

Lecture 6

★ Section 5.5 - Part 1

Multiple Eigenvalues

Bonus Material

Warm up:

Find the eigenvalues of the matrix

$$\underline{A} = \begin{bmatrix} 2 & 0 \\ 7 & 2 \end{bmatrix}$$

Ans: $\det(\underline{A} - \lambda \underline{I}) = 0$

$$\begin{vmatrix} 2-\lambda & 0 \\ 7 & 2-\lambda \end{vmatrix} = (2-\lambda)^2 - 0 \cdot 7 = 0$$

$$(2-\lambda)^2 = 0$$

$$\lambda = 2$$

multiplicity $k=2$ I. Complex Eigenvalues:

$$\underline{x}' = \begin{bmatrix} 1 & 1 \\ -1 & 1 \end{bmatrix} \underline{x}$$

$$\lambda = 1 \pm i$$

eigenvectors

$$\underline{v}^{(1)} = \begin{bmatrix} 1 \\ i \end{bmatrix}$$

$$\underline{v}^{(2)} = \begin{bmatrix} 1 \\ -i \end{bmatrix}$$

One possible general soln:

$$\underline{x}(t) = c_1 e^{(1+i)t} \begin{bmatrix} 1 \\ i \end{bmatrix} + c_2 e^{(1-i)t} \begin{bmatrix} 1 \\ -i \end{bmatrix}$$

WANT: Real-valued solutionsEuler's formula: $e^{it} = \cos(t) + i \sin(t)$

$$\underline{x}^{(1)}(t) = e^t \underbrace{e^{it}}_{\underline{w}} \begin{bmatrix} 1 \\ i \end{bmatrix} = e^t \left\{ \underbrace{\begin{bmatrix} \cos(t) \\ -\sin(t) \end{bmatrix}}_{\underline{w}} + i \underbrace{\begin{bmatrix} \sin(t) \\ \cos(t) \end{bmatrix}}_{\underline{v}} \right\}$$

$$\underline{x}^{(2)}(t) = e^t \{ \underline{w} - i \underline{v} \}$$

New basis:

$$\hat{\underline{x}}^{(1)}(t) = \frac{1}{2} (\underline{x}^{(1)} + \underline{x}^{(2)}) = e^t \underline{w}$$

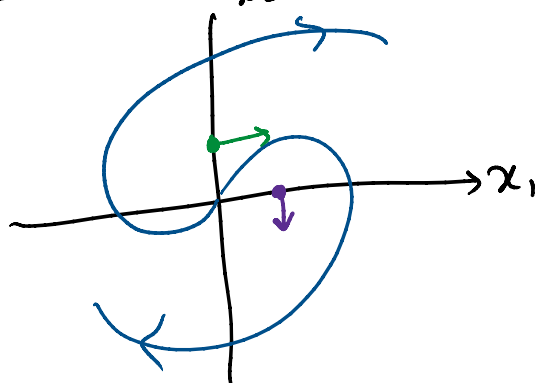
$$\hat{\underline{x}}^{(2)}(t) = \frac{1}{2i} (\underline{x}^{(1)} - \underline{x}^{(2)}) = e^t \underline{v}$$

Real valued solution:

$$\underline{x}(t) = C_1 e^t \underline{w} + C_2 e^t \underline{v}$$

$$\underline{x}(t) = C_1 e^t \begin{bmatrix} \cos(t) \\ -\sin(t) \end{bmatrix} + C_2 e^t \begin{bmatrix} \sin(t) \\ \cos(t) \end{bmatrix}$$

phase portrait:



$e^t \rightarrow \text{exp growth}$
 $\underline{w}, \underline{v} \rightarrow \text{oscillate around } (0,0)$

out spiral

spiral source

(spiral sink if arrows point to origin)

Q: Clockwise or Counter clockwise
 (CW) (CCW)

Evaluate $\underline{u}(t)$ and $\underline{v}(t)$ @ $t=0$

$$\underline{u} = \begin{bmatrix} \cos(t) \\ -\sin(t) \end{bmatrix}$$

$$\underline{u}' = \begin{bmatrix} -\sin(t) \\ -\cos(t) \end{bmatrix}$$

$$\underline{u}(0) = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$\underline{u}'(0) = \begin{bmatrix} 0 \\ -1 \end{bmatrix}$$

$$\underline{v} = \begin{bmatrix} \sin(t) \\ \cos(t) \end{bmatrix}$$

$$\underline{v}' = \begin{bmatrix} \cos(t) \\ -\sin(t) \end{bmatrix}$$

$$\underline{v}(0) = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$$\underline{v}'(0) = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

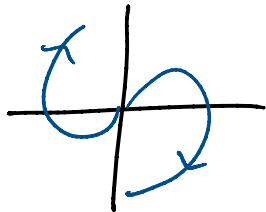
streamlines move in CW direction

phase portraits for complex eigenvalues

$$\lambda = a \pm bi$$

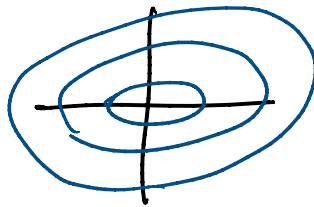
$$\text{Real}(\lambda) = a$$

$$\text{Real}(\lambda) > 0$$



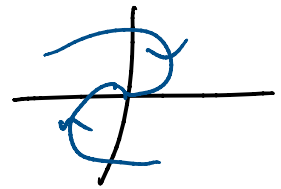
spiral source

$$\text{Re}(\lambda) = 0$$

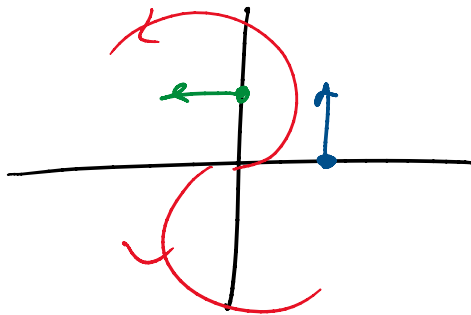


center

$$\text{Real}(\lambda) < 0$$



spiral sink



CCW spiral

$$\underline{u}(0) = \begin{bmatrix} 0 \\ 1 \end{bmatrix} \quad \underline{u}' = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

II Multiple Eigenvalue Solutions: → Lecture started Here

In Chap 3 (MA266) we solved:

$$y'' - by' + 9y = 0$$

Convert to a system of ODE

$$\underline{x}' = \begin{bmatrix} 0 & 1 \\ -9 & 6 \end{bmatrix} \underline{x}$$

these 2 ODEs are equivalent

Compare

1D

eqn $y'' - 6y' + 9y = 0$

char
eqn.

$$r^2 - 6r + 9 = 0$$

roots/
eigenvalues

$$(r - 3)^2 = 0$$

$$r = 3$$

multiplicity $k=2$
(repeated root)

fundamental
solutions

$$y_1(t) = e^{3t}$$

need a 2nd linearly
independent soln

→ multiply by t
(Reduction of order)

$$y_2(t) = te^{3t}$$

2D

$$\underline{x}' = \begin{bmatrix} 0 & 1 \\ -9 & 6 \end{bmatrix} \underline{x}$$

$$\det(\underline{A} - \lambda \underline{I}) = 0$$

$$\begin{vmatrix} -\lambda & 1 \\ -9 & 6-\lambda \end{vmatrix} = 0$$

$$\lambda^2 - 6\lambda + 9 = 0$$

$$(\lambda - 3)^2 = 0$$

$$\lambda = 3$$

algebraic multiplicity $k=2$
of times eigenvalue is repeated

$$\lambda = 3$$

$$(\underline{A} - 3\underline{I})\underline{v} = \underline{0}$$

$$\begin{bmatrix} -3 & 1 \\ -9 & 3 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$-3v_1 + v_2 = 0 \quad v_1 \text{ is a free variable}$$

$$v_2 = 3v_1$$

$$\underline{v} = \begin{bmatrix} v_1 \\ 3v_1 \end{bmatrix} = \begin{bmatrix} 1 \\ 3 \end{bmatrix} \quad \text{choose } v_1 = 1$$

only 1 eigenvector

geometric multiplicity $\rho = 1$

(# of eigenvectors correspond to λ)

Need to find a 2nd
linearly independent
vector u

NOTE: When

p
geometric
multiplicity
(# of eigenvectors)

<

k
algebraic
multiplicity
(# times λ is repeated)

We say that the eigenvalue λ is defective

Define the defect $d = k - p$

In our example: $p = 1$ < $k = 2$

so $\lambda = 3$ is defective with $d = k - p = 1$
one fundamental solution

$$\underline{x}^{(1)} = e^{3t} \begin{bmatrix} 1 \\ 3 \end{bmatrix}$$

Need to find a generalized eigenvector $\underline{u}$

In 2D: Solve $(\underline{A} - \lambda \underline{I}) \underline{u} = \underline{v}$

NOTE: This also means $(\underline{A} - \lambda \underline{I})^2 \underline{u} = \underline{0}$

$$(\underline{A} - \lambda \underline{I})^2 \underline{u} = (\underline{A} - \lambda \underline{I}) \underbrace{(\underline{A} - \lambda \underline{I}) \underline{u}}_{\underline{v}} = (\underline{A} - \lambda \underline{I}) \underline{v} = \underline{0}$$

b/c $\underline{v}$ is an eigenvector

Solve $(\underline{A} - \lambda \underline{I}) \underline{u} = \underline{v}$

$$\begin{bmatrix} -3 & 1 \\ -9 & 3 \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \end{bmatrix} = \begin{bmatrix} 1 \\ 3 \end{bmatrix}$$

$$-3u_1 + u_2 = 1$$

$$u_2 = 1 - 3u_1$$

u_1 is a free variable

choose $u_1 = 0$

$$\underline{u} = \begin{bmatrix} u_1 \\ 1 - 3u_1 \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

NOTE:

$$\underline{u} = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$$\underline{v} = \begin{bmatrix} 1 \\ 3 \end{bmatrix}$$

these are linearly independent

Second fundamental solution

$$\begin{aligned} \underline{x}^{(2)} &= e^{3t} (t\underline{v} + \underline{u}) = e^{3t} \left\{ t \begin{bmatrix} 1 \\ 3 \end{bmatrix} + \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right\} \\ &= e^{3t} \begin{bmatrix} t \\ 3t+1 \end{bmatrix} \end{aligned}$$

General solution:

$$\underline{x}(t) = C_1 \underline{x}^{(1)} + C_2 \underline{x}^{(2)}$$

$$= C_1 e^{3t} \begin{bmatrix} 1 \\ 3 \end{bmatrix} + C_2 e^{3t} \begin{bmatrix} t \\ 3t+1 \end{bmatrix}$$

Compare to the 1D solution

$$y(t) = C_1 e^{3t} + C_2 t e^{3t}$$

$$\underline{x} = \begin{bmatrix} x_1(t) \\ x_2(t) \end{bmatrix}$$

In 2D

$$x_1 = y(t) = C_1 e^{3t} + C_2 t e^{3t}$$

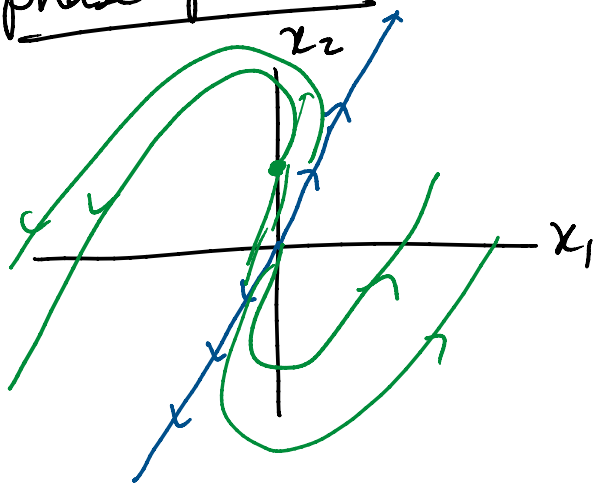
$$x_2 = y' = C_1 e^{3t} + C_2 (3t+1) e^{3t}$$

these solutions are equivalent.

Can derive $\underline{x}^{(2)}$ using

Reduction of Order

phase portrait



$$\underline{x}(t) = c_1 e^{3t} \begin{bmatrix} 1 \\ 3 \end{bmatrix} + c_2 e^{3t} \begin{bmatrix} t \\ 3t+1 \end{bmatrix}$$

1. Draw eigenvector $\underline{v} = \begin{bmatrix} 1 \\ 3 \end{bmatrix}$

2. $\lambda = 3$ is $\oplus$
so arrows point out

3. As $t \rightarrow \infty$
 $e^{3t} t \begin{bmatrix} 1 \\ 3 \end{bmatrix}$ dominates
 $\underline{x}$ goes parallel to $\begin{bmatrix} 1 \\ 3 \end{bmatrix}$

improper
nodal
source

4. Let $c_1 = 0, c_2 = 1$

$$\underline{x}' = 3e^{3t} \begin{bmatrix} t \\ 3t+1 \end{bmatrix} + e^{3t} \begin{bmatrix} 1 \\ 3 \end{bmatrix}$$

$$\underline{x}'(0) = 3 \begin{bmatrix} 0 \\ 1 \end{bmatrix} + \begin{bmatrix} 1 \\ 3 \end{bmatrix} = \begin{bmatrix} 1 \\ 6 \end{bmatrix} @ t=0 \quad \underline{x}(0) = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

goes parallel to $\begin{bmatrix} 1 \\ 3 \end{bmatrix}$

$\underline{x}(t) = e^{3t} \begin{bmatrix} t \\ 3t+1 \end{bmatrix}$ plug into a graph

III. Complete Eigenvalues:

Not every repeated eigenvalue is defective

$$\begin{matrix} p \\ \text{geometric} \\ \text{multiplicity} \\ (\# \text{ of eigenvectors}) \end{matrix} = \begin{matrix} k \\ \text{algebraic} \\ \text{multiplicity} \\ (\# \text{ times } \lambda \text{ is repeated}) \end{matrix}$$

then λ is called complete

Ex in 2D

$$\underline{x}' = \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix} \underline{x}$$

$$\det(A - \lambda I) = \begin{vmatrix} 2-\lambda & 0 \\ 0 & 2-\lambda \end{vmatrix} = (\lambda-2)^2 = 0$$

$$\lambda = 2$$

alg. mult $k=2$

$$\boxed{\lambda=2} \quad (A - 2I)\underline{v} = \underline{0}$$

$$\begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

0 equations

2 unknowns

v_1 and v_2 are free vars

want 2 linearly independent eigenvectors

$$\underline{v}^{(1)} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$\underline{v}^{(2)} = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

geometric multiplicity $p=2$

$\lambda=2$ is complete!

Fundamental solutions

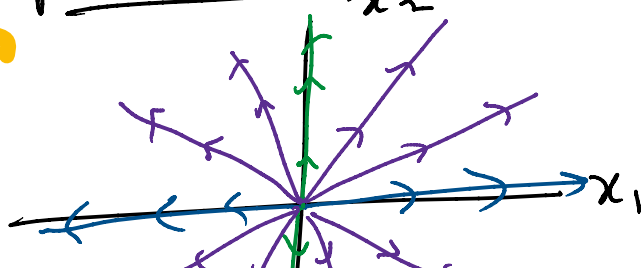
$$\underline{x}^{(1)} = e^{2t} \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$\underline{x}^{(2)} = e^{2t} \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

General solution

$$\underline{x}(t) = C_1 e^{2t} \begin{bmatrix} 1 \\ 0 \end{bmatrix} + C_2 e^{2t} \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

phase portrait:



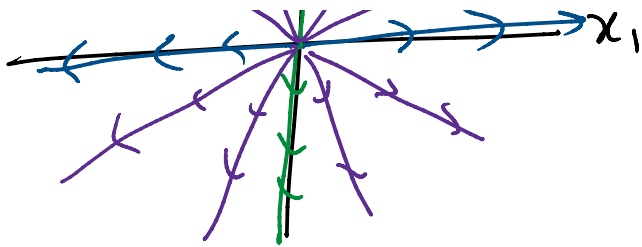
1. Draw eigenvectors

$$\underline{v}^{(1)} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$\underline{v}^{(2)} = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

2. $\lambda=2$ is $\oplus$
arrows point out

Bonus



proper model source

2. $\lambda = 2$ is $\oplus$
arrows point out

3. as $t \rightarrow \infty$
both $x^{(1)}$ and $x^{(2)}$ have
 e^{2t}
grow at same rate

makes sense b/c $\underline{\underline{A}} = \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix} = 2\underline{\underline{I}}$

$$\underline{x}' = \underline{\underline{A}}\underline{x} = 2\underline{\underline{I}}\underline{x} = 2\underline{x}$$

every vector $\underline{x}$ is an eigenvector!

Next class (in 3D) multiple eigenvectors