 1 \end{bmatrix}$

... matrix fun $\underline{A}(t)$ is continuous

Def: We say that a matrix fun $\underline{A}(t)$ is continuous at a point t if each of its elements is continuous

Def: The derivative of a matrix fun is defined by elementwise differentiation

Ex: $\underline{x}(t) = \begin{bmatrix} t \\ t^2 \\ e^{-t} \end{bmatrix}$ $\underline{x}'(t) = \frac{d\underline{x}}{dt} = \begin{bmatrix} 1 \\ 2t \\ -e^{-t} \end{bmatrix}$

sum and product rules

$$\frac{d}{dt} (\underline{A}(t) + \underline{B}(t)) = \underline{A}' + \underline{B}'$$

$$\frac{d}{dt} (\underline{A} \underline{B}) = \underline{A} \underline{B}' + \underline{A}' \underline{B}$$

hw problem to show this

$$\frac{d}{dt} (c \underline{A}(t)) = c \underline{A}'$$

c is a scalar const (doesn't depend on t)

V First Order Linear Systems :

system of ODEs $\rightarrow$ matrix form

$$\frac{d\underline{x}}{dt} = \underbrace{\underline{P}(t)}_{\text{coefficient matrix}} \underline{x} + \underline{f}(t)$$

$$(n \times 1) \quad (n \times n)(n \times 1) \quad (n \times 1)$$

Ex: 1st order system

$$x_1' = 4x_1 - 3x_2$$

$$x_2' = 6x_1 - 7x_2$$

matrix form

$$\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}' = \begin{bmatrix} 4 & -3 \\ 6 & -7 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

verify $\underline{x}(t) = \begin{bmatrix} 3e^{2t} \\ 2e^{2t} \end{bmatrix}$ is a soln

Verify $\underline{x}(t) = \begin{bmatrix} 3e^{2t} \\ 2e^{2t} \end{bmatrix}$ is a soln

$$\underline{x}' \stackrel{?}{=} \begin{bmatrix} 4 & -3 \\ 6 & -7 \end{bmatrix} \underline{x}$$

VI. Associated Homogeneous Eqn

when $f(t) = 0$ the eqn is homogeneous

$$(*) \quad \underline{x}' = \underline{P}(t) \underline{x}$$

If $\underline{P}(t)$ is an $n \times n$ matrix, then we expect (*) to have n linearly independent solutions

$$\underline{x}_1(t), \underline{x}_2(t), \dots, \underline{x}_n(t)$$

Since the system is linear, the Principle of Superposition applies

$$\underline{x}(t) = c_1 \underline{x}_1(t) + c_2 \underline{x}_2(t) + \dots + c_n \underline{x}_n(t)$$

where $c_1, c_2, \dots, c_n$ are scalar constants

then $\underline{x}(t)$ also solves (*)

$$\text{Ex: } \underline{x}' = \begin{bmatrix} 4 & -3 \\ 6 & -7 \end{bmatrix} \underline{x}$$

$$\text{has solutions } \underline{x}_1(t) = \begin{bmatrix} 3e^{2t} \\ 2e^{2t} \end{bmatrix} \quad \underline{x}_2(t) = \begin{bmatrix} e^{-5t} \\ 3e^{-5t} \end{bmatrix}$$

Then the general solution is

$$\underline{x}(t) = c_1 \underline{x}_1(t) + c_2 \underline{x}_2(t) \\ = c_1 \begin{bmatrix} 3e^{2t} \\ 2e^{2t} \end{bmatrix} + c_2 \begin{bmatrix} e^{-5t} \\ 3e^{-5t} \end{bmatrix}$$

$$\underline{x}(t) = \dots$$

$$= c_1 \begin{bmatrix} 3e^{2t} \\ 2e^{2t} \end{bmatrix} + c_2 \begin{bmatrix} e^{-5t} \\ 3e^{-5t} \end{bmatrix}$$

VII Linear Independence: Wronskian

If $\underline{x}_1, \dots, \underline{x}_n$ are solutions to ODE (*)
the Wronskian is

$$W(t) = \det \begin{bmatrix} | & | & \dots & | \\ \underline{x}_1(t) & \underline{x}_2(t) & \dots & \underline{x}_n(t) \\ | & | & \dots & | \end{bmatrix} \quad (n \times n)$$

If $W(t) \neq 0$ then are linearly independent

Ex: $W(t) = \det \begin{bmatrix} 3e^{2t} & e^{-5t} \\ 2e^{2t} & 3e^{-5t} \end{bmatrix} = (3e^{2t})(3e^{-5t}) - (2e^{2t})(e^{-5t})$

$$= 9e^{-3t} - 2e^{-3t}$$

$$= 7e^{-3t} \neq 0$$

So $\underline{x}_1$ and $\underline{x}_2$ are linearly independent

★ Summary:

- $\det \begin{pmatrix} a & b \\ c & d \end{pmatrix} = ad - bc$

- use expansion by minors for determinants of $n \times n$ matrices

... related functions — take derivatives elementwise

- matrix-valued functions — take derivatives elementwise

- Homogeneous Linear Systems

$$\underline{x}' = \underline{P}(t)\underline{x} \quad \text{where } \underline{P}(t) \text{ is } n \times n$$

have n linearly independent solutions

$$\underline{x}_1(t), \underline{x}_2(t), \dots, \underline{x}_n(t)$$

use the Principle of Superposition to get the general solution:

$$\underline{x}(t) = c_1 \underline{x}_1(t) + \dots + c_n \underline{x}_n(t)$$

- Use the Wronskian to determine linear independence.