

★ Section 6.2 - Part 1

Linear & Almost Linear Systems

Warm up:

Recall the Taylor Series of a function $f(x)$ at the point $x=0$ is defined by:

$$f(x) \approx f(0) + x f'(0) + \frac{1}{2} x^2 f''(0) + \dots + \frac{x^n}{n!} f^{(n)}(0) + \dots$$

Find the first 3 terms of the Taylor Series of $f(x) = x^2 + 3e^x$

Ans: $f(x) \approx f(0) + x f'(0) + \frac{1}{2} x^2 f''(0)$

$$f(0) = [x^2 + 3e^x] \Big|_{x=0} = 0 + 3e^0 = 3$$

$$f'(0) = [2x + 3e^x] \Big|_{x=0} = 3$$

$$f''(0) = [2 + 3e^x] \Big|_{x=0} = 5$$

$$f(x) \approx \boxed{3 + 3x + \frac{5}{2}x^2}$$

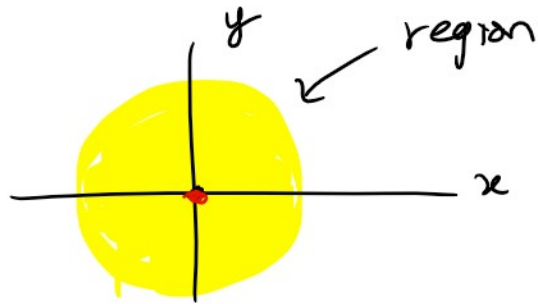
I, Stability of Linear Systems:

$$\begin{bmatrix} x \\ y \end{bmatrix}' = \underbrace{\begin{bmatrix} a & b \\ c & d \end{bmatrix}}_{\underline{\underline{A}}} \begin{bmatrix} x \\ y \end{bmatrix}$$

- the origin $(0,0)$ is always a critical point
- If $\det(\underline{\underline{A}}) = ad - bc \neq 0$, then the origin

- If $\det(\underline{A}) = ad - bc \neq 0$, then the origin is an isolated critical point

there is a small region around $(0,0)$ where it is the only c.p.



The characteristic eqn: $\det(\underline{A} - \lambda \underline{I}) = 0$
 $\lambda^2 - T\lambda + D = 0$

$$T = \text{trace}(\underline{A}) = a + d$$

$$D = \det(\underline{A})$$

The eigenvalues

$$\lambda = \frac{T}{2} \pm \frac{1}{2} \sqrt{T^2 - 4D}$$

We can classify the critical point $(0,0)$

λ	Type of c.p.	stable?
real, distinct same sign	improper node	yes if both $\lambda < 0$ (asympt. stable)
real, distinct opposite sign	saddle point	NO
real, equal	proper or improper node	Yes, if $\lambda < 0$ (asympt. stable)

complex conjugate $a \pm bi$	spiral point	yes if $\text{Re}(\lambda) < 0$ (asympt. stable)
pure imaginary $\pm bi$	center	yes
$\lambda_1 = 0, \lambda_2 \neq 0$	parallel lines	yes if $\lambda_2 < 0$

Thm: (Stability of Linear Systems)

Let λ_1 and λ_2 be the eigenvalues of
 $\underline{x}' = \underline{A}\underline{x}$ where $\det(\underline{A}) \neq 0$

Then, the critical point $(0,0)$ is:

1. Asymptotically stable if $\text{Re}(\lambda) < 0$
2. Stable if $\text{Re}(\lambda) = 0$
3. unstable otherwise

By looking at the eigenvalues λ , we can assess the stability of $(0,0)$

Ex: $\begin{bmatrix} x \\ y \end{bmatrix}' = \begin{bmatrix} -1 & -1 \\ 6 & 2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$

$$D = \det(\underline{A}) = (-1)(2) - 6(-1) = 4$$

$D \neq 0$ so $(0,0)$ is an isolated c.p.

$$T = \text{trace}(\underline{A}) = -1 + 2 = 1$$

Char. eqn. $\lambda^2 - T\lambda + D = 0$
 $\lambda^2 - \lambda + 4 = 0$

$$\lambda^2 - \lambda + 4 = 0$$

$$\lambda = \frac{1}{2} \pm \frac{1}{2} \sqrt{(-1)^2 - 4 \cdot 1 \cdot 4} = \frac{1}{2} \pm \frac{\sqrt{15}}{2} i$$

$$\operatorname{Re}(\lambda) = \operatorname{Re}\left(\frac{1}{2} \pm \frac{\sqrt{15}}{2} i\right) = \frac{1}{2} > 0 \quad \text{unstable}$$

and $(0,0)$ is a spiral source

Ex: $\begin{bmatrix} x \\ y \end{bmatrix}' = \begin{bmatrix} -4 & 1 \\ -6 & 2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$

$$D = \det(A) = -4(2) - 1(-6) = -2$$

$D \neq 0$ so $(0,0)$ is isolated

$$T = \operatorname{trace}(A) = -4 + 2 = -2$$

Char. eqn. $\lambda^2 - T\lambda + D = 0$

$$\lambda^2 + 2\lambda - 2 = 0$$

$$\lambda = \frac{-2}{2} \pm \frac{1}{2} \sqrt{2^2 - 4 \cdot (-2)}$$

$$= -1 \pm \frac{1}{2} \sqrt{12} = -1 \pm \sqrt{3}$$

$$\lambda_1 = -1 + \sqrt{3} > 0$$

$$\lambda_2 = -1 - \sqrt{3} < 0$$

$\operatorname{Re}(\lambda_1) > 0 \rightarrow$ unstable
saddle point.

II. Small Perturbations:

Q: What happens if we perturb a system by a little bit ε ? (assume $\varepsilon \ll 1$)

Ex: $\begin{bmatrix} x \\ y \end{bmatrix}' = \begin{bmatrix} -1 & -1+\varepsilon \\ 6 & 2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$

still linear

$$D = \det(\underline{A}) = (-1)(2) - 6(-1+\varepsilon) = -2 + 6 - 6\varepsilon = 4 - 6\varepsilon \neq 0 \quad \text{so } (0,0) \text{ is isolated}$$

$$T = \text{trac}(\underline{A}) = -1 + 2 = 1$$

char. eqn: $\lambda^2 - T\lambda + D = 0$

$$\lambda^2 - \lambda + 4 - 6\varepsilon = 0$$

$$\begin{aligned} \lambda &= \frac{1}{2} \pm \frac{1}{2} \sqrt{(-1)^2 - 4 \cdot 1 \cdot (4 - 6\varepsilon)} \\ &= \frac{1}{2} \pm \frac{1}{2} \sqrt{1 - 16 + 24\varepsilon} \\ &= \frac{1}{2} \pm \frac{1}{2} \sqrt{-15 + 24\varepsilon} \end{aligned}$$

Q: is $-15 + 24\varepsilon > 0$

$$24\varepsilon > 15$$

$$\varepsilon > \frac{15}{24} = \frac{5}{8}$$

but $\varepsilon \ll 1 \Rightarrow \Leftarrow$

No, $-15 + 24\varepsilon < 0$

eigenvalues $\lambda = \frac{1}{2} \pm bi$

so $(0,0)$ is unstable and spiral source
 $\wedge$
 remains

$\varepsilon \ll 1$
 if $\varepsilon < \frac{1}{10}$

remains
even after the perturbation $\epsilon \gg 1$

NOTE: In most cases, a small perturbation of Δ will NOT change the stability of the system

However, a perturbation can change the type of critical point (see A2)

III, Almost Linear Systems:

The Taylor series expansion of a function of two variables $f(x, y)$ at a point (x_0, y_0) is defined

$$f(x, y) = f(x_0, y_0) + f_x(x_0, y_0)(x - x_0) + f_y(x_0, y_0)(y - y_0) + r(x - x_0, y - y_0)$$

where $f_x(x_0, y_0) = \left. \frac{\partial f}{\partial x} \right|_{(x_0, y_0)}$

$$f_y(x_0, y_0) = \left. \frac{\partial f}{\partial y} \right|_{(x_0, y_0)}$$

and $r(x, y)$ is called the remainder
 $r(x, y) \sim O(x^2 + y^2)$

If x and y are small, then $r(x, y)$ is an order of magnitude smaller

$$\text{So } f(x, y) \approx f(x_0, y_0) + f_x(x_0, y_0)(x - x_0) + f_y(x_0, y_0)(y - y_0)$$

Ex: Find the Taylor series at $(0,0)$ of
 $f(x,y) = x^3y - \sin(2x) + e^y$

Ans: $f(0,0) = 0 - \sin(0) + e^0 = 1$

$$\frac{\partial f}{\partial x}(0,0) = \left[3x^2y - 2\cos(2x) \right] \Big|_{(0,0)} = -2$$

$$\frac{\partial f}{\partial y}(0,0) = \left[x^3 + e^y \right] \Big|_{(0,0)} = 1$$

$$\text{so } f(x,y) \approx 1 + (-2)(x-0) + (1)(y-0) \\ \approx 1 - 2x + y$$

these terms are now linear

GOAL: Use Taylor series to linearize a nonlinear system around a critical point.

Ex: $x' = F(x,y)$ let (x_*, y_*) is a critical point of the system
 $y' = G(x,y)$

By definition $F(x_*, y_*) = 0$
 $G(x_*, y_*) = 0$

Now, let's Taylor expand F and G around (x_*, y_*)

$$x' = F(x,y) = \cancel{F(x_*, y_*)} + F_x(x_*, y_*)(x-x_*) + F_y(x_*, y_*)(y-y_*) + r(x,y)$$

$$y' = G(x,y) = \cancel{G(x_*, y_*)} + G_x(x_*, y_*)(x-x_*) + G_y(x_*, y_*)(y-y_*) + s(x,y)$$

b/c (x_*, y_*) is a critical point

small
if $x-x_* < 1$
...

b/c (x_*, y_*) is a critical point

small
if $x - x_* < 1$
 $y - y_* < 1$

In matrix form:

$$(*) \begin{bmatrix} x' \\ y' \end{bmatrix} = \underbrace{\begin{bmatrix} F_x(x_*, y_*) & F_y(x_*, y_*) \\ G_x(x_*, y_*) & G_y(x_*, y_*) \end{bmatrix}}_{\underline{J} - \text{Jacobian matrix}} \begin{bmatrix} x - x_* \\ y - y_* \end{bmatrix} + \underbrace{\begin{bmatrix} r(x, y) \\ s(x, y) \end{bmatrix}}_{\text{very small near } (x_*, y_*)}$$

This is called the almost linear system
let $x_1 = x - x_*$ and $x_2 = y - y_*$
 $x_1' = x'$ $x_2' = y'$

$$(\square) \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}' = \begin{bmatrix} \underline{J} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \quad \text{we call this the associated linear system}$$

We can consider the almost linear system (*) is a perturbation of the linear system (□)

Q: What can the linear system (□) tell us about the almost linear system (*)?

Thm: The almost linear system (*) will have the same type of critical point and the same stability as the linear system (□)

UNLESS $\lambda_1 = \lambda_2$ or $\lambda = \pm bi$

★ Summary:

- a nonlinear system

$$x' = F(x, y)$$

$$y' = G(x, y)$$

has a critical point (x_*, y_*) when

$$F(x_*, y_*) = 0 = G(x_*, y_*)$$

- Use Taylor series to get the almost linear system

$$\begin{bmatrix} x' \\ y' \end{bmatrix} = \underbrace{\begin{bmatrix} F_x(x_*, y_*) & F_y(x_*, y_*) \\ G_x(x_*, y_*) & G_y(x_*, y_*) \end{bmatrix}}_{\underline{\underline{J}} - \text{Jacobian matrix}} \begin{bmatrix} x - x_* \\ y - y_* \end{bmatrix} + \begin{bmatrix} r(x, y) \\ s(x, y) \end{bmatrix}$$

- Find the associated linear system and evaluate the type and stability of the c.p.

$$\underline{\underline{x}}' = \underline{\underline{J}} \underline{\underline{x}}$$

$$\text{where } \underline{\underline{x}} = \begin{bmatrix} x - x_* \\ y - y_* \end{bmatrix}$$

Ex:
$$\begin{aligned} x' &= 4x + 7y - (x^2 + 3y^2) r(x,y) \\ y' &= x - 2y - 13xy s(x,y) \end{aligned}$$

1. Claim: $(0,0)$ is a critical point

2. Calculate the Jacobian

$$\underline{J} = \begin{bmatrix} F_x & F_y \\ G_x & G_y \end{bmatrix} \bigg|_{(0,0)}$$

$$= \begin{bmatrix} 4-2x & 7+6y \\ 1-13y & -2-13x \end{bmatrix} \bigg|_{(0,0)} = \begin{bmatrix} 4 & 7 \\ 1 & -2 \end{bmatrix}$$

Associated
Linear system:

$$\begin{bmatrix} x' \\ y' \end{bmatrix} = \underline{J} \underline{\dot{x}} = \begin{bmatrix} 4 & 7 \\ 1 & -2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$

$$\begin{aligned} x' &= 4x - 7y \\ y' &= x - 2y \end{aligned}$$

Taylor Series

$$F(x,y) = F(0,0) + F_x(0,0)x + F_y(0,0)y + r(x,y)$$

keep all
the linear
terms from
autonomous
system