

## ★ A Gallery of Solution Curves

Warm up: Find the trace  $T$  of the matrix  $\underline{\underline{A}}$

$$\underline{\underline{A}} = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$$

Ans:  $T = \text{trace}(\underline{\underline{A}}) = a + d$

For a 2D linear systems:

$$\underline{x}' = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \underline{x}$$

the phase portrait depends on the eigenvalues and eigenvectors of  $\underline{\underline{A}}$

eigenvectors:  $\det(\underline{\underline{A}} - \lambda \underline{\underline{I}}) = 0$

$$\begin{vmatrix} a-\lambda & b \\ c & d-\lambda \end{vmatrix} = (a-\lambda)(d-\lambda) - bc \\ = \lambda^2 - a\lambda - d\lambda + ad - bc = 0$$

$$\lambda^2 - \underbrace{(a+d)}_{T = \text{trace}(\underline{\underline{A}})} \lambda + \underbrace{(ad-bc)}_{D = \det(\underline{\underline{A}})} = 0$$

$$\lambda^2 - T\lambda + D = 0$$

eigenvalues are roots of 2nd degree polynomial.

Three major cases:

- I. Real distinct  $\lambda$
- II. Repeated  $\lambda$  with  $k=2$
- III. Complex  $\lambda$

- ... broken into subcases.

III. Complex  
 Each case can be broken into subcases.

I. Real distinct  $\lambda$ :

(a)  $\lambda$  opposite signs:

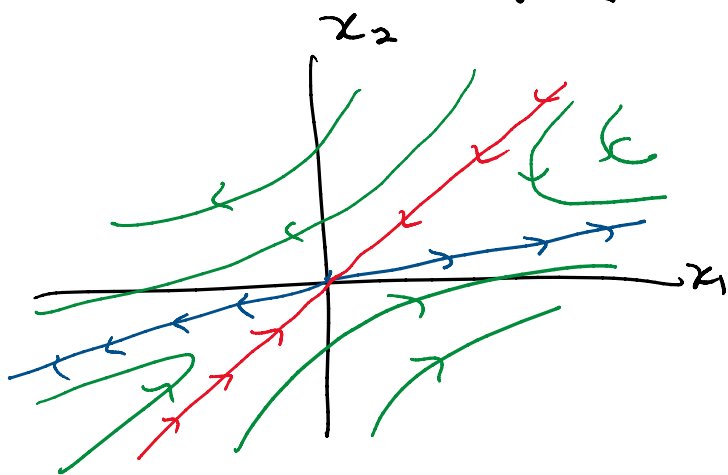
Ex:  $\underline{x}' = \begin{bmatrix} 3 & -4 \\ 1 & 2 \end{bmatrix} \underline{x}$

$\lambda_1 = 2 \quad \underline{v}^{(1)} = \begin{bmatrix} 4 \\ 1 \end{bmatrix}$

$\lambda_2 = -1 \quad \underline{v}^{(2)} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$

general solution:

$\underline{x}(t) = c_1 e^{2t} \begin{bmatrix} 4 \\ 1 \end{bmatrix} + c_2 e^{-t} \begin{bmatrix} 1 \\ 1 \end{bmatrix}$



1. Draw the eigenvectors
2. Draw connecting curves

Saddle point

1 ev points in  
 1 ev points out

(b)  $\lambda$  both negative

Ex:  $\underline{x}' = \begin{bmatrix} 0 & -1 \\ 2 & -3 \end{bmatrix} \underline{x}$

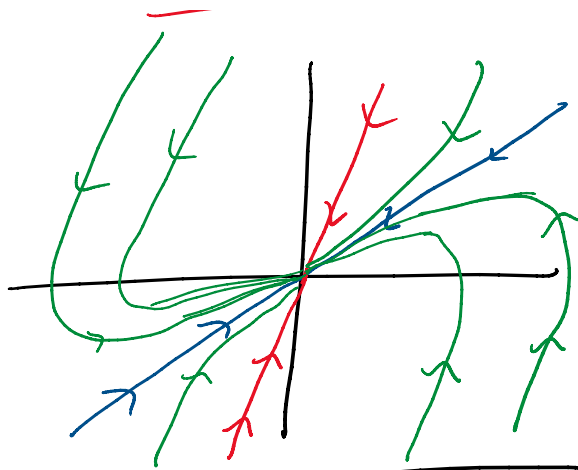
$\lambda_1 = -1 \quad \underline{v}^{(1)} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$

$\lambda_2 = -2 \quad \underline{v}^{(2)} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$

general solution:

$\underline{x}(t) = c_1 e^{-t} \begin{bmatrix} 1 \\ 1 \end{bmatrix} + c_2 e^{-2t} \begin{bmatrix} 1 \\ 2 \end{bmatrix}$

1. Draw eigenvectors



improper nodal sink

- multiple solns approach origin
- tangent to the same line  $\begin{bmatrix} 1 \\ 1 \end{bmatrix}$

(c)  $\lambda$  both positive

improper nodal source

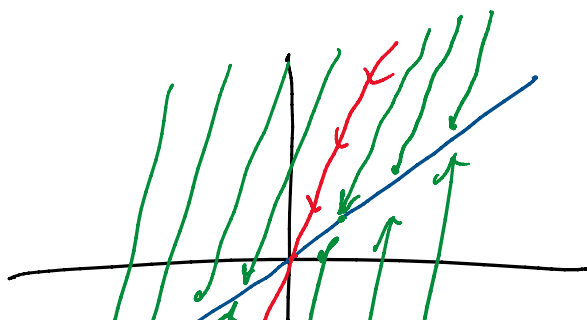
Same as (b) but with arrows flipped as  $t \rightarrow \infty$ ,  $\underline{x} \rightarrow +\infty$

(d) one zero eigenvalue

Ex:  $\underline{x}' = \begin{bmatrix} 1 & -1 \\ 2 & -2 \end{bmatrix} \underline{x}$

$\lambda_1 = 0$       $\underline{v}^{(1)} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$

$\lambda_2 = -1$       $\underline{v}^{(2)} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$

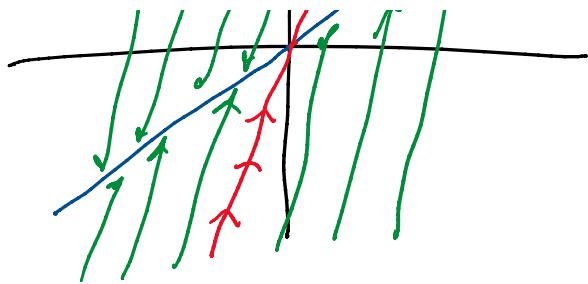


1. Draw eigenvectors
2. Limit as  $t \rightarrow \infty$   
 $e^{-t}$  "dominates"  
 $\underline{x} \rightarrow$  parallel  $\begin{bmatrix} 1 \\ 1 \end{bmatrix}$
3. Limit as  $t \rightarrow -\infty$   
 $e^{-2t}$  dominates  
 $\underline{x} \rightarrow$  parallel  $\begin{bmatrix} 1 \\ 2 \end{bmatrix}$

general solution:

$$\underline{x}(t) = c_1 \begin{bmatrix} 1 \\ 1 \end{bmatrix} + c_2 e^{-t} \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

1. Draw eigenvectors
2. Limits at  $t \rightarrow \infty$   
 $e^{-t} \rightarrow 0$   
 $\underline{x} \rightarrow c_1 \begin{bmatrix} 1 \\ 1 \end{bmatrix}$



parallel lines

$\lambda_2 < 0 \rightarrow$  stop on  $\underline{v}^{(1)}$   
 $\lambda_2 > 0 \rightarrow$  emanate from  $\underline{v}^{(1)}$

$$\underline{x} \rightarrow c_1 \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

3. limit as  $t \rightarrow -\infty$   
 $\underline{x} \rightarrow$  parallel  $\begin{bmatrix} 1 \\ 2 \end{bmatrix}$

## II. Real repeated $\lambda$ :

(a) If  $\lambda$  is complete

geometric mult  
 $p$

=

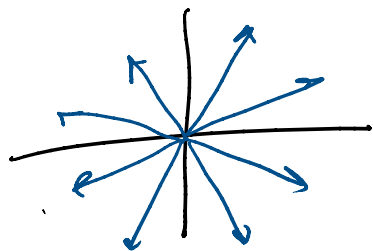
algebraic mult  
 $k$

# of eigenvectors = 2

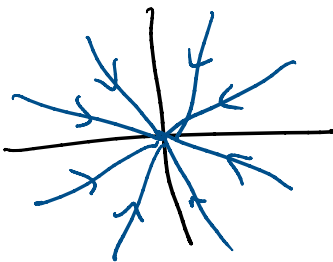
2 linearly indep eigenvectors  $\underline{v}^{(1)}$  and  $\underline{v}^{(2)}$

General solution:  $\underline{x}(t) = c_1 e^{\lambda t} \underline{v}^{(1)} + c_2 e^{\lambda t} \underline{v}^{(2)}$

if  $\lambda > 0$



proper nodal source



proper nodal sink

(b) If  $\lambda$  is defective

(b) If  $\lambda$  is defective

geometric mult  $p <$

algebraic mult  $k=2$

# of eigenvectors = 1

Ex:  $\underline{x}' = \begin{bmatrix} 4 & 1 \\ -1 & 2 \end{bmatrix} \underline{x}$

$\lambda = 3$  w/ <sup>alg</sup> mult  $k=2$

$\lambda = 3 \quad \begin{bmatrix} 1 & 1 \\ -1 & -1 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$

$v_1 + v_2 = 0$   
 $v_2 = -v_1$

$\underline{v} = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$

one eigenvector  $\Rightarrow p=1$

Need to find generalized eigenvector  $\underline{u}$

$\begin{bmatrix} 1 & 1 \\ -1 & -1 \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \end{bmatrix} = \begin{bmatrix} 1 \\ -1 \end{bmatrix} \rightarrow$

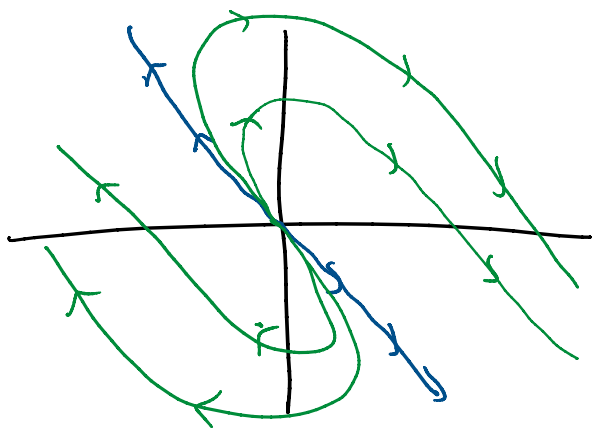
$u_1 + u_2 = 1$   
 $u_2 = 1 - u_1$

$\underline{u} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$

General solution:

$\underline{x}(t) = C_1 e^{\lambda t} \underline{v} + C_2 e^{\lambda t} \{ t \underline{v} + \underline{u} \}$

$\underline{x}(t) = C_1 e^{3t} \begin{bmatrix} 1 \\ -1 \end{bmatrix} + C_2 e^{3t} \left\{ t \begin{bmatrix} 1 \\ -1 \end{bmatrix} + \begin{bmatrix} 1 \\ 0 \end{bmatrix} \right\}$



improper nodal source

1. Draw eigenvector

2. limit as  $t \rightarrow \infty$   
 $t e^{3t}$  dominates  
 $\underline{x} \rightarrow$  parallel  $\begin{bmatrix} 1 \\ -1 \end{bmatrix}$

(if  $\lambda < 0$ , sink)

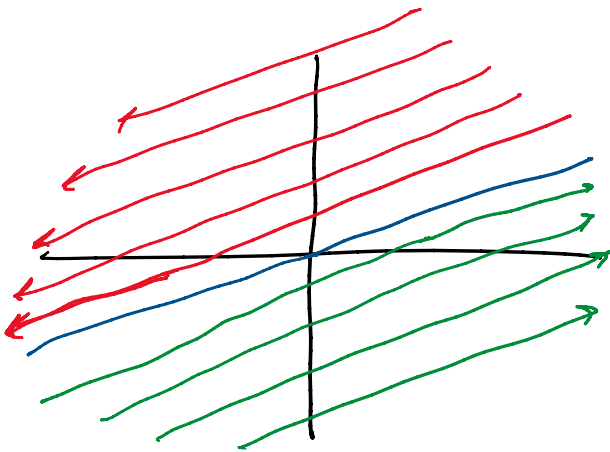
(c)  $\lambda = 0$  repeated

Ex:  $\underline{x}' = \begin{bmatrix} 2 & -4 \\ 1 & -2 \end{bmatrix} \underline{x}$

char eqn:  $\lambda^2 = 0$   
 $\lambda = 0$  w/  $k=2$

$\lambda = 0$   $\underline{v} = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$   $p=1$ , generalized eigenvector  $\underline{u} = \begin{bmatrix} 3 \\ 1 \end{bmatrix}$

general solution:  $\underline{x}(t) = c_1 \begin{bmatrix} 2 \\ 1 \end{bmatrix} + c_2 \left\{ t \begin{bmatrix} 2 \\ 1 \end{bmatrix} + \begin{bmatrix} 3 \\ 1 \end{bmatrix} \right\}$



Variation on

parallel lines

1. Draw eigenvector

2. limit as  $t \rightarrow \infty$   
 $t$  dominates

$\underline{x} \rightarrow$  parallel  $\begin{bmatrix} 2 \\ 1 \end{bmatrix}$

3. plug in  $c_1=0, c_2=1$

$\underline{x} = t \begin{bmatrix} 2 \\ 1 \end{bmatrix} + \begin{bmatrix} 3 \\ 1 \end{bmatrix}$

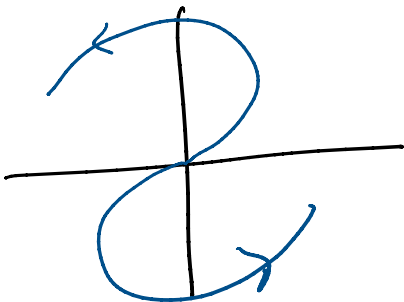
4. plug in  $c_1=0, c_2=-1$

$\underline{x} = -t \begin{bmatrix} 2 \\ 1 \end{bmatrix} - \begin{bmatrix} 3 \\ 1 \end{bmatrix}$

III. Complex  $\lambda$ :

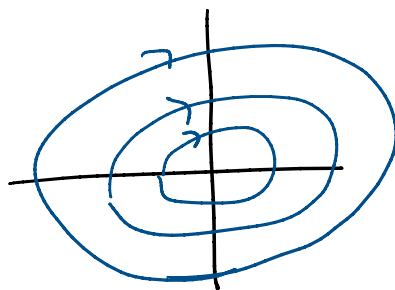
$\lambda = a \pm bi$

(a)  $\text{Re}(\lambda) > 0$



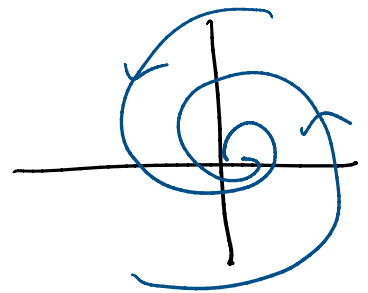
spiral source

(b)  $\text{Re}(\lambda) = 0$



center

(c)  $\text{Re}(\lambda) < 0$



spiral sink

→ look at solution to determine direction of rotation.

$$\lambda = a \pm bi \quad \underline{x}(t) = e^{at} (C_1 \underline{u} + C_2 \underline{v})$$

evaluate: 
$$\begin{cases} \underline{u}(0) & \underline{v}(0) \\ \underline{u}'(0) & \underline{v}'(0) \end{cases}$$

Ex: 
$$\underline{x}' = \begin{bmatrix} 6 & -17 \\ 8 & -6 \end{bmatrix} \underline{x} \quad \lambda = \pm 10i$$

$$\lambda = 10i \rightarrow \begin{bmatrix} 6-10i & -17 \\ 8 & -6-10i \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$8v_1 - (6+10i)v_2 = 0$$

$$v_1 = \frac{(6+10i)v_2}{8} = \frac{(3+5i)v_2}{4}$$

$v_2$  is a free variable, choose  $v_2 = 4$

$$\underline{v}^{(1)} = \begin{bmatrix} 3+5i \\ 4 \end{bmatrix}$$

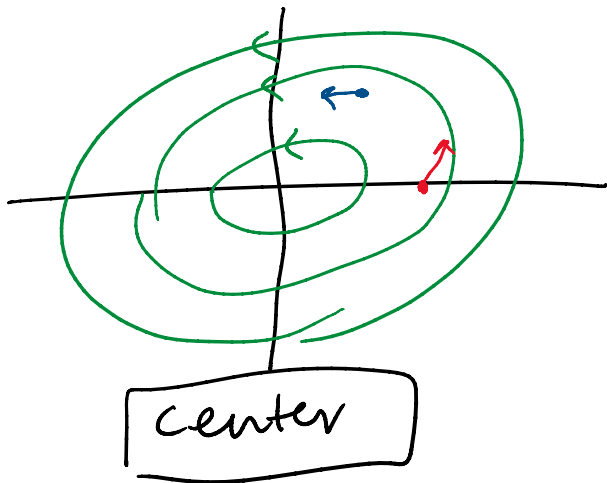
$$\underline{x}^{(1)} = e^{10it} \begin{bmatrix} 3+5i \\ 4 \end{bmatrix} = (\cos(10t) + i\sin(10t)) \begin{bmatrix} 3+5i \\ 4 \end{bmatrix}$$

$$= \begin{bmatrix} 3\cos(10t) + 3i\sin(10t) + 5i\cos(10t) - 5\sin(10t) \\ 4\cos(10t) + 4i\sin(10t) \end{bmatrix}$$

$$= \underbrace{\begin{bmatrix} 3\cos(10t) - 5\sin(10t) \\ 4\cos(10t) \end{bmatrix}}_{\underline{u}} + i \underbrace{\begin{bmatrix} 3\sin(10t) + 5\cos(10t) \\ 4\sin(10t) \end{bmatrix}}_{\underline{v}}$$

general solution:  $\underline{x}(t) = c_1 \underline{u} + c_2 \underline{v}$

$$\underline{x}(t) = c_1 \begin{bmatrix} 3 \cos(10t) - 5 \sin(10t) \\ 4 \cos(10t) \end{bmatrix} + c_2 \begin{bmatrix} 3 \sin(10t) + 5 \cos(10t) \\ 4 \sin(10t) \end{bmatrix}$$



1. center b/c  $\text{Re}(\lambda) = 0$

2.  $\underline{u}(0) = \begin{bmatrix} 3 \\ 4 \end{bmatrix}$   $\underline{u}'(0) = \begin{bmatrix} -50 \\ 0 \end{bmatrix}$

3.  $\underline{v}(0) = \begin{bmatrix} 5 \\ 0 \end{bmatrix}$   $\underline{v}'(0) = \begin{bmatrix} 30 \\ 40 \end{bmatrix}$

ccw direction