Homework 9

Due December 2nd on paper at the beginning of class. Please let me know if you have a question or find a mistake.

- Exercise 14 from Chapter 4, page 74 of do Carmo's book https://link-springer-com. ezproxy.lib.purdue.edu/book/10.1007/978-3-642-57951-6. For part (b), give two constructions of a suitable triple (P,Q,R) as follows. Give one following the hint: this is an implementation of a general formula from Poincaré's lemma, and is applicable to differential forms of any degree in any dimension. Give a second, simpler one, which works in this special case by setting one of P, Q and R equal to zero and then solving the system by integration and back substitution. Prove the difference (P₁, Q₁, R₁) − (P₂, Q₂, R₂) between the two solutions is given by (∂_xf, ∂_yf, ∂_zf) for some smooth f, and find f in terms of P₁, P₂, Q₁, Q₂, R₁, R₂.
- 2. Let $\varphi(r, \theta, z) = (r \cos \theta, r \sin \theta, z)$ be the cylindrical coordinate map. Find functions a, b, and c, such that $e_1 = \varphi_* a \partial r$, $e_2 = \varphi_* b \partial \theta$ and $e_3 = \varphi_* c \partial z$ are an orthonormal frame. Compute the pull-backs of the dual frame $\varphi^* \omega_j$ for j = 1, 2, 3 and of the connection one forms $\varphi^* \omega_{jk}$ for j, k = 1, 2, 3.
- 3. (a) Exercise 5 from Chapter 5, page 97 of do Carmo's book https://link-springer-com. ezproxy.lib.purdue.edu/book/10.1007/978-3-642-57951-6. To solve this, find an orthonormal frame of the form e₁ = a∂_x, e₂ = b∂_y, for suitable positive functions a and b. Then find the dual frame ω₁, ω₂, and find ω₁₂ by writing ω₁₂ = fdx + hdy and solving for f and h by plugging into dω₁ = ω₁₂ ∧ ω₂ and dω₂ = ω₁ ∧ ω₁₂. Finally solve for K by plugging into dω₁₂ = -Kω₁ ∧ ω₂.
 - (b) The most important case is when K is a constant. Let $U = \{(x, y) : y > 0\}$. For each constant c < 0, find $g: U \to (0, \infty)$ such that K(x, y) = c for all $(x, y) \in U$. (This generalizes Exercise 2 from the previous page).