



Our solution $\underline{X}(s)$ often has the form

$$\underline{X}(s) = F(s) \cdot G(s)$$

Take the Laplace Transform of that and we get

$$x(t) = d^{-1}\{\underline{X}(s)\} = d^{-1}\{F(s)G(s)\}$$

So can $d^{-1}\{F(s)\} \cdot d\{G(s)\} = d^{-1}\{F(s)G(s)\}$?

Suppose we have the IVP $\begin{cases} x'' + x = \cos(t) \\ x(0) = x'(0) = 0 \end{cases}$

$$\text{We get } \underline{X}(s) = \frac{s}{(s^2+1)^2} = \frac{s}{s^2+1} \cdot \frac{1}{s^2+1} = d\{\cos(t)\} \cdot d\{\sin(t)\}$$

$$\text{Let's see if } \frac{s}{(s^2+1)^2} = d\{\cos(t)\sin(t)\}$$

$$\text{Well } d\{\cos(t)\sin(t)\} = d\left\{\frac{1}{2}\sin(2t)\right\} \quad (\text{double angle formula})$$

$$= \frac{1}{2} d\{\sin(2t)\}$$

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..

$$\begin{aligned}
 & -\frac{1}{2} \cdot 2 \sin(2t) \\
 &= \frac{1}{2} \cdot \frac{2}{s^2 + 2^2} \quad (\text{by the table}) \\
 &= \frac{1}{s^2 + 4}
 \end{aligned}$$

Hence does $\frac{1}{s^2 + 4} = \frac{1}{(s^2 + 1)^2}$? No!!!

Hence $\mathcal{L}\{F(s) \cdot G(s)\} \neq \mathcal{L}\{F(s)\} \cdot \mathcal{L}\{G(s)\}$

So do there exist a formula for the product of Laplace Transforms?
YES!

Before we state the formula we need one more thing

Def: The convolution of two functions $f(t)$ and $g(t)$ is defined by

$$(f * g)(t) = \int_0^t f(u)g(t-u)du$$

Written HW: Prove that $(f * g) = (g * f)$
i.e. order of f and g doesn't matter.

Thm 1: (Convolution Property)

For two functions $f(t)$ and $g(t)$

$$\mathcal{L}\{(f * g)(t)\} = \mathcal{L}\{f(t)\} \cdot \mathcal{L}\{g(t)\} = F(s)G(s)$$

and equivalently .

$$(f * g)(t) = \mathcal{L}^{-1}\{F(s)G(s)\}$$

Ex 1: Find the inverse Laplace Transform of $H(s) = \frac{2}{(s+1)(s-3)}$
... (linearity for this problem)

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(Note we can use partial fractions for this problem)

Using the convolution property,

$$H(s) = \underbrace{\left(\frac{2}{s+1}\right)}_{F(s)} \underbrace{\left(\frac{1}{s-3}\right)}_{G(s)}$$

$$\text{So } f(t) = \mathcal{L}^{-1}\{F(s)\} = \mathcal{L}^{-1}\left\{\frac{2}{s+1}\right\} = 2 \mathcal{L}^{-1}\left\{\frac{1}{s+1}\right\} = 2e^{-t}$$

$$g(t) = \mathcal{L}^{-1}\{G(s)\} = \mathcal{L}^{-1}\left\{\frac{1}{s-3}\right\} = e^{3t}$$

$$\begin{aligned} \text{So } \mathcal{L}^{-1}\{H(s)\} &= \mathcal{L}^{-1}\{F(s)G(s)\} \stackrel{\text{By Thm}}{=} (f * g)(t) \\ &= \int_0^t f(u)g(t-u)du \\ &= \int_0^t 2e^{-u} e^{3(t-u)} du \\ &= \int_0^t 2e^{-u} e^{3t} e^{-3u} du \\ &= 2e^{3t} \int_0^t e^{-4u} du \\ &= 2e^{3t} \left(\frac{e^{-4u}}{-4} \right) \Big|_0^t \\ &= \frac{2e^{3t}}{-4} (e^{-4t} - 1) \\ &= -\frac{1}{2} (e^{-t} - e^{3t}) \end{aligned}$$

Note we can also use the convolution property to write down solutions to ODE.

Ex 2: Solve the IVP:

Ex 2: Solve the IVP:

$$\begin{cases} x'' + x = \cos(t) \\ x(0) = x'(0) = 0 \end{cases}$$

In the beginning of class we said

$$\underline{X}(s) = \frac{s}{(s^2 + 1)^2} = \underbrace{\frac{s}{s^2 + 1}}_{F(s)} \cdot \underbrace{\frac{1}{s^2 + 1}}_{G(s)}$$

$$\text{So } f(t) = \mathcal{L}^{-1}\{F(s)\} = \mathcal{L}^{-1}\left\{\frac{s}{s^2 + 1}\right\} = \cos(t)$$

$$g(t) = \mathcal{L}^{-1}\{G(s)\} = \mathcal{L}^{-1}\left\{\frac{1}{s^2 + 1}\right\} = \sin(t)$$

$$\text{So } \mathcal{L}^{-1}\{\underline{X}(s)\} = \mathcal{L}^{-1}\{F(s)G(s)\} = (f * g)(t) \quad (\text{by Thm})$$

$$= \int_0^t f(w)g(t-w)dw$$

$$= \int_0^t \cos(w)\sin(t-w)dw$$

$$= \int_0^t \frac{1}{2} [\sin(t) + \sin(t-2w)] dw$$

$$= \frac{1}{2} \sin(t) \int_0^t dw + \frac{1}{2} \int_0^t \sin(t-2w) dw$$

$$= \frac{1}{2} \sin(t) \left[w \right]_0^t + \frac{1}{2} \cdot \left[-\frac{\cos(t-2w)}{-2} \right]_0^t$$

$$= \frac{1}{2} \sin(t) \cdot t + \frac{1}{4} (\cos(t-2t) - \cos(t))$$

$$= \frac{1}{2} \sin(t) + \frac{1}{4} (\cos(-t) - \cos(t)) \quad \begin{matrix} \text{Remember} \\ \cos(-t) = \cos(t) \end{matrix}$$

$$= \frac{1}{2} \sin(t)$$

Now Differentiation of Transforms

Thm 2: (Differentiation of Transforms) Let $f(t)$ be a function, then

$$d\{ -t f(t) \} = F'(s)$$

which equivalently

$$-t f(t) = d^{-1}\{ F'(s) \} \Leftrightarrow f(t) = -\frac{1}{t} d^{-1}\{ F'(s) \}$$

Note: If we repeatedly use this formula we get

$$d\{ t^n f(t) \} = (-1)^n F^{(n)}(s)$$

Ex 3: Find $d\{ t^2 \sin(\pi t) \}$

Note $d\{ t^n f(t) \} = (-1)^n F^{(n)}(s)$

In our case $n=2$ and $f(t) = \sin(\pi t)$. So

$$\begin{aligned} d\{ t^2 \sin(\pi t) \} &= (-1)^2 F^{(2)}(s) \\ &= (-1)^2 \frac{d^2}{ds^2} (d^{-1}\{ \sin(\pi t) \}) \\ &= \frac{d^2}{ds^2} \left(\frac{\pi}{s^2 + \pi^2} \right) \\ &= \frac{d}{ds} \left(\frac{-\pi}{(s^2 + \pi^2)^2} \cdot 2s \right) \\ &= \frac{d}{ds} \left(\frac{-2\pi s}{(s^2 + \pi^2)^2} \right) \\ &= \frac{-2\pi (s^2 + \pi^2)^2 + (-2\pi s) \cdot 2(s^2 + \pi^2) \cdot 2s}{(s^2 + \pi^2)^4} \end{aligned}$$

$$\frac{(s^2 + \pi^2)^{4/3}}{2\pi[-s^2 - \pi^2 + 2s^2]} = \frac{2\pi[s^2 - \pi^2]}{(s^2 + \pi^2)^3}$$

Lastly integration with transforms

Thm 3: (Integration with transforms) Let $f(t)$ be a function

$$\mathcal{L}\left\{ \frac{f(t)}{t} \right\} = \int_s^{\infty} F(u) du$$

and equivalently

$$\frac{f(t)}{t} = \mathcal{L}^{-1}\left\{ \int_s^{\infty} F(u) du \right\}$$

$$f(t) = t \mathcal{L}^{-1}\left\{ \int_s^{\infty} F(u) du \right\}$$

$$\text{Ex 4: Find } \mathcal{L}^{-1}\left\{ \frac{2s}{(s^2-1)^2} \right\}$$

$$\text{Note that } f(t) = \mathcal{L}^{-1}\left\{ F(s) \right\} = t \mathcal{L}^{-1}\left\{ \int_0^{\infty} F(u) du \right\}$$

$$\text{In our case } F(s) = \frac{2s}{(s^2-1)^2}$$

$$\text{So } \mathcal{L}^{-1}\left\{ \frac{2s}{(s^2-1)^2} \right\} = t \mathcal{L}^{-1}\left\{ \int_s^{\infty} \frac{2u}{(u^2-1)^2} du \right\}$$

$$= t \mathcal{L}^{-1}\left\{ \lim_{R \rightarrow \infty} \int_s^R \frac{2u}{(u^2-1)^2} du \right\}$$

$$= +d^{-1} \left\{ \lim_{R \rightarrow \infty} \int_s^{\infty} \frac{(u^2-1)^{-1}}{2u} du \right\}$$

$a = u^2 - 1$
 $da = 2u du$

$$= +d^{-1} \left\{ \lim_{R \rightarrow \infty} \int \frac{da}{a^2} \right\}.$$

$$= +d^{-1} \left\{ \lim_{R \rightarrow \infty} \int a^{-2} da \right\}$$

$$= +d^{-1} \left\{ \lim_{R \rightarrow \infty} \left[\frac{a^{-1}}{-1} \right] \right\}$$

$$= +d^{-1} \left\{ \lim_{R \rightarrow \infty} \left(\frac{-1}{u^2-1} \right) \Big|_s^R \right\}$$

$$= +d^{-1} \left\{ \lim_{R \rightarrow \infty} \left[\frac{-1}{R^2-1} - \frac{-1}{s^2-1} \right] \right\}$$

$= 0$

$$= +d^{-1} \left\{ \frac{1}{s^2-1} \right\}$$

$\Big) \text{ by the table}$

$$= + \sinh(t)$$